

Least Squares Solution by QR

Recall 2-norm invariant under orthogonal transformations:

$$\|Qx\|_2^2 = x^T Q^T Q x = x^T x = \|x\|_2^2$$

makes sense: rotating or reflecting a vector doesn't change its length

CASE I : A has independent columns

$$\begin{matrix} A \\ m \times n \end{matrix} = \begin{matrix} Q \\ m \times m \end{matrix} \begin{matrix} R \\ m \times n \end{matrix}$$

$$\begin{matrix} m \\ \left(A \right) \\ n \end{matrix} = \begin{matrix} \left(\begin{matrix} \hat{Q} & | & \tilde{Q} \\ \hline \end{matrix} \right) \\ \begin{matrix} n & & m-n \end{matrix} \end{matrix} \begin{matrix} \left(\begin{matrix} \hat{R} \\ 0 \\ \hline \end{matrix} \right) \\ \begin{matrix} n \\ m-n \end{matrix} \end{matrix}$$

$$A = \hat{Q} \hat{R} + \tilde{Q} 0$$

$$\|r\|_2^2 = \|b - Ax\|_2^2$$

$$= \|b - \hat{Q}\hat{R}x\|_2^2$$

$$= \|Q^T b - Q^T \hat{Q}\hat{R}x\|_2^2$$

$$= \left\| \begin{pmatrix} \hat{Q}^T b \\ \tilde{Q}^T b \end{pmatrix} - \begin{pmatrix} \hat{R}x \\ 0 \end{pmatrix} \right\|_2^2$$

$$= \|\hat{Q}^T b - \hat{R}x\|_2^2 + \|\tilde{Q}^T b\|_2^2$$

Choose $\hat{R}x = \hat{Q}^T b$

$$x = (\hat{R})^{-1} \hat{Q}^T b$$

Solve by
back substit.

$$\|r\|_2^2 = \|\tilde{Q}^T b\|_2^2$$

CASE II.

$$\text{rank}(A) = r$$

$$AP = Q \begin{pmatrix} \hat{R} & S \\ 0 & 0 \end{pmatrix} \quad \begin{matrix} \hat{R} \\ r \times r \end{matrix} \text{ nonsingular}$$
$$= (\hat{Q} | \tilde{Q}) \begin{pmatrix} \hat{R} & S \\ 0 & 0 \end{pmatrix}$$

$$\|b - Ax\|_2^2$$

$$= \|b - APP^T x\|_2^2$$

$$= \|b - APy\|_2^2$$

$$= \|b - Q \begin{pmatrix} \hat{R} & S \\ 0 & 0 \end{pmatrix} y\|_2^2 = \|Q^T b - \begin{pmatrix} \hat{R} & S \\ 0 & 0 \end{pmatrix} y\|_2^2$$

$$= \left\| \begin{pmatrix} \hat{Q}^T b \\ \tilde{Q}^T b \end{pmatrix} - \begin{pmatrix} \hat{R} y_1 + S y_2 \\ 0 \end{pmatrix} \right\|_2^2$$

$$= \|\hat{Q}^T b - (\hat{R} y_1 + S y_2)\|_2^2 + \|\tilde{Q}^T b\|_2^2$$

$$\hat{R} y_1 + S y_2 = \hat{Q}^T b$$

Solution is not unique. One solution:

$$y_1 = \hat{R}^{-1} \hat{Q}^T b \quad (\text{by back subst.})$$

$$y_2 = 0$$

Least Squares with a Penalty Term

(Strang II.2)

regularized

least squares

A has dependent columns
($Ax=0$ has non-trivial solution)

then $A^T A$ is not invertible

Tikhonov regularization (ridge regression)

$$\min \|Ax - b\|_2^2 + \delta^2 \|x\|_2^2$$

Normal equations

$$\begin{pmatrix} Ax \\ \delta x \end{pmatrix} \approx \begin{pmatrix} b \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} A^T & \delta I \end{pmatrix} \begin{pmatrix} A \\ \delta I \end{pmatrix} x = \begin{pmatrix} A^T & \delta I \end{pmatrix} \begin{pmatrix} b \\ 0 \end{pmatrix}$$

$$\Rightarrow \underbrace{(A^T A + \delta^2 I)}_{\text{invertible}} x = A^T b$$

check:

$$\begin{aligned} A^T A + \delta^2 I &= V \Sigma^T U^T U \Sigma V^T + \delta^2 I \\ &= V \Sigma^T \Sigma V^T + \delta^2 V V^T \\ &= V (\Sigma^T \Sigma + \delta^2 I) V^T \end{aligned}$$

