

Matlab 'eig'

$$Av = \lambda Bv$$

QZ or generalized Schur decomposition

- ignores symmetry of  $A$  or  $B$

Cholesky - symm  $A$  + spd  $B$

Algorithm: Rayleigh Quotient Iteration

$x_0 =$  arbitrary non-zero vector

for  $k=1, 2, \dots$

$$\sigma_k = x_{k-1}^T A x_{k-1} / x_{k-1}^T x_{k-1}$$

$$\text{Solve } (A - \sigma_k I) y_k = x_{k-1}$$

$$x_k = y_k / \|y_k\|_\infty$$

end

[compute shift]

[next vector]

[normalize]

- quadratic convergence rate (for non-defective eigenval)

- cubic for normal matrices (including symm)

$$AA^T = A^T A$$

- but must refactor the matrix each iteration - high cost

#### 4.5.4 Deflation

- Assume found  $(\lambda_1, \vec{x}_1)$  s.t.  $A\vec{x}_1 = \lambda_1 \vec{x}_1$

- Find  $H$  (e.g., Householder) s.t.  $H\vec{x}_1 = \alpha \vec{e}_1$

$$\text{Then } \frac{1}{\alpha} \vec{x}_1 = H^{-1} \vec{e}_1$$

$$HAH^{-1} \vec{e}_1 = HA \left( \frac{1}{\alpha} \vec{x}_1 \right) = \frac{1}{\alpha} HA \vec{x}_1 = \frac{\lambda_1}{\alpha} H \vec{x}_1 = \lambda_1 \vec{e}_1$$

i.e. first column of  $HAH^{-1}$  is  $\lambda_1 \vec{e}_1$

$$H A H^{-1} = \begin{pmatrix} \lambda_1 & \vec{b}^T \\ 0 & B \\ \vdots & \\ 0 & \end{pmatrix}$$

B has eigenvalues  $\lambda_2, \dots, \lambda_n$

- Next, assume

$$B \vec{y}_2 = \lambda_2 \vec{y}_2$$

- Then

$$A \begin{pmatrix} \gamma \\ \vec{y}_2 \end{pmatrix} = \begin{pmatrix} \lambda_1 & \vec{b}^T \\ 0 & B \end{pmatrix} \begin{pmatrix} \gamma \\ \vec{y}_2 \end{pmatrix} = \begin{pmatrix} \lambda_1 \gamma + \vec{b}^T \vec{y}_2 \\ B \vec{y}_2 \end{pmatrix} = \begin{pmatrix} \lambda_1 \gamma + \vec{b}^T \vec{y}_2 \\ \lambda_2 \vec{y}_2 \end{pmatrix}$$

- choose  $\gamma$  s.t.

$$\lambda_1 \gamma + \vec{b}^T \vec{y}_2 = \lambda_2 \gamma$$

$$\Rightarrow \gamma = \frac{\vec{b}^T \vec{y}_2}{(\lambda_2 - \lambda_1)}$$

- Then  $A \begin{pmatrix} \gamma \\ \vec{y}_2 \end{pmatrix} = \lambda_2 \begin{pmatrix} \gamma \\ \vec{y}_2 \end{pmatrix}$

Another approach to deflation (next page) ...

- this general approach (deflation) may lose accuracy

- explicit deflation not recommended if want many  $(\lambda, \vec{v})$  pairs

- can enhance accuracy by using inverse iteration with estimated eigenvalue to refine.

## Alternative approach to deflation

$$A\vec{x}_1 = \lambda_1 \vec{x}_1$$

Let  $\vec{u}_1$  be any vector s.t.

$$\vec{u}_1^T \vec{x}_1 = \lambda_1$$

Then matrix

$$(A - \lambda_1 \vec{u}_1 \vec{u}_1^T)$$

has eigenvalues  $0, \lambda_2, \dots, \lambda_n$

$k=1$

$$(A - \lambda_1 \vec{u}_1 \vec{u}_1^T) \vec{x}_1 = A\vec{x}_1 - \lambda_1 \vec{u}_1 \vec{u}_1^T \vec{x}_1 = \lambda_1 \vec{x}_1 - \lambda_1 \vec{x}_1 = 0$$

