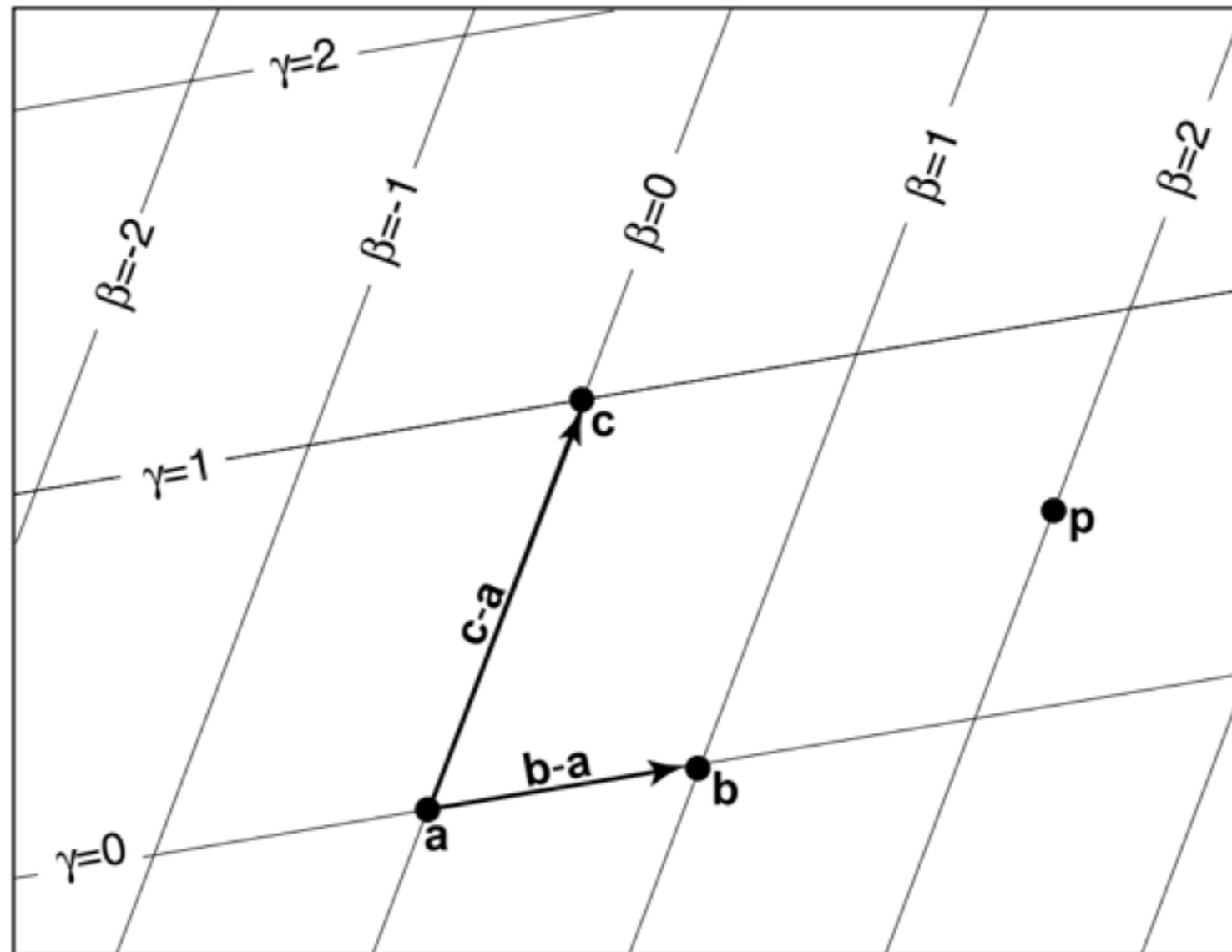


# Triangles

# barycentric coordinates

$$\mathbf{p} = \mathbf{a} + \beta(\mathbf{b} - \mathbf{a}) + \gamma(\mathbf{c} - \mathbf{a})$$



# barycentric coordinates

$$\mathbf{p} = \mathbf{a} + \beta(\mathbf{b} - \mathbf{a}) + \gamma(\mathbf{c} - \mathbf{a})$$

$$\mathbf{p} = (1 - \beta - \gamma)\mathbf{a} + \beta\mathbf{b} + \gamma\mathbf{c}$$

$$\alpha \equiv 1 - \beta - \gamma$$

$$\mathbf{p}(\alpha, \beta, \gamma) = \alpha\mathbf{a} + \beta\mathbf{b} + \gamma\mathbf{c}$$

$$\alpha + \beta + \gamma = 1$$

# barycentric coordinates

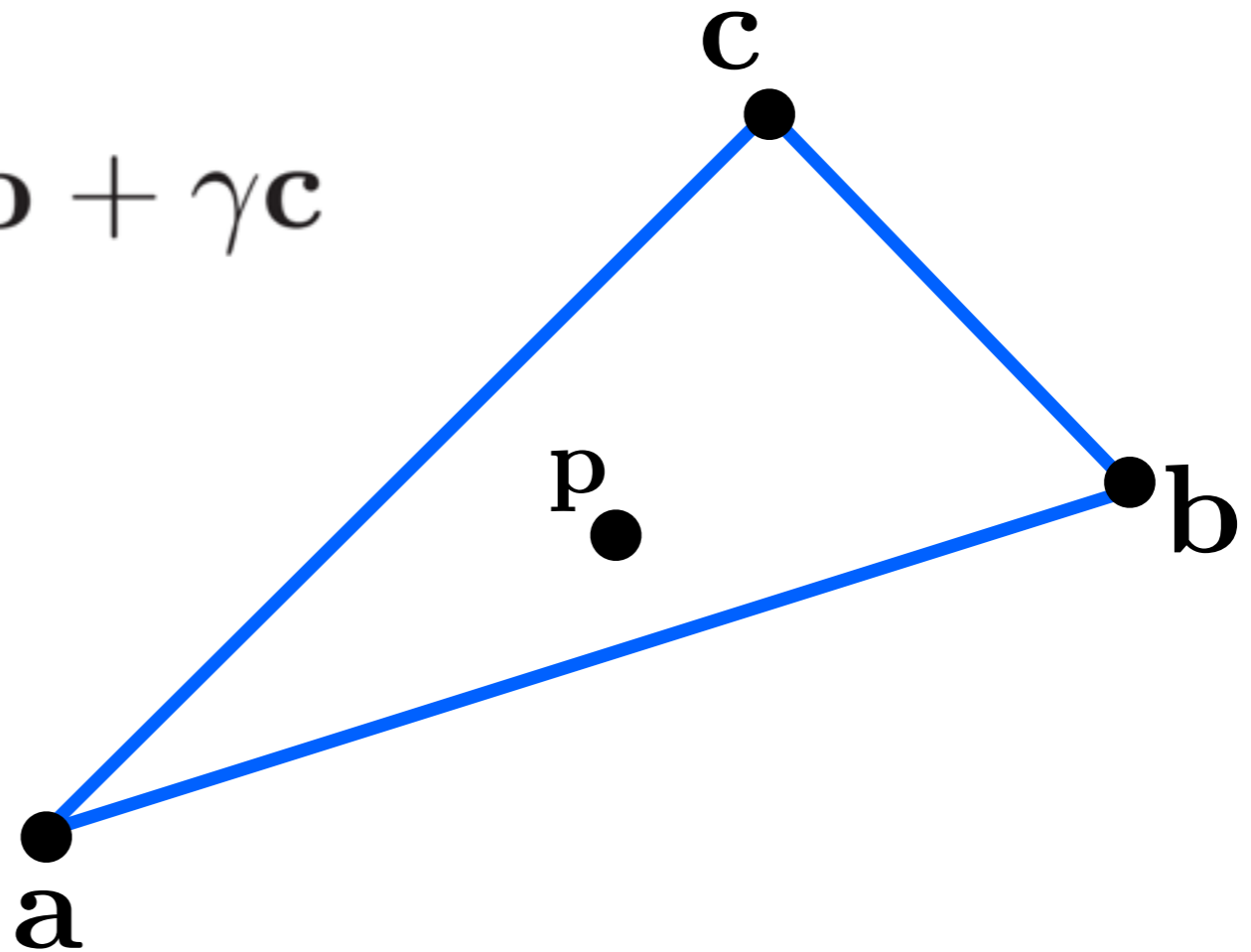
If  $\mathbf{p}$  inside the triangle,

$$\mathbf{p}(\alpha, \beta, \gamma) = \alpha \mathbf{a} + \beta \mathbf{b} + \gamma \mathbf{c}$$

$$0 < \alpha < 1$$

$$0 < \beta < 1$$

$$0 < \gamma < 1.$$



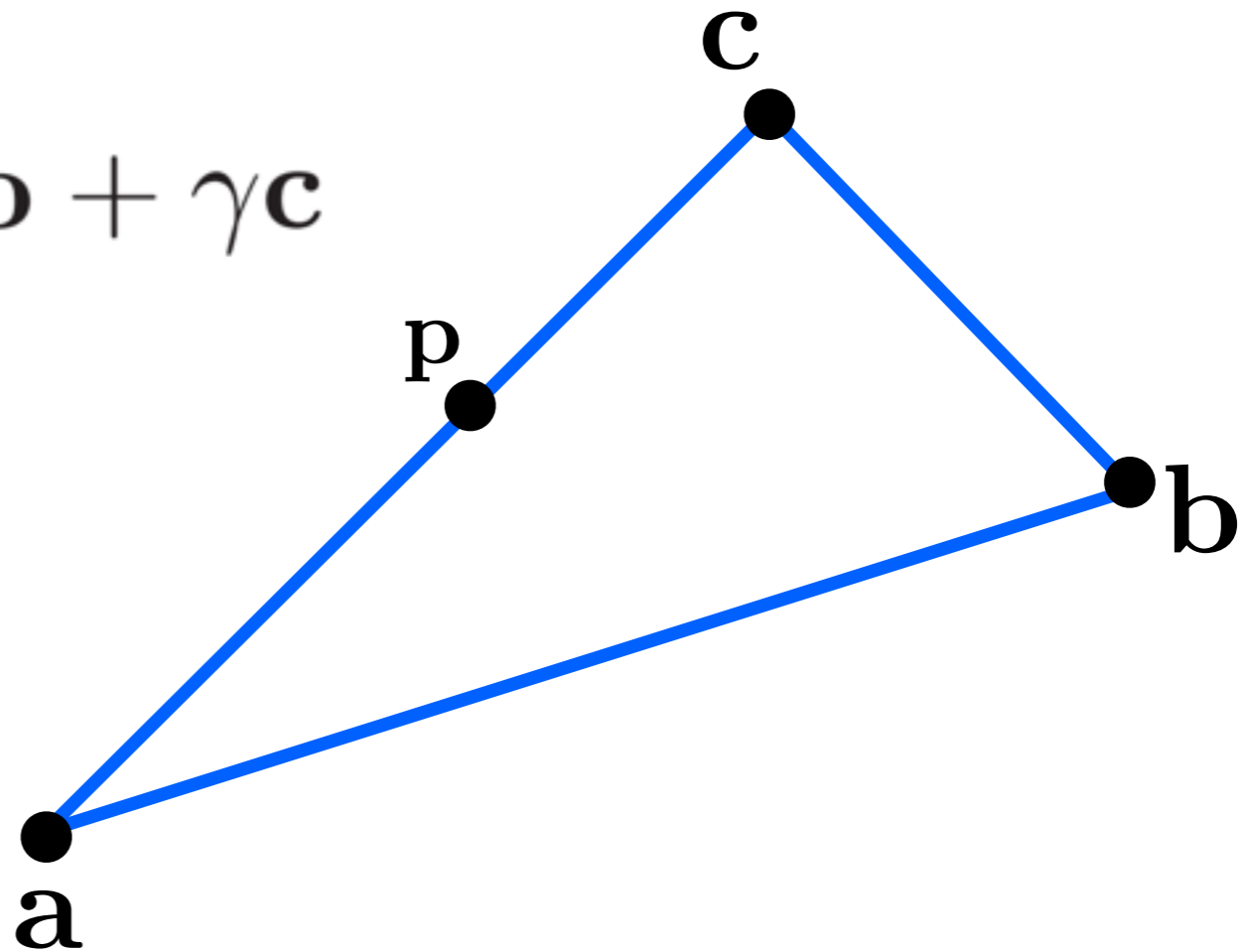
# barycentric coordinates

If  $\mathbf{p}$  on an edge, e.g.,

$$\mathbf{p}(\alpha, \beta, \gamma) = \alpha \mathbf{a} + \beta \mathbf{b} + \gamma \mathbf{c}$$