Aside:

Section III.4

$$\min \frac{1}{2} \|Ax - b\| + \lambda \|x\|_1,$$

instead of \hat{x} with min. norm,

the l^1 norm leads to a sparse \hat{x}

First, look at scalar case

$$\textcircled{1} \quad (A^T A + \delta^2 I) x = A^T b$$

Scalar

$$(\sigma^2 + \delta^2) x = \sigma b$$

$$x = \frac{\sigma}{\sigma^2 + \delta^2} b$$

if $\sigma \neq 0$, then $\frac{\sigma}{\sigma^2 + \delta^2} \rightarrow \frac{1}{\sigma}$ as $\delta \rightarrow 0$

if $\sigma = 0$, then $\frac{\sigma}{\sigma^2 + \delta^2} = 0$ for any $\delta > 0$

diagonal consider $A = \Sigma$, then

$$\textcircled{1} \Rightarrow (\Sigma^T \Sigma + \delta^2 I)^{-1} \Sigma^T$$

is diagonal with entries $(\sigma_i^2 + \delta^2)^{-1} \sigma_i$
Same argument as before...

any A

$$\begin{aligned} \textcircled{1} \quad & (V \Sigma^T U^T U \Sigma V^T + \delta^2 I)^{-1} V \Sigma^T U^T \\ &= V (\Sigma^T \Sigma + \delta^2 I)^{-1} \cancel{V^T} V \Sigma^T U^T \\ &= V (\Sigma^T \Sigma + \delta^2 I)^{-1} \Sigma^T U^T \\ &\rightarrow A^+ \text{ as } \delta \rightarrow 0 \end{aligned}$$

Example

$$\begin{pmatrix} 2 & 0 \\ 0 & 2^{-100} \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix} \Rightarrow \begin{aligned} x &= \frac{1}{2} \\ y &= 2^{100} \end{aligned}$$

regularized

$$\min \left\| \begin{pmatrix} 2 & 0 \\ 0 & 2^{-100} \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} - \begin{pmatrix} 1 \\ 1 \end{pmatrix} \right\|_2^2 + \delta^2 \left\| \begin{pmatrix} x \\ y \end{pmatrix} \right\|_2^2$$

$$(A^T A + \delta^2 I) x = A^T b$$

$$\Rightarrow \begin{pmatrix} 2 & 0 \\ 0 & 2^{-100} \end{pmatrix}^T \begin{pmatrix} 2 & 0 \\ 0 & 2^{-100} \end{pmatrix} + \begin{pmatrix} \delta^2 & 0 \\ 0 & \delta^2 \end{pmatrix} = \begin{pmatrix} 2 & 0 \\ 0 & 2^{-100} \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$\Rightarrow \left(\begin{pmatrix} 4 & 0 \\ 0 & 2^{-200} \end{pmatrix} + \begin{pmatrix} \delta^2 & 0 \\ 0 & \delta^2 \end{pmatrix} \right) \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 2 \\ 2^{-100} \end{pmatrix}$$

$$\begin{pmatrix} 4 + \delta^2 & 0 \\ 0 & 2^{-200} + \delta^2 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 2 \\ 2^{-100} \end{pmatrix}$$

$$\Rightarrow (4 + \delta^2) x = 2$$

$$(2^{-200} + \delta^2) y = 2^{-100}$$

$$\Rightarrow x = \frac{2}{4 + \delta^2}, \quad y = \frac{2^{-100}}{2^{-200} + \delta^2}$$

without regularization y is huge
w/ regularization y is tiny

Tikhonov regularization

- + effective for dealing with null spaces and numerical issues
- + can improve conditioning
- \hat{x} will not satisfy $A\hat{x} = b$
- $(A^T A + \delta^2 I)$ may be poorly conditioned, increasing δ^2 improves conditioning but makes $Ax = b$ less accurate.

