

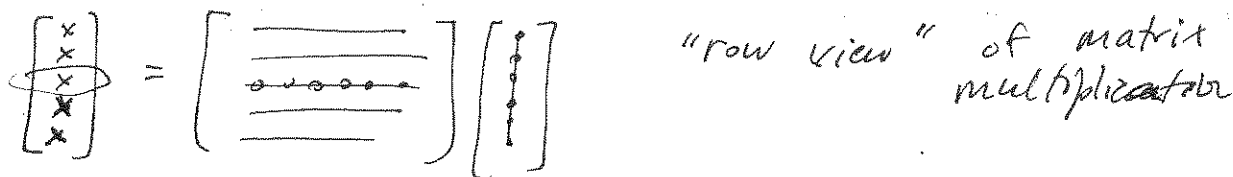
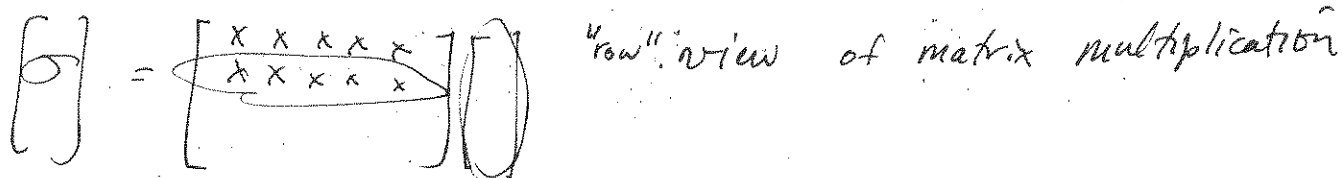
① Intro (T&B, Lecture 1)

Lecture 2

matrix A vector x vector b Ax mat-ve
 entries a_{ij} x_i b_i of x s-v

② A linear map $b = Ax$ ~~map~~

③ Matrix-Vector Multiplication ~~$b_i = \sum_{j=1}^n a_{ij} x_j$~~

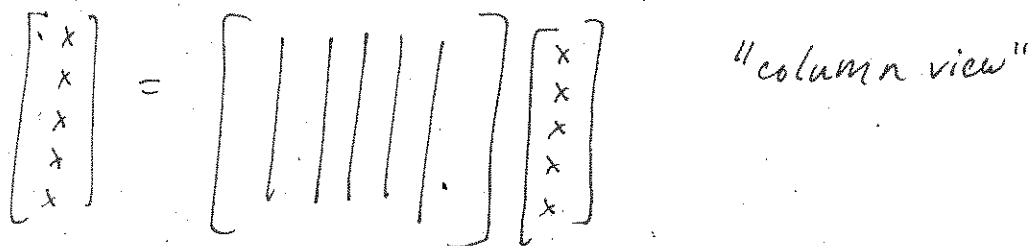


$$b = Ax$$

$$b_i = \sum_{k=1}^n a_{ik} x_k$$

"row view"

④



$$\begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{bmatrix} = \begin{bmatrix} | & | & \dots & | \\ \vec{a}_1 & \vec{a}_2 & \dots & \vec{a}_n \\ | & | & \dots & | \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}$$

$$\vec{b} = \sum_{j=1}^n x_j \vec{a}_j = x_1 \vec{a}_1 + x_2 \vec{a}_2 + \dots + x_n \vec{a}_n$$

\vec{b} is linear combination of \vec{a}_j

Ex. Vandermonde Matrix

Matrix - Matrix

~~B=AC~~ B=AC

b_{ij} = ∑_{k=1}ⁿ a_{ik} c_{kj}

~~b_j~~ = ∑_{k=1}ⁿ ~~a_k~~ c_{kj}

Ex. Outer product

$\begin{bmatrix} | \\ \vec{u} \\ | \end{bmatrix} \begin{matrix} \vec{v} \\ \vec{v}^T \end{matrix} [v_1 \ v_2 \ \dots \ v_n] = \begin{bmatrix} | & | & & | \\ v_1 \vec{u} & v_2 \vec{u} & \dots & v_n \vec{u} \\ | & | & & | \end{bmatrix}$
 $= \begin{bmatrix} v_1 u_1 & v_2 u_1 & & v_n u_1 \\ v_1 u_2 & v_2 u_2 & & v_n u_2 \\ \vdots & \vdots & \dots & \vdots \\ v_1 u_n & v_2 u_n & & v_n u_n \end{bmatrix}$

Ex. upper triangular, U

B = AU = $\begin{bmatrix} a_{11} & \dots & a_{1n} \\ & & 1 \end{bmatrix} \begin{bmatrix} | \\ \vdots \\ | \end{bmatrix}$

~~b_{ij}~~ b_j = ∑_{k=1}^j a_{jk}

Range & Nullspace

range : set of vectors that can be expressed as

"column
space"

$$Ax$$

i.e. space ~~is~~ spanned by columns of A .

nullspace

vectors x ~~is~~ s.t.

