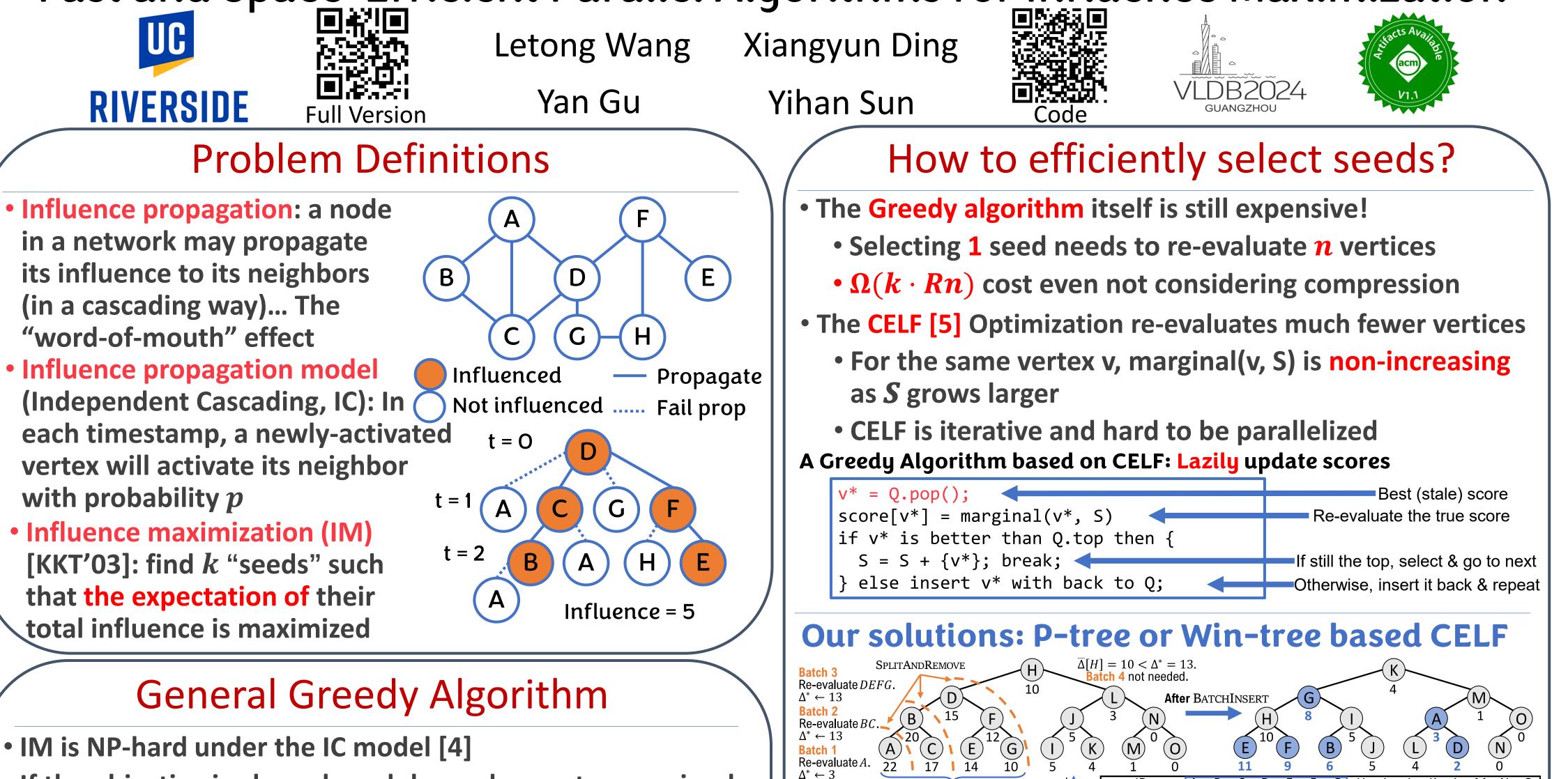
## Fast and Space-Efficient Parallel Algorithms for Influence Maximization



 If the objective is also submodular and monotone: a simple greedy algorithm is (1-1/e)-approximation [4]