$$\beta = 0$$

$$\alpha + \gamma = 1$$

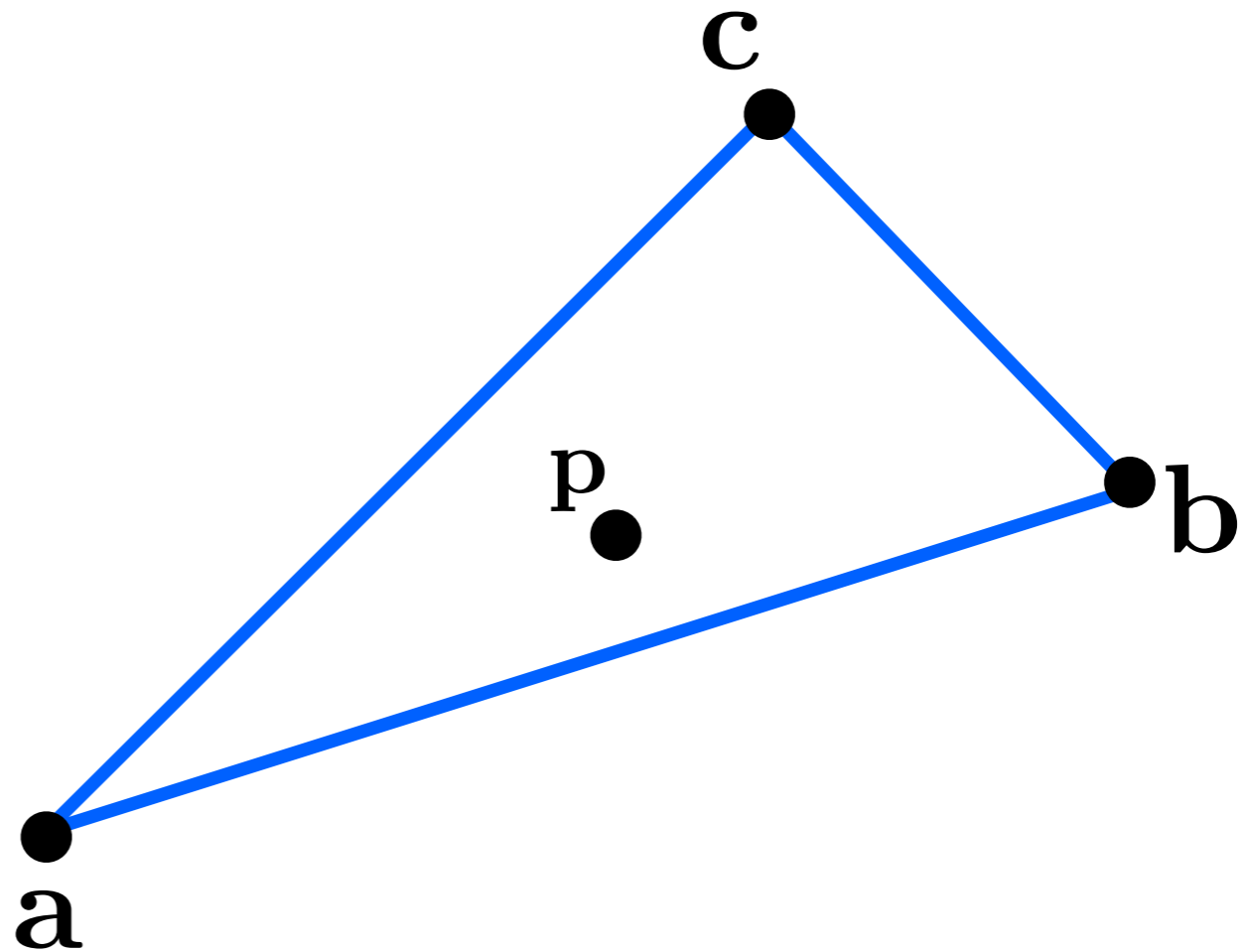


# barycentric coordinates

$$\mathbf{p} = \alpha \mathbf{a} + \beta \mathbf{b} + \gamma \mathbf{c}$$

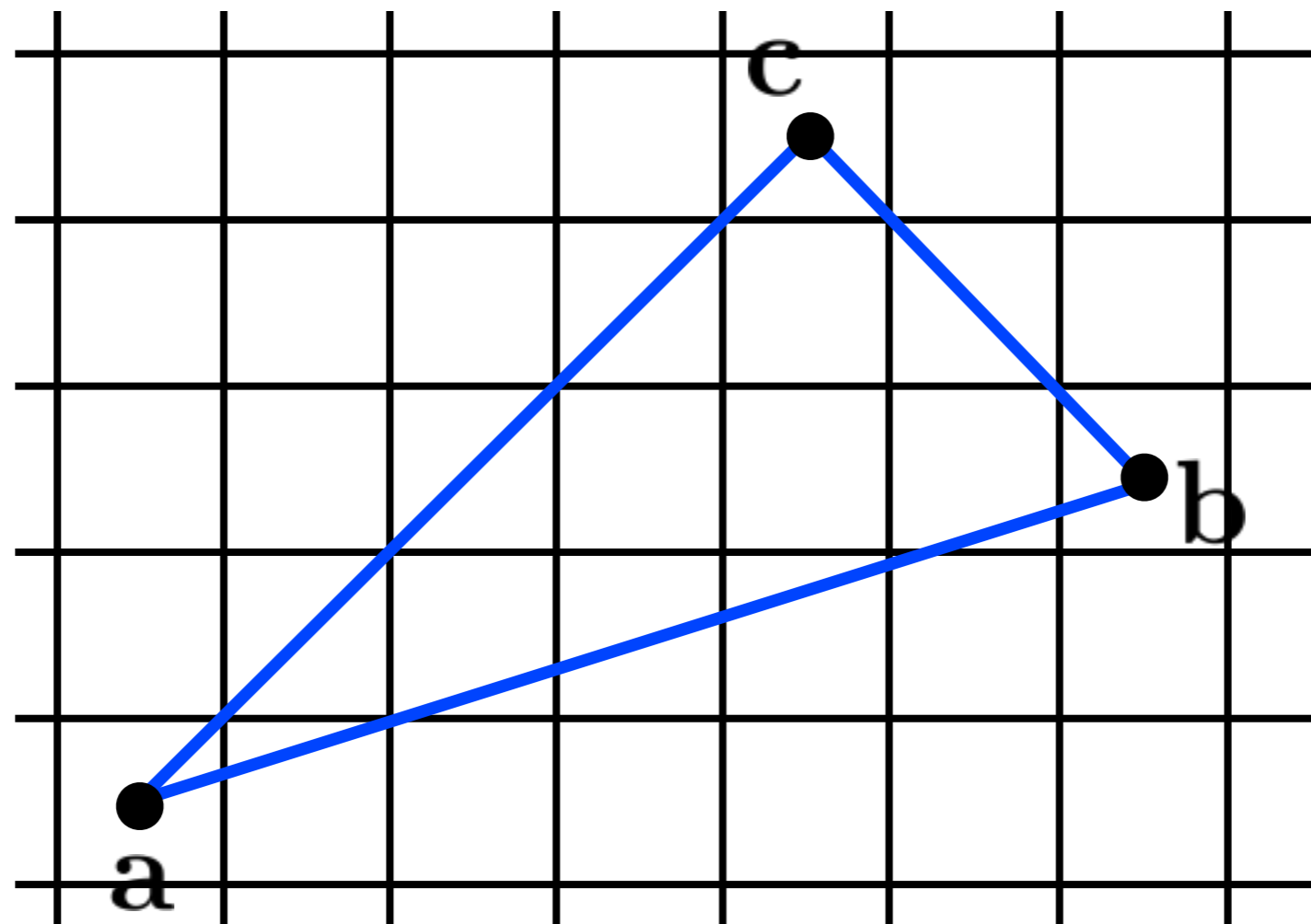
What are  $(\alpha, \beta, \gamma)$  ?

<whiteboard>



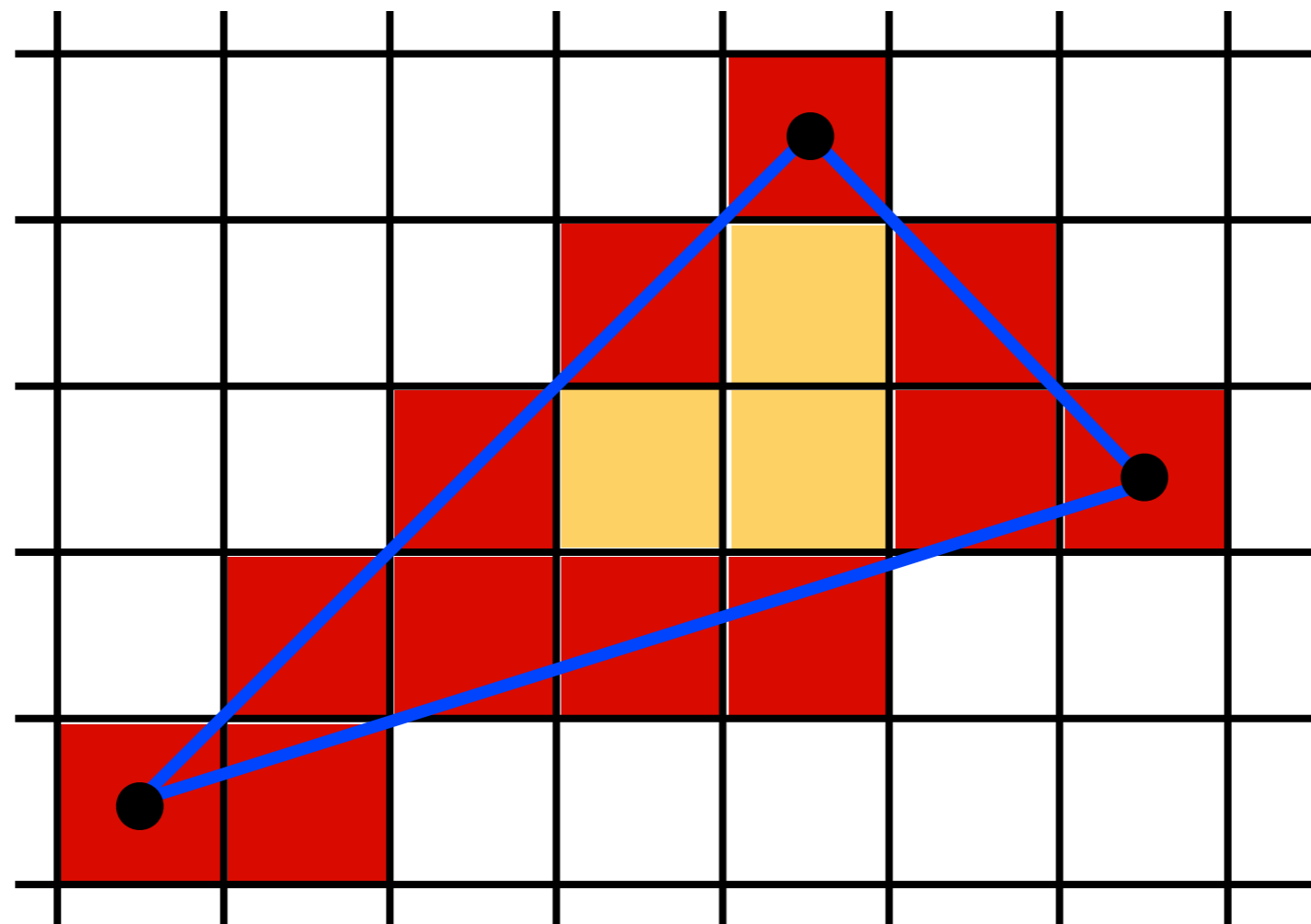
# Triangle rasterization

Which pixels should be used to approximate a triangle?



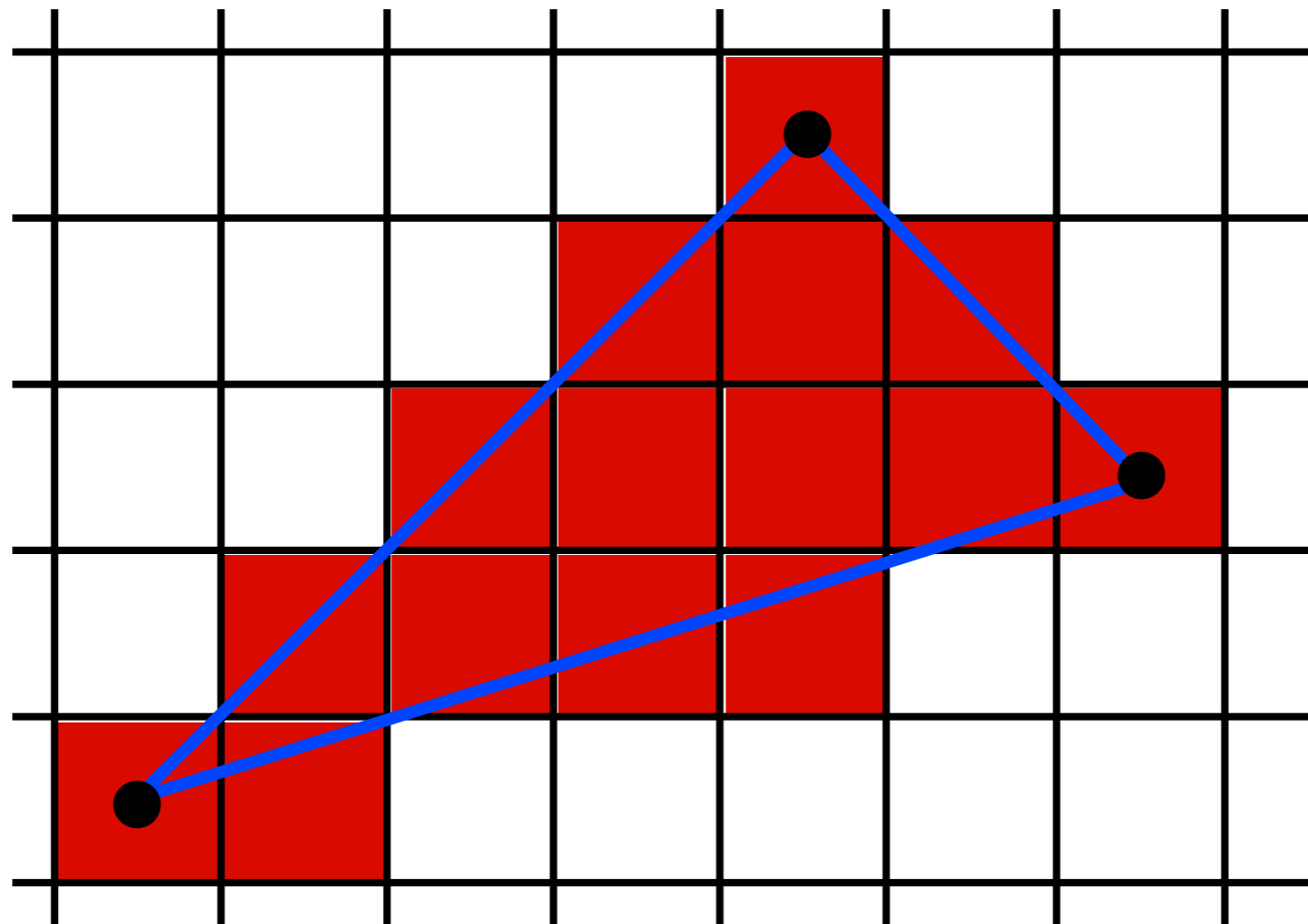


# Which pixels should be used to approximate a triangle?



Use Midpoint Algorithm for edges and fill in?

# Which pixels should be used to approximate a triangle?

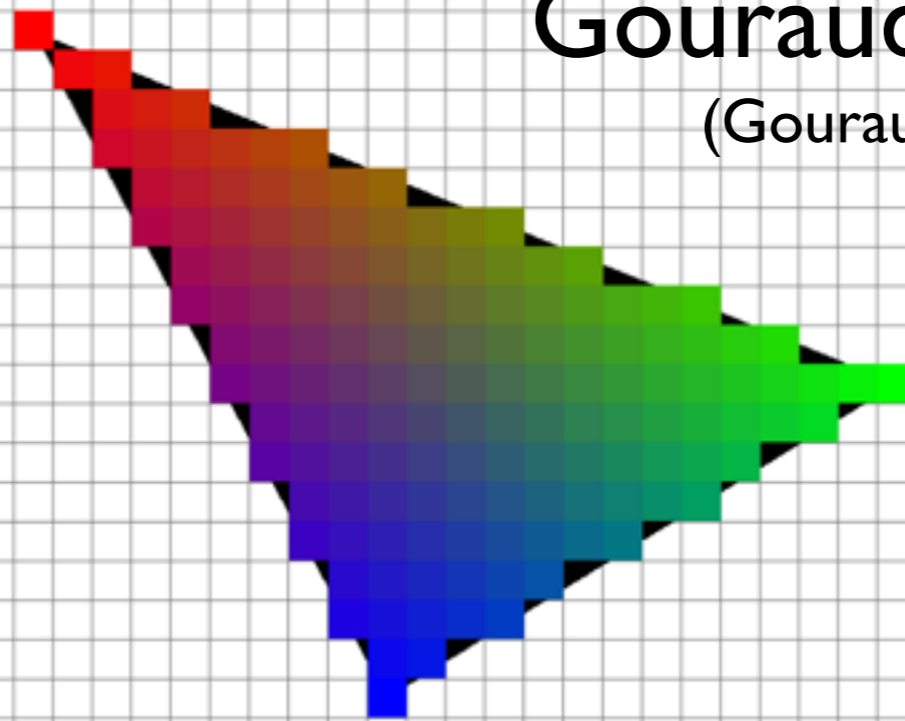


Use an approach based on barycentric coordinates

# We can interpolate attributes using barycentric coordinates

$$\mathbf{c} = \alpha \mathbf{c}_0 + \beta \mathbf{c}_1 + \gamma \mathbf{c}_2$$

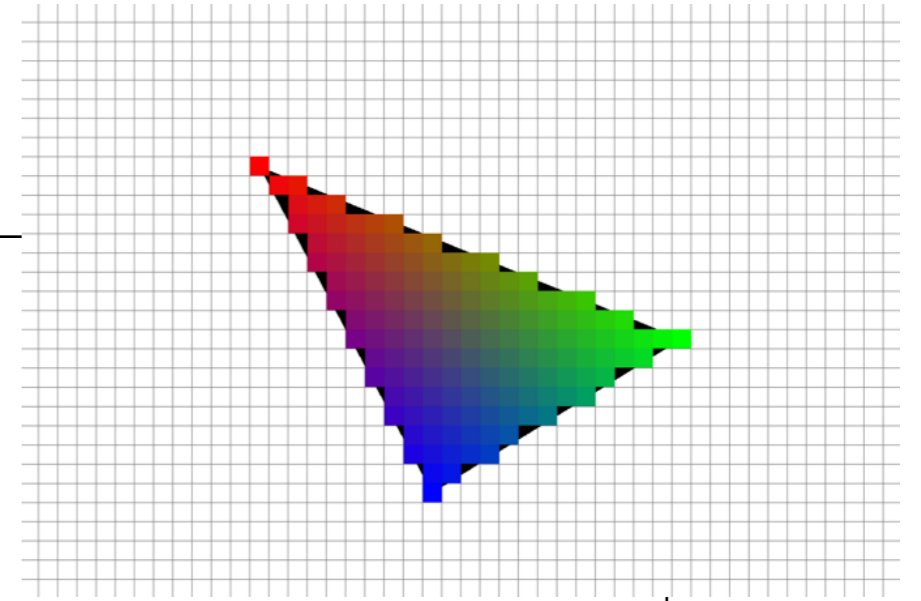
**Gouraud shading**  
(Gouraud, 1971)



<http://jtibble.dyndns.org/graphics/eecs487/eecs487.html>

# Triangle rasterization algorithm

```
for all x do
  for all y do
    compute  $(\alpha, \beta, \gamma)$  for  $(x, y)$ 
    if  $(\alpha \in [0, 1]$  and  $\beta \in [0, 1]$  and  $\gamma \in [0, 1])$  then
       $\mathbf{c} = \alpha\mathbf{c}_0 + \beta\mathbf{c}_1 + \gamma\mathbf{c}_2$ 
      drawpixel $(x, y)$  with color  $\mathbf{c}$ 
```