$$Ax = \vec{0}$$

rank :

dim (col space)

inverse

$$A^{-1}A = AA^{-1} = I.$$

2.1. Linear systems

linear transformation $\mathbb{R}^n \rightarrow \mathbb{R}^n$, $y, x \in \mathbb{R}^n$

$$f(x) = Ax$$

$$f(\alpha x) = \alpha f(x)$$

$$f(x+y) = f(x) + f(y)$$

$$f(x) = Ax = y$$

2.2. Existence & Uniqueness A is $n \times n$ matrix

A nonsingular if any one of:

(1) has an inverse A^{-1}

$$AA^{-1} = A^{-1}A = I$$

(2) $\det(A) \neq 0$

(3) $\text{rank}(A) = n$

(4) if $z \neq 0$, $Az \neq 0$. (no nullspace)

A nonsingular $\Rightarrow Ax = b$ has unique solution for any b .

$$\begin{pmatrix} 2 & 3 \\ 5 & 4 \end{pmatrix}$$

A singular \Rightarrow # of solutions depends on b .

(*) $\begin{pmatrix} 2 & 3 \\ 4 & 6 \end{pmatrix}$

- $b \in \text{span}(A)$ infinitely many solutions
- $b \notin \text{span}(A)$ no solutions

Ex. 2.2

(1)

$$\begin{pmatrix} 2 & 3 \\ 4 & 6 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 4 \\ 8 \end{pmatrix}$$

$$2x + 3y = 4 \Rightarrow y = \frac{4-2x}{3}$$

$$4x + 6\left(\frac{4-2x}{3}\right) = 4x - \frac{12x}{3} + \frac{24}{3} = 8 = 8 \checkmark$$

(1) $\begin{pmatrix} 2 & 3 \\ 4 & 6 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 4 \\ 8 \end{pmatrix}$, unique sol'n

$$\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 8 \\ \frac{4-2 \cdot 8}{3} \end{pmatrix}$$

(3) $\begin{pmatrix} 2 & 3 \\ 4 & 6 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 4 \\ 6 \end{pmatrix}$

no sol'n

§ 2.3 Sensitivity & Conditioning

$$Ax = b$$

if we perturb the data (A & b), what happens to the solution x ?

To measure, "size" of vectors & matrices.

Vector Norms

1-norm

$$\|x\|_1 = \sum_{i=1}^n |x_i|$$

2-norm

$$\|x\|_2 = \left[\sum_{i=1}^n |x_i|^2 \right]^{1/2}$$

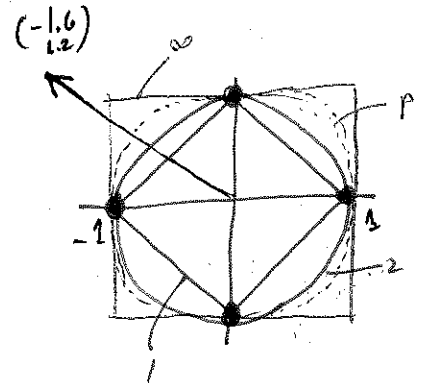
p-norm

$$\|x\|_p = \left[\sum_{i=1}^n |x_i|^p \right]^{1/p}$$

∞ -norm

$$\|x\|_\infty = \max_{1 \leq i \leq n} |x_i|$$

unit sphere



Norm properties

1. $\|x\| > 0$ if $x \neq 0$
2. $\|\alpha x\| = |\alpha| \|x\|$
3. $\|x+y\| \leq \|x\| + \|y\|$

similar qualitative results. Different norms convenient.

• see different unit "spheres"

- the norm of a vector is the factor by which the corresponding sphere must be expanded or shrunk to encompass the vector

Ex. 1

$$\vec{x} = \begin{pmatrix} -1.6 \\ 1.2 \end{pmatrix} \quad \|x\|_1 = 2.8, \quad \|x\|_2 = 2.0, \quad \|x\|_\infty = 1.6$$

For any x , $\|x\|_1 \geq \|x\|_2 \geq \|x\|_\infty$

Also $\|x\|_1 \leq \sqrt{n} \|x\|_2$, $\|x\|_2 \leq \sqrt{n} \|x\|_\infty$, $\|x\|_1 \leq n \|x\|_\infty$

§ 2.3.2 Matrix Norms

induced matrix norm:

$$\|A\| = \max_{x \neq 0} \frac{\|Ax\|}{\|x\|}$$

$$\|A\|_1 = \max_j \sum_{i=1}^n |a_{ij}| \quad [\text{max column sum}]$$

$$\|A\|_\infty = \max_i \sum_{j=1}^n |a_{ij}| \quad [\text{max row sum}]$$

(agree w/ corresponding vector norms for $n \times 1$ matrix)

Example

$$A = \begin{bmatrix} 2 & -1 & -1 \\ 1 & 0 & 1 \\ 3 & -1 & 4 \end{bmatrix} \Rightarrow \|A\|_1 = 6, \|A\|_\infty = 8$$

Matrix norm properties

Δ
norm

1. $\|A\| > 0$ if $A \neq 0$
2. $\|\alpha A\| = |\alpha| \|A\|$
3. $\|A+B\| \leq \|A\| + \|B\|$

For
p-norms

4. $\|AB\| \leq \|A\| \|B\|$
 5. $\|Ax\| \leq \|A\| \|x\|$
- ← "submultiplicative"