CSI30 : Computer Graphics Lecture 6: Graphics Pipeline (cont.)

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Graphics Pipeline



Transform



"Modelview" Transformation



Project



Projection: map 3D scene to 2D image



OpenGL Super Bible, 5th Ed.

Orthographic projection



Orthographic, or parallel projection

- parallel lines appear parallel (unlike perspective proj.)
- equal length lines appear equal length (unlike perspective proj.)

OpenGL Orthogonal Viewing

glOrtho(left,right,bottom,top,near,far)



near and far measured from camera Orthographic, or parallel projection

- square or rectangular viewing volume
- anything outside volume is not drawn

Perspective projection



OpenGL Perspective Viewing

glFrustum(xmin, xmax, ymin, ymax, near, far)



Clip



Clip against view volume



Clipping against a plane

What's the equation for the plane through **q** with normal **N**?





implicit line equation:

$f(\mathbf{X}) = \mathbf{N} \cdot (\mathbf{X} - \mathbf{X}_0) = 0$

Clipping against a plane

What's the equation for the plane through **q** with normal **N**?

$$f(\mathbf{p}) = ? = 0$$

<whiteboard>



Clipping against a plane

What's the equation for the plane through **q** with normal **N**?

$$f(\mathbf{p}) = \mathbf{N} \cdot (\mathbf{p} - \mathbf{q}) = 0$$



Intersection of line and plane



How can we distinguish between these cases?



Intersection of line and plane



 $f(\mathbf{a})f(\mathbf{b}) \ge 0$

 $f(\mathbf{a})f(\mathbf{b}) < 0$



Intersection of line and plane

How can we find the intersection point?

<whiteboard>



Clip against view volume



We write down the line equations p_cb(s) and p_ab(t) and find the s and t where they intersect the plane.

Hidden Surface Removal



Occlusion



"painter's algorithm" draw primitives in back-to-front order

Occlusion



"painter's algorithm" draw primitives in backto-front order

> **problem**: triangle intersection

who's in front of whom?

Occlusion



also, sorting primitives by depth is **slow**

at each pixel, record distance to the closest object that has been drawn in a *depth* buffer

at each pixel, record distance to the closest object that has been drawn in a *depth* buffer



- assume both spheres of the same size, red drawn last





done in the **fragment blending** phase – each fragment must carry a depth



http://www.beyond3d.com/content/articles/41/