# Triangle rasterization algorithm

for all  $x$  do

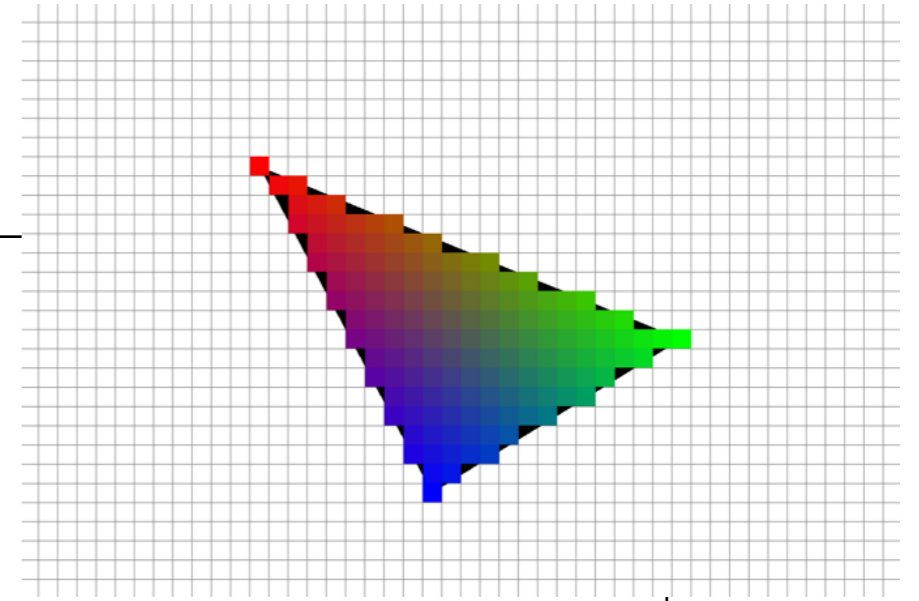
for all  $y$  do

compute  $(\alpha, \beta, \gamma)$  for  $(x, y)$

if  $(\alpha \in [0, 1]$  and  $\beta \in [0, 1]$  and  $\gamma \in [0, 1])$  then

$$c = \alpha c_0 + \beta c_1 + \gamma c_2$$

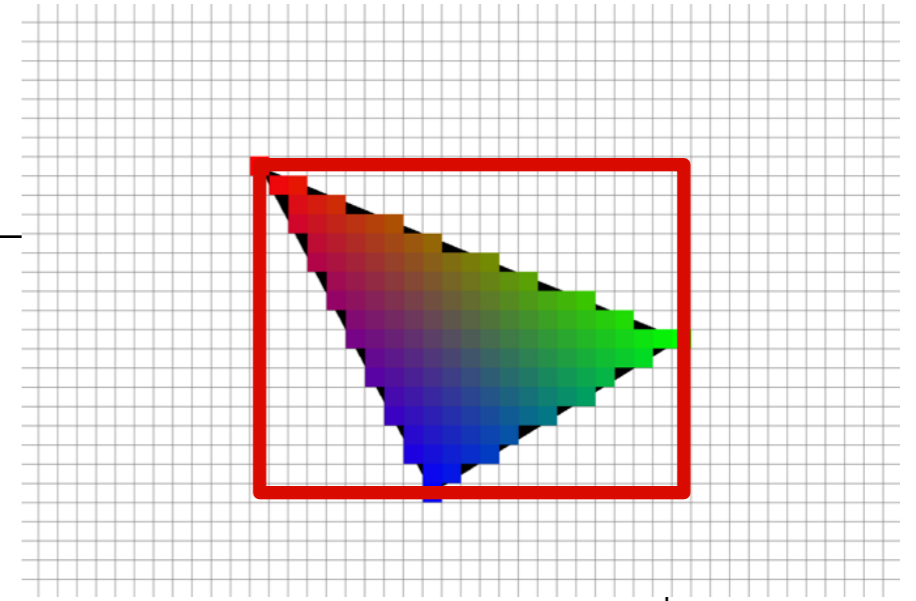
drawpixel( $x, y$ ) with color  $c$



# Triangle rasterization algorithm

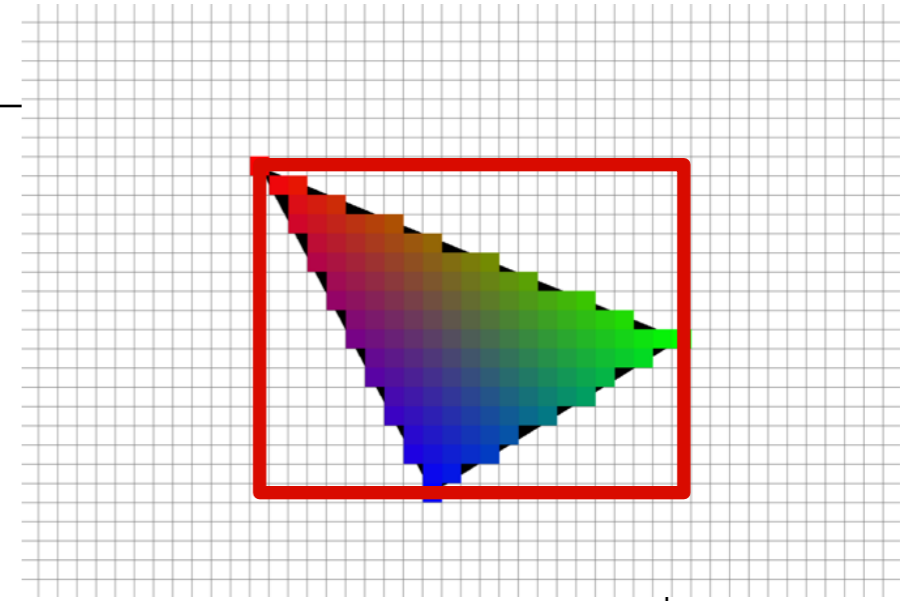
use a bounding rectangle

```
for x in [x_min, x_max]
  for y in [y_min, y_max]
    compute  $(\alpha, \beta, \gamma)$  for  $(x, y)$ 
    if  $(\alpha \in [0, 1]$  and  $\beta \in [0, 1]$  and  $\gamma \in [0, 1])$  then
       $c = \alpha c_0 + \beta c_1 + \gamma c_2$ 
      drawpixel(x, y) with color c
```



# Triangle rasterization algorithm

```
for x in [x_min, x_max]
  for y in [y_min, y_max]
     $\alpha = f_{bc}(x, y) / f_{bc}(x_a, y_a)$ 
     $\beta = f_{ca}(x, y) / f_{ca}(x_b, y_b)$ 
     $\gamma = f_{ab}(x, y) / f_{ab}(x_c, y_c)$ 
    if ( $\alpha \in [0, 1]$  and  $\beta \in [0, 1]$  and  $\gamma \in [0, 1]$ ) then
       $\mathbf{c} = \alpha \mathbf{c}_0 + \beta \mathbf{c}_1 + \gamma \mathbf{c}_2$ 
      drawpixel(x,y) with color c
```

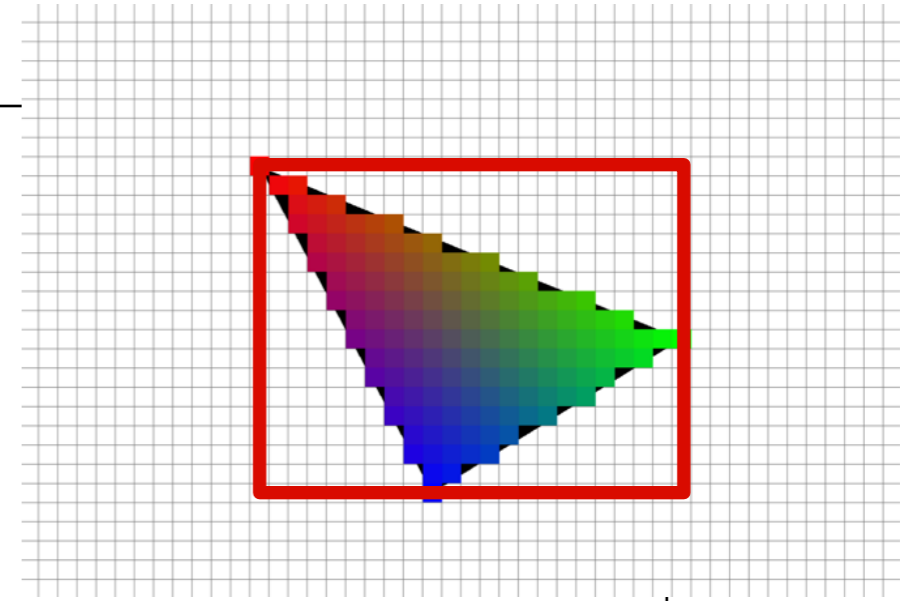


<whiteboard>

# Triangle rasterization algorithm

## Optimizations?

```
for x in [x_min, x_max]
  for y in [y_min, y_max]
     $\alpha = f_{bc}(x, y) / f_{bc}(x_a, y_a)$ 
     $\beta = f_{ca}(x, y) / f_{ca}(x_b, y_b)$ 
     $\gamma = f_{ab}(x, y) / f_{ab}(x_c, y_c)$ 
    if ( $\alpha \in [0, 1]$  and  $\beta \in [0, 1]$  and  $\gamma \in [0, 1]$ ) then
       $\mathbf{c} = \alpha \mathbf{c}_0 + \beta \mathbf{c}_1 + \gamma \mathbf{c}_2$ 
      drawpixel(x,y) with color c
```

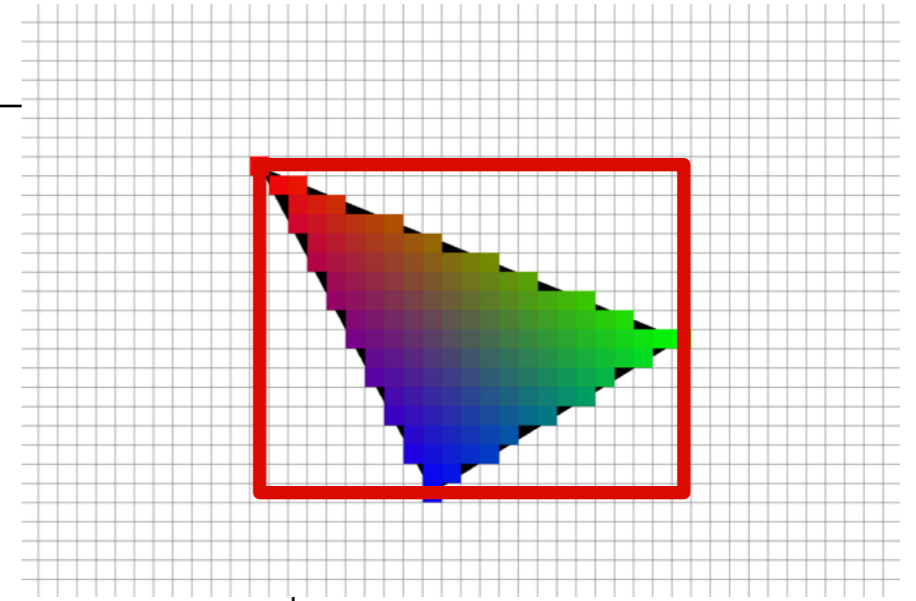




# Triangle rasterization algorithm

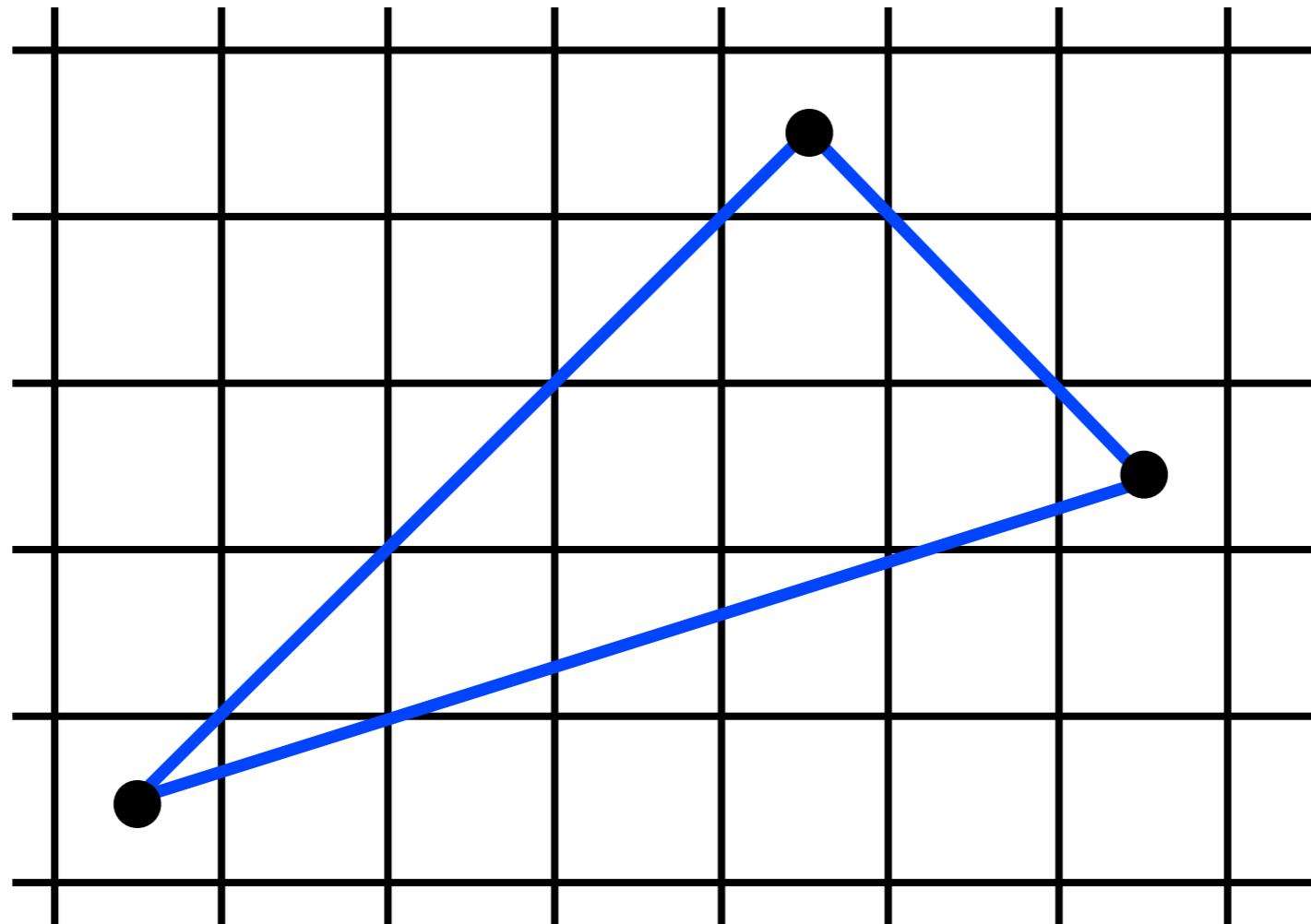
## Optimizations?

```
for x in [x_min, x_max]
  for y in [y_min, y_max]
     $\alpha = f_{bc}(x, y) / f_{bc}(x_a, y_a)$ 
     $\beta = f_{ca}(x, y) / f_{ca}(x_b, y_b)$ 
     $\gamma = f_{ab}(x, y) / f_{ab}(x_c, y_c)$ 
    if ( $\alpha \geq 0$  and  $\beta \geq 0$  and  $\gamma \geq 0$ ) then
       $\mathbf{c} = \alpha \mathbf{c}_0 + \beta \mathbf{c}_1 + \gamma \mathbf{c}_2$ 
      drawpixel(x,y) with color c
```

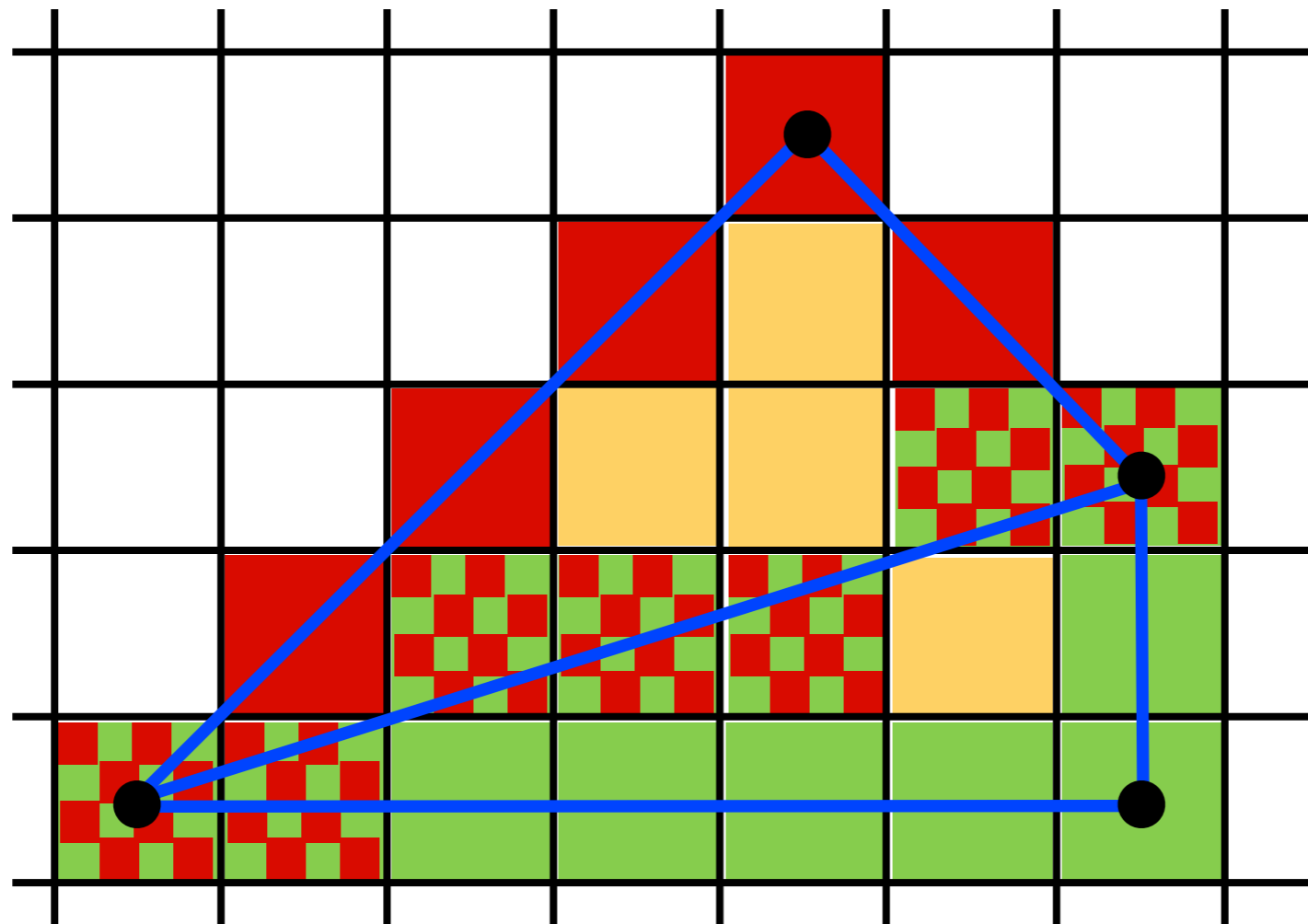


make computation of bary. coords. incremental  
color can also be computed incrementally  
don't need to check upper bound