$k=2, \dots, n$

$$\begin{aligned} (A - \lambda_1 \vec{u}_1 \vec{u}_1^T) \vec{x}_k &= A\vec{x}_k - \lambda_1 \vec{u}_1 \vec{u}_1^T \vec{x}_k = \lambda_k \vec{x}_k - (\vec{u}_1^T \vec{x}_k) \vec{x}_1 \\ &= \lambda_k \left( \vec{x}_k - \frac{(\vec{u}_1^T \vec{x}_k)}{\lambda_k} \vec{x}_1 \right) \end{aligned}$$

So  $\left( \vec{x}_k - \frac{(\vec{u}_1^T \vec{x}_k)}{\lambda_k} \vec{x}_1 \right)$  is an ~~eigenvector~~ eigenvector for eigenvalue  $\lambda_k$ .

(check:

$$(A - \lambda_1 \vec{u}_1 \vec{u}_1^T) \left( \vec{x}_k - \frac{(\vec{u}_1^T \vec{x}_k)}{\lambda_k} \vec{x}_1 \right)$$

$$= (A - \lambda_1 \vec{u}_1 \vec{u}_1^T) \vec{x}_k - \frac{(\vec{u}_1^T \vec{x}_k)}{\lambda_k} (A - \lambda_1 \vec{u}_1 \vec{u}_1^T) \vec{x}_1$$

$$= \lambda_k \left( \vec{x}_k - \frac{(\vec{u}_1^T \vec{x}_k)}{\lambda_k} \vec{x}_1 \right) \quad \checkmark$$

- Choices of  $\vec{u}_1$ :
- $\vec{u}_1 = \vec{x}_1$ , if  $A$  symm. and  $\|\vec{x}_1\|_2 = 1$
  - $\vec{u}_1 = \lambda_1 \vec{y}_1$ , where  $A^T \vec{y}_1 = \lambda_1 \vec{y}_1$  +  $\vec{y}_1^T \vec{x}_1 = 1$
  - $\vec{u}_1 = A^T \vec{e}_k$ , if  $\|\vec{x}_1\|_0 = 1$  +  $k^{\text{th}}$  component of  $(\vec{x}_1)_k = 1$

## Section 4.2.5 : Localizing Eigenvalues

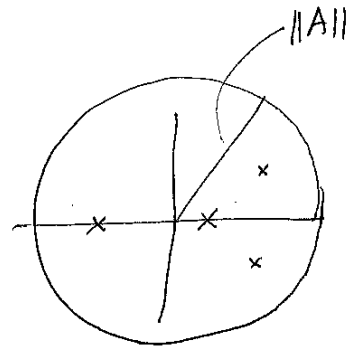
- [1] - can get some crude information about eigenvalues locations

Know  $\|\lambda x\| = \|Ax\|$

for vector-induced norm,

$$\Rightarrow |\lambda| \|x\| \leq \|A\| \|x\|$$

$$\Rightarrow |\lambda| \leq \|A\|$$



- [2] Gershgorin's Theorem : A  $n \times n$  matrix eigenvalues lie in union of  $n$  discs,  $k^{\text{th}}$  disc centered at  $a_{kk}$  and radius  $\sum_{j \neq k} |a_{kj}|$

Let  $A\vec{x} = \lambda\vec{x}$ , with  $\|\vec{x}\|_{\infty} = 1$   
and  $|x_k| = 1$  ( $k^{\text{th}}$  component of  $\vec{x}$ )

$$A\vec{x} = \lambda\vec{x}$$

$k^{\text{th}}$  row:  $\sum_{j=1}^n a_{kj} x_j = \lambda x_k \Rightarrow (\lambda - a_{kk}) x_k = \sum_{j \neq k} a_{kj} x_j$

taking absolute values

$$|\lambda - a_{kk}| |x_k| \leq \sum_{j \neq k} |a_{kj}| |x_j|$$

$$\Rightarrow |\lambda - a_{kk}| \leq \sum_{j \neq k} |a_{kj}|$$

$$A_2 = \begin{pmatrix} 4 & \frac{1}{2} & 0 \\ \frac{3}{5} & 5 & \frac{3}{5} \\ 0 & \frac{1}{2} & 3 \end{pmatrix}$$

eigenvalues •

Example

$$A_1 = \begin{pmatrix} 4 & -\frac{1}{2} & 0 \\ \frac{3}{5} & 5 & -\frac{3}{5} \\ 0 & \frac{1}{2} & 3 \end{pmatrix}$$

eigenvalues x

