

True/False

For each question, indicate whether the statement is true or false by circling T or F, respectively.

- ① (T/F) A system of nonlinear equations has either no solutions, exactly one solution, or infinitely many solutions.
- ② (T/F) The convergence rate of Newton's Method for solving $f(x) = 0$ depends on f .
- ③ (T/F) If the errors in successive iterations of an algorithm are $10^{-2}, 10^{-1}, 10^{-6}, 10^{-8}, \dots$, then the algorithm is exhibiting quadratic convergence.

For questions 4-5, consider fixed point iteration for finding a point x^* such that $g(x^*) = x^*$.

- ④ (T/F) The iteration is locally convergent if $|g'(x^*)| < 1$.
5. (T/F) Newton's Method for solving $f(x) = 0$ is an example of fixed point iteration, with $g(x) = -f(x)/f'(x)$.

Multiple Choice

Instructions: For the multiple choice problems, circle exactly one of (a) - (e).

6. Which of the following statements about Newton's method for finding a root of a nonlinear equation are true?

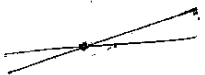
- ~~F~~ (a) The cost per iteration of the Secant method is greater than that of Newton's method.
- ~~F~~ (b) Newton's method exhibits quadratic convergence for any initial guess x_0 .
- ~~T~~ (c) Newton's method is an example of a fixed point iteration scheme.
- ~~F~~ (d) When Newton's method converges, then it converges with a quadratic convergence rate.
- (e) None of the above.

7. Which of the following statements are true?

- ~~F~~ I. Finding the root of a function which is nearly "flat" around the root is a well-conditioned problem.
- ~~T~~ II. The bisection method has linear convergence with constant $1/2$.
- ~~F~~ III. If the errors in successive iterations of an algorithm are $10^{-2}, 10^{-4}, 10^{-6}, \dots$, then the algorithm is exhibiting quadratic convergence.

- (a) I only
- (b) II only
- (c) III only
- (d) II and III only
- (e) None

$f(x) = 0$



re root finding

8. Which of the following statements are true?

~~F~~ I. An eigenvector corresponding to a given eigenvalue is unique.

~~T~~ II. Scaling a matrix by a ~~constant~~ *scalar* c will scale its eigenvalues by that ~~constant~~.

~~T~~ III. If a matrix has an eigenvalue of 0, then it is not invertible.

identity

$$Ax = \lambda x$$

scalar

$$(cA)x = (c\lambda)x$$

(a) I only

(b) II only

(c) III only

(d) I and III only

(e) I, II and III

Written Response

21. Nonlinear Equations: Newton's Method. Consider the system of equations

$$\begin{aligned}x^2 - y^2 &= 0 \\ 2xy &= 1\end{aligned}$$

Carry out one iteration of Newton's Method for finding a solution to this system, with starting value $\vec{x}_0 = (0, 1)^T$.

$$\begin{aligned}f_1(x, y) &= x^2 - y^2 = 0 \\ f_2(x, y) &= 2xy - 1 = 0\end{aligned}$$

$$\Rightarrow \begin{aligned}\frac{\partial f_1}{\partial x} &= 2x \\ \frac{\partial f_1}{\partial y} &= -2y\end{aligned}$$

Newton's method

$$\vec{x}_{k+1} = \vec{x}_k + \vec{s}_k$$

~~$$J_f(\vec{x}_k) \vec{s}_k = -f(\vec{x}_k)$$~~

$$\frac{\partial f_2}{\partial x} = 2y$$

$$\frac{\partial f_2}{\partial y} = 2x$$

$$J_f(\vec{x}_k) \vec{s}_k = -f(\vec{x}_k)$$

$$J_f(x, y) = \begin{pmatrix} \frac{\partial f_1}{\partial x_1} & \frac{\partial f_1}{\partial x_2} \\ \frac{\partial f_2}{\partial x_1} & \frac{\partial f_2}{\partial x_2} \end{pmatrix} \Big|_{(x, y)} = \begin{pmatrix} 2x & -2y \\ 2y & 2x \end{pmatrix}$$

