

# CS230 : Computer Graphics

## Lecture 5: Perspective Transformations and Hidden Surfaces

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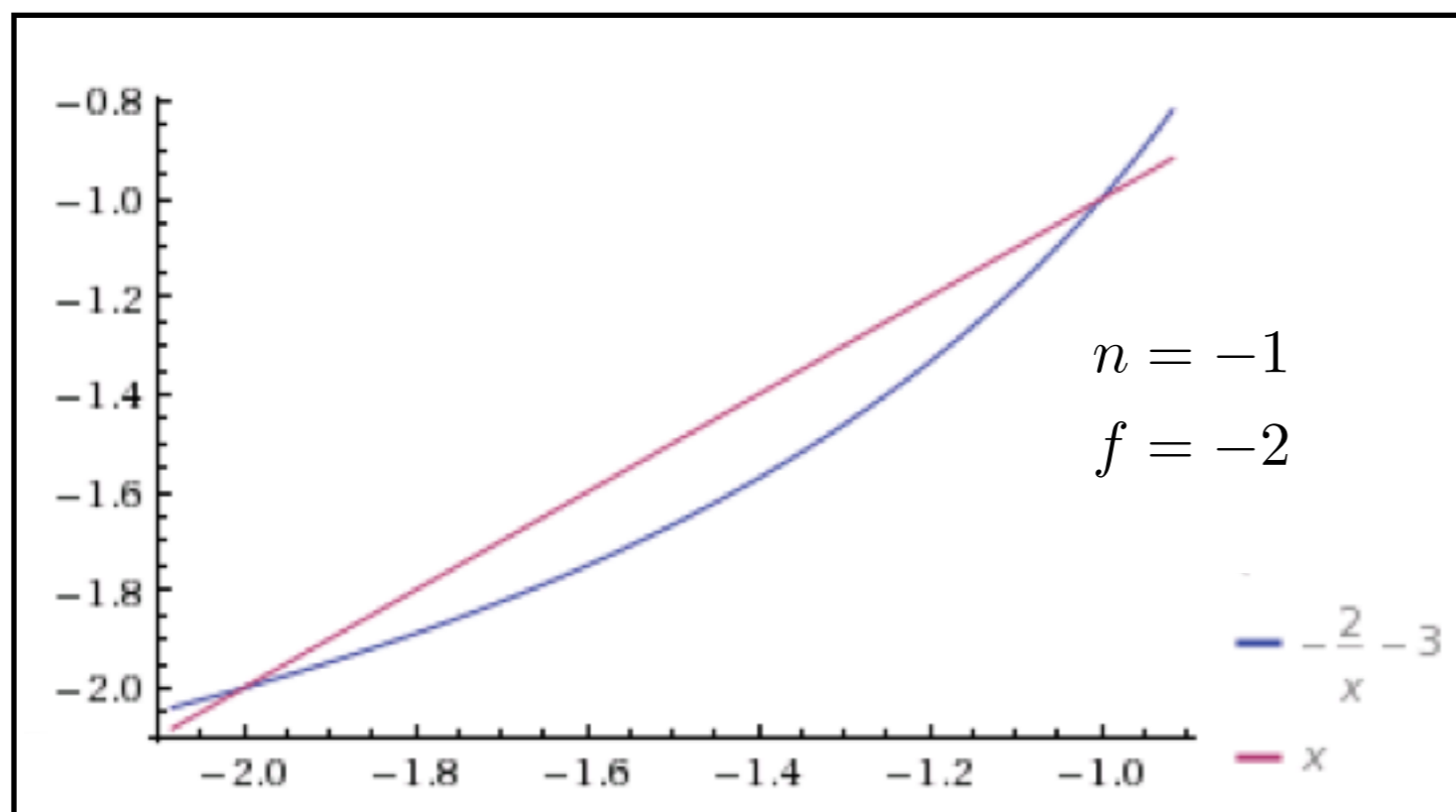
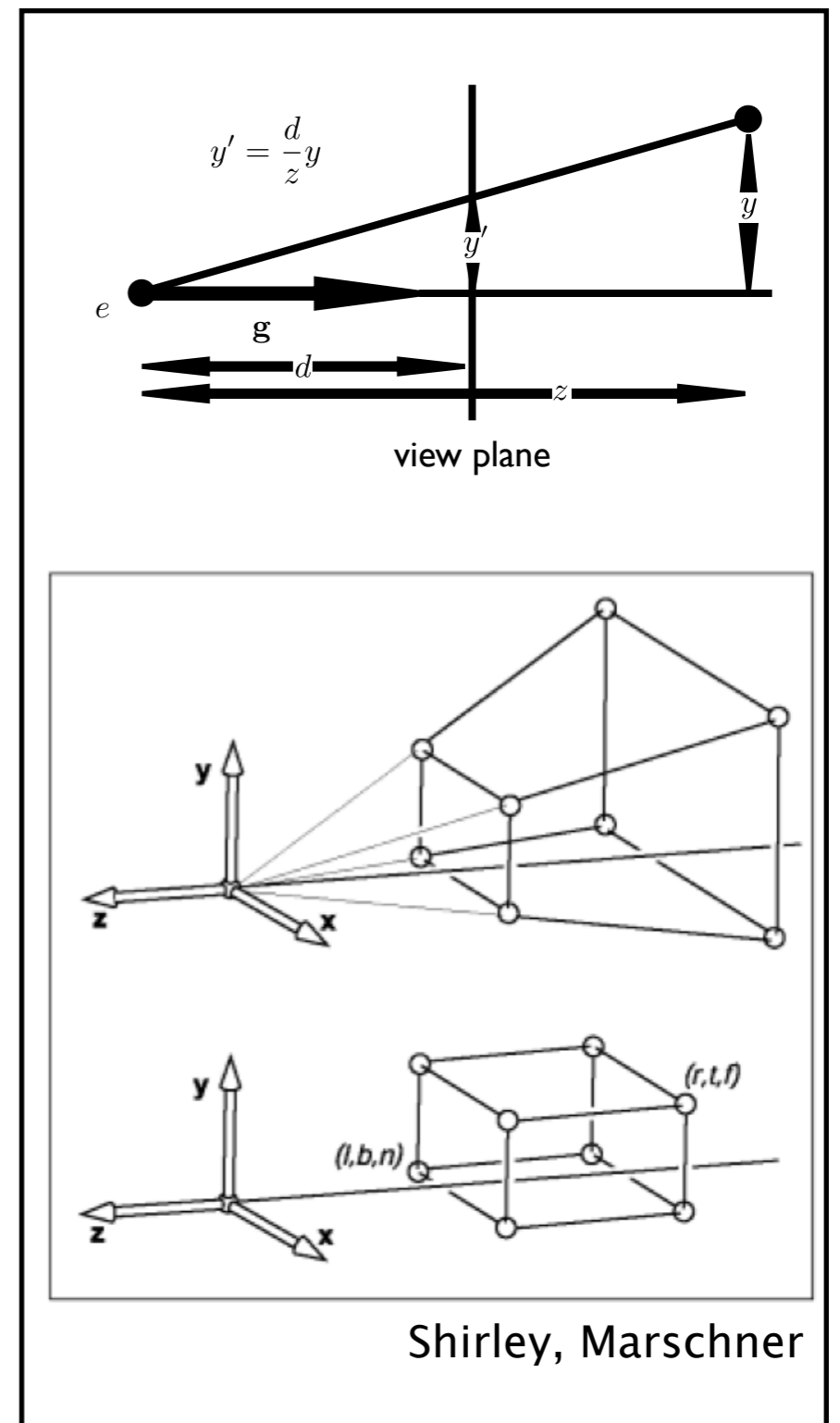
UC Riverside

# Perspective Projection (continued)

# Perspective Projection

$$P = \begin{pmatrix} n & 0 & 0 & 0 \\ 0 & n & 0 & 0 \\ 0 & 0 & n + f & -fn \\ 0 & 0 & 1 & 0 \end{pmatrix}$$

$$M_{per} = M_{orth}P \quad \langle \text{whiteboard} \rangle$$

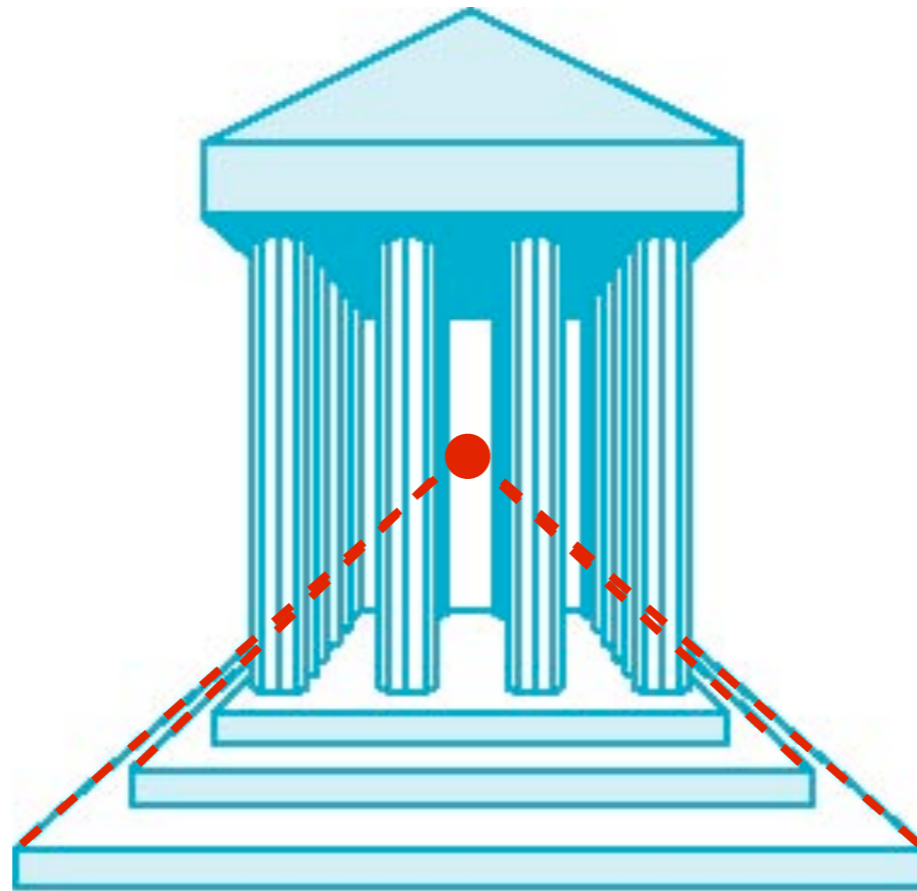


This does not preserve  $z$  completely, but it preserves  $z = n, f$  and is **monotone** (preserves ordering) with respect to  $z$

# One-Point Perspective

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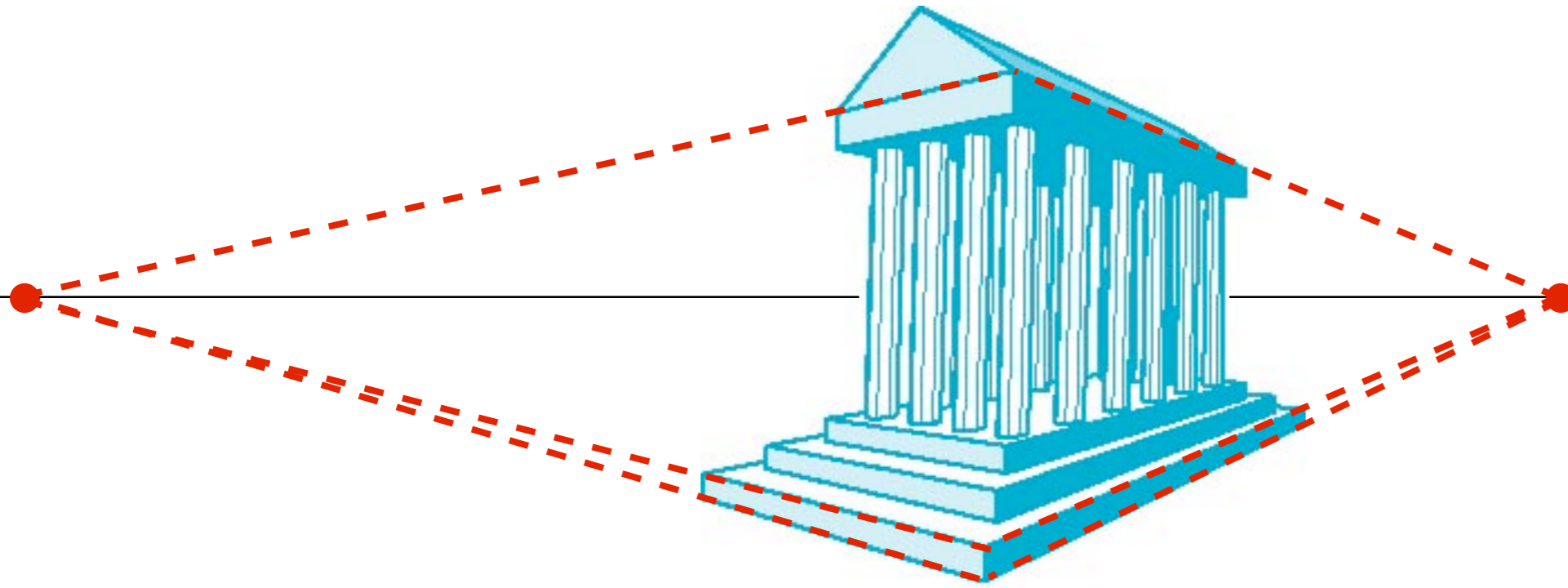
- One principal face parallel to projection plane
- One vanishing point for cube



