## CS 210 Midterm

Spring 2017

Name	
Student ID	
Signature	

You may not ask any questions during the exam. If you believe that there is something wrong with a question, write down what you think the question is trying to ask, and answer that.

Question	Points	Score
1	3	
2	3	
3	3	
4	3	
5	3	
6	3	
7	3	
8	3	
9	3	
10	3	
11	4	
12	4	
13	4	
14	4	
15	4	
16	4	
17	4	
18	4	
19	18	
20	20	
Total	100	

## True/False

For each question, indicate whether the statement is true or false by circling T or F, respectively.

- 1. (T/F) Division of two positive floating point numbers may cause overflow.
- 2. (T/F) The condition number (in 2-norm) of  $A^TA$  is the same as the condition number (in 2-norm) of A.
- 3. (T/F) A good algorithm will produce an accurate solution regardless of the conditioning of the problem being solved.
- 4. (T/F) If A is nonsingular, then  $A\mathbf{x} = \mathbf{b}$  may have more than one solution.
- 5. (T/F) Gaussian elimination can be used to compute a triangular factorization of a matrix.
- 6. (T/F) Any symmetric real matrix has a Cholesky factorization.
- 7. (T/F) The singular value decomposition of a matrix A will give orthonormal bases for range(A), null(A), range $(A^T)$ , and null $(A^T)$ .
- 8. (T/F) **x** is a solution to the least squares problem  $\min_{\mathbf{x}} ||b A\mathbf{x}||_2$  if and only if  $A^T A\mathbf{x} = A^T b$ .
- 9.  $(T/\overline{F})$  The QR decomposition can be stably computed through the classical Gram-Schmidt algorithm.
- 10. (T/F) A Householder matrix is an reflection matrix.

## Multiple Choice

Instructions: For the multiple choice problems, circle exactly one of (a) - (e).

- 11. Which one statement about floating point numbers is true?
  - (a) If two numbers are exactly representable in floating point, then the result of an arithmetic operation on them is also an exactly representable floating point number.
  - (b) Floating point addition is commutative, but not associative.
  - (c) Floating point numbers are distributed uniformly througout their range.
  - (d) In a unnormalized floating point system, the representation of a number is unique.
  - (e) None of the above.
- 12. Which one of the following statements is <u>false</u>?
  - (a) A symmetric matrix, A, satisfies  $||A||_1 = ||A||_{\infty}$ .
  - (b) A permutation matrix, P, satisfies  $||P||_2 = 1$ .
  - (c) An orthogonal matrix, Q, satisfies  $||Q||_2 = 1$ .
  - (d) If A is singular matrix, then  $||A||_2 = 0$ .
  - (e) For any vector  $\mathbf{x}$ ,  $||\mathbf{x}||_1 \ge ||\mathbf{x}||_{\infty}$ .

- 13. Let A be an  $n \times n$  matrix. Which of the following properties would necessarily imply that A is singular?
  - I. The columns of A are linearly dependent.
  - II. A has a singular value that is 0.
  - III.  $A\mathbf{z} = \mathbf{0}$ , for some  $\mathbf{z} \neq \mathbf{0}$ .
  - (a) II only
  - (b) I and II only
  - (c) I and III only
  - (d) II and III only
  - (e) I, II and III
- 14. Which of the following statements are true?
  - I. A problem is ill-conditioned if its solution is highly sensitive to changes in its data.
  - II. We can improve conditioning of a problem by switching from single to double precision arithmetic.
  - III. In order to solve a problem numerically, it is necessary to have both a well-conditioned problem and a stable algorithm.
  - (a) I only
  - (b) II only
  - (c) I and III only
  - (d) II and III only
  - (e) I, II and III
- 15. Which of the following statements are true?
  - I. The number of solutions of  $A\mathbf{x} = \mathbf{b}$  never depends on  $\mathbf{b}$ .
  - II. If A is singular, then  $A\mathbf{x} = \mathbf{b}$  has either no solution or infinitely many solutions.
  - III. If  $A\mathbf{x} = \mathbf{b}$  then  $\mathbf{b}$  must be in the columnspace of A.
  - (a) II only
  - (b) I and II only
  - (c) I and III only
  - (d) II and III only
  - (e) I, II and III

- 16. Which of the following statements about the Singular Value Decomposition (SVD) are true?
  - I. Every real matrix has an SVD.
  - II. If a matrix Q is orthogonal, then its singular values are all 1.
  - III. A matrix with rank r will have exactly r singular values that are greater than 0.
  - (a) I only
  - (b) I and II only
  - (c) I and III only
  - (d) II and III only
  - (e) I, II and III
- 17. Let  $A = U\Sigma V^T$  be the Singular Value Decomposition (SVD) of the matrix A and let  $A^+$  denote the pseudoinverse of A. Which of the following statements are true?
  - I. The SVD reveals the rank of a matrix.
  - II.  $A^+ = U\Sigma^+V^T$  where  $\Sigma^+$  is the pseudoinverse of  $\Sigma$ .
  - III. The rank of A is the same as the rank of  $A^+$ .
  - (a) I only
  - (b) III only
  - (c) I and II only
  - (d) I and III only
  - (e) I, II and III
- 18. Which of the following statements about the Least Squares (LS) problem  $\min_{\mathbf{x}} ||\mathbf{b} A\mathbf{x}||_2$  are true?
  - I. The solution of the LS problems satisfies  $A^T A \mathbf{x} = A^T \mathbf{b}$ .
  - II. The solution of the LS problem is always unique.
  - III. If  $\mathbf{b} \in \text{Range}(A)$ , then the LS problem has a residual of norm 0.
  - (a) I only
  - (b) III only
  - (c) I and II only
  - (d) I and III only
  - (e) I, II and III

## Written Response

19. LU Factorization. Consider the  $3 \times 3$  matrix

$$A = \begin{pmatrix} 2 & 4 & 3 \\ 6 & 14 & 10 \\ 4 & 10 & 10 \end{pmatrix}.$$

- (a) Find unit lower triangular matrices  $M_1$  and  $M_2$  such that  $M_2M_1A=U$  where U is an upper triangular matrix.
- (b) Express A as A = LU where L is a unit lower triangular matrix, and U is the upper triangular matrix you found above.
- (c) Explain how you would use the factors L and U to solve the linear equations  $A\mathbf{x} = \mathbf{b}$ .

20. Least Squares. Let  $A \in \mathbb{R}^{m \times n}$ , where m > n. Consider the least squares (LS) problem

$$\min_{\mathbf{x}} ||\mathbf{b} - A\mathbf{x}||_2.$$

- (a) Assume A has full rank. Show how you would use the QR decomposition  $A = Q \begin{pmatrix} R \\ 0 \end{pmatrix}$  to solve the LS problem.
- (b) Now assume A is rank-deficient with rank r < n. Show how you would use the Singular Value Decomposition  $A = U\Sigma V^T$ , with  $\Sigma = \operatorname{diag}(\sigma_1, \ldots, \sigma_r, 0, \ldots, 0)$ , to solve the LS problem.
- (c) In parts (a) and (b) is the solution unique? Why or why not?