Weighted Least Squares

minimizing $\|b - Ax\|_2^2$

means giving equal weight to all the equations

But if we know something more about the data, we can assign greatest weight to most reliable data.

Weighted Least Squares:

$$\min \|W^{\frac{1}{2}}(b - Ax)\|_2^2$$

$$\Rightarrow A^T W A x = A^T W b$$

normal equations

ex. W is matrix of inv. variances

$$\text{diag}(\sigma_1^{-2}, \sigma_2^{-2}, \dots, \sigma_n^{-2})$$

Example Let $x = b_1$ and $x = b_2$ be indep. noisy measurements of x with variances σ_1^2, σ_2^2 , respectively. Solve by weighted L.S.

mean $\frac{X_1 + X_2 + \dots + X_n}{n} = \mu$

Variance $\sigma^2 = \frac{1}{n} \sum_{i=1}^n (X_i - \mu)^2$

regular L.S.

$$\begin{pmatrix} 1 \\ 1 \end{pmatrix} x = \begin{pmatrix} b_1 \\ b_2 \end{pmatrix}$$

normal eq: $(1 \ 1) \begin{pmatrix} 1 \\ 1 \end{pmatrix} x = (1 \ 1) \begin{pmatrix} b_1 \\ b_2 \end{pmatrix}$

$$2x = b_1 + b_2 \Rightarrow \boxed{x = \frac{b_1 + b_2}{2}}$$

weighted L.S.

$$\frac{1}{\sigma_1^2} x = \frac{1}{\sigma_1^2} b_1$$

$$\frac{1}{\sigma_2^2} x = \frac{1}{\sigma_2^2} b_2$$

$$\begin{pmatrix} \frac{1}{\sigma_1^2} \\ \frac{1}{\sigma_2^2} \end{pmatrix} x = \begin{pmatrix} \frac{1}{\sigma_1^2} b_1 \\ \frac{1}{\sigma_2^2} b_2 \end{pmatrix}$$

$$\left(\frac{1}{\sigma_1^2} + \frac{1}{\sigma_2^2} \right) x = \frac{1}{\sigma_1^2} b_1 + \frac{1}{\sigma_2^2} b_2$$

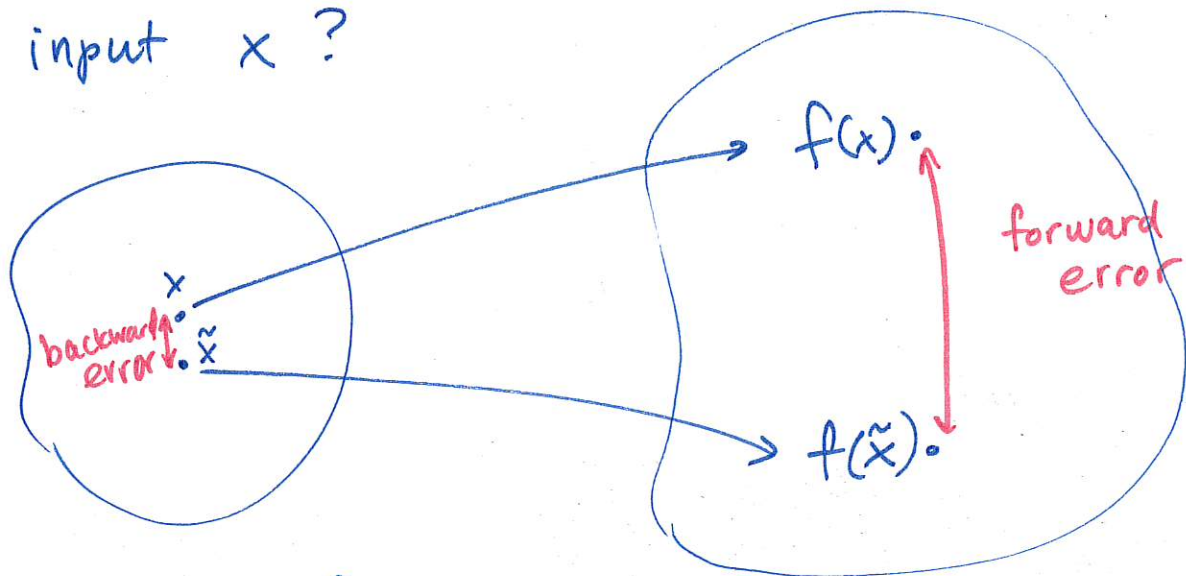
$$\Rightarrow x = \frac{\sigma_1^2 \sigma_2^2}{\sigma_1^2 + \sigma_2^2} \left(\frac{1}{\sigma_1^2} b_1 + \frac{1}{\sigma_2^2} b_2 \right)$$