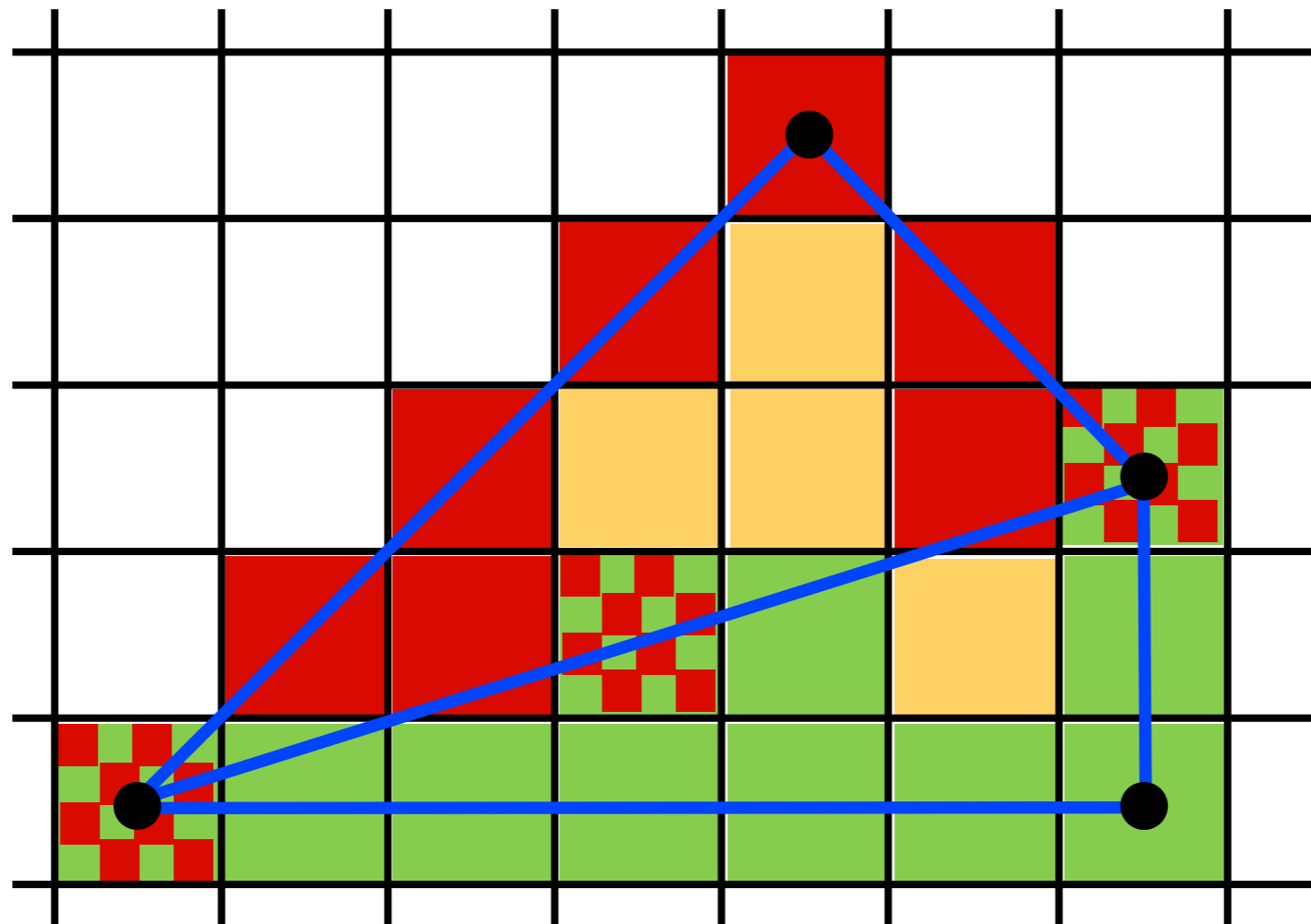
# Triangle rasterization issues



# Who should fill in shared edge?



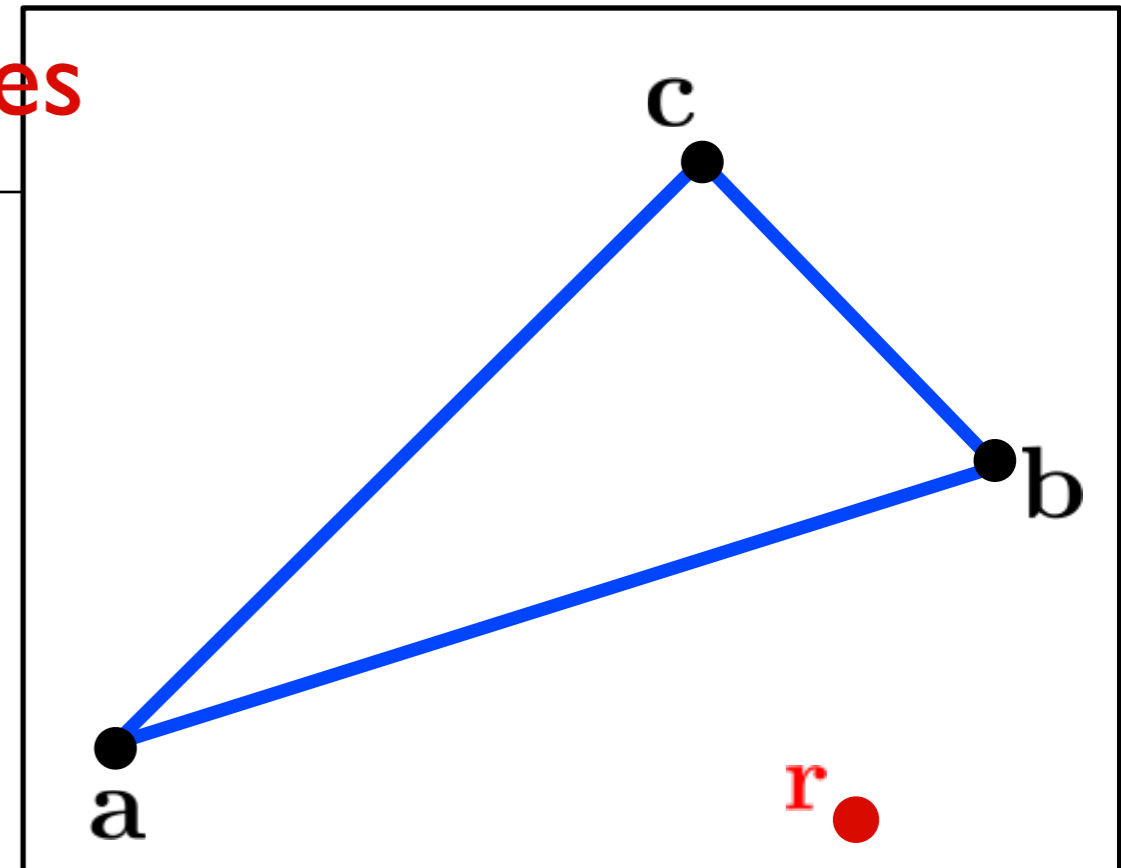
# Who should fill in shared edge?



# Triangle rasterization algorithm

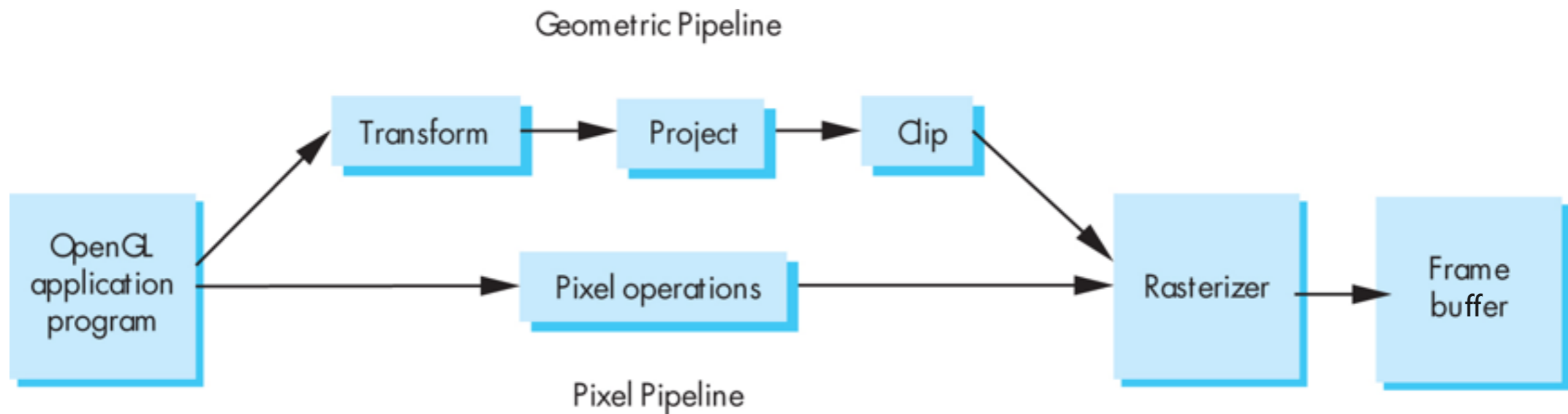
dealing with shared triangle edges

```
for x in [x_min, x_max]
  for y in [y_min, y_max]
     $\alpha = f_{bc}(x, y) / f_{bc}(x_a, y_a)$ 
     $\beta = f_{ac}(x, y) / f_{ac}(x_b, y_b)$ 
     $\gamma = f_{ab}(x, y) / f_{ab}(x_c, y_c)$ 
    if ( $\alpha \geq 0$  and  $\beta \geq 0$  and  $\gamma \geq 0$ ) then
      if ( $\alpha > 0$  or  $f_{bc}(\mathbf{a})f_{bc}(\mathbf{r}) > 0$ ) and
         ( $\beta > 0$  or  $f_{ca}(\mathbf{b})f_{ca}(\mathbf{r}) > 0$ ) and
         ( $\gamma > 0$  or  $f_{ab}(\mathbf{c})f_{ab}(\mathbf{r}) > 0$ )
        then
           $\mathbf{c} = \alpha\mathbf{c}_0 + \beta\mathbf{c}_1 + \gamma\mathbf{c}_2$ 
          drawpixel(x,y) with color c
```