# Two-Point Perspective

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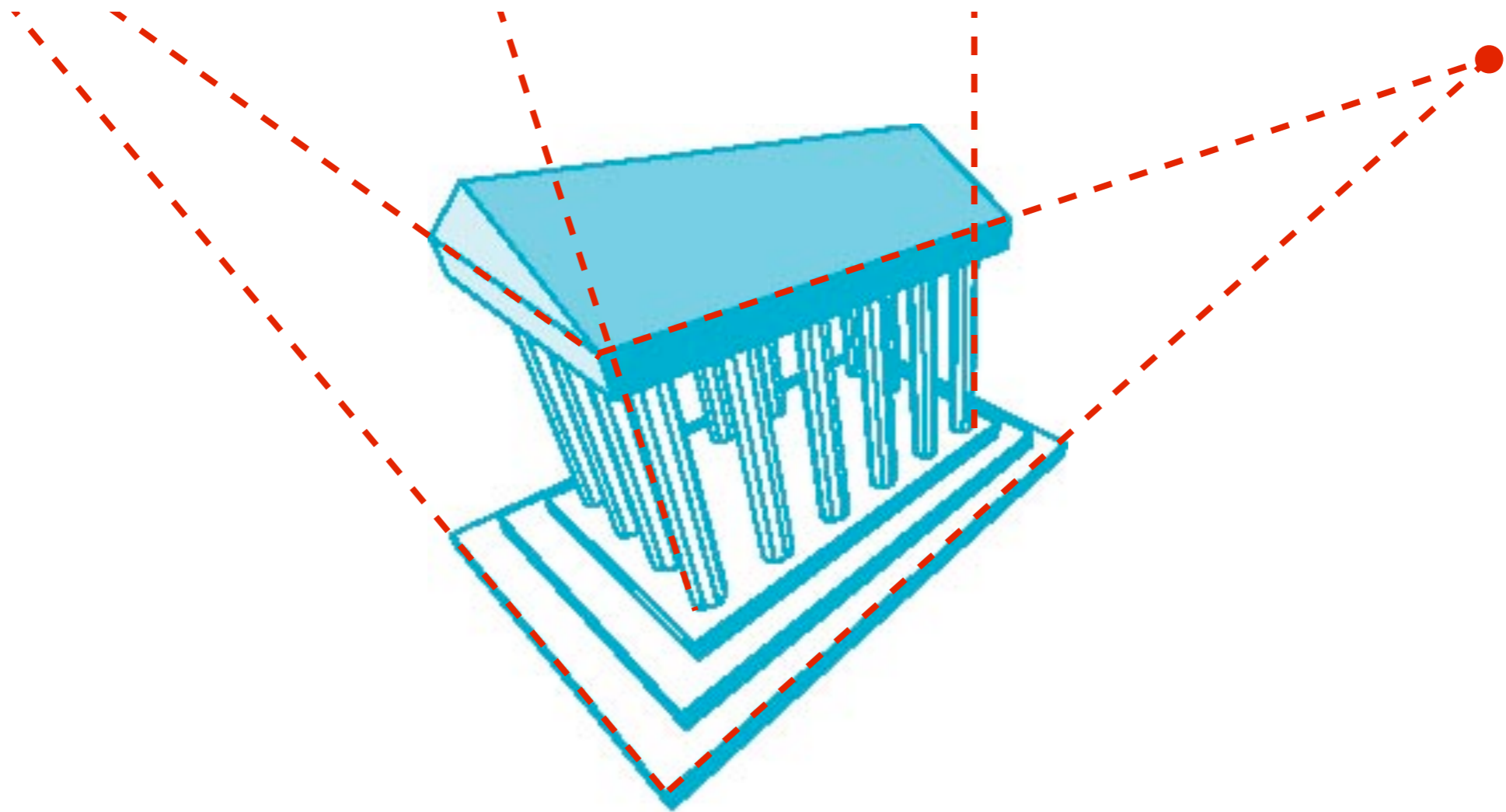
- On principal direction parallel to projection plane
- Two vanishing points for cube



# Three-Point Perspective

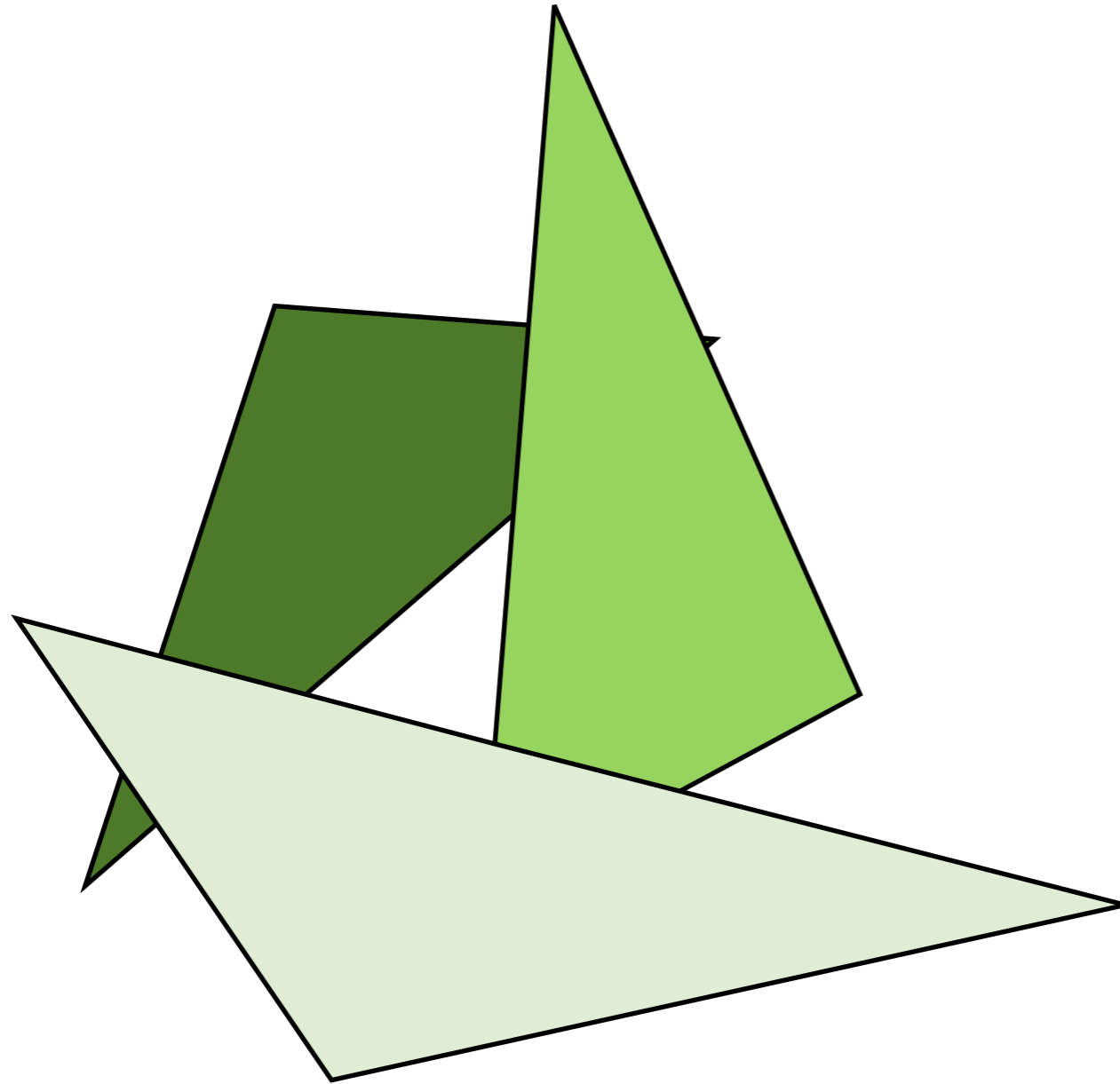
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- No principal face parallel to projection plane
- Three vanishing points for cube



# Hidden Surface Removal

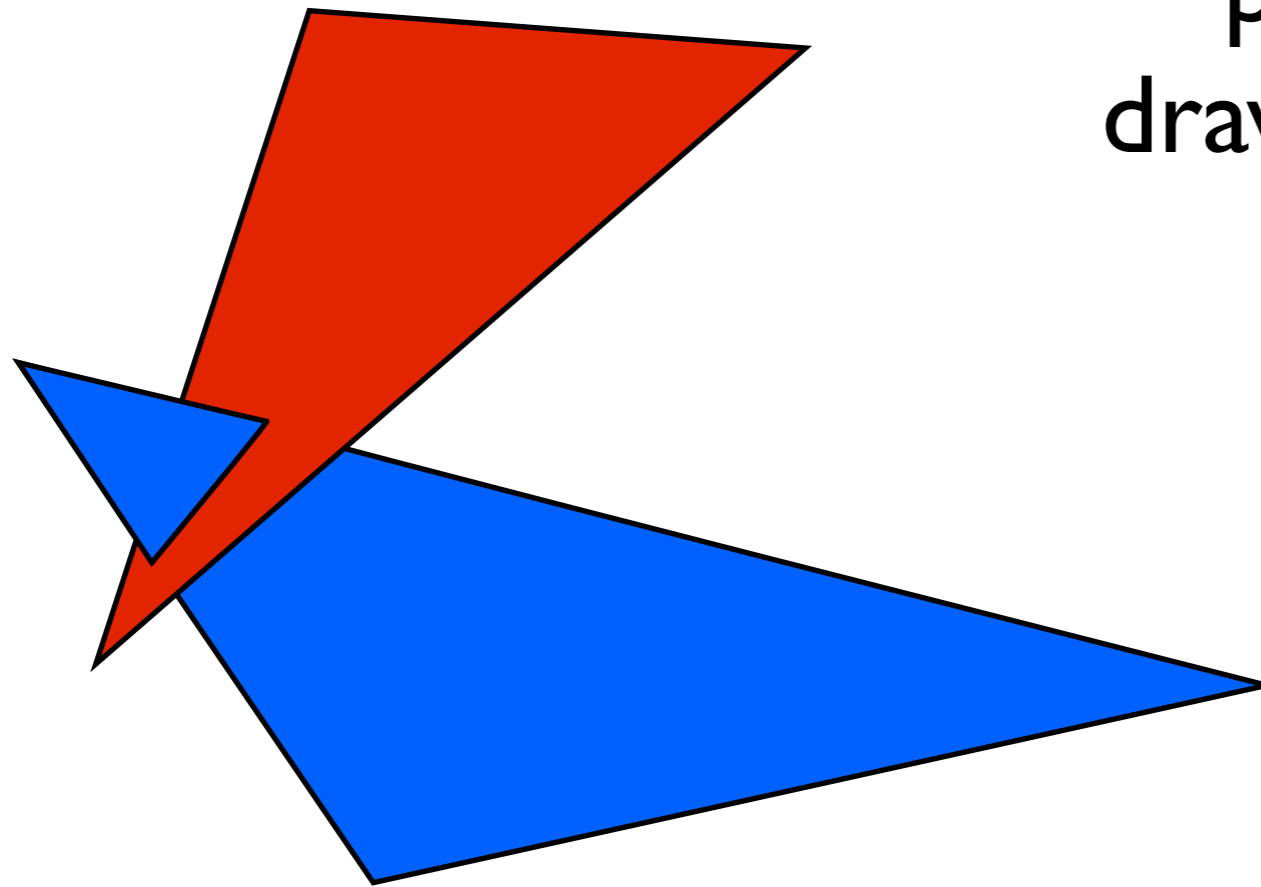
# Occlusion



“painter’s algorithm”  
draw primitives in  
back-to-front order



# Occlusion

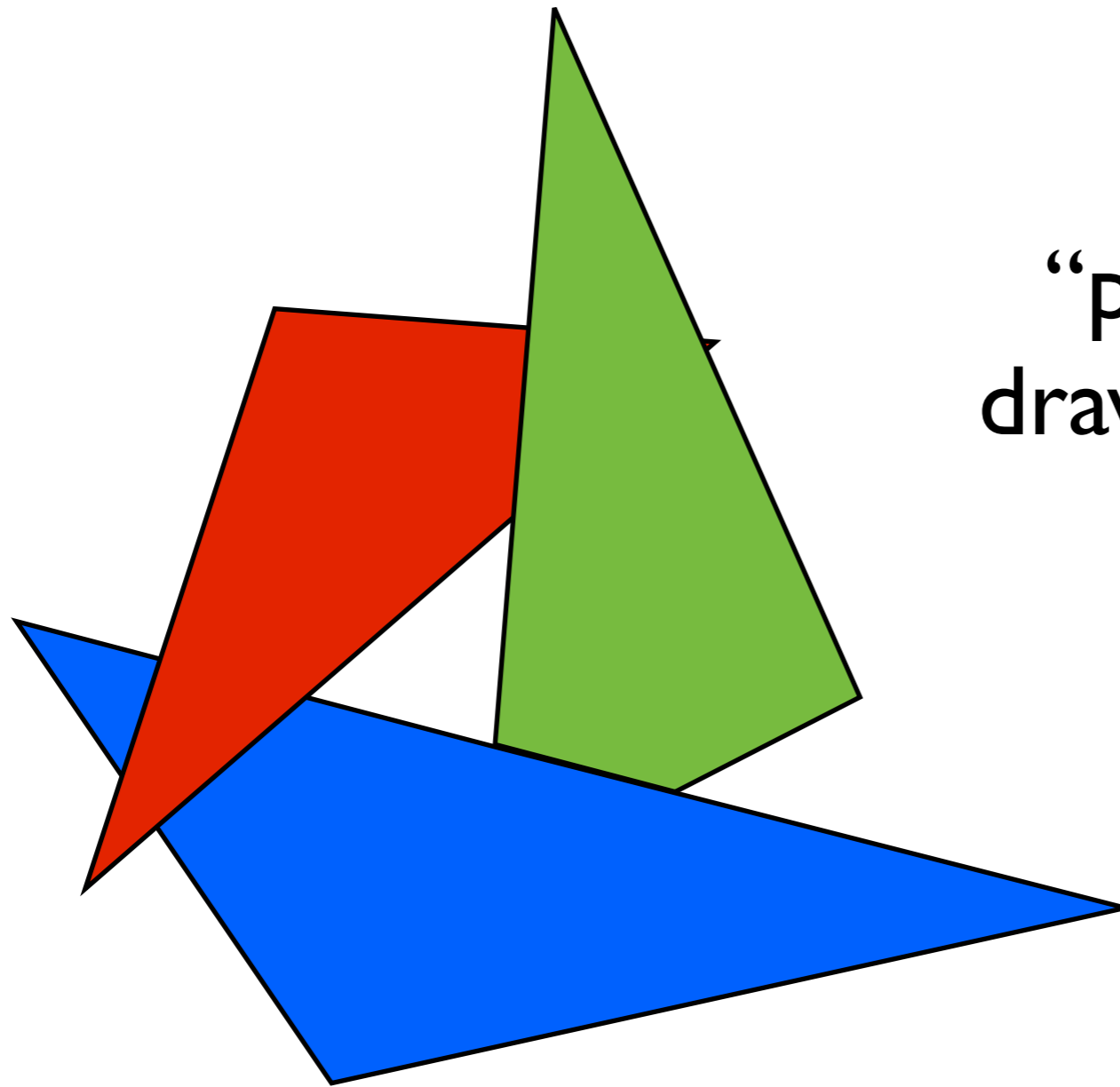


“painter’s algorithm”  
draw primitives in back-  
to-front order

**problem:**  
triangle  
intersection

who’s in front of whom?