$$\vec{x}_0 = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$J_f(\vec{x}_0) = \begin{pmatrix} 0 & -2 \\ 2 & 0 \end{pmatrix}$$

$$\begin{pmatrix} 0 & -2 \\ 2 & 0 \end{pmatrix} \begin{pmatrix} s_1 \\ s_2 \end{pmatrix} = -f\left(\begin{pmatrix} 0 \\ 1 \end{pmatrix}\right) = -\begin{pmatrix} -1 \\ -1 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$\Rightarrow \begin{aligned}-2s_2 &= 1 \\ 2s_1 &= 1\end{aligned} \Rightarrow s_1 = \frac{1}{2}, s_2 = -\frac{1}{2}$$

22. Optimization. Consider the function

$$\phi(x) = \frac{1}{2}x^T Ax - b^T x + c,$$

where $A \in \mathbb{R}^{n \times n}$ is symmetric.

(a) What are the critical points of ϕ ?

(b) How would you classify the critical points of ϕ as maxima, minima or saddle points?

(a) points x , where $\vec{\nabla} \phi(x) = \vec{0}$

$$\nabla \phi(x) = \frac{1}{2} (A + A^T)x - \vec{b}$$

$$= Ax - b, \text{ since } A \text{ is symmetric}$$

$$\text{Setting } \nabla \phi(x) = 0 \Rightarrow$$

$$Ax - b = 0$$

$$\Rightarrow Ax = b$$

\therefore critical pts. of ϕ are those x satisfying

$$Ax = b.$$

(b) by properties of A

if all $\lambda(A) > 0 \Rightarrow$ minimum

all $\lambda(A) < 0 \Rightarrow$ max.

some $\lambda(A) < 0$ and some $\lambda(A) > 0$
saddle

some $\lambda(A) = 0$

21. (cont).

~~Ex~~

$$\begin{pmatrix} x \\ y \end{pmatrix}_{1} = \begin{pmatrix} x \\ y \end{pmatrix}_0 + \begin{pmatrix} s_1 \\ s_2 \end{pmatrix}_0$$

$$= \begin{pmatrix} x \\ y \end{pmatrix}_0 + \begin{pmatrix} \frac{1}{2} \\ -\frac{1}{2} \end{pmatrix}$$

$$\vec{x}_1 = \begin{pmatrix} 0 \\ 1 \end{pmatrix} + \begin{pmatrix} \frac{1}{2} \\ -\frac{1}{2} \end{pmatrix} = \begin{pmatrix} \frac{1}{2} \\ \frac{1}{2} \end{pmatrix}$$

General quadratic is

$$f(\vec{x}) = \frac{1}{2} \vec{x}^T A \vec{x} - \vec{b}^T \vec{x} + c$$

$$\nabla f(\vec{x}) = \frac{1}{2} (A^T + A) \vec{x} - \vec{b}$$

assume A is symmetric, then

$$\nabla f(\vec{x}) = A \vec{x} - \vec{b}$$

$$H_f(\vec{x}) = A$$

Critical points, x^* such that

$$\nabla f(\vec{x}^*) = 0 \iff A \vec{x}^* = \vec{b}$$

classify critical points by $H_f(x^*) = A$

- A positive definite \Rightarrow minimum at x^*
- A negative definite \Rightarrow maximum at x^*
- A has both positive & negative λ , but is invertible (no $\lambda = 0$) \Rightarrow saddle at x^*
- A has one or more zero eigenvalues

A is singular

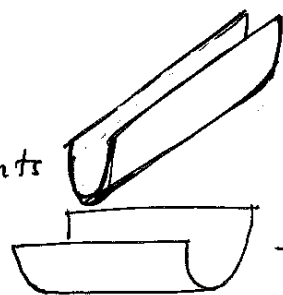
$$Ax = b$$

solutions none or

infinite

\rightarrow no critical points

\rightarrow infinitely many



e.g.
 $f(x,y) = x^2 + y^2$

e.g.
 $f(x,y) = x^2$