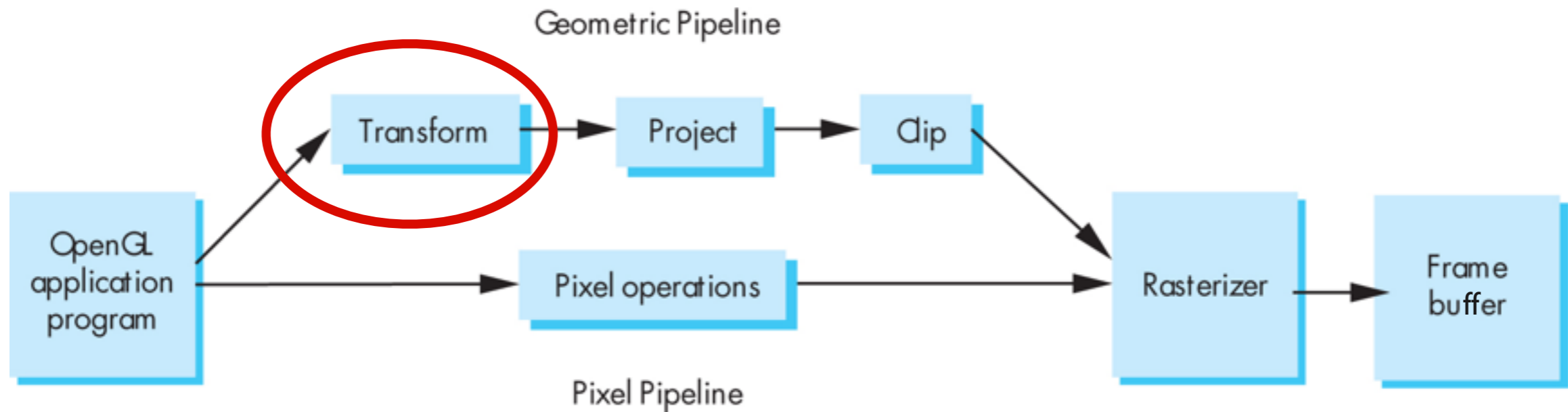


# Graphics Pipeline (cont.)

# Graphics Pipeline

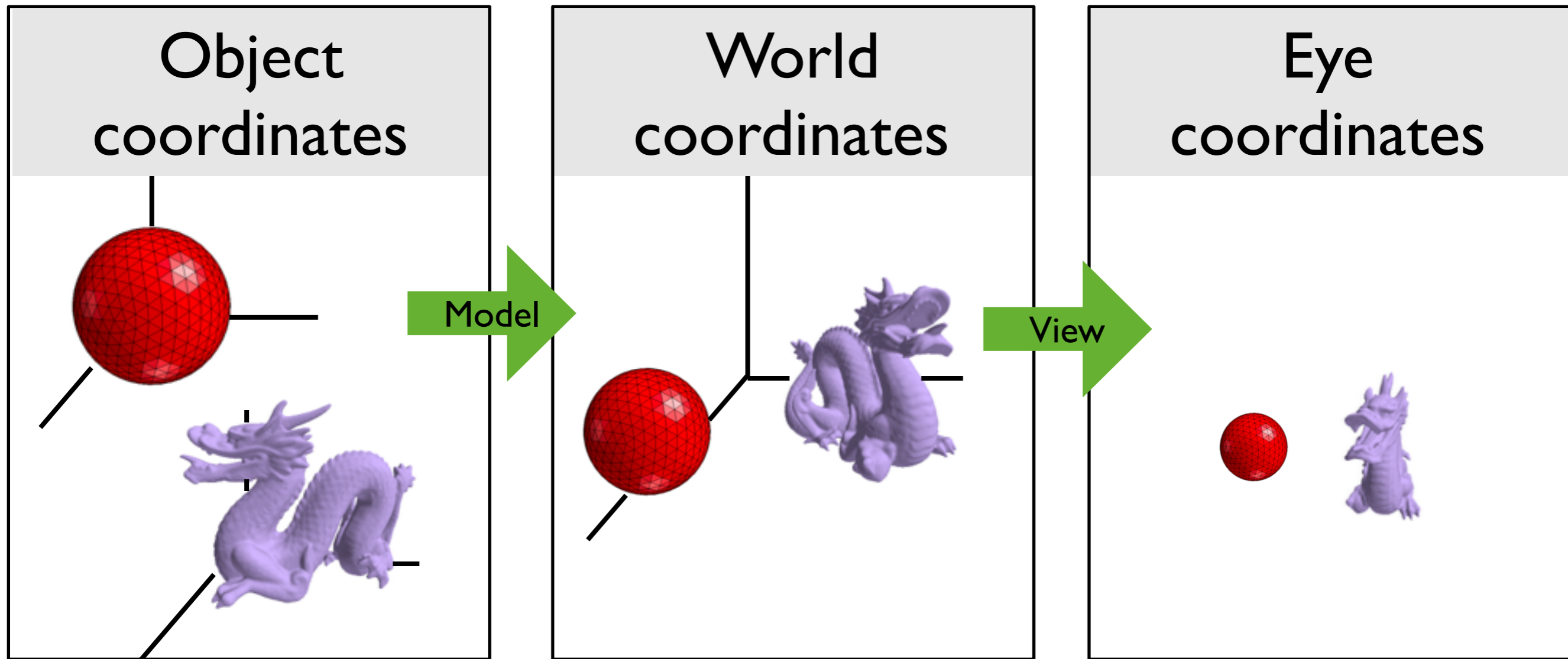


# Transform

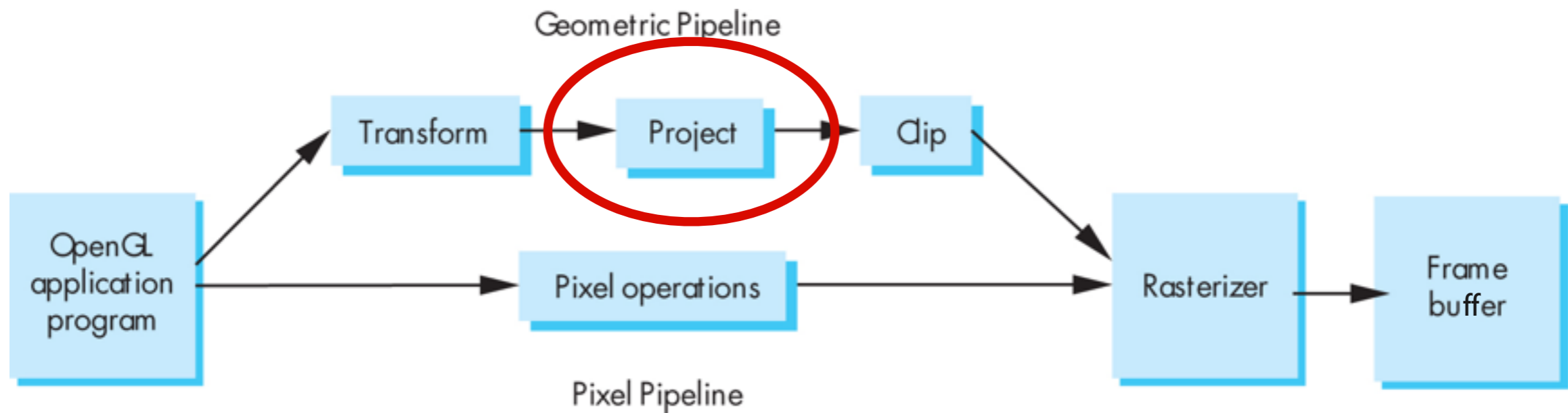




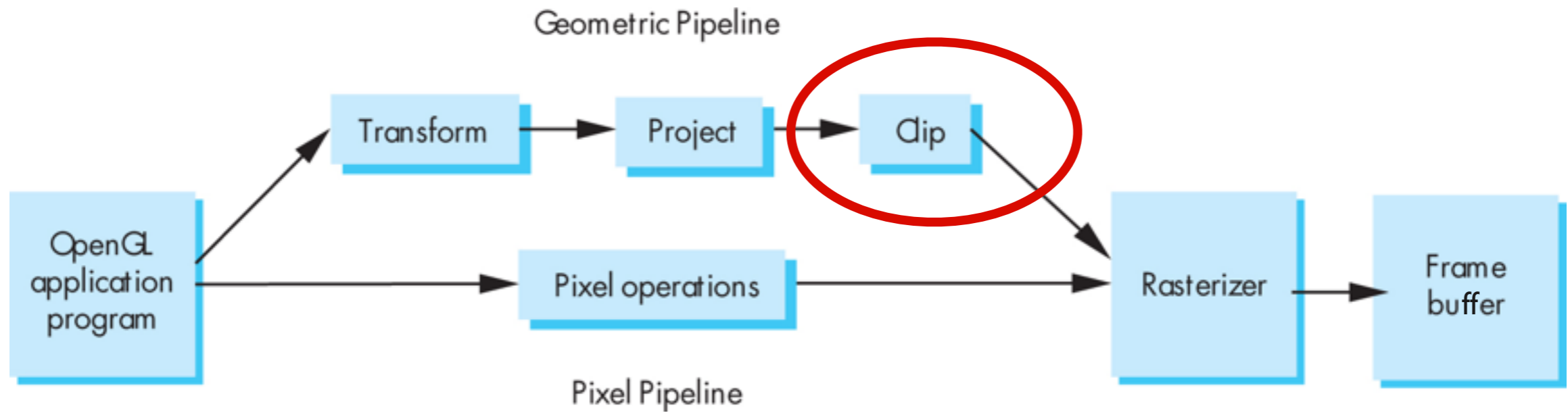
# “Modelview” Transformation



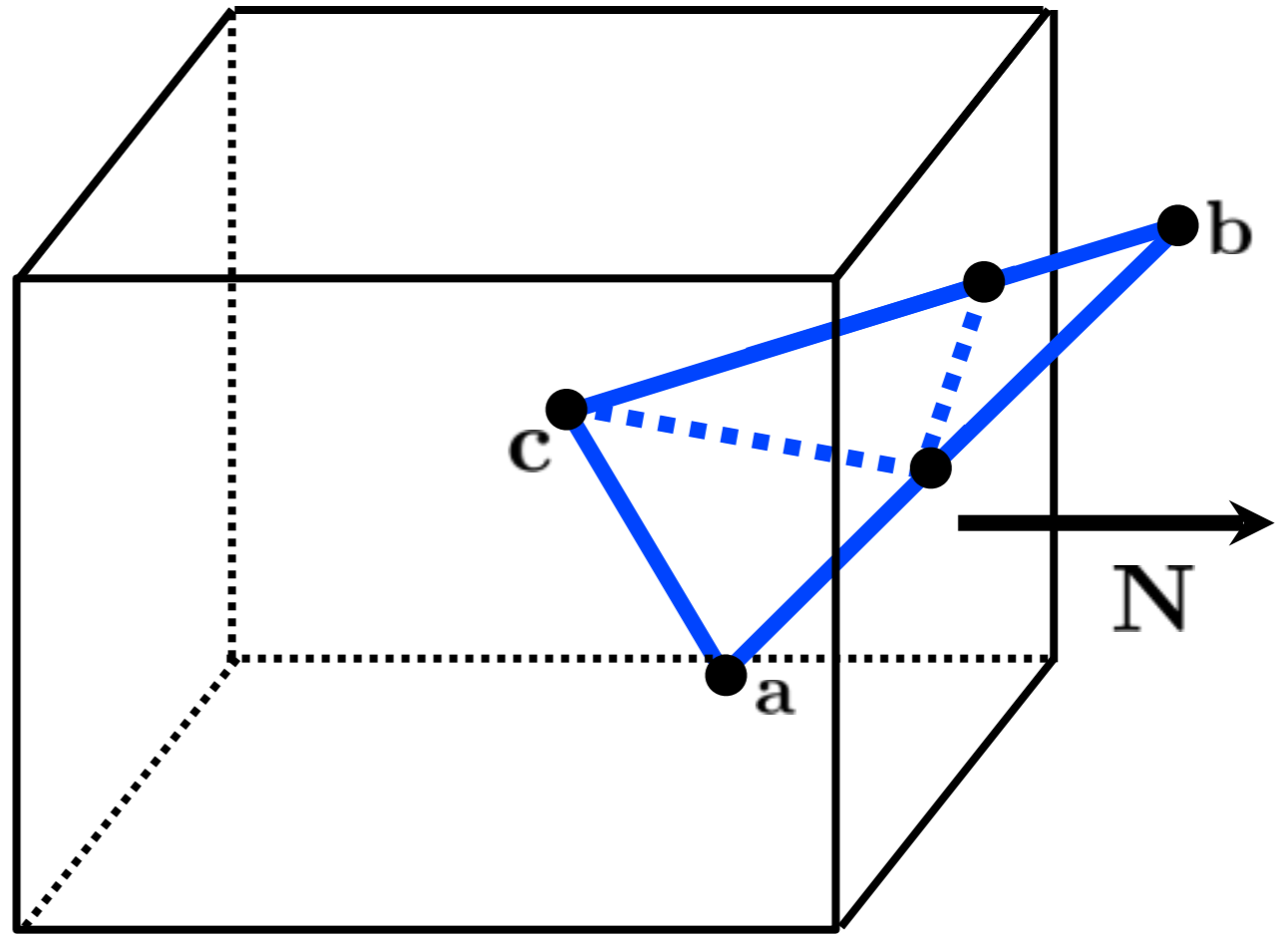
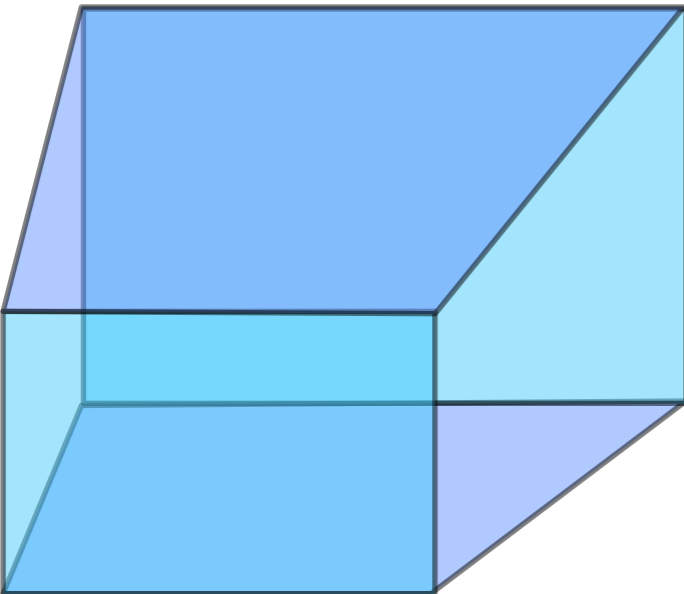
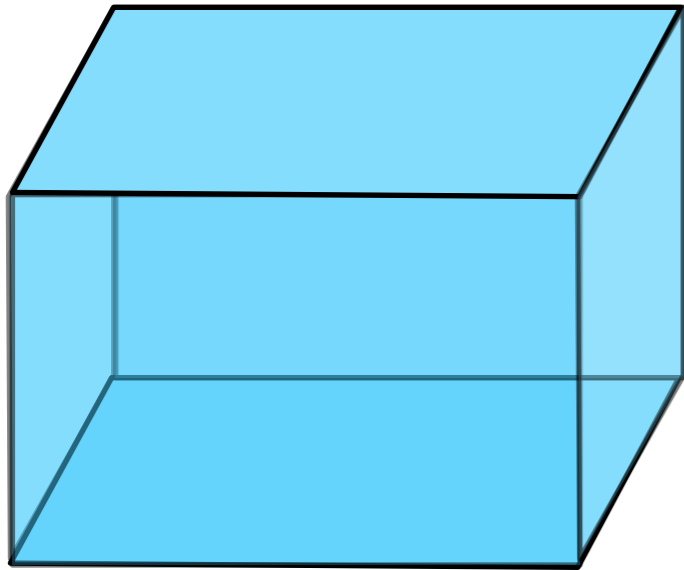
# Project



# Clip



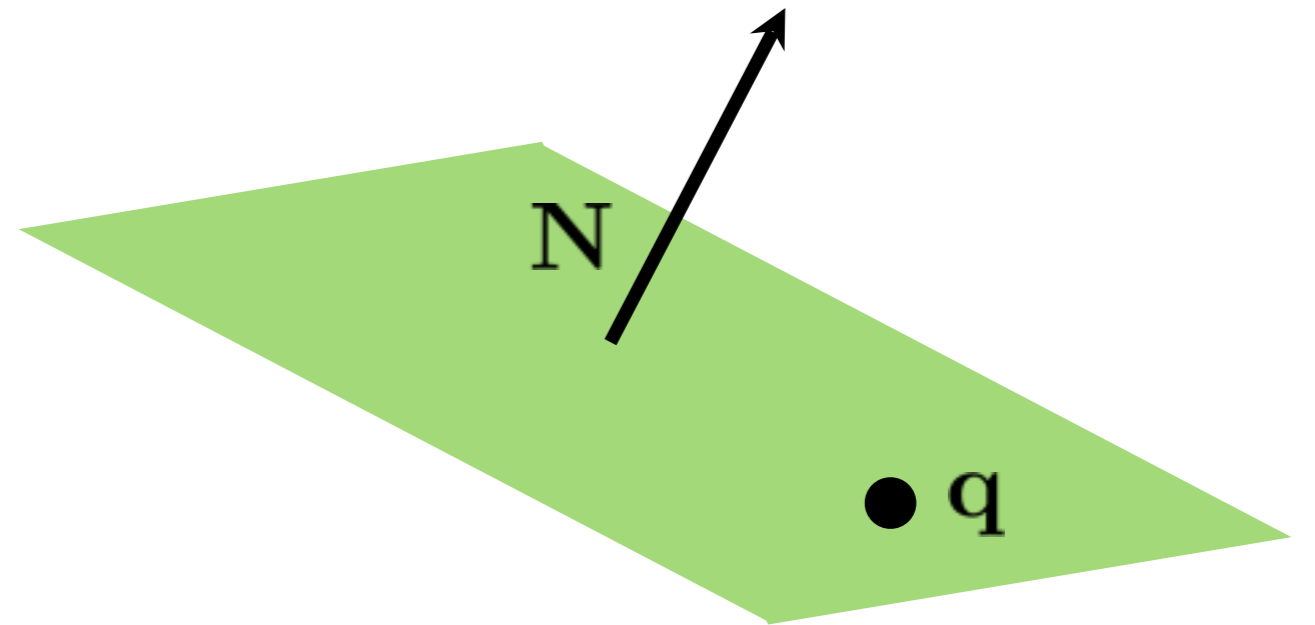
# Clip against view volume



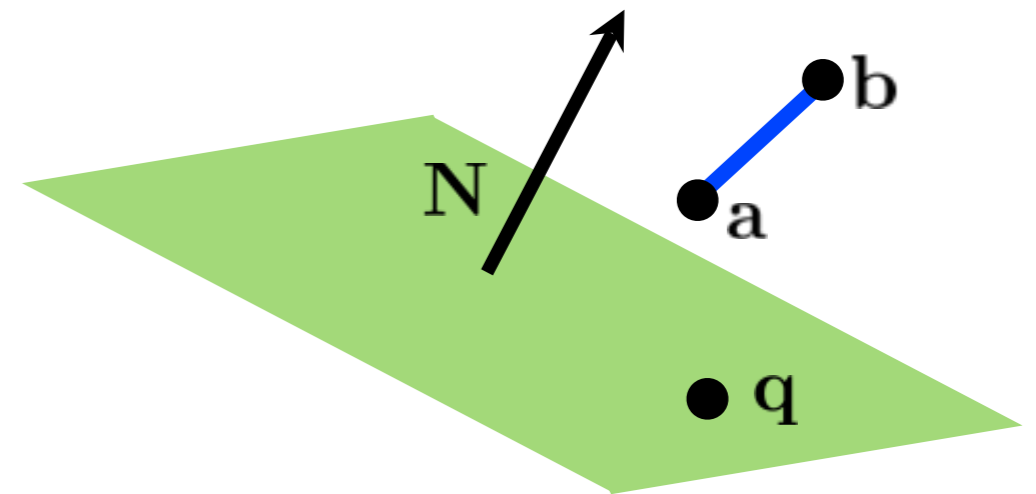
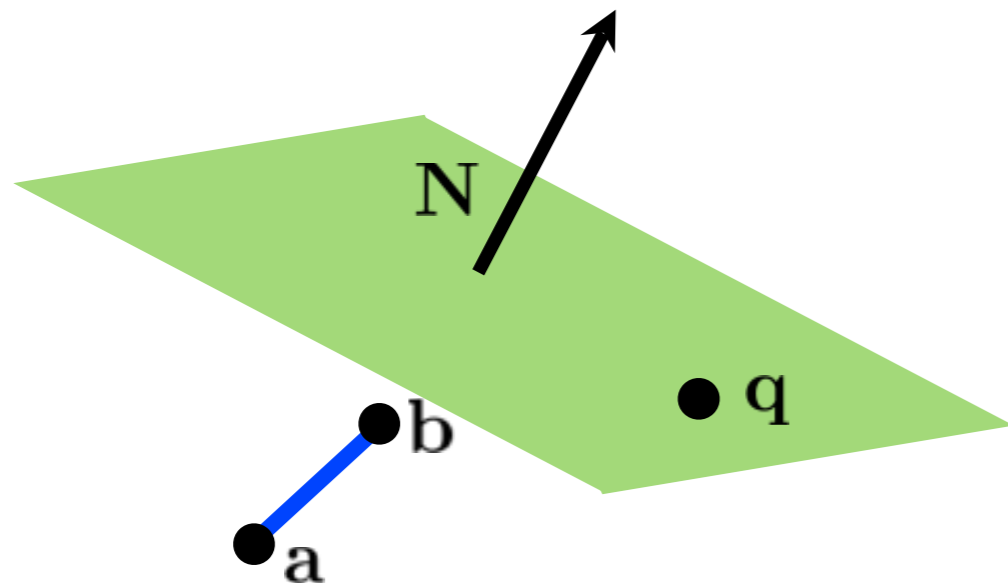
# Clipping against a plane

What's the equation for  
the plane through  $\mathbf{q}$   
with normal  $\mathbf{N}$ ?