## A Greedy Algorithm:

- Start from empty seed set S
- Repeatedly adding the vertex with the highest marginal gain to S.

```
marginal(S, v) = influence(S \cup \{v\}) - influence(S)
S = { }
for i = 1 to k {
  v^* = \arg \max \operatorname{marginal}(S, v)
  S = S \cup \{v\}
```

# How to compute the influence $\sigma(S)$ ?

• Simulation [4,5]: simulate the influence propagation for R rounds and use the average<sub>Simulation</sub> 1: influence = 5

• Very expensive in time

- Simulation 2: influence = 4
- Influence({D}) = ?
- Simulation 3: influence = 4

#### Expectation = 4.333 • Memoization [2]: memorizing the simulation results of the influence propagation for *R* rounds and use the average

- Very expensive in space A A sketch is a subgraph: B
- where edges represent

 ID
 A
 B
 C
 D
 E
 F
 G
 H
 I
 J
 K
 L
 M
 N
 O

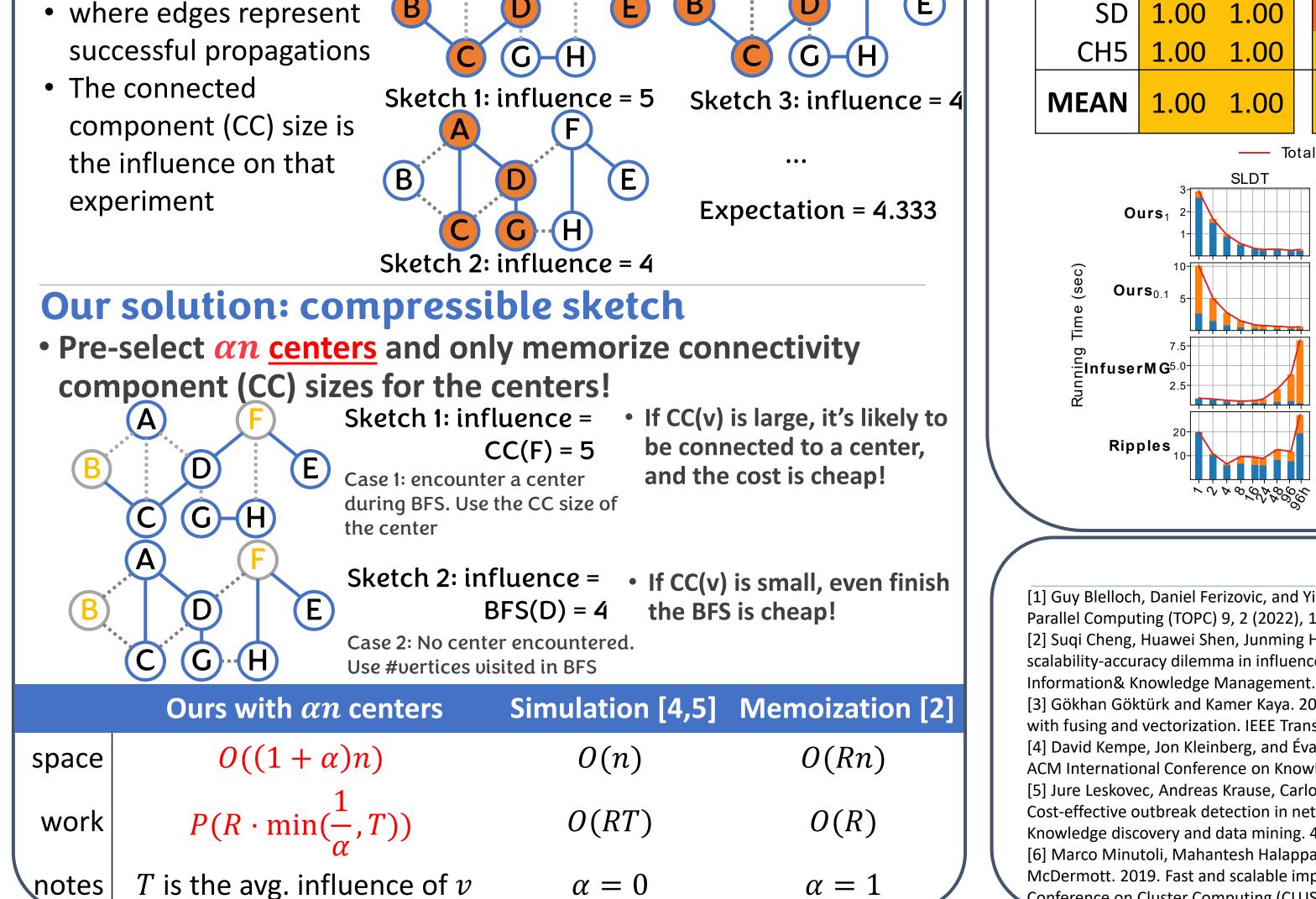
 Stale score  $\overline{\Delta}$  22
 20
 17
 15
 14
 12
 10
 10
 5
 5
 4
 4
 1
 0
 0