$$\boxed{x = \frac{\sigma_2^2 b_1 + \sigma_1^2 b_2}{\sigma_1^2 + \sigma_2^2}}$$

$$\frac{\frac{1}{\sigma_1^2} + \frac{1}{\sigma_2^2}}{\frac{1}{\sigma_1^2} + \frac{1}{\sigma_2^2}} = \frac{\sigma_2^2 + \sigma_1^2}{\sigma_1^2 \sigma_2^2}$$

condition number of function $f(x)$

How sensitive is f to perturbations in its input x ?



Does f amplify errors in input?

If it does too much, computing with f is dangerous. Numerical errors (roundoff errors) will be amplified + degrade quality of computed solution. (accuracy)

Quantify how much f amplifies errors in input:

$$K_f = \frac{\left[\frac{|f(\tilde{x}) - f(x)|}{|f(x)|} \right]}{\left[\frac{|\tilde{x} - x|}{|x|} \right]}$$

(relative error in output, f)

(relative error in input)

K_f is an amplification factor

Matrix condition number

$$K_A = \frac{\left(\frac{\|A\tilde{x} - Ax\|}{\|Ax\|} \right)}{\left(\frac{\|\tilde{x} - x\|}{\|x\|} \right)} = \text{cond}(A)$$

rearrange

$$K_A = \frac{\left(\frac{\|A(\tilde{x} - x)\|}{\|\tilde{x} - x\|} \right)}{\left(\frac{\|Ax\|}{\|x\|} \right)}$$

$$\leq \frac{\|A\|}{\left(\frac{\|Ax\|}{\|x\|} \right)}$$

Let $y = Ax \Rightarrow x = A^{-1}y$

$$= \frac{\|A\|}{\left(\frac{\|y\|}{\|A^{-1}y\|} \right)} = \|A\| \left(\frac{\|A^{-1}y\|}{\|y\|} \right)$$

$$\leq \|A\| \|A^{-1}\|$$

In 2-norm

$$K_A = \|A\|_2 \|A^{-1}\|_2 = \sigma_1 \cdot \frac{1}{\sigma_n}$$

$$K_A = \frac{\sigma_1}{\sigma_n} = \text{cond}_2(A)$$

$\text{cond}(A) = 1$ good
 $\text{cond}(A) \geq 1$

normal equations square the

condition number

$$\text{Cond}(A^T A) = \text{Cond}(A)^2$$

check

$$\bullet A^T A = V \Sigma^T U^T U \Sigma V^T = V \Sigma^T \Sigma V^T$$

$$\Rightarrow \text{cond}_2(A^T A) = \frac{\sigma_1^2}{\sigma_n^2}$$

$$\bullet A = U \Sigma V^T$$

$$\text{Cond}(A) = \frac{\sigma_1}{\sigma_n}$$

Example

$$A = \begin{pmatrix} 1 & 1 \\ \varepsilon & 0 \\ 0 & \varepsilon \end{pmatrix}$$