# Occlusion



“painter’s algorithm”  
draw primitives in back-  
to-front order

**problem:**  
occlusion cycle

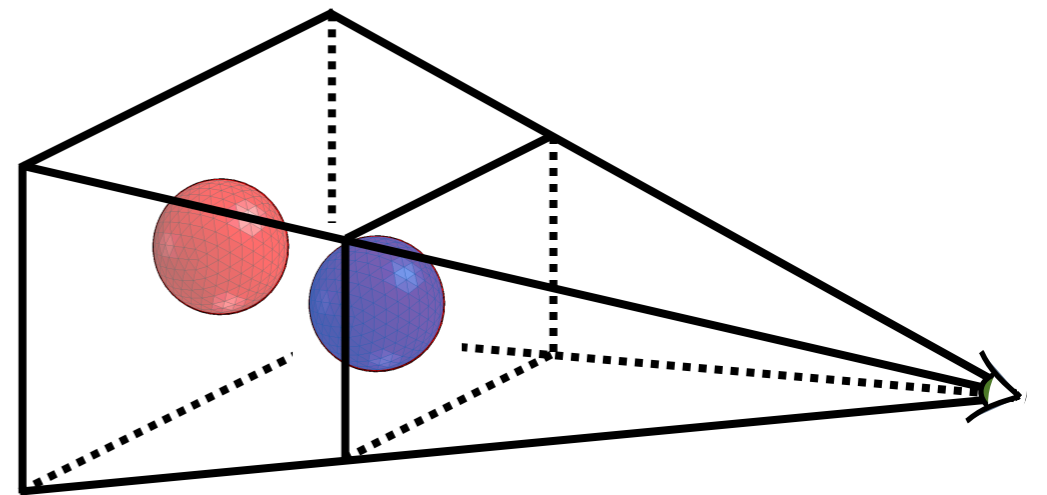
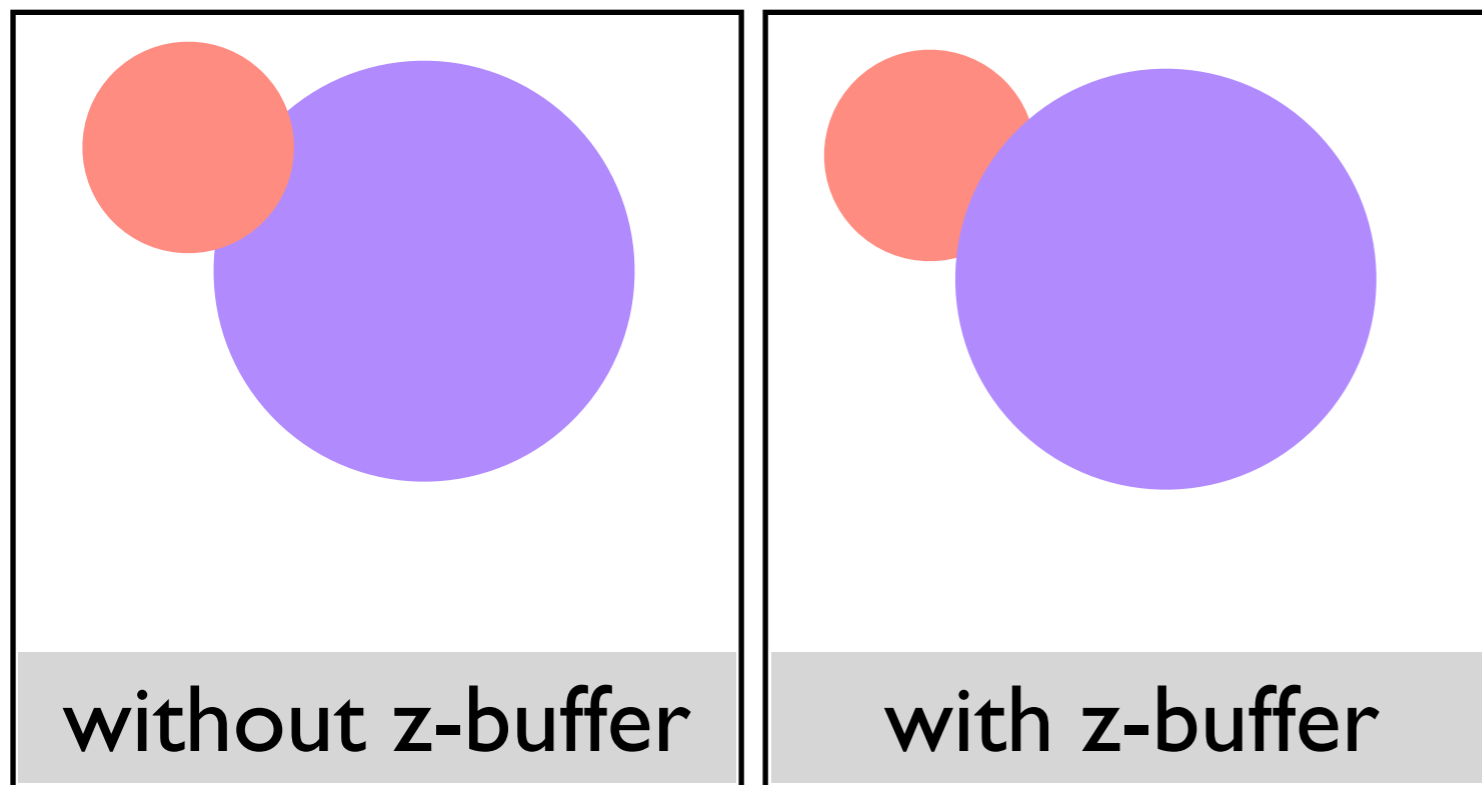
also, sort primitives by depth is **slow**

# Use a *z-buffer* for hidden surface removal

at each pixel, record distance to the closest object that has been drawn in a *depth* buffer

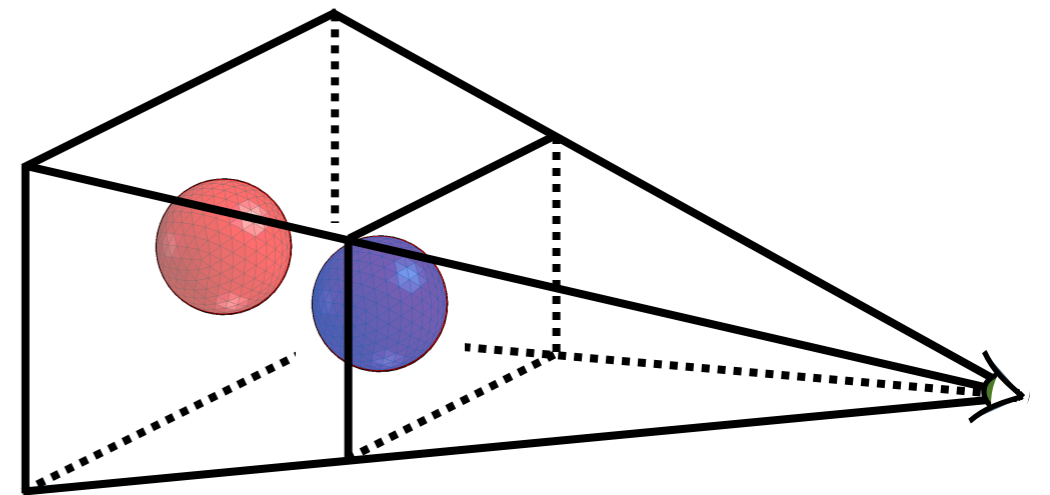
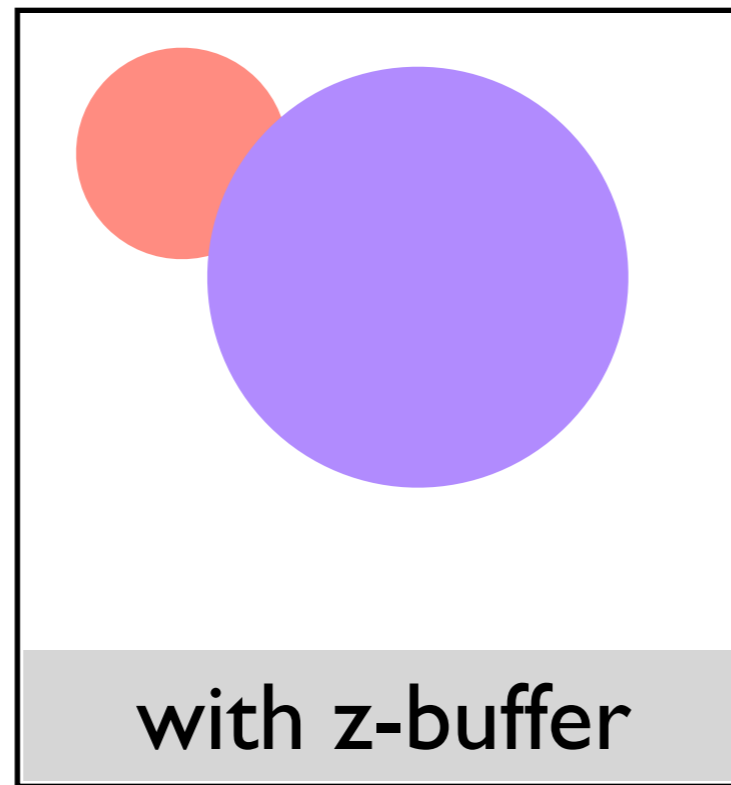
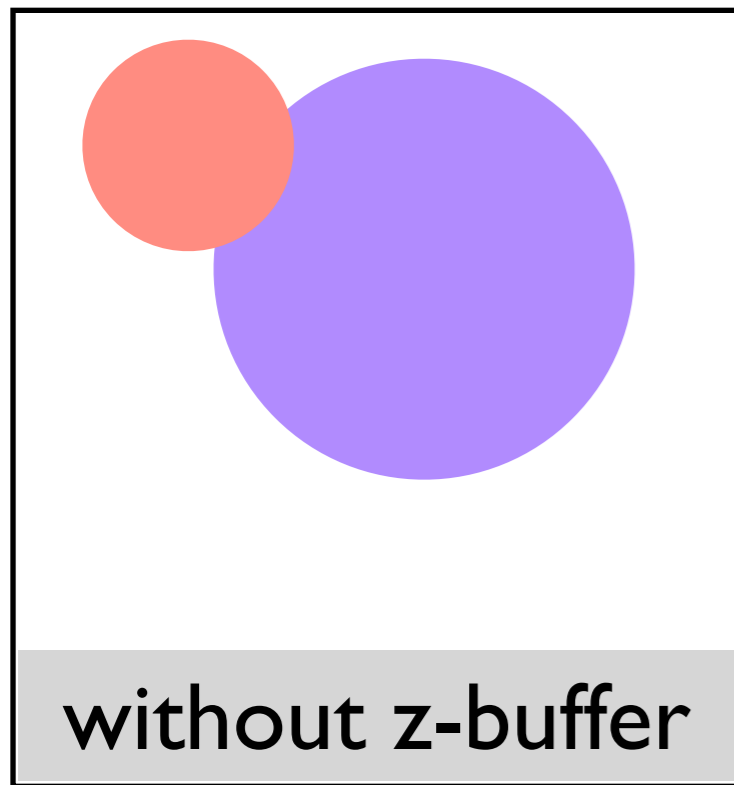
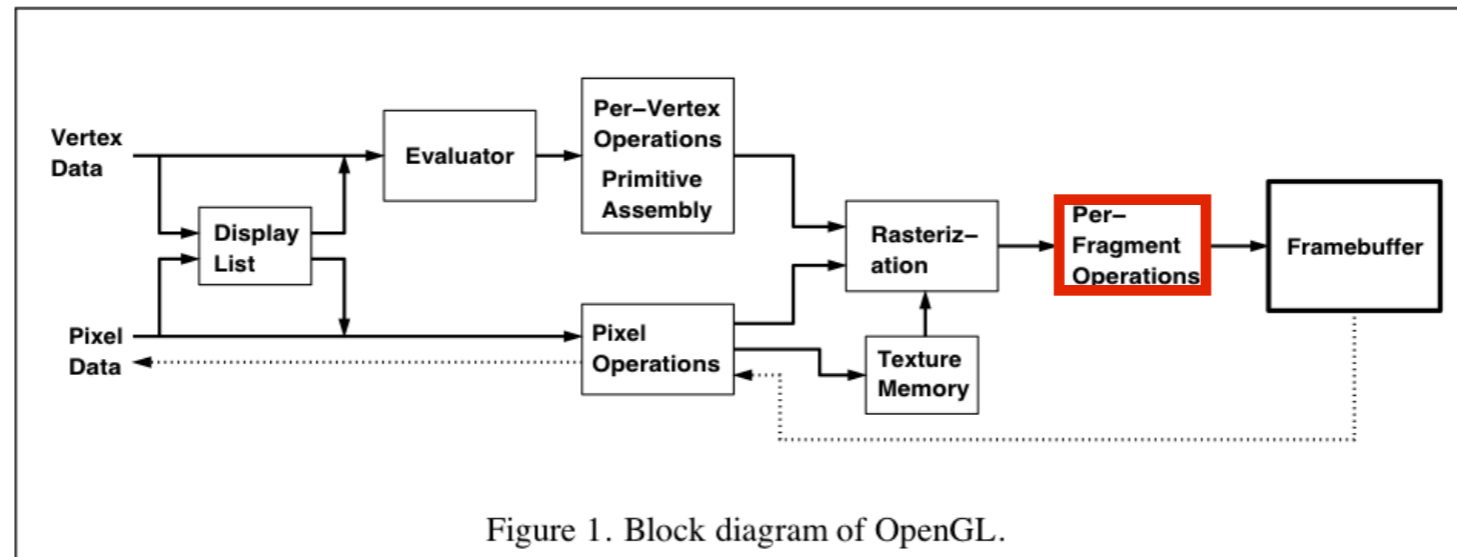
# Use a *z-buffer* for hidden surface removal

at each pixel, record distance to the closest object that has been drawn in a *depth* buffer



