

**Ex 2.13** G.E.

$$\begin{aligned}x + 2y + 2z &= 3 \\4x + 4y + 2z &= 6 \\4x + 6y + 4z &= 10\end{aligned}$$

$$\underbrace{\begin{pmatrix} 1 & 2 & 2 \\ 4 & 4 & 2 \\ 4 & 6 & 4 \end{pmatrix}}_A \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 3 \\ 6 \\ 10 \end{pmatrix}$$

$$M_1 A = \begin{pmatrix} 1 & 2 & 2 \\ -4 & 1 & 0 \\ -4 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 2 & 2 \\ 4 & 4 & 2 \\ 4 & 6 & 4 \end{pmatrix} = \begin{pmatrix} 1 & 2 & 2 \\ 0 & -4 & -6 \\ 0 & -2 & -4 \end{pmatrix}$$

$$M_2 M_1 A = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -\frac{1}{2} & 1 \end{pmatrix} \begin{pmatrix} 1 & 2 & 2 \\ 0 & -4 & -6 \\ 0 & -2 & -4 \end{pmatrix} = \begin{pmatrix} 1 & 2 & 2 \\ 0 & -4 & -6 \\ 0 & 0 & -1 \end{pmatrix}$$

$$A = \left[ M_1^{-1} M_2^{-1} \right] (M_2 M_1 A) = \left[ \begin{pmatrix} 1 & 2 & 2 \\ 4 & 1 & 0 \\ 4 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \end{pmatrix} \right] \begin{pmatrix} 1 & 2 & 2 \\ 0 & -4 & -6 \\ 0 & 0 & -1 \end{pmatrix}$$
$$\begin{pmatrix} 1 & 2 & 2 \\ 4 & 1 & 0 \\ 4 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 2 & 2 \\ -4 & 6 \\ 1 \end{pmatrix}$$

Lecture 20. Gaussian Elimination.

LECTURE 3

$$\underbrace{M_{n-1} \dots M_2 M_1}_{L^{-1}} A = U$$

$$A = LU$$

L "unit lower triangular"

General Formula for  $M_k$

$$M_k a = \begin{pmatrix} 1 & & & & & \\ & 1 & & & & \\ & & \ddots & & & \\ & & & 1 & & \\ & & & & \ddots & \\ & & & & & 1 \end{pmatrix} \begin{pmatrix} a_1 \\ a_2 \\ \vdots \\ a_k \\ \vdots \\ a_n \end{pmatrix} = \begin{pmatrix} a_1 \\ a_2 \\ \vdots \\ a_k \\ 0 \\ \vdots \\ 0 \end{pmatrix}$$

↑ k<sup>th</sup> column

$$m_i = \frac{a_i}{a_k}$$

$a_k$  is the "pivot"

•  $M_k$  is unit lower triangular

•  $M_k$  is of the form

$$I - \vec{m}_k \vec{e}_k^T$$

$$\vec{m}_k = \begin{pmatrix} 0 \\ \vdots \\ 0 \\ m_{k+1,k} \\ \vdots \\ m_{n,k} \end{pmatrix}$$

⊗ •  $M_k^{-1}$  is really easy to compute:

$$M_k^{-1} = I + \vec{m}_k \vec{e}_k^T \quad (\text{check})$$

⊗ • L is really easy to compute

$$L^{-1} = M_{n-1} M_{n-2} \dots M_2 M_1$$

$$L = \left( \begin{matrix} & & & \\ & & & \\ & & & \\ & & & \end{matrix} \right)^{-1}$$

$$= M_1^{-1} M_2^{-1} \dots M_{n-1}^{-1}$$

$$M_j^{-1} M_k^{-1} = (I + m_j e_j^T) (I + m_k e_k^T) = I + m_j e_j^T + m_k e_k^T + m_j e_j^T m_k e_k^T$$

but  $e_j^T m_k = 0$  when  $j < k$ .