$$\varepsilon^2 < \varepsilon_{\text{mach}}$$

$$A^T A = \begin{pmatrix} 1 & \varepsilon & 0 \\ \varepsilon & 1 & 0 \\ 0 & 0 & \varepsilon \end{pmatrix} \begin{pmatrix} 1 & 1 \\ \varepsilon & 0 \\ 0 & \varepsilon \end{pmatrix} = \begin{pmatrix} 1+\varepsilon^2 & 1 \\ \varepsilon & 1+\varepsilon^2 \\ 0 & \varepsilon \end{pmatrix} \approx \begin{pmatrix} 1 & 1 \\ \varepsilon & \varepsilon \\ 0 & \varepsilon \end{pmatrix}$$

properties

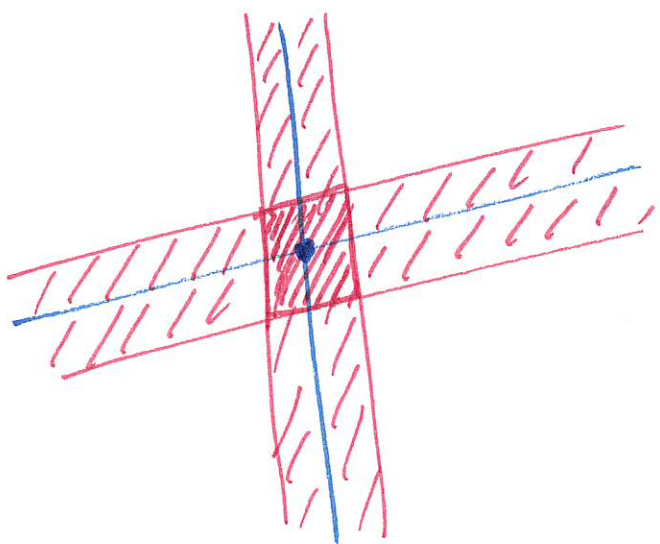
1. $\text{cond}(A) \geq 1$

2. $\text{cond}(I) = 1$

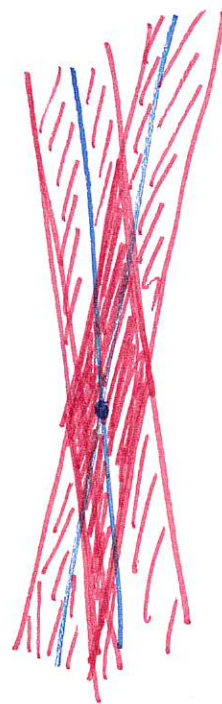
3. $\text{cond}(\alpha A) = \text{cond}(A)$

4. D diagonal, $\text{cond}(D) = \frac{\max_i |d_i|}{\min_i |d_i|}$

intuition



well-conditioned



ill-conditioned

$f(x)$ f differentiable

$$K_f = \frac{|f(\tilde{x}) - f(x)|}{|\tilde{x} - x|} \bigg/ \frac{|f(x)|}{|x|}$$

$$\Delta x = \tilde{x} - x$$

$$K_f = \frac{|f(x + \Delta x) - f(x)|}{|\Delta x|} \bigg/ \frac{|f(x)|}{|x|} \rightarrow \frac{|f'(x)|}{|f(x)|} |x|$$

Example $f(x) = \sqrt{x} = x^{\frac{1}{2}}$

$$f'(x) = \frac{1}{2} x^{-\frac{1}{2}}$$

$$K_f = \frac{|\frac{1}{2} x^{-\frac{1}{2}} x|}{|x^{\frac{1}{2}}|} = \frac{1}{2}$$

well-conditioned

Example $f(x) = \tan(x) = \frac{\sin(x)}{\cos(x)}$

$$f'(x) = \sec^2(x) = 1 + \tan^2(x)$$

$$K_f = \frac{|x(1 + \tan^2(x))|}{|\tan(x)|}$$

very large near $\frac{\pi}{2} = x$