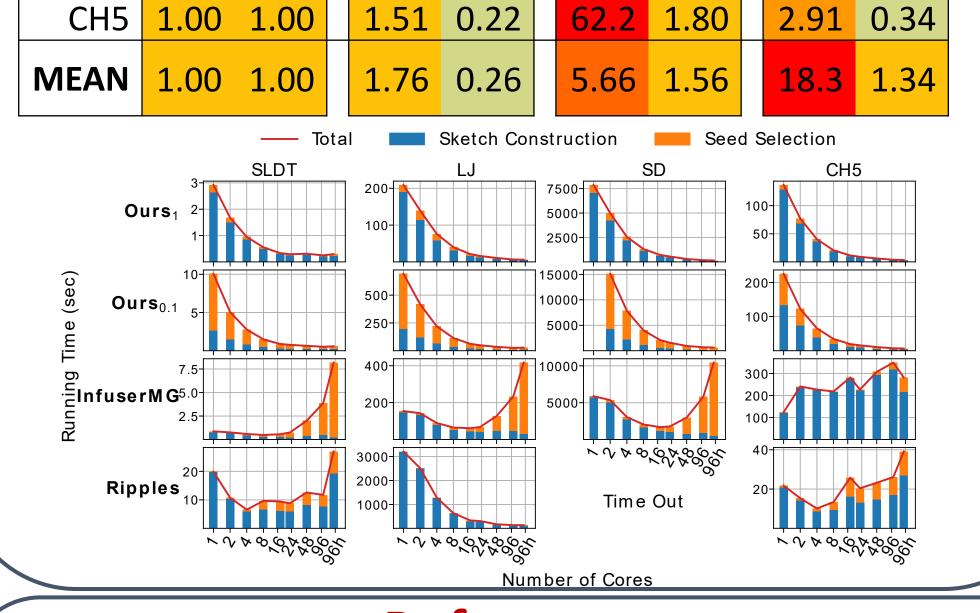
 True score  $\Delta$  3
 6
 13
 2
 11
 9
 8
 < CABDEFG Updated to true  $\rightarrow$  13 3 Re-evaluated by CELF (A to E) scores Solution based on Parallel Trees (P-trees)[1] • **P-tree:** binary search trees support: • split, batch\_insert, construction • "prefix-doubling": evaluate batches of size 1, 2, 4, 8, ... until the **best new score** is **better** than all the stale scores! • **Theorem:** The total number of evaluations for P-tree is at most twice as that of CELF • (Another) Solution based on Winning Trees • Slightly better in practice, but no worst-case guarantee **Experimental Results** • Setup • Machine: 96 cores, 1.5TB memory • **Baselines:** Ours<sub>1</sub>=ours with no compression, Ours<sub>0,1</sub>=ours with  $\alpha = 0.1$ , InfuserMG [3] and Ripples [6] are parallel baseline systems Ours<sub>0.1</sub> **Ours**<sub>1</sub> InfuserMG Ripples Time Space Time Space Time Space Time Space 1.76 0.38 SLDT 1.00 1.00 1.60 1.17 22.8 1.65

10.2 1.76

11.2 1.69

21.7 3.41





3.42 0.27

4.18 0.36

1.00 1.00

LJ

Ε

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