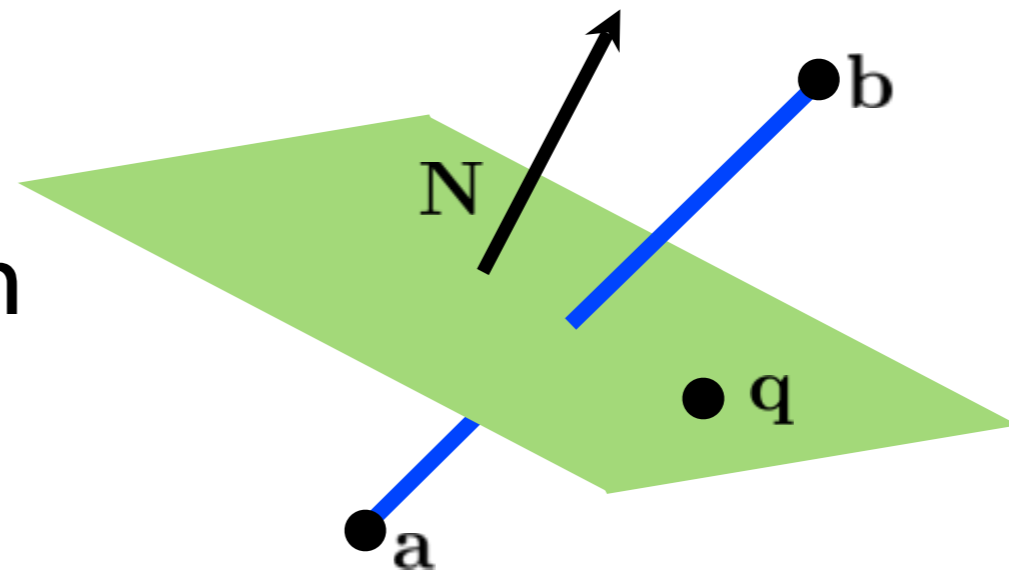
$$f(\mathbf{p}) = \mathbf{N} \cdot (\mathbf{p} - \mathbf{q}) = 0$$



# Intersection of line and plane

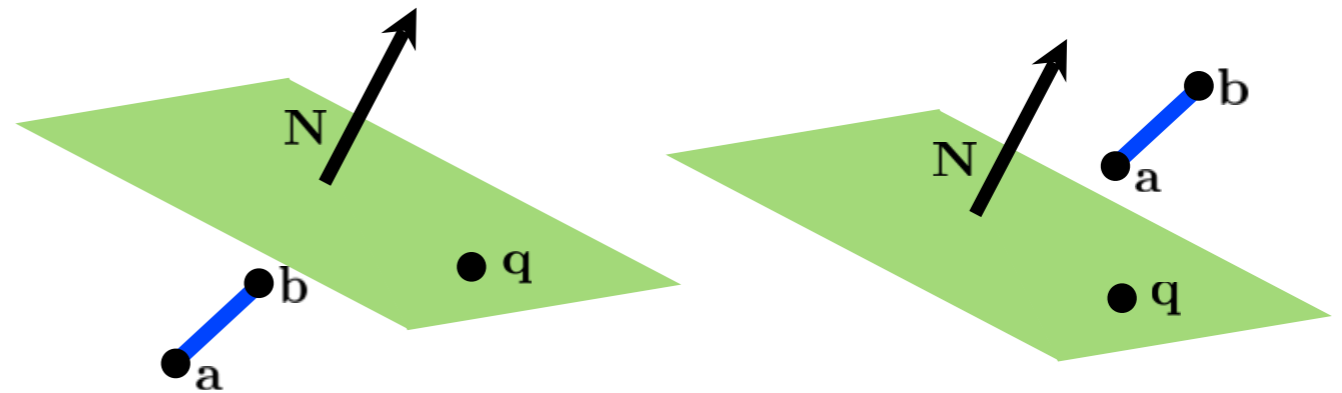


How can we distinguish between these cases?

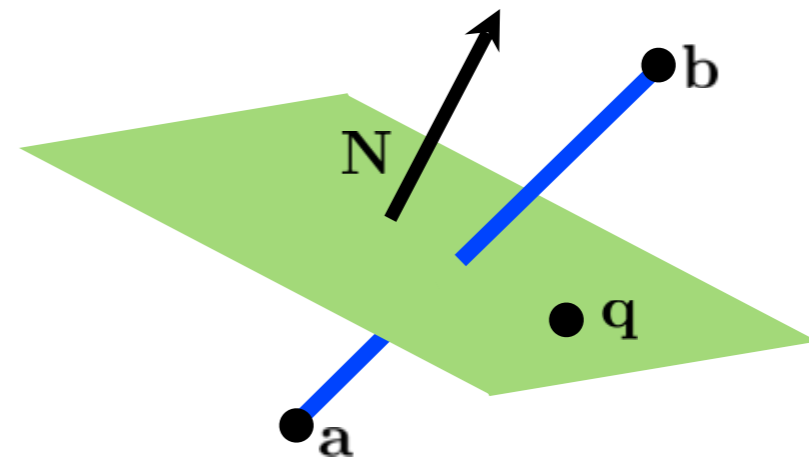


# Intersection of line and plane

$$f(\mathbf{a})f(\mathbf{b}) \geq 0$$

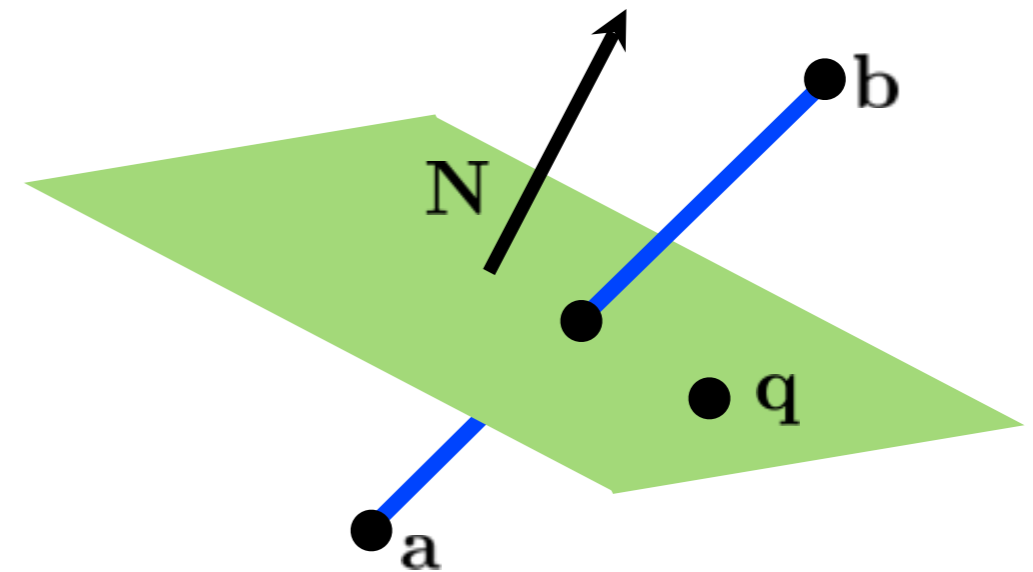


$$f(\mathbf{a})f(\mathbf{b}) < 0$$



# Intersection of line and plane

How can we find the intersection point?



<whiteboard>

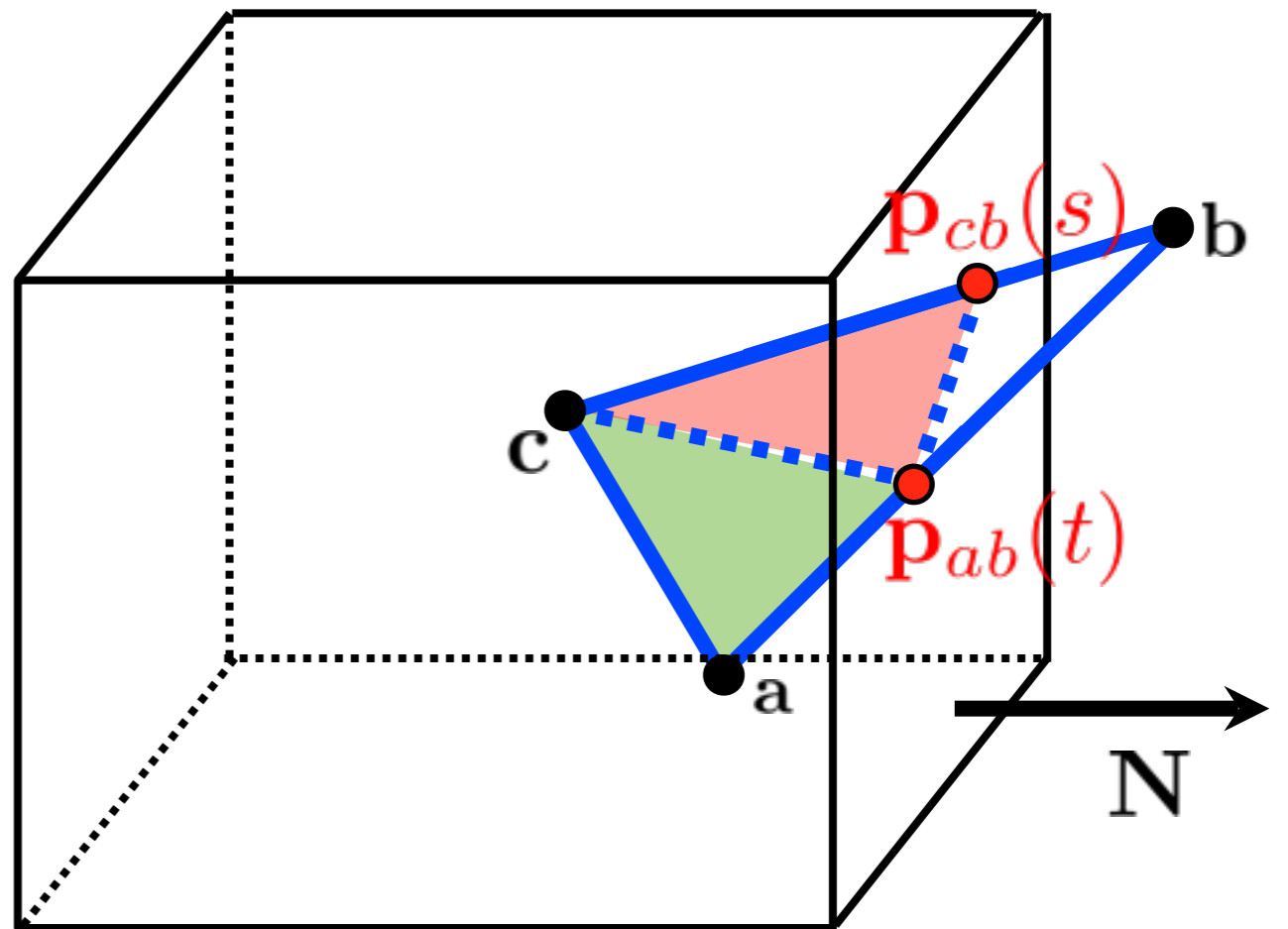


# Clip against view volume

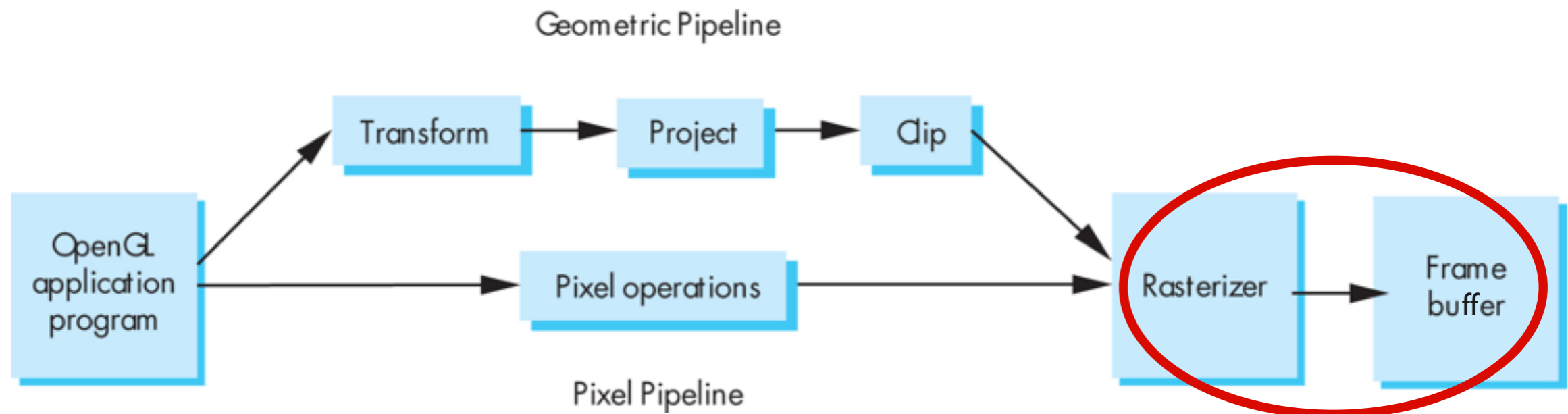
$$s = \frac{\mathbf{N} \cdot (\mathbf{q} - \mathbf{c})}{\mathbf{N} \cdot (\mathbf{b} - \mathbf{c})}$$

$$t = \frac{\mathbf{N} \cdot (\mathbf{q} - \mathbf{a})}{\mathbf{N} \cdot (\mathbf{b} - \mathbf{a})}$$