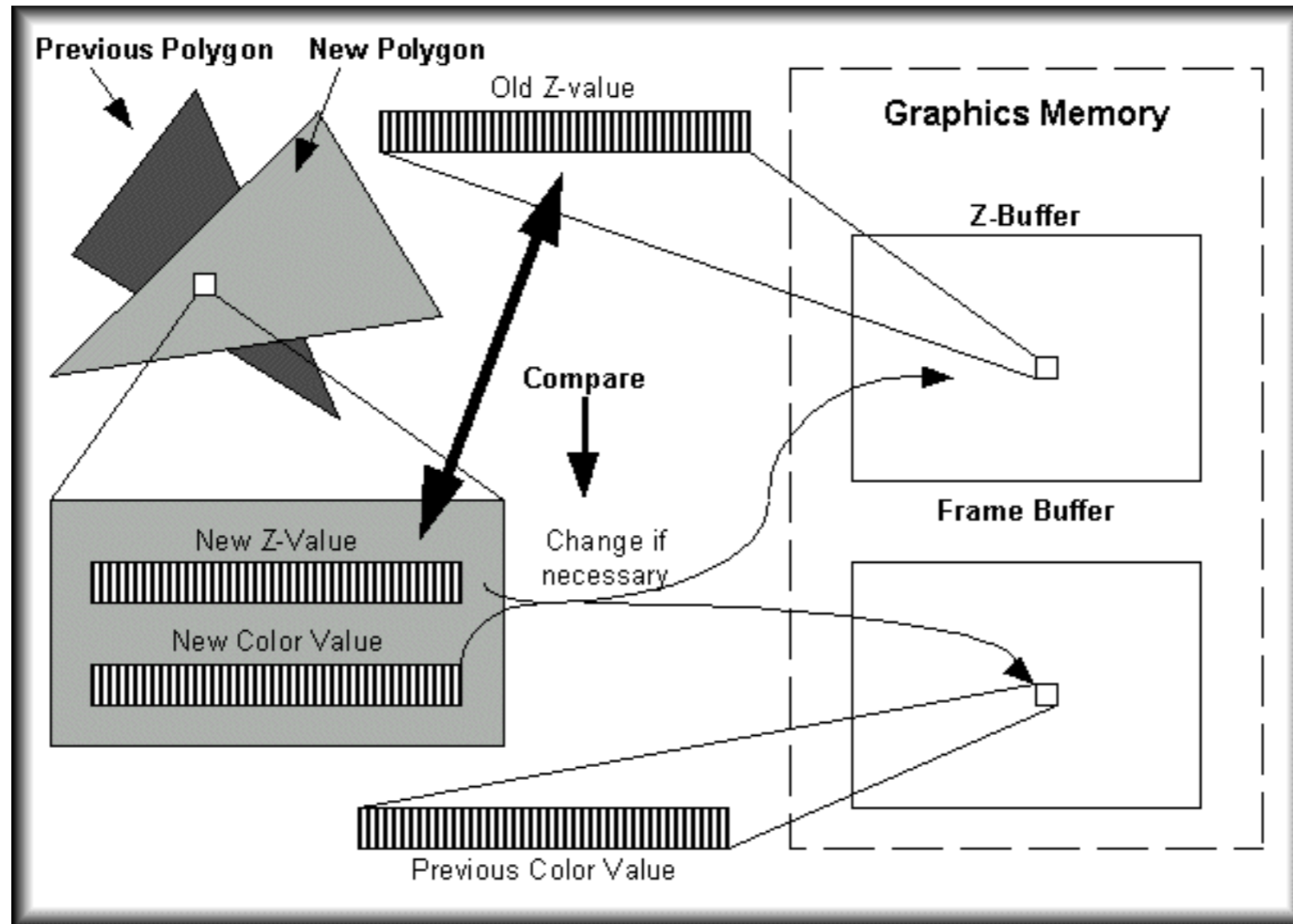
- assume both spheres of the same size, red drawn last

# Use a *z-buffer* for hidden surface removal



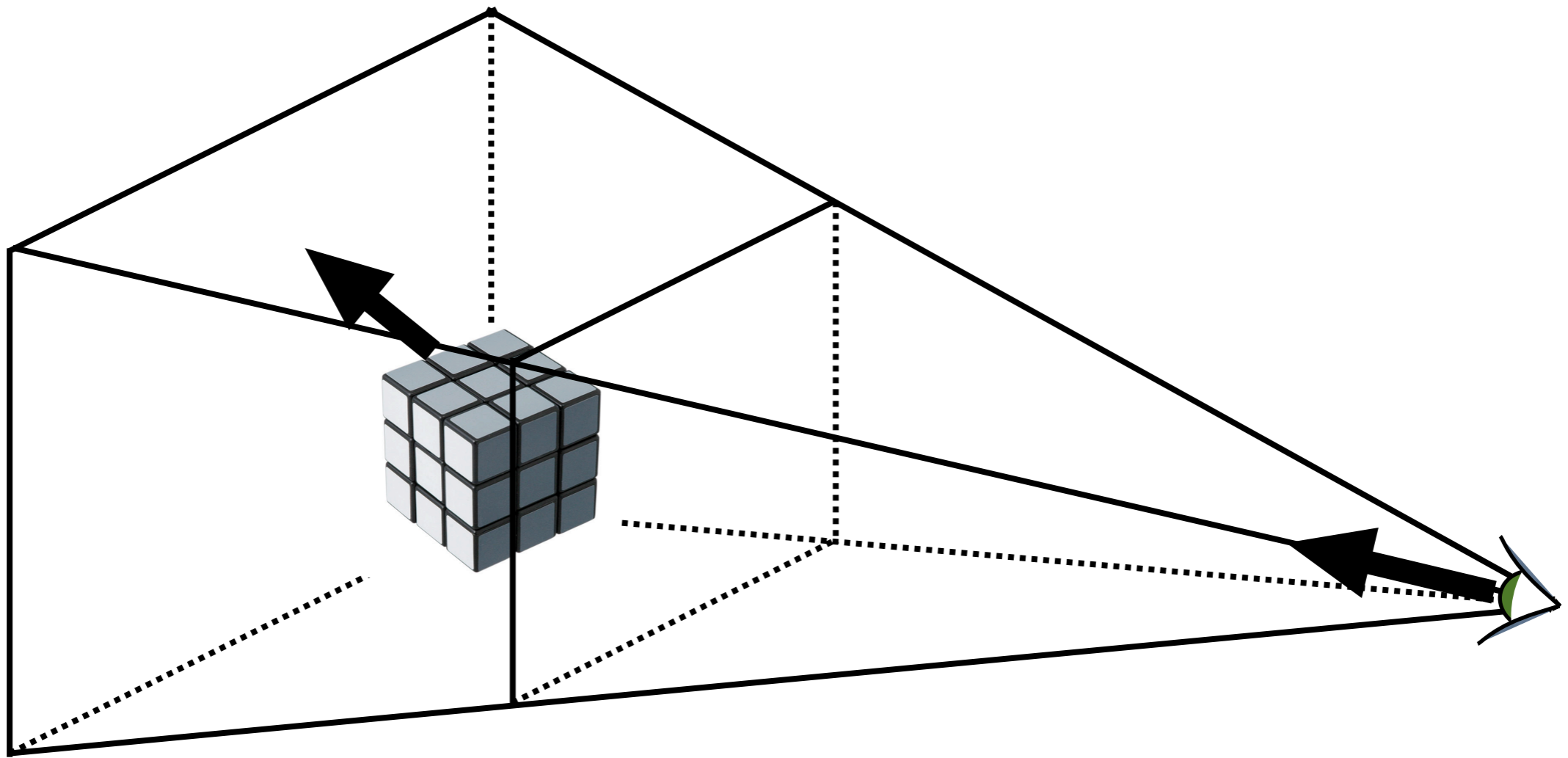
done in the **fragment blending** phase  
– each fragment must carry a depth

# Use a *z-buffer* for hidden surface removal



<http://www.beyond3d.com/content/articles/41/>

# Backface culling: another way to eliminate hidden geometry



# Hidden Surface Removal in OpenGL

```
glutInitDisplayMode(GLUT_DOUBLE | GLUT_RGB | GLUT_DEPTH);  
  
glEnable(GL_DEPTH_TEST);  
  
glEnable(GL_CULL_FACE);
```

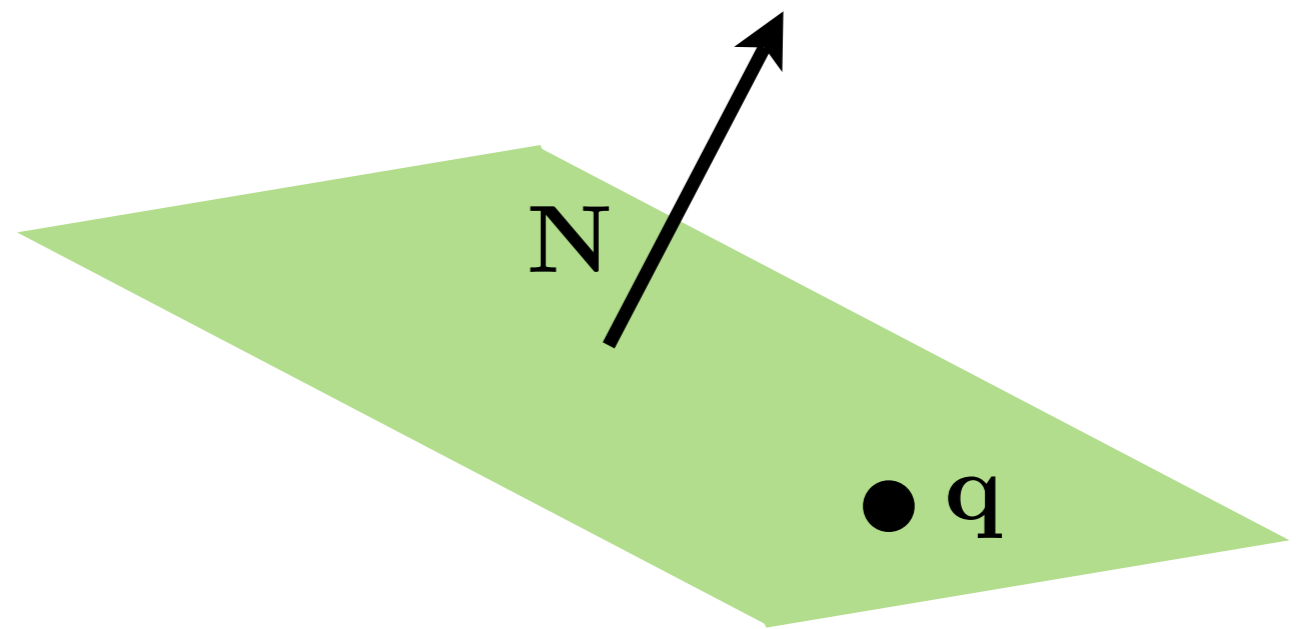
**Note:** For a perspective transformation, there is more in the depth buffer for z-values closer to the near plane

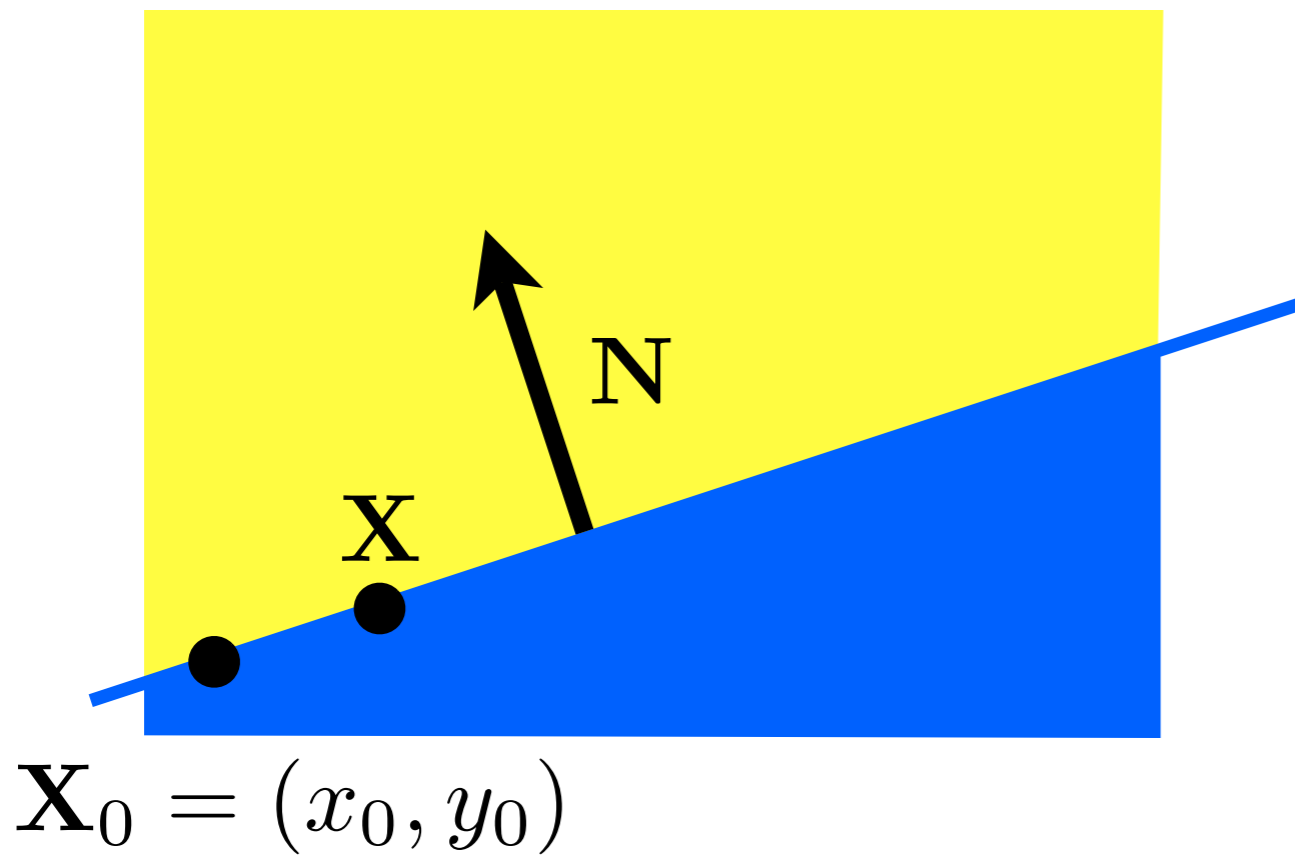


Clipping

# Clipping against a plane

What's the equation for  
the plane through  $\mathbf{q}$   
with normal  $\mathbf{N}$ ?





implicit line equation:

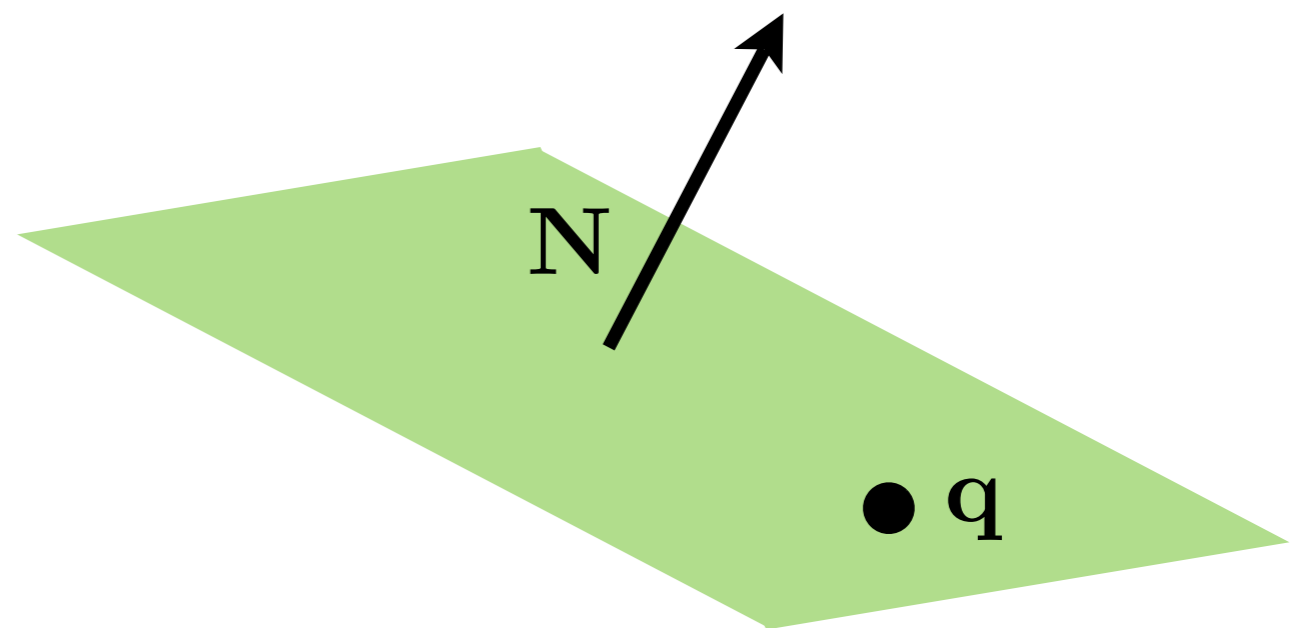
$$f(\mathbf{X}) = \mathbf{N} \cdot (\mathbf{X} - \mathbf{X}_0) = 0$$