And all terms in product  $m_j e_j^T m_k e_k^T$  will have  $j < k$   
 Therefore

$$L = M_1^{-1} M_2^{-1} \dots M_{n-1}^{-1}$$

$$L = I + m_1 e_1^T + m_2 e_2^T + \dots + m_{n-1} e_{n-1}^T$$

i.e.,  $L = \begin{bmatrix} 1 & & & & \\ m_{21} & 1 & & & \\ m_{31} & m_{32} & 1 & & \\ \vdots & \vdots & \ddots & \ddots & \\ m_{n1} & m_{n2} & \dots & m_{n-1,n} & 1 \end{bmatrix}$

Algorithm Gaussian Elimination  
LU Factorization

```

for k = 1, ..., n-1
  if akk = 0 stop
  for i = k+1 ... n
    mik = aik / akk
  end
  for j = k+1 ... n
    for i = k+1 ... n
      aij = aij - mik akj
    end
  end
end
    
```

[ for each column  
 (except last) ]

[  ]

[ compute elements of L,  
~~of~~ L<sub>k</sub> ]

[ update to find  
 elements of U ]

(upper  $k \times n$  elements  
 untouched  
 because  $M_k^{-1}$  is  
 the identity there)

In place: write  $m_{ik}$  directly into lower part of matrix.  
 replace  $m_{ik}$  with  $a_{ik}$  above

# Operation Count

$$\begin{aligned} & \sum_{k=1}^{n-1} \left[ \sum_{i=k+1}^n 1 + \sum_{j=k+1}^n \sum_{i=k+1}^n 2 \right] \\ &= \sum_{k=1}^{n-1} \left[ n-(k+1)+1 + 2 \sum_{j=k+1}^n n-(k+1)+1 \right] \\ &= \sum_{k=1}^{n-1} \left[ n-k + 2 \sum_{j=k+1}^n n-k \right] \\ &= \sum_{k=1}^{n-1} \left[ n-k + 2(n-k)(n-(k+1)+1) \right] \\ &= \sum_{k=1}^{n-1} \left[ (n-k) + 2(n-k)(n-k) \right] \\ &= \sum_{k=1}^{n-1} (n-k) [2(n-k) + 1] \end{aligned}$$

$$m = n - k$$

$$k=1 \Rightarrow m = n-1$$

$$k=n-1 \Rightarrow m = n-n+1 = 1$$

$$= \sum_{m=1}^{n-1} m [2m + 1]$$

$$= \sum_{m=1}^{n-1} (2m^2 + m)$$

$$= 2 \cdot \frac{(n-1)(n)(2n-2+1)}{6} + \frac{(n-1)n}{2}$$

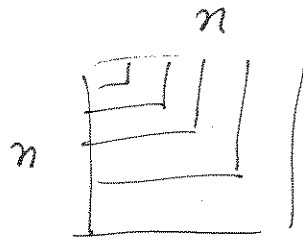
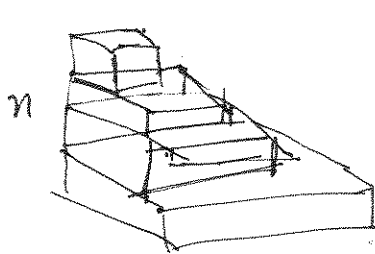
$$= \frac{n(n-1)(2n-1)}{3} + \frac{n(n-1)}{2}$$

$$\sim \frac{2}{3} n^3$$

$$S_n = \sum_{i=1}^n i^2 = \frac{n(n+1)(2n+1)}{6}$$

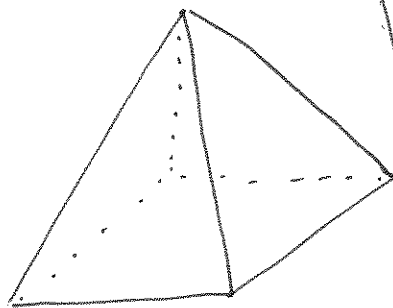
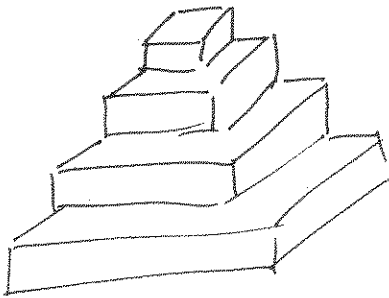
# How to estimate operation count geometrically