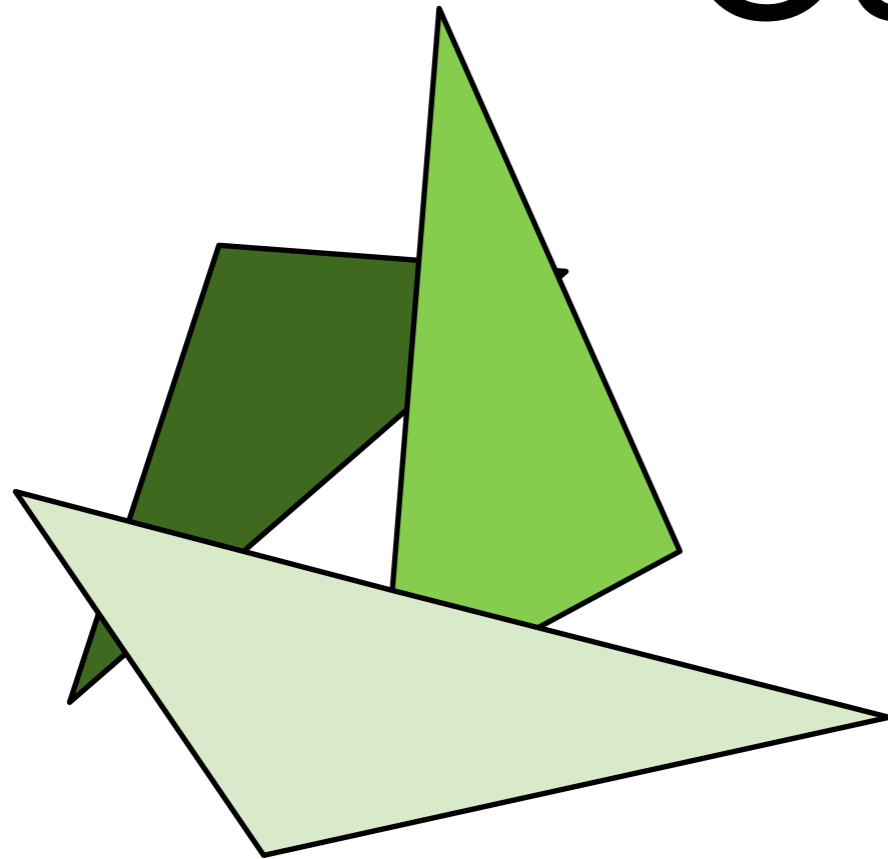
need to generate new  
triangles



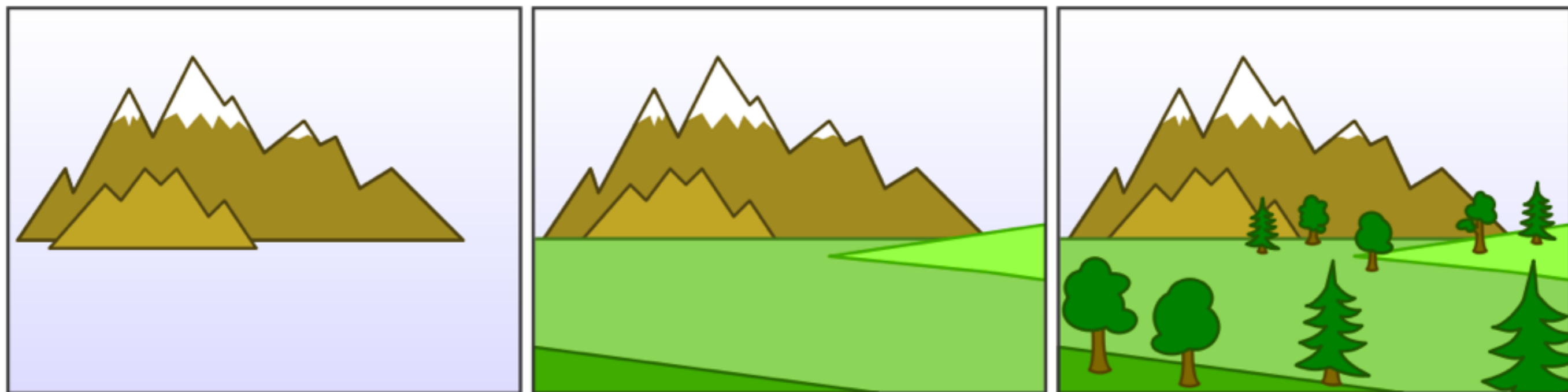
# Hidden Surface Removal



# Occlusion

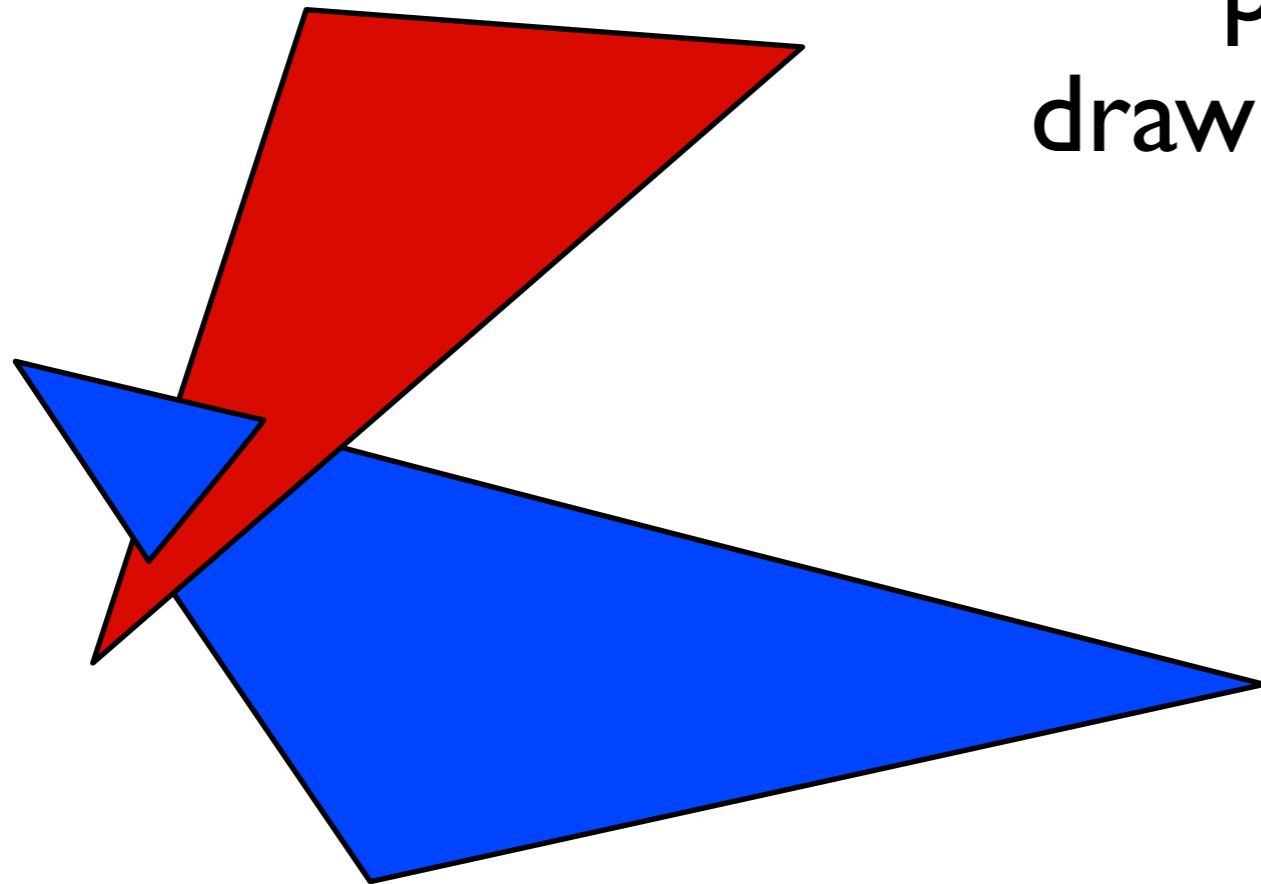


“painter’s algorithm”  
draw primitives in  
back-to-front order



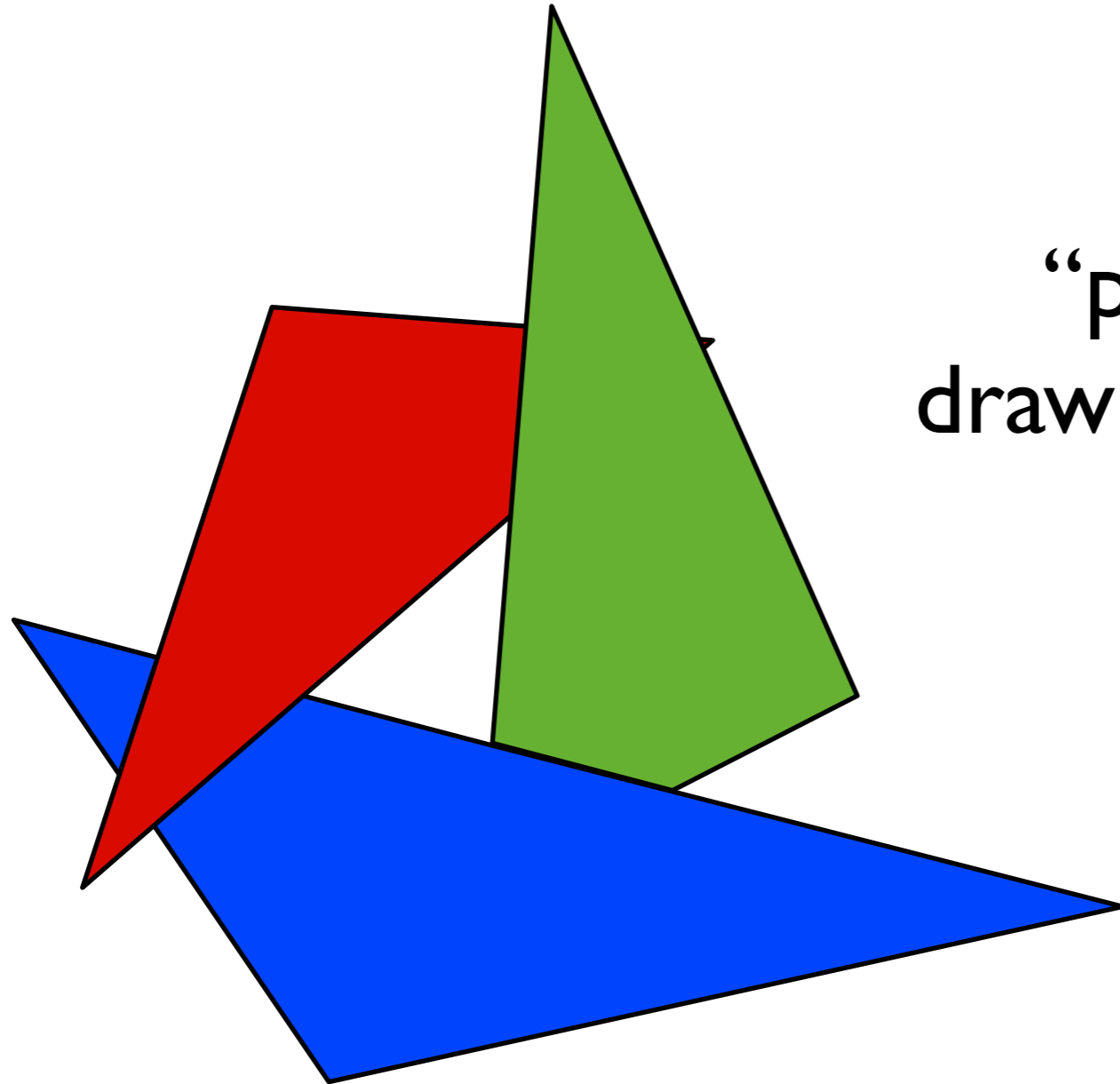
# Occlusion

“painter’s algorithm”  
draw primitives in back-to-  
front order



**problem:**  
triangle  
intersection

# Occlusion



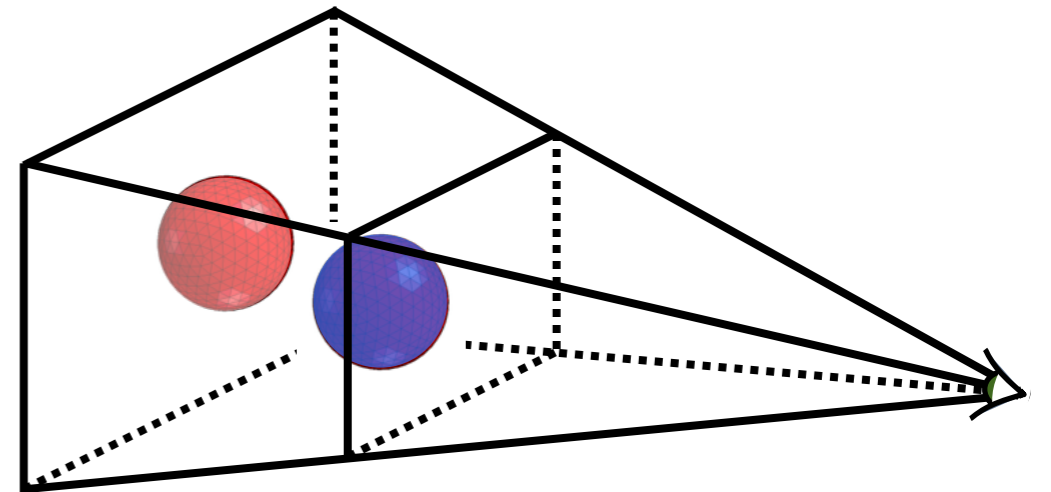
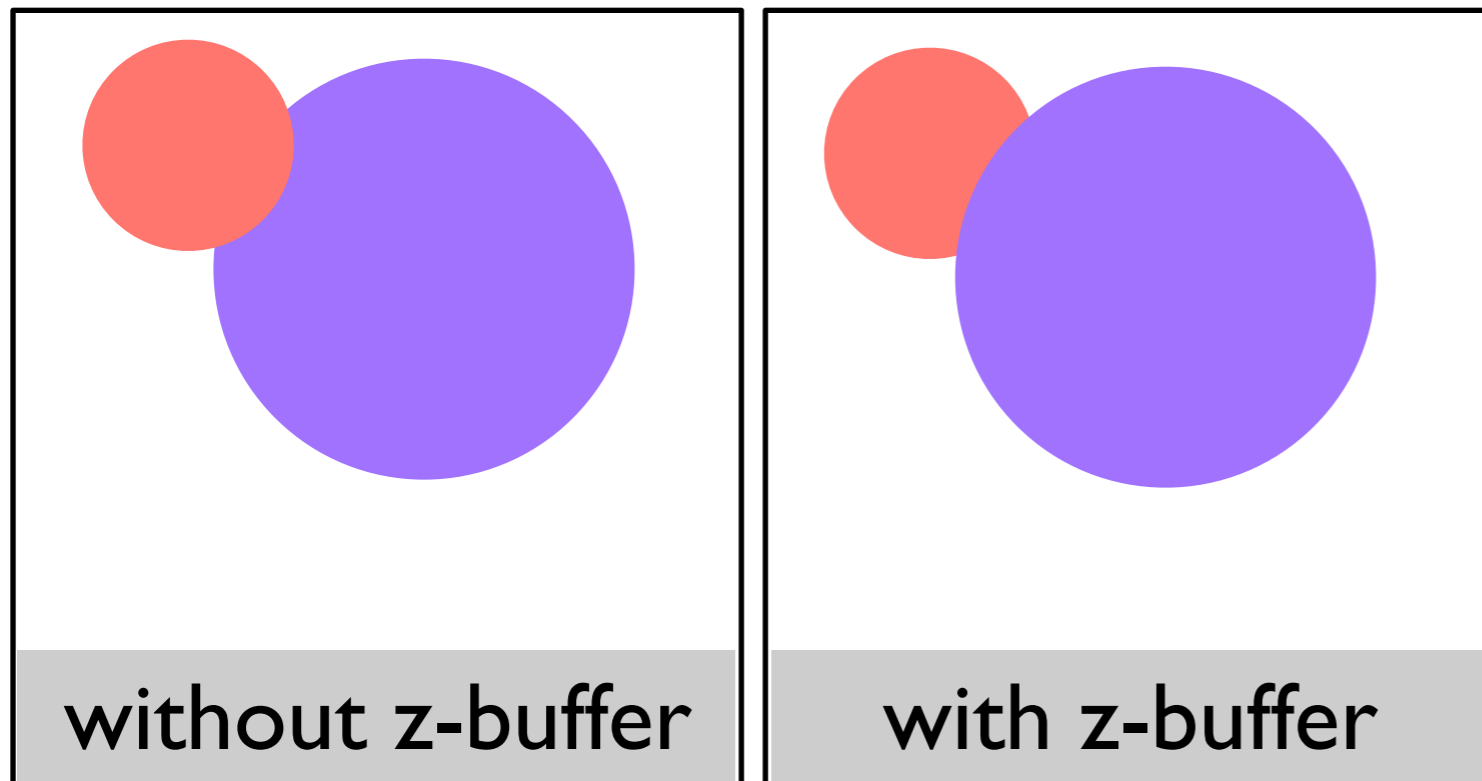
“painter’s algorithm”  
draw primitives in back-to-  
front order

**problem:**  
occlusion cycle

# Use a *z-buffer* for hidden surface removal

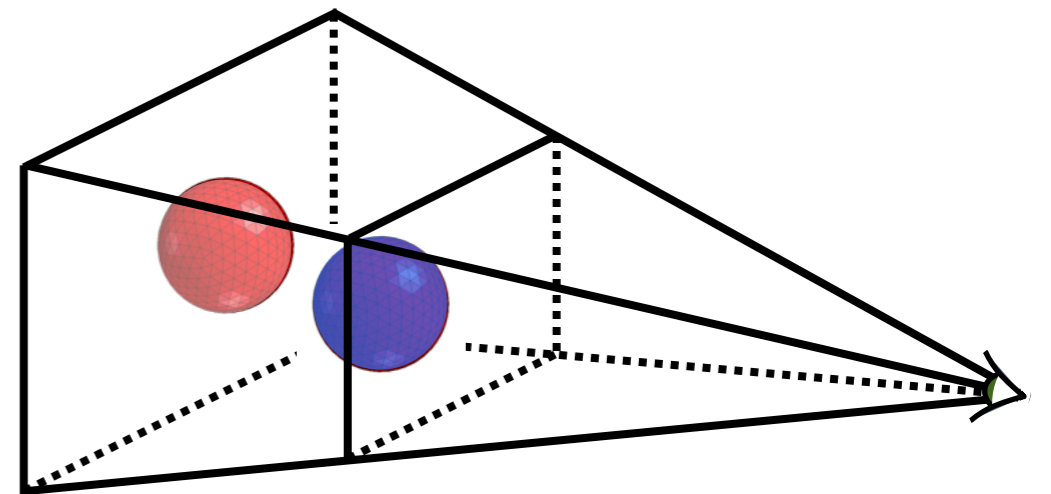
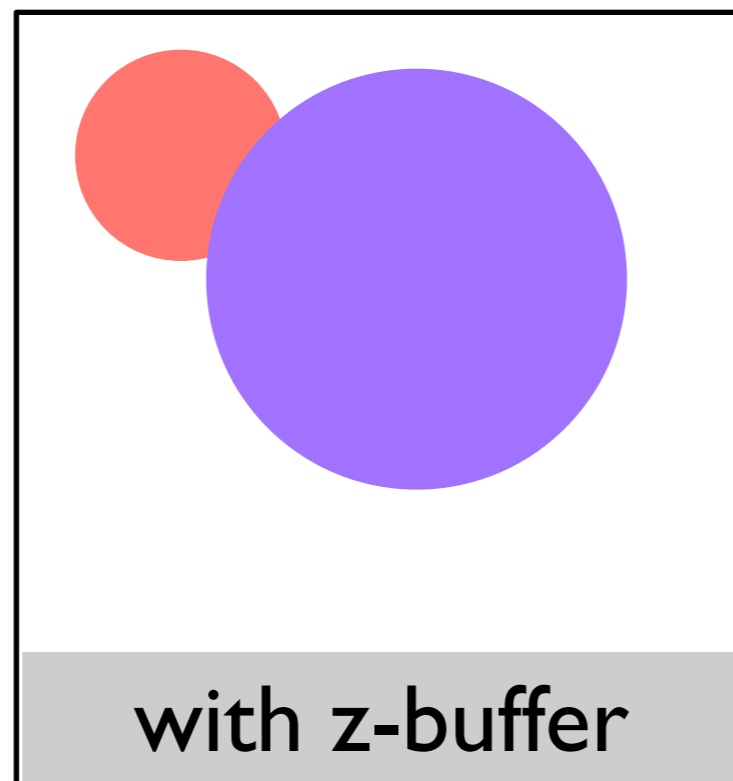
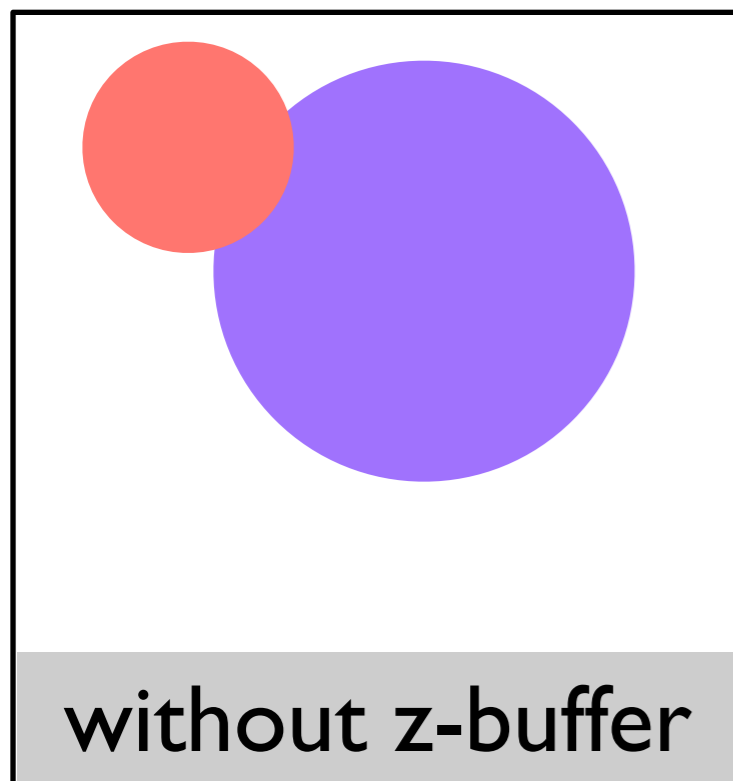
test depth on a pixel by pixel basis

