

# CS 130 : Computer Graphics

Texture Mapping

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# There are limits to geometric modeling



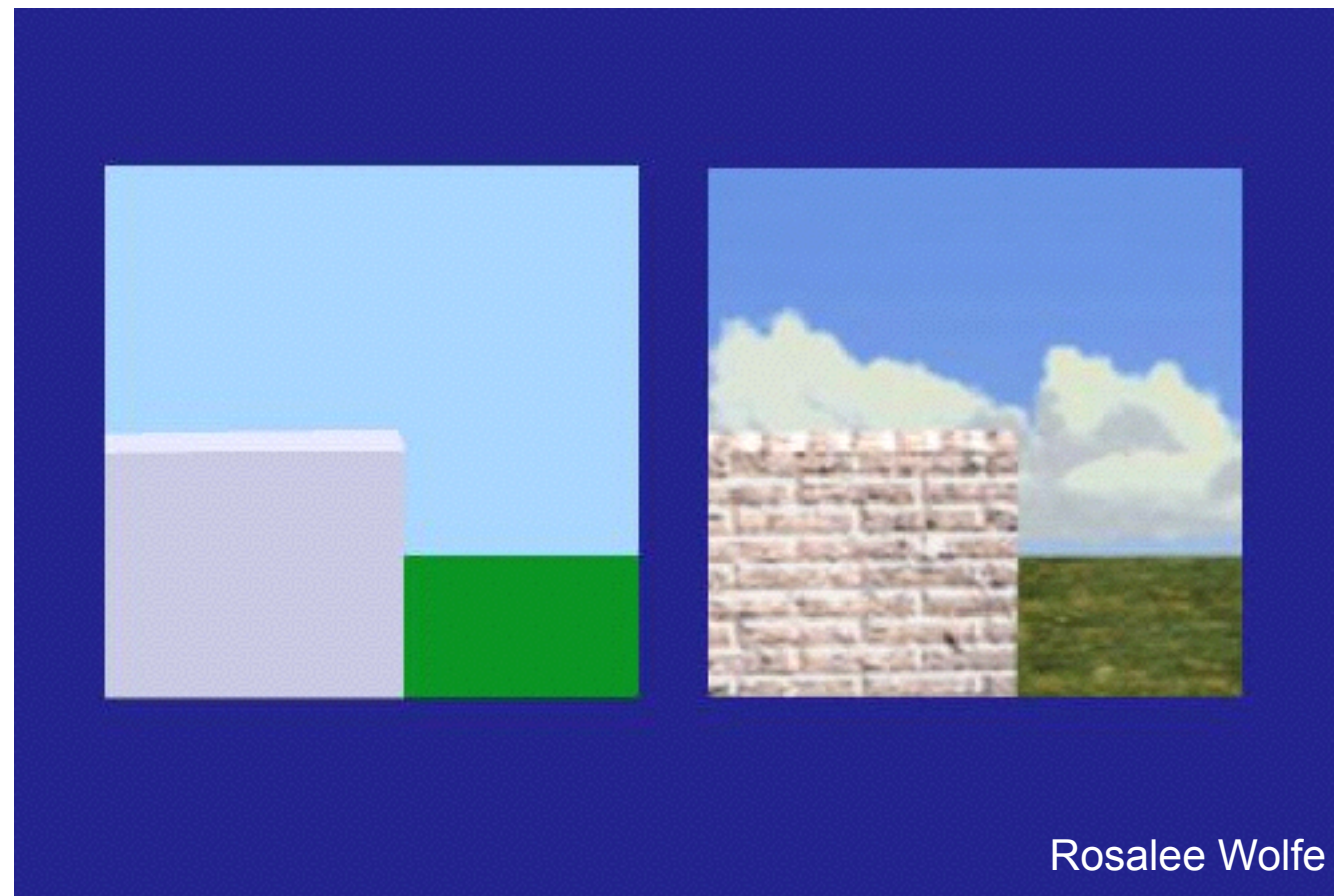
<http://www.beinteriordecorator.com>



National Geographic

Although modern GPUs can render millions of triangles/sec, that's not enough sometimes...