# Clipping against a plane

What's the equation for  
the plane through  $\mathbf{q}$   
with normal  $\mathbf{N}$ ?

$$f(\mathbf{p}) = ? = 0$$

<whiteboard>

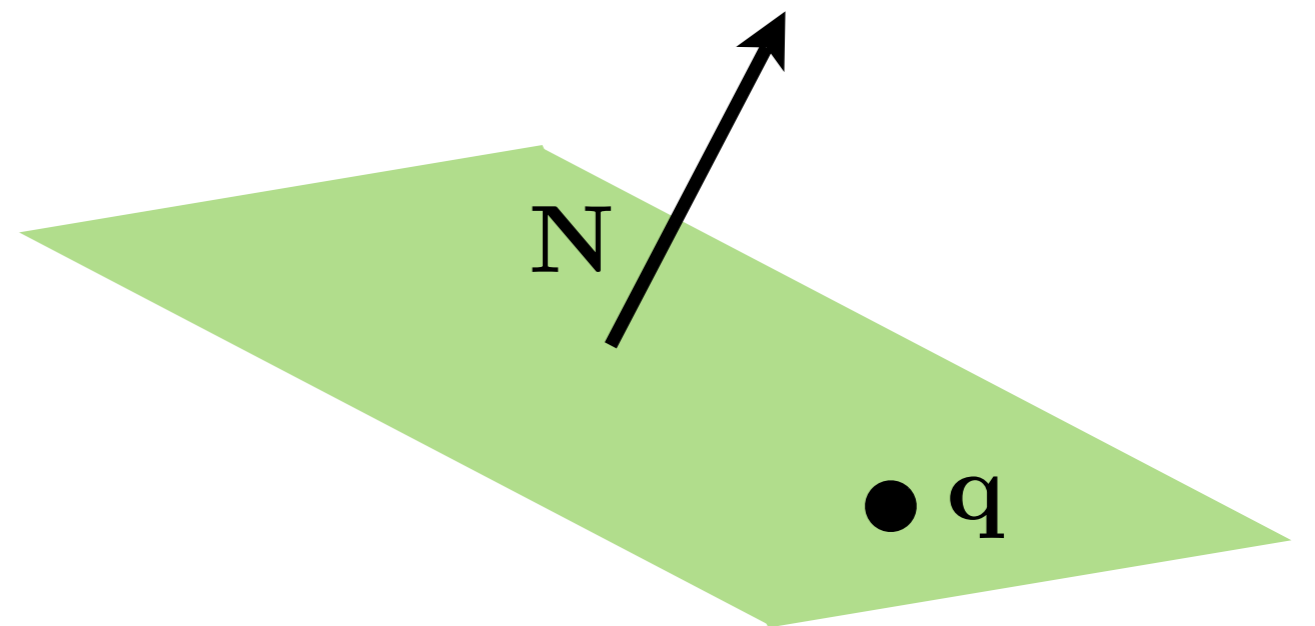


# Clipping against a plane

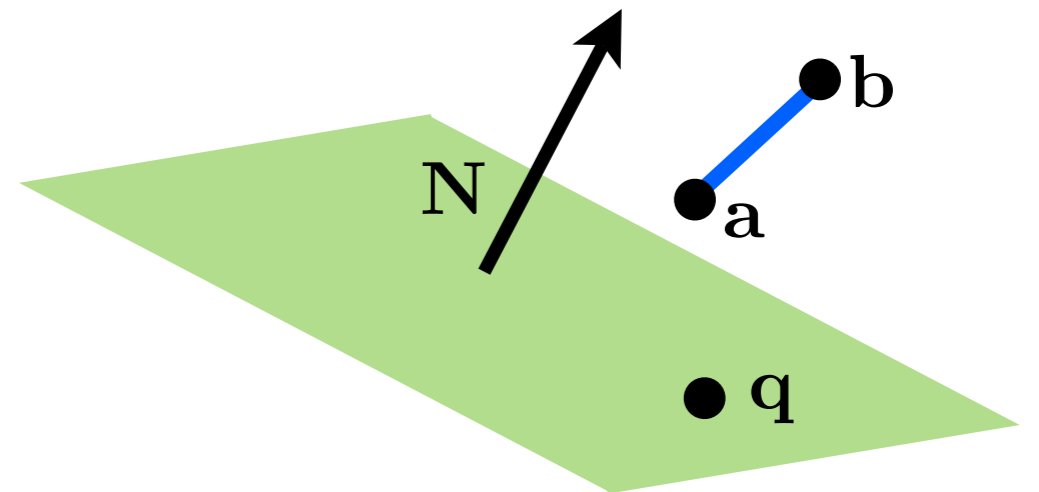
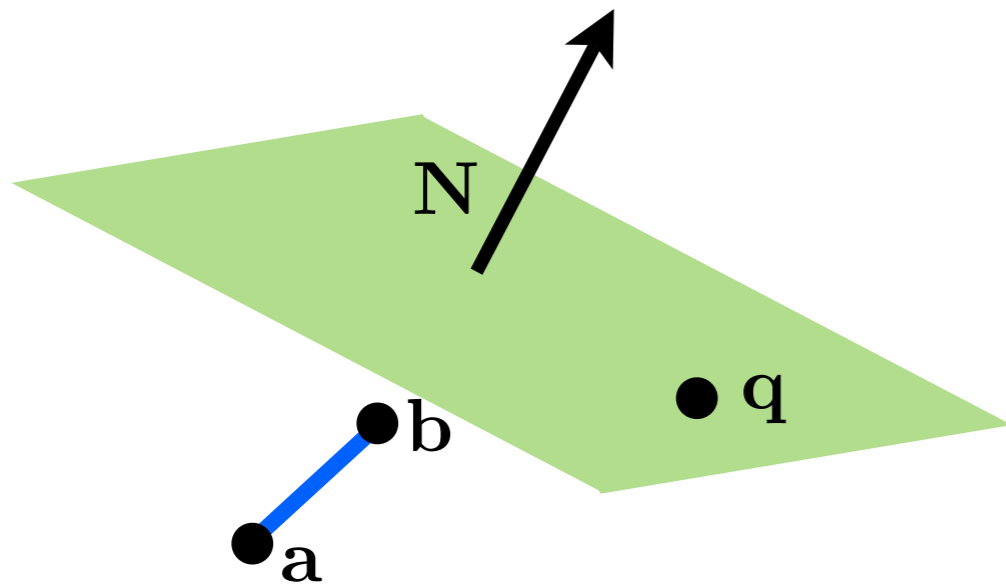
What's the equation for  
the plane through  $\mathbf{q}$   
with normal  $\mathbf{N}$ ?

$$f(\mathbf{p}) = \mathbf{N} \cdot (\mathbf{p} - \mathbf{q}) = 0$$

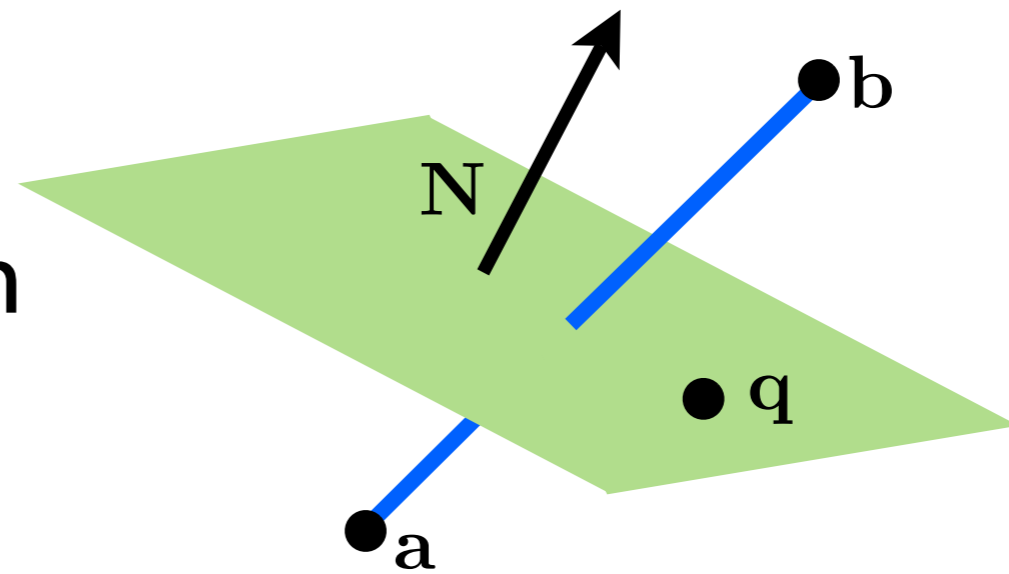
$$f(\mathbf{p}) = \mathbf{N} \cdot \mathbf{p} + D = 0$$



# Intersection of line and plane

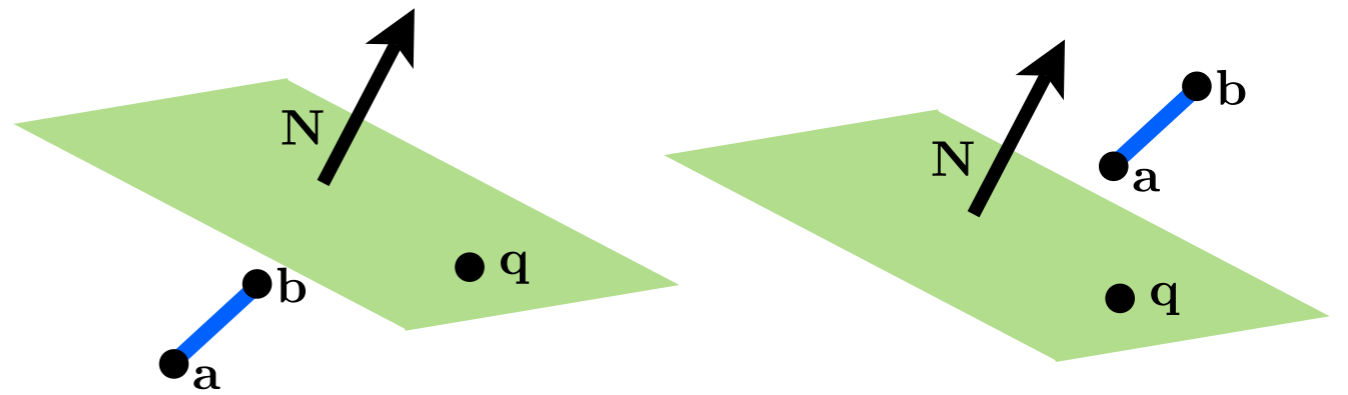


How can we distinguish between these cases?

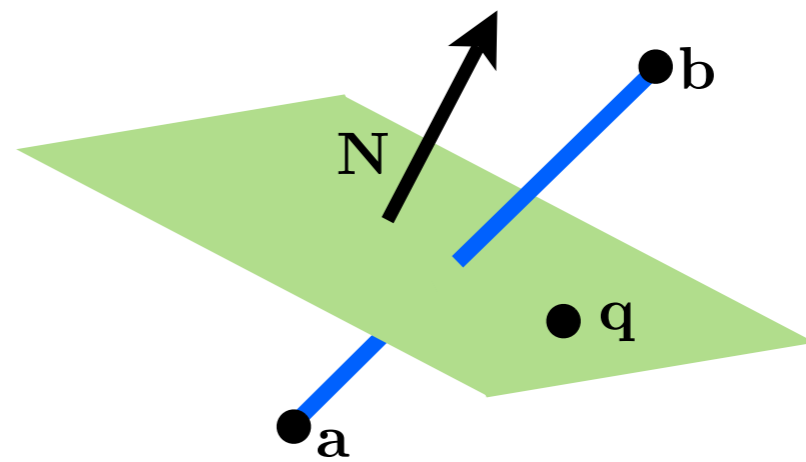


# Intersection of line and plane

$$f(\mathbf{a})f(\mathbf{b}) \geq 0$$

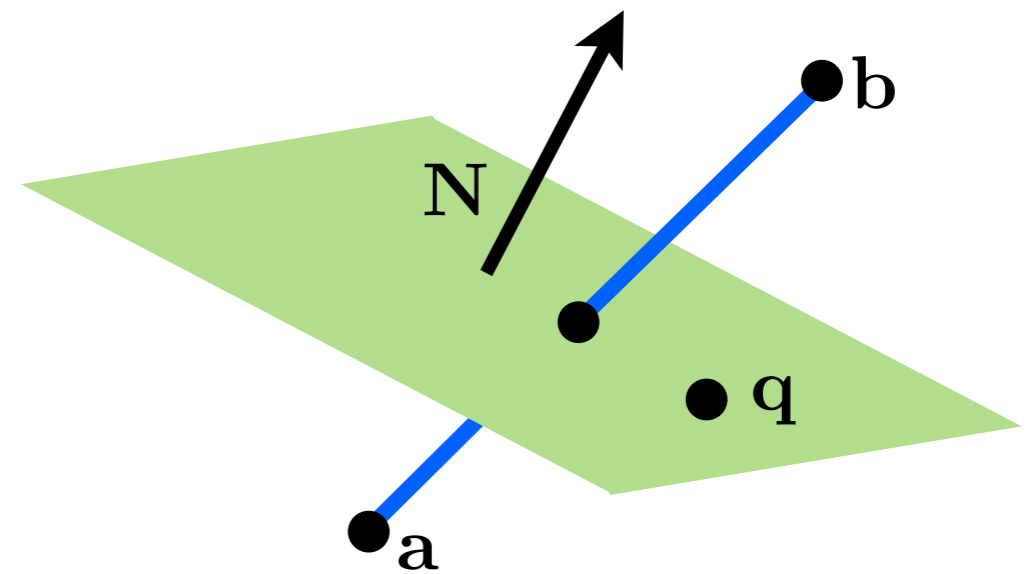


$$f(\mathbf{a})f(\mathbf{b}) < 0$$



# Intersection of line and plane

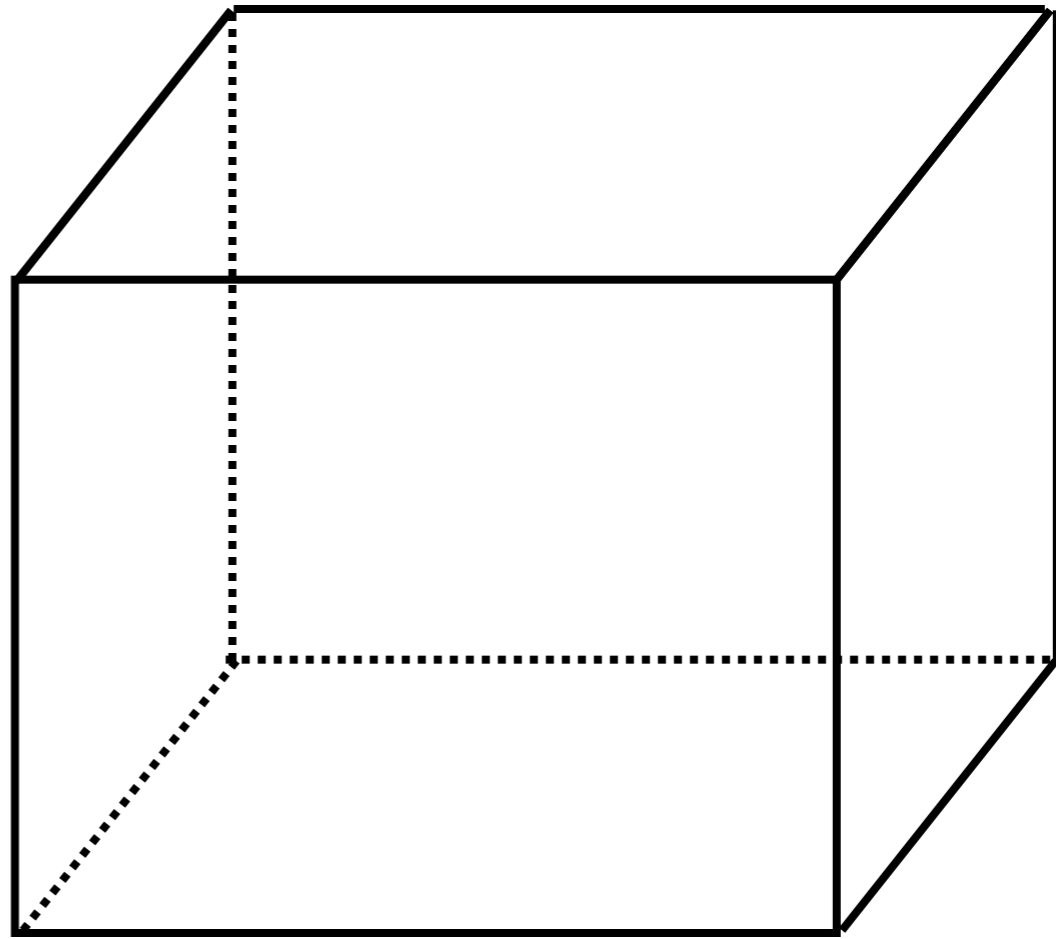
How can we find the intersection point?



<whiteboard>

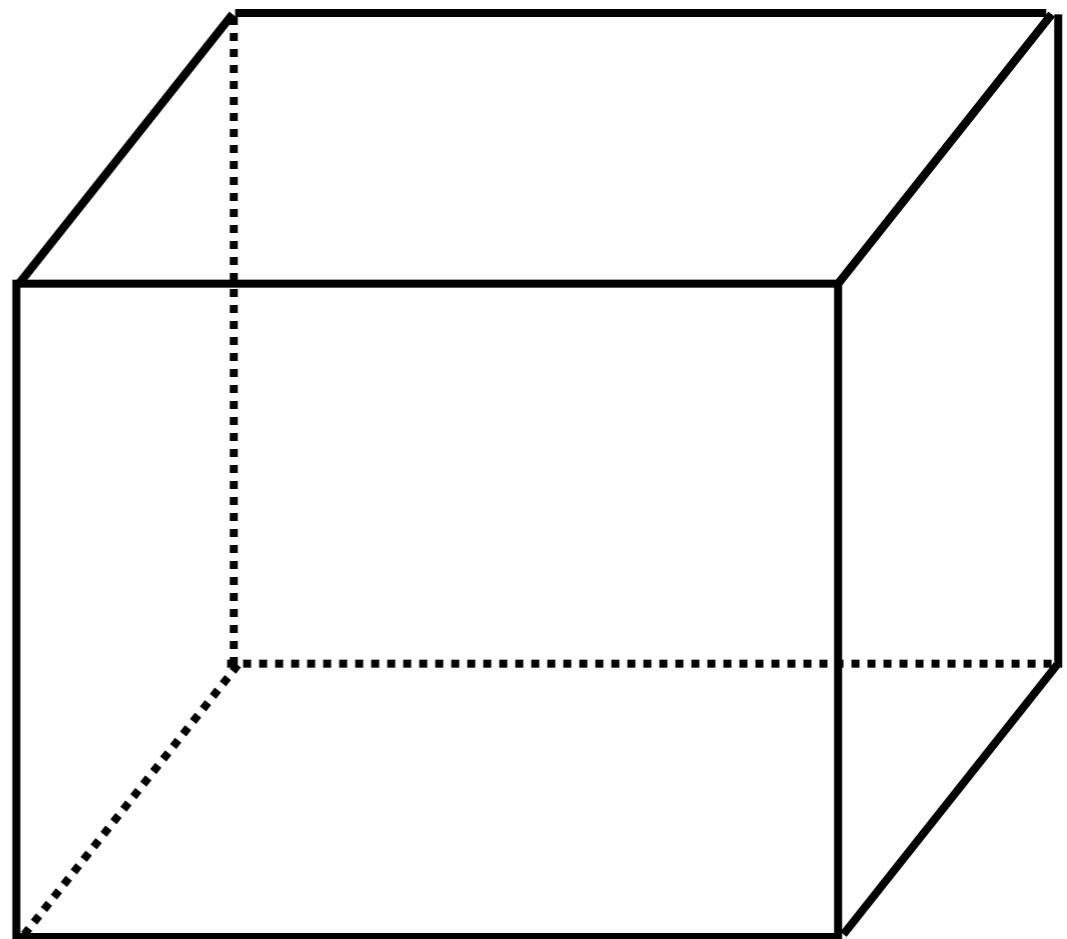
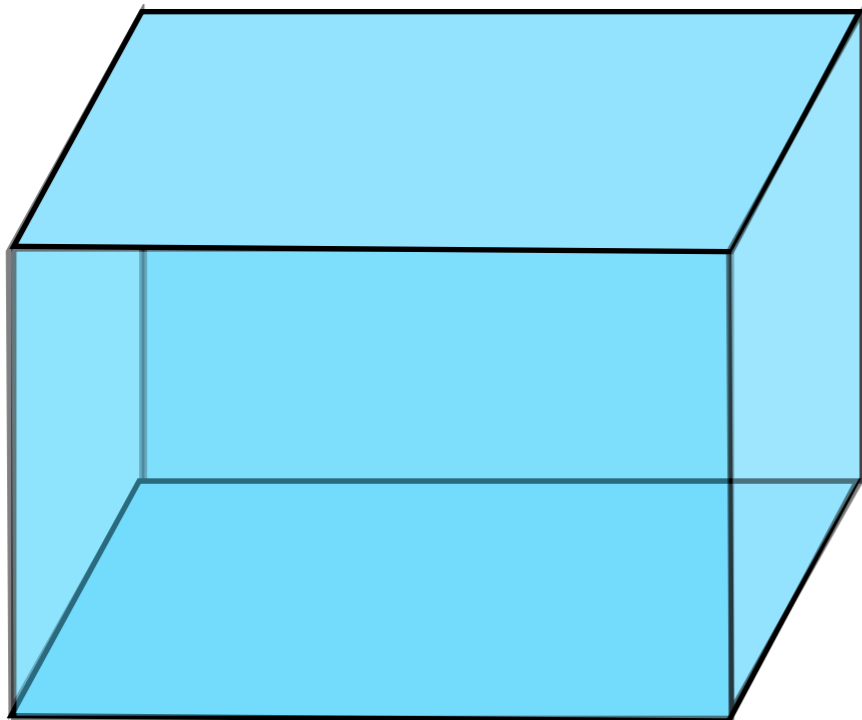


# Clipping against the viewing volume

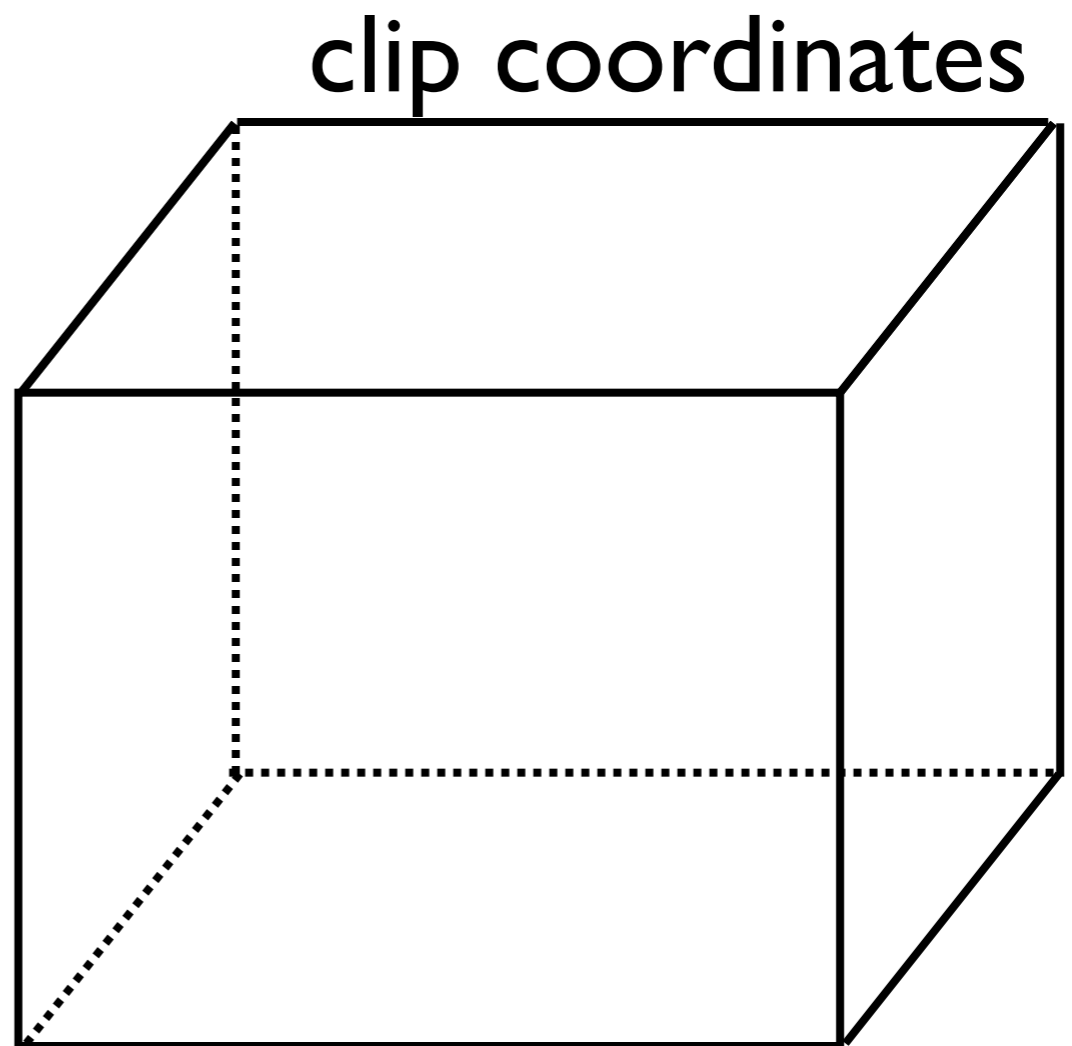
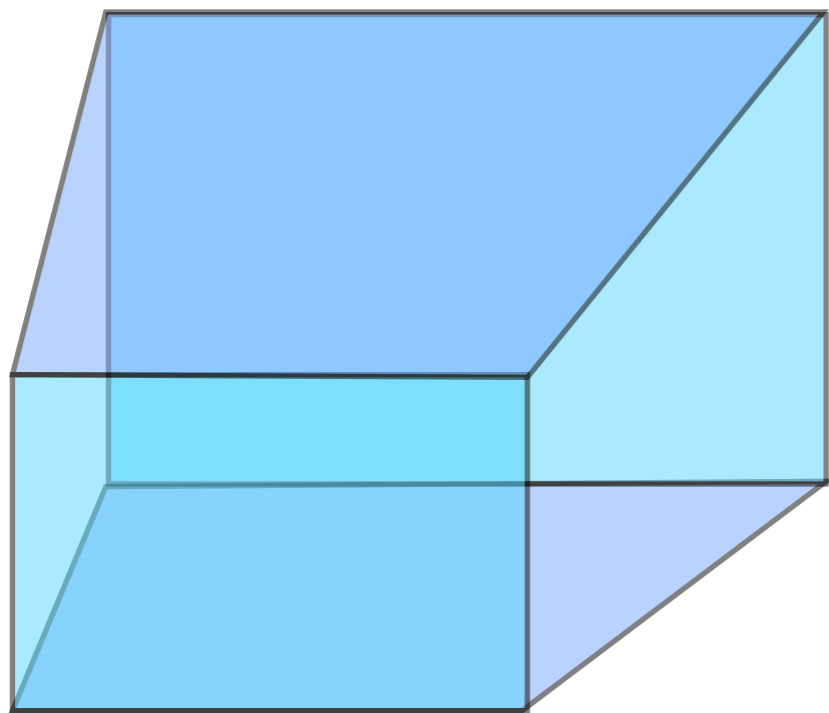


# Orthographic projection viewing volume

clip coordinates

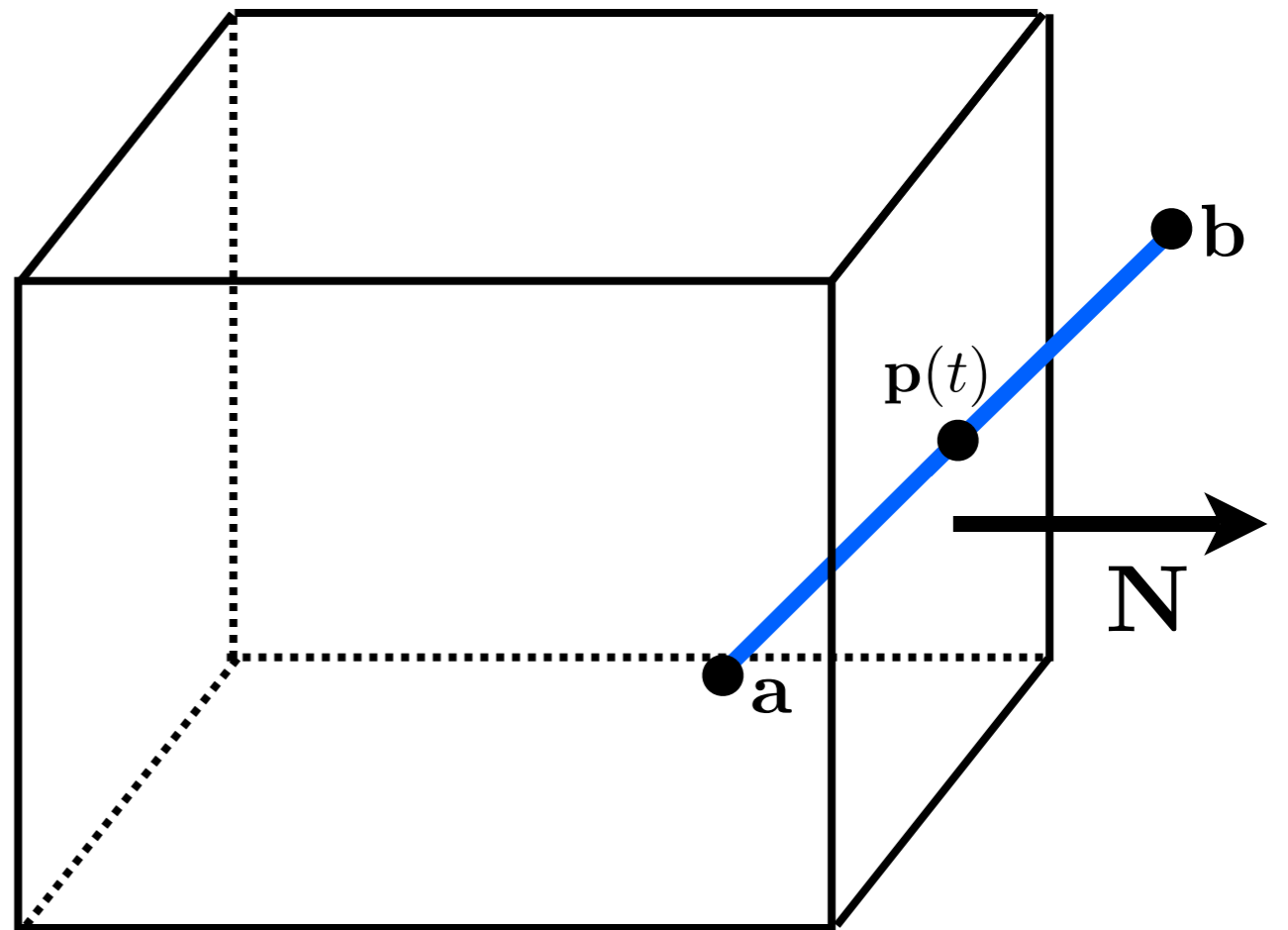


# Perspective projection viewing volume



# Clipping against the viewing volume

$$t = \frac{\mathbf{N} \cdot \mathbf{a} + D}{\mathbf{N} \cdot (\mathbf{a} - \mathbf{b})}$$

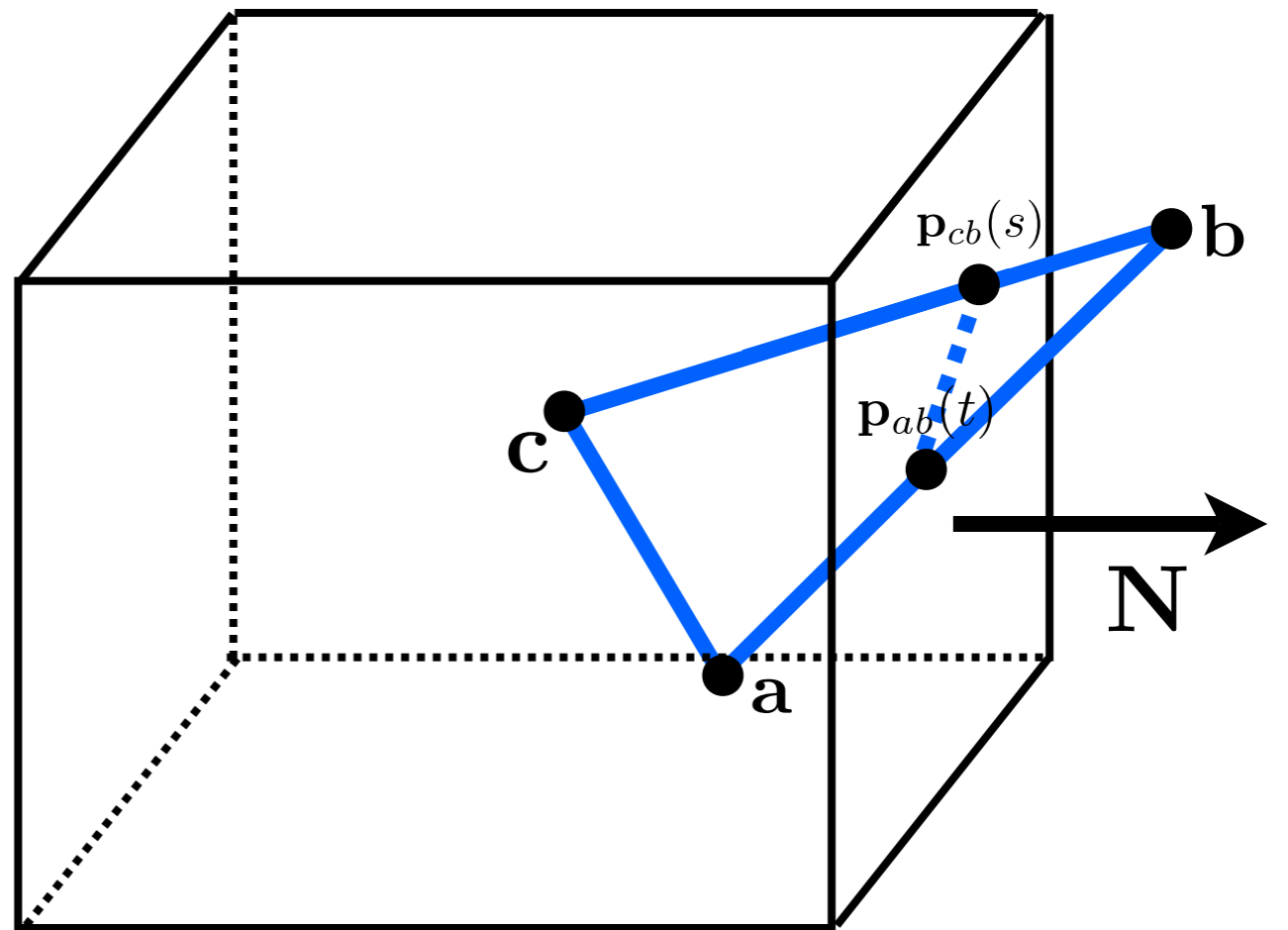


**N** is particularly simple for the orthographic viewing volume in NDC

# Clipping against the viewing volume

$$s = \frac{\mathbf{N} \cdot \mathbf{c} + d}{\mathbf{N} \cdot (\mathbf{c} - \mathbf{b})}$$

$$t = \frac{\mathbf{N} \cdot \mathbf{a} + D}{\mathbf{N} \cdot (\mathbf{a} - \mathbf{b})}$$



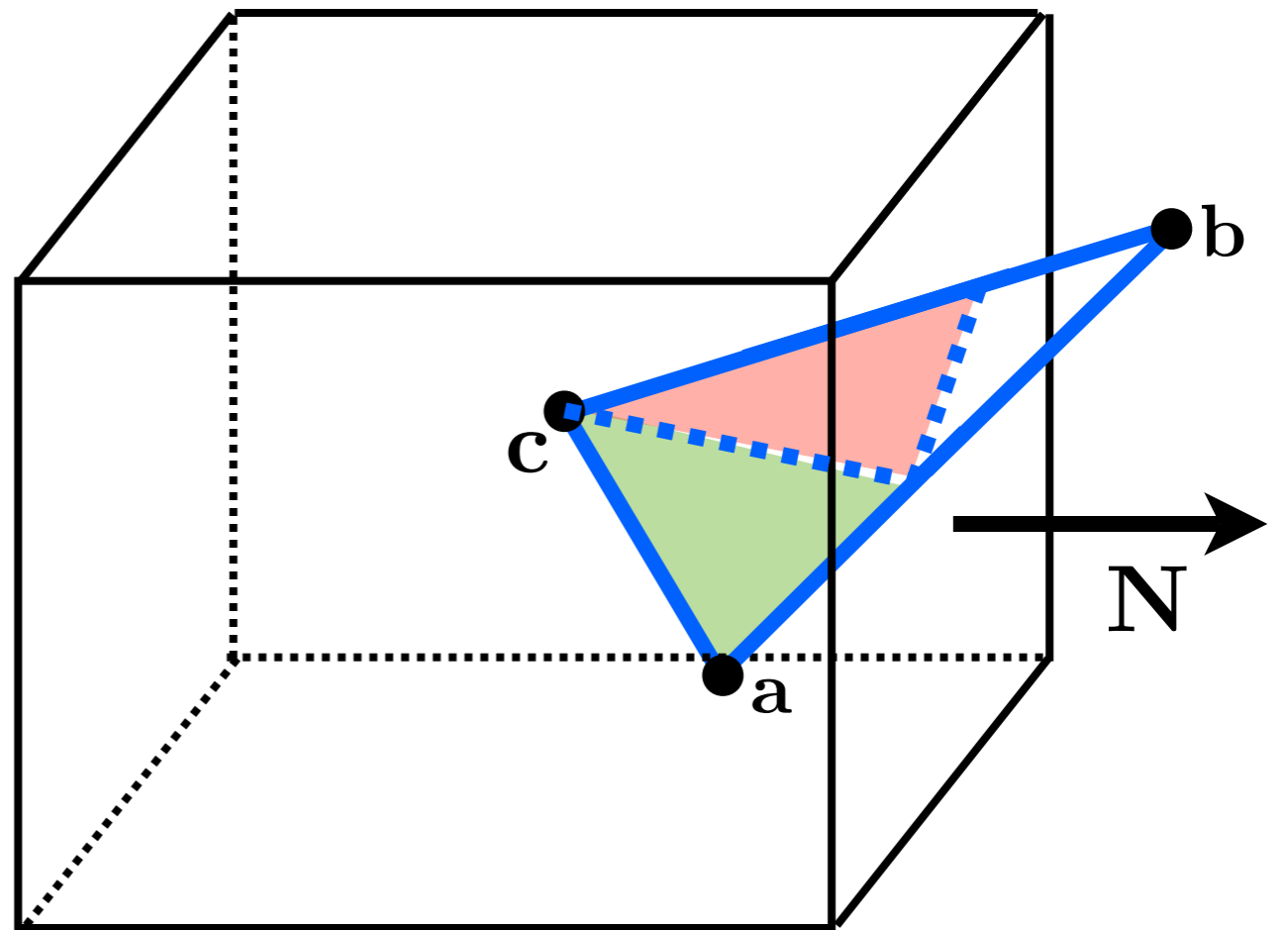
$\mathbf{N}$  is particularly simple for the orthographic viewing volume in NDC

# Clipping against the viewing volume

$$s = \frac{\mathbf{N} \cdot \mathbf{c} + d}{\mathbf{N} \cdot (\mathbf{c} - \mathbf{b})}$$

$$t = \frac{\mathbf{N} \cdot \mathbf{a} + D}{\mathbf{N} \cdot (\mathbf{a} - \mathbf{b})}$$

need to generate new  
triangles

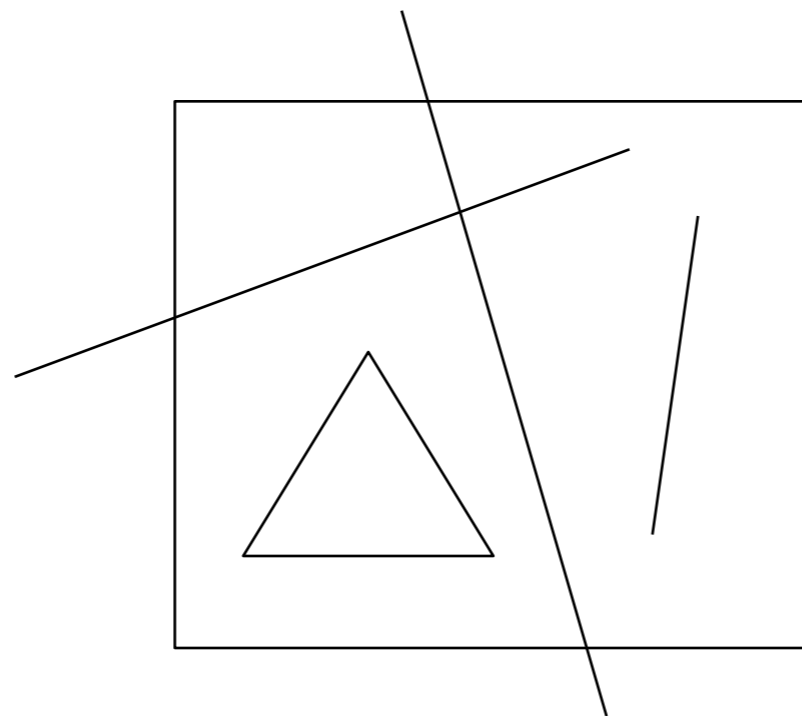


**N** is particularly simple for the orthographic viewing volume in NDC

# Clipping

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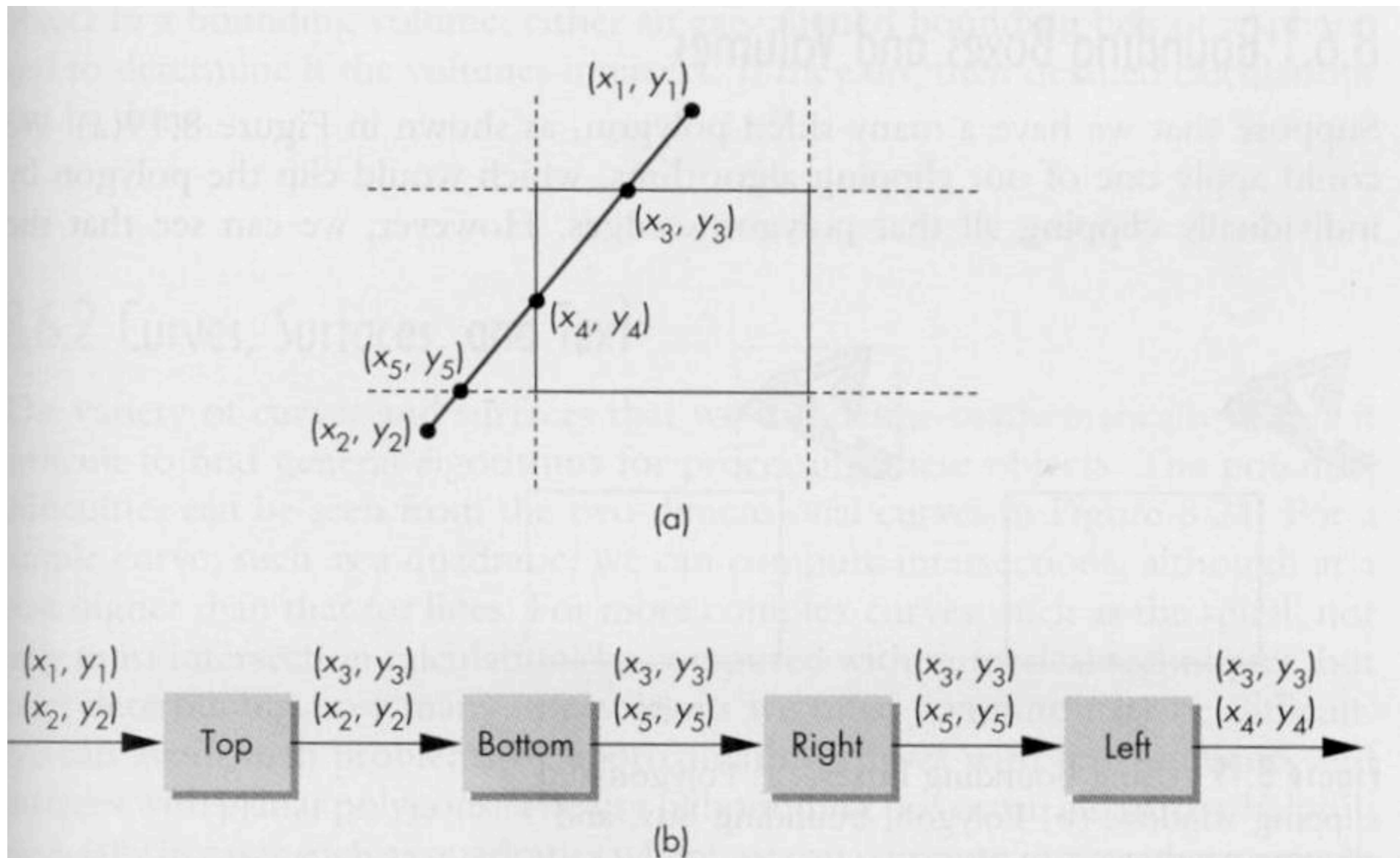
- Removing the unseen geometry
- Direct (brute-force) solution - solve simultaneous equations for intersections of lines/edges at window edges