red drawn last

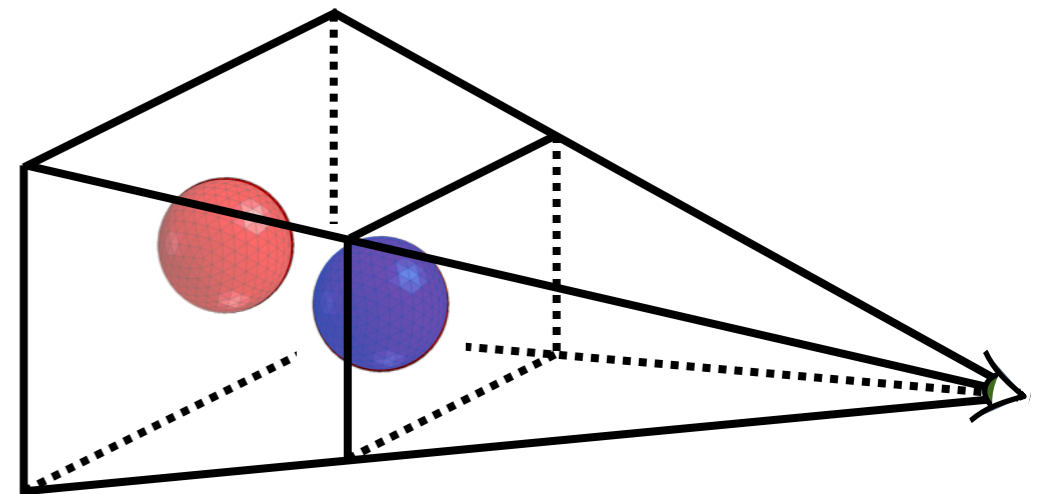
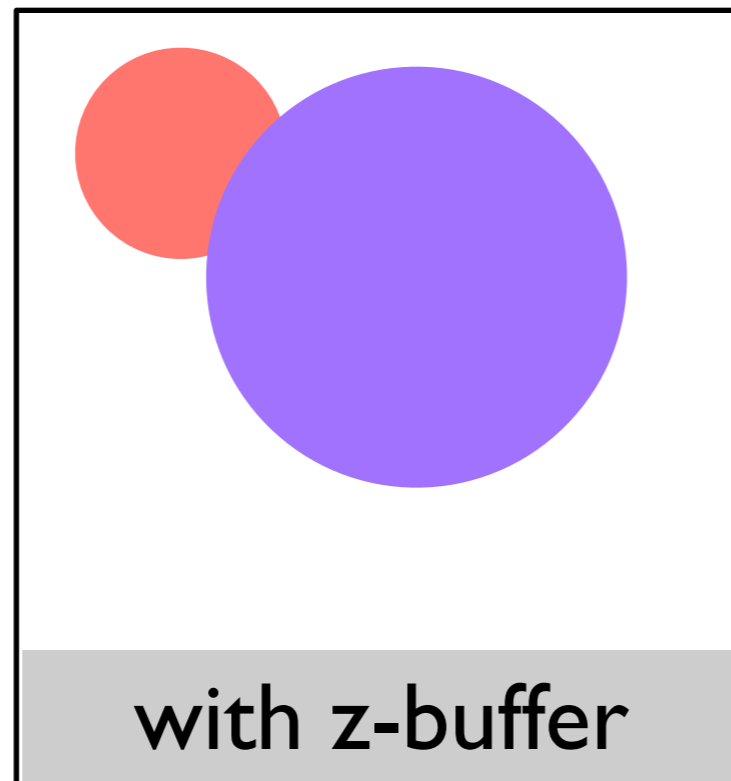
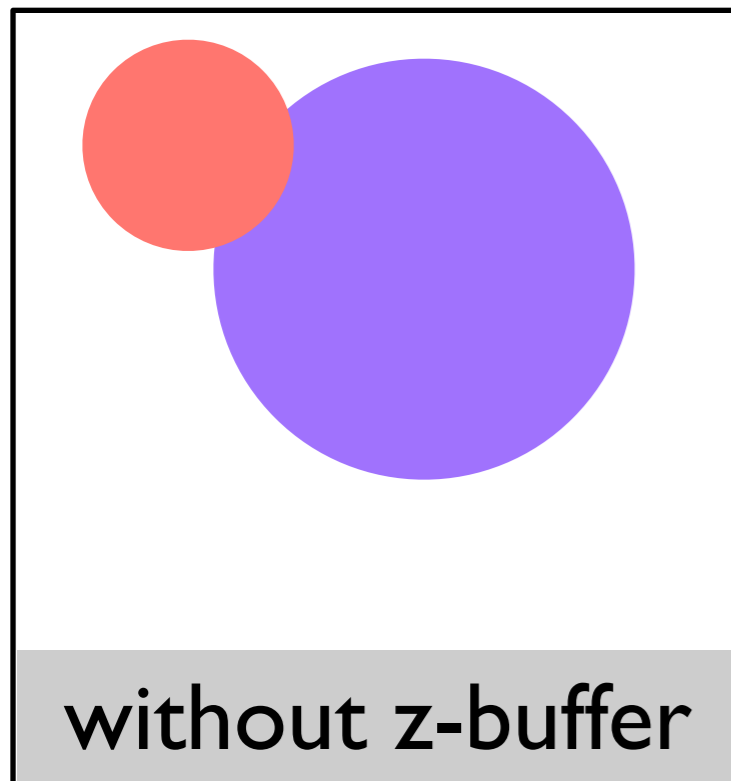
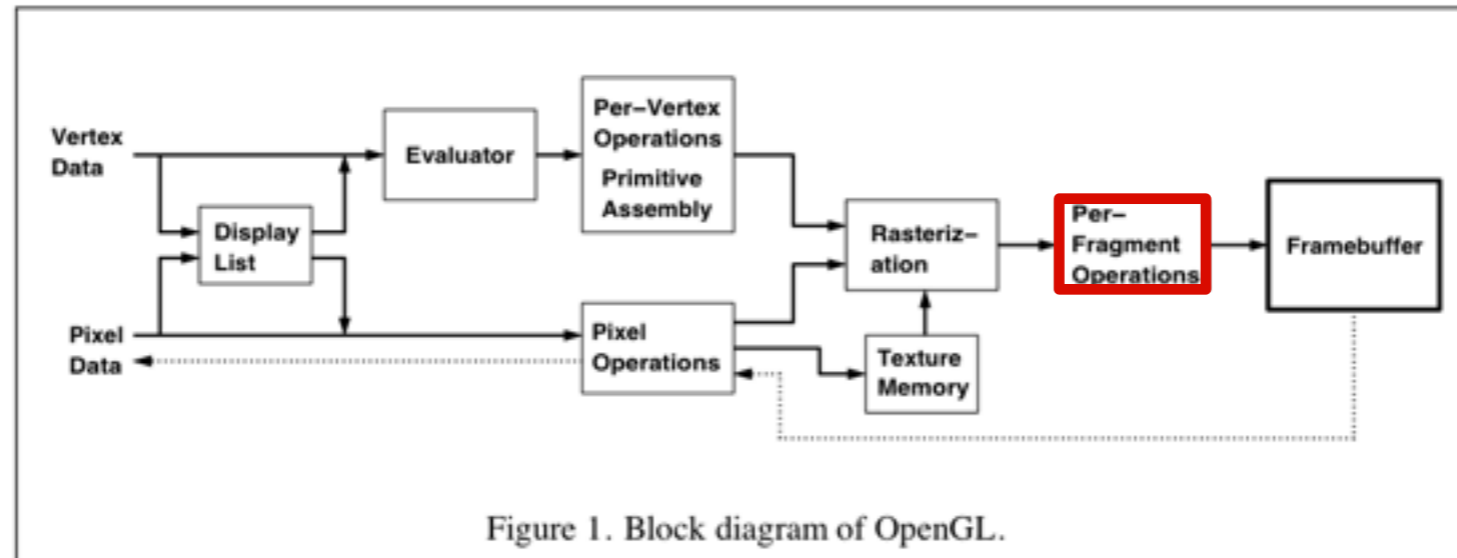


# Use a *z-buffer* for hidden surface removal

at each pixel, record distance to the closest object that has been drawn in a *depth* buffer

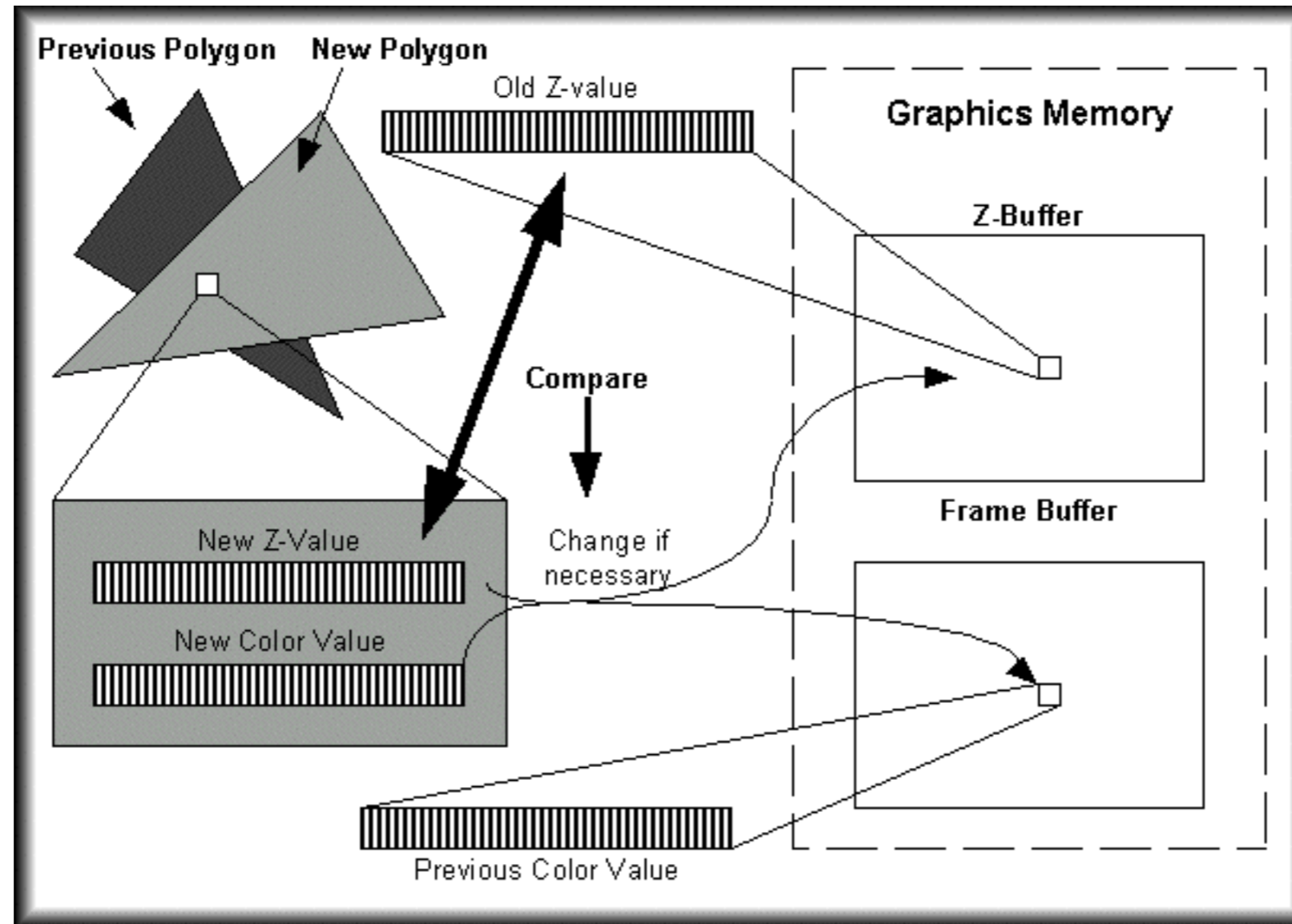


# Use a *z-buffer* for hidden surface removal



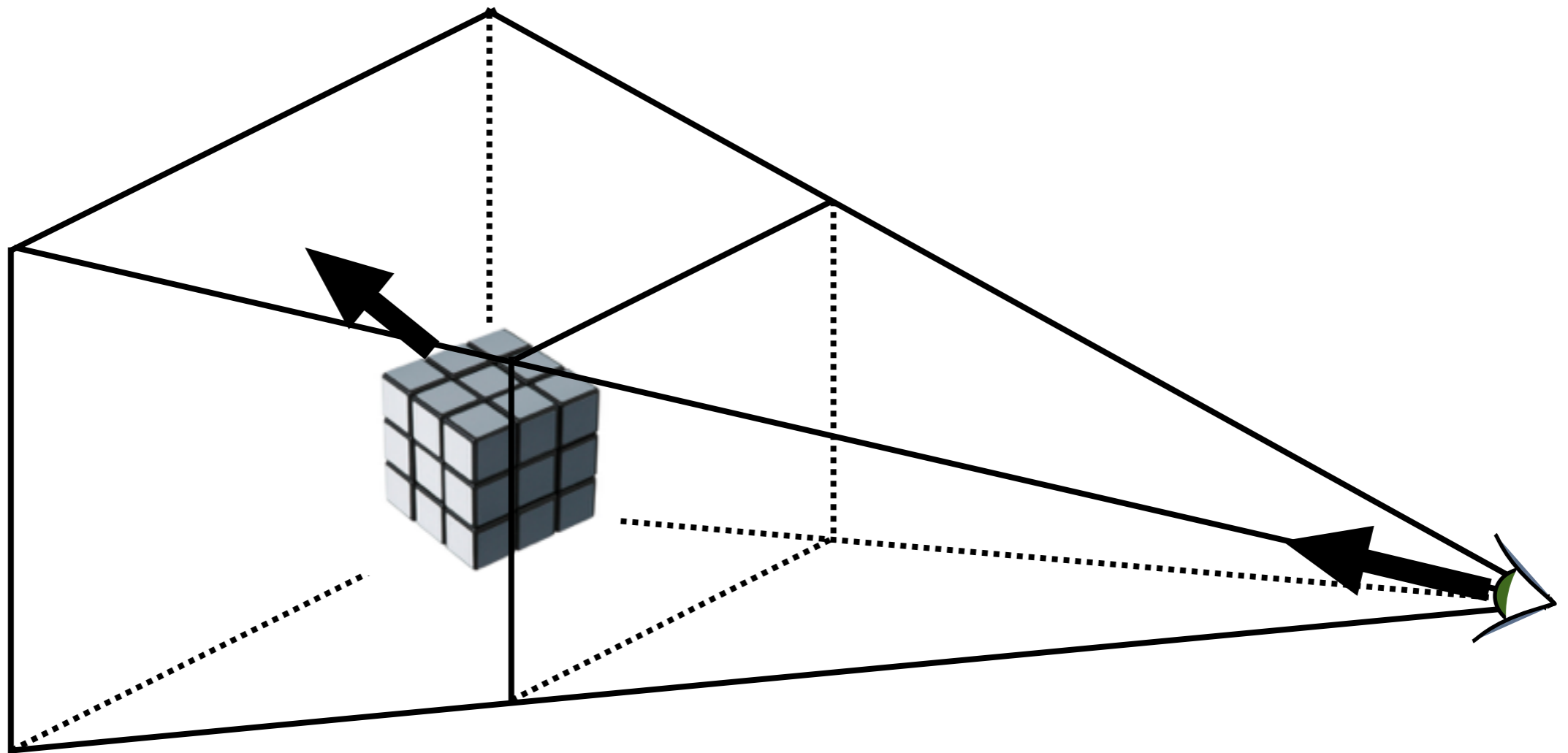


# Use a *z-buffer* for hidden surface removal



<http://www.beyond3d.com/content/articles/41/>

# Backface culling: another way to eliminate hidden geometry



# Hidden Surface Removal in OpenGL

```
glutInitDisplayMode(GLUT_DOUBLE | GLUT_RGB | GLUT_DEPTH);  
  
glEnable(GL_DEPTH_TEST);  
  
glEnable(GL_CULL_FACE);
```

For a perspective transformation, there is more precision in the depth buffer for z-values closer to the near plane