- dominate by operation in inner most loop  
2 flops



$$V = \frac{1}{3} b h = \frac{1}{3} n^3$$

$$\text{ops} \sim \frac{2}{3} n^3$$



pyramid with  
Volume =  $\frac{1}{3} b h$

# Instability of Gaussian Elimination (w/o pivoting)

Example

$$A = \begin{bmatrix} 0 & 1 \\ 1 & 1 \end{bmatrix}$$

full rank

$$\kappa_2 = (3 + \sqrt{5})/2 \approx 2.618$$

but G.E. fails right away!

$$A = \begin{bmatrix} 10^{-20} & 1 \\ 1 & 1 \end{bmatrix}$$

factors

$$L = \begin{bmatrix} 1 & 0 \\ 10^{20} & 1 \end{bmatrix}, \quad U = \begin{bmatrix} 10^{-20} & 1 \\ 0 & 1 - 10^{+20} \end{bmatrix}$$

assume  
after  
rounding

$$\tilde{L} = \begin{bmatrix} 1 & 0 \\ 10^{20} & 1 \end{bmatrix}, \quad \tilde{U} = \begin{bmatrix} 10^{-20} & 1 \\ 0 & -10^{20} \end{bmatrix}$$

$$\tilde{A} = \tilde{L}\tilde{U} = \begin{bmatrix} 10^{-20} & 1 \\ 1 & 0 \end{bmatrix} \quad \underline{\text{not}} \text{ close to } A!$$

$$\begin{array}{l} \text{e.g. } Ax = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \Rightarrow x \approx \begin{pmatrix} -1 \\ 1 \end{pmatrix} \\ \tilde{A}\tilde{x} = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \Rightarrow \tilde{x} = \begin{pmatrix} 0 \\ 1 \end{pmatrix} \end{array} \quad \left. \vphantom{\begin{array}{l} \text{e.g. } Ax = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \Rightarrow x \approx \begin{pmatrix} -1 \\ 1 \end{pmatrix} \\ \tilde{A}\tilde{x} = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \Rightarrow \tilde{x} = \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right\} \text{large error} \\ \text{in solve.}$$

Gaussian Elimination (as presented so far)

is not stable!

Add pivoting to stabilize.

$$\begin{pmatrix} 1 & 2 & 2 \\ 4 & 4 & 2 \\ 4 & 6 & 4 \end{pmatrix}$$

$$\begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 2 & 2 \\ 4 & 4 & 2 \\ 4 & 6 & 4 \end{pmatrix}$$

$P_1$

$A$

$$\begin{pmatrix} 1 & & \\ -\frac{1}{4} & 1 & \\ -1 & 0 & 1 \end{pmatrix} \begin{pmatrix} 4 & 4 & 2 \\ 1 & 2 & 2 \\ 4 & 6 & 4 \end{pmatrix} = \begin{pmatrix} 4 & 4 & 2 \\ 0 & 1 & \frac{3}{2} \\ 0 & 2 & 2 \end{pmatrix}$$

$M_1$

$P_1 A$

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} 4 & 4 & 2 \\ 0 & 1 & \frac{3}{2} \\ 0 & 2 & 2 \end{pmatrix}$$

$P_2$

$||$

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -\frac{1}{2} & 1 \end{pmatrix} \begin{pmatrix} 4 & 4 & 2 \\ 0 & 2 & 2 \\ 0 & 1 & \frac{3}{2} \end{pmatrix}$$

$M_2$

$$= \begin{pmatrix} 4 & 4 & 2 \\ 0 & 2 & 2 \\ 0 & 0 & \frac{5}{4} \end{pmatrix}$$

$U$

$$M_2 P_2 M_1 P_1 A$$

$$= U$$