A point or vertex is visible if  
 $x_{left} < x < x_{right}$   
and  
 $y_{bot} < y < y_{top}$

# Clipping lines

Pipeline, clip each edge of the window separately:

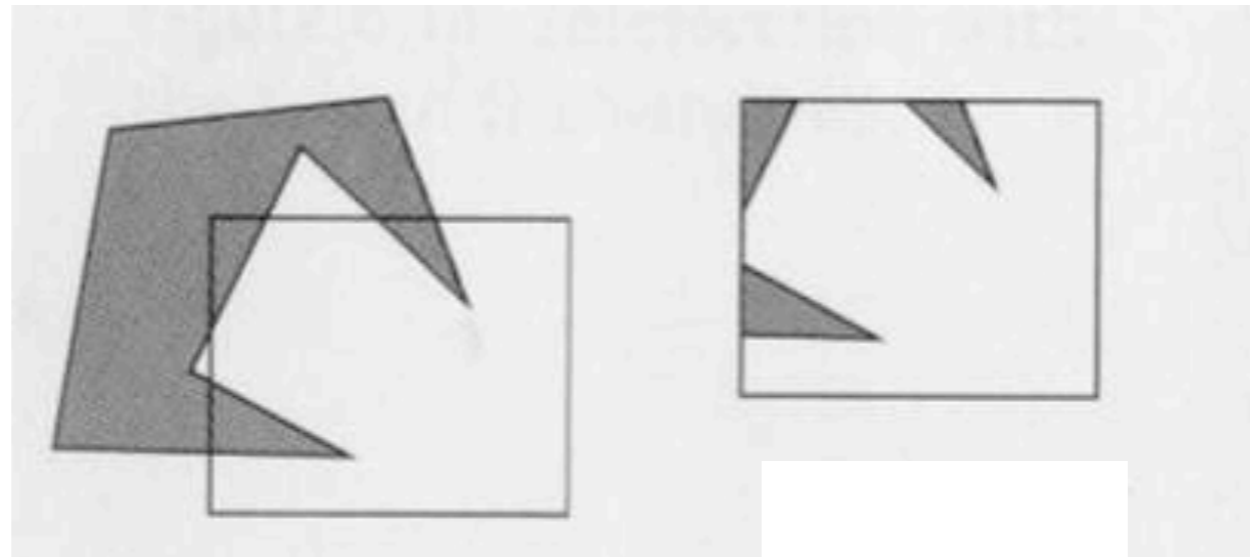




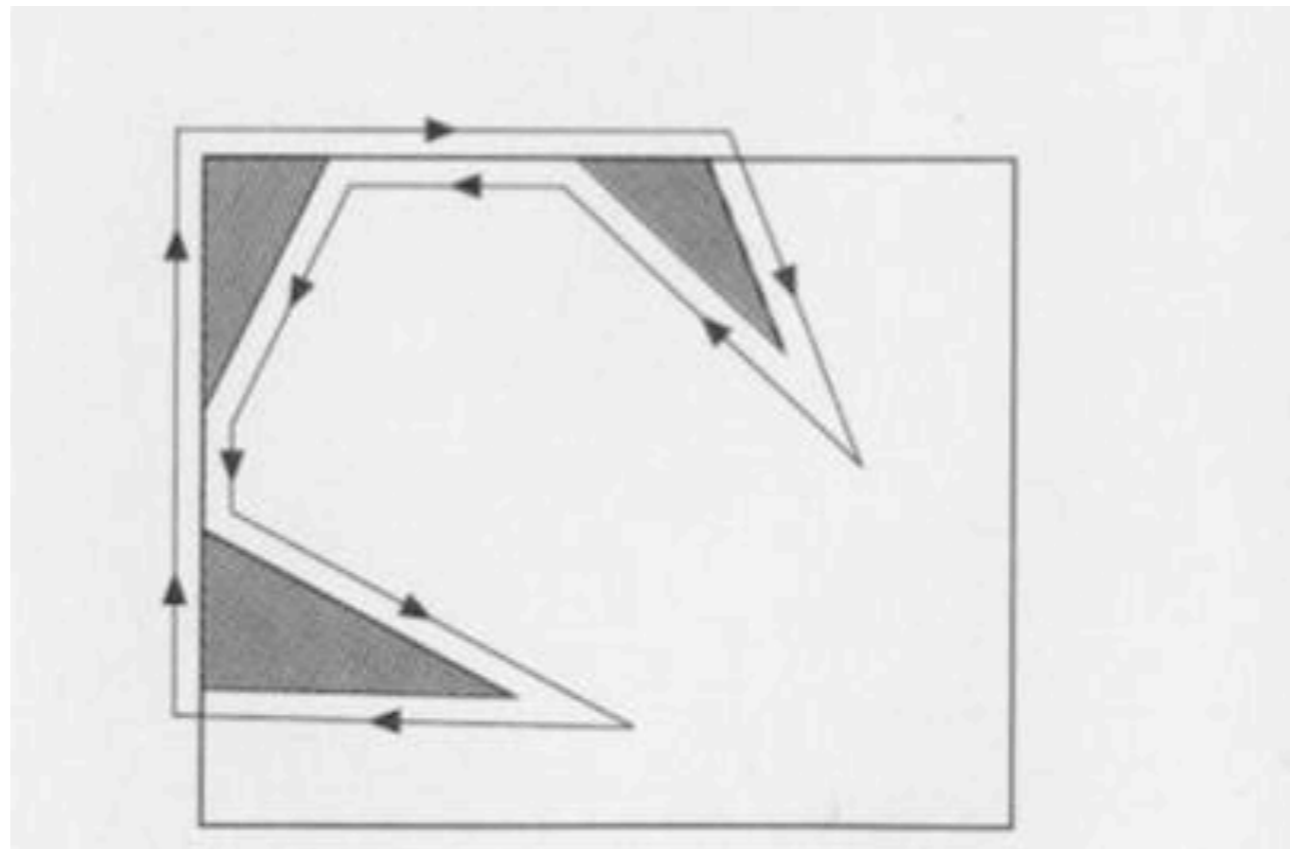
# Clipping polygons

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Clip the vertices that are outside of the window and create new vertices at window border

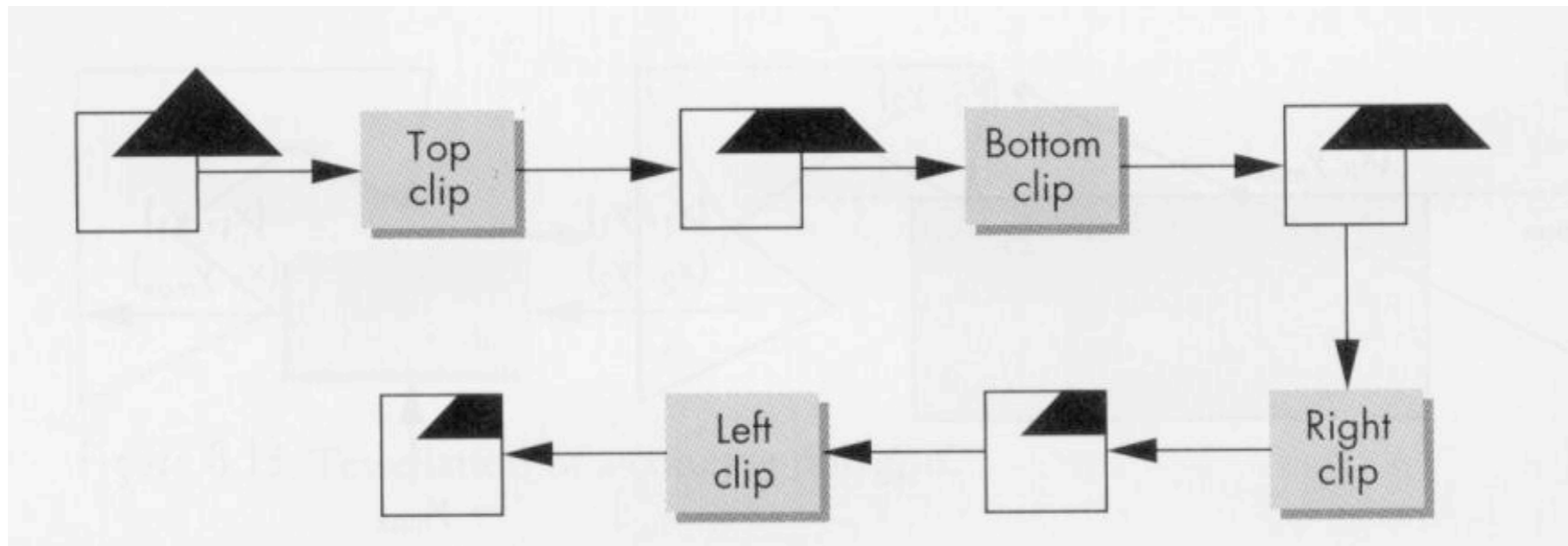


Result is still a single polygon but may have more vertices and an odd shape



# Clipping polygons

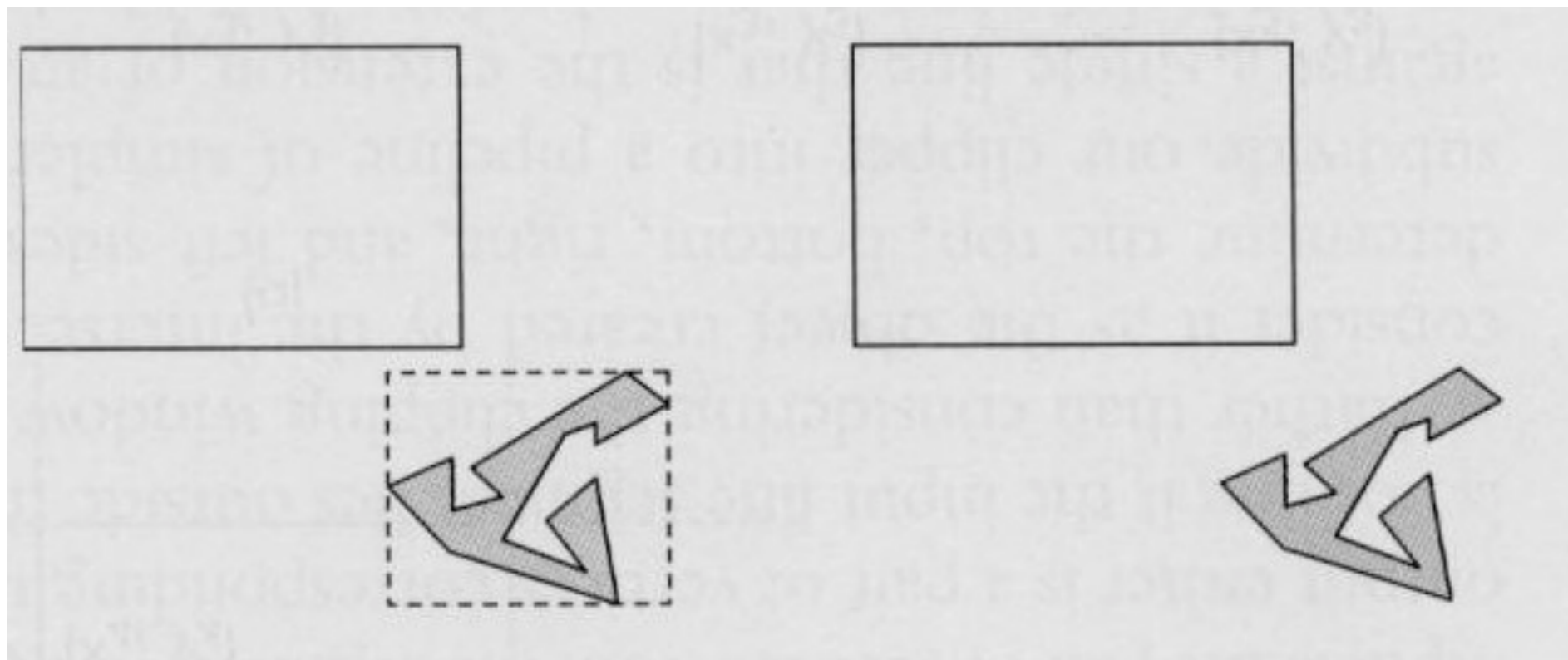
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# Clipping polygons

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**Bounding box** - surrounds each polygon



# Cohen-Sutherland Algorithm

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- Region Checks: Trivially reject or accept for clipping
- Good for large or small windows (all is in or out of window, respectively)
- Each vertex is assigned an 4-bit outcode

1001	1000	1010
0001	0000	0010
0101	0100	0110

A line can be **trivially accepted** if both endpoints have an outcode of 0000.

A line can be **trivially rejected** if any of the same two bits in the outcodes are both equal to 1 (both endpoints are left, right, above, below the window)

# Clipping 3D

Adds far and near clipping planes for 3D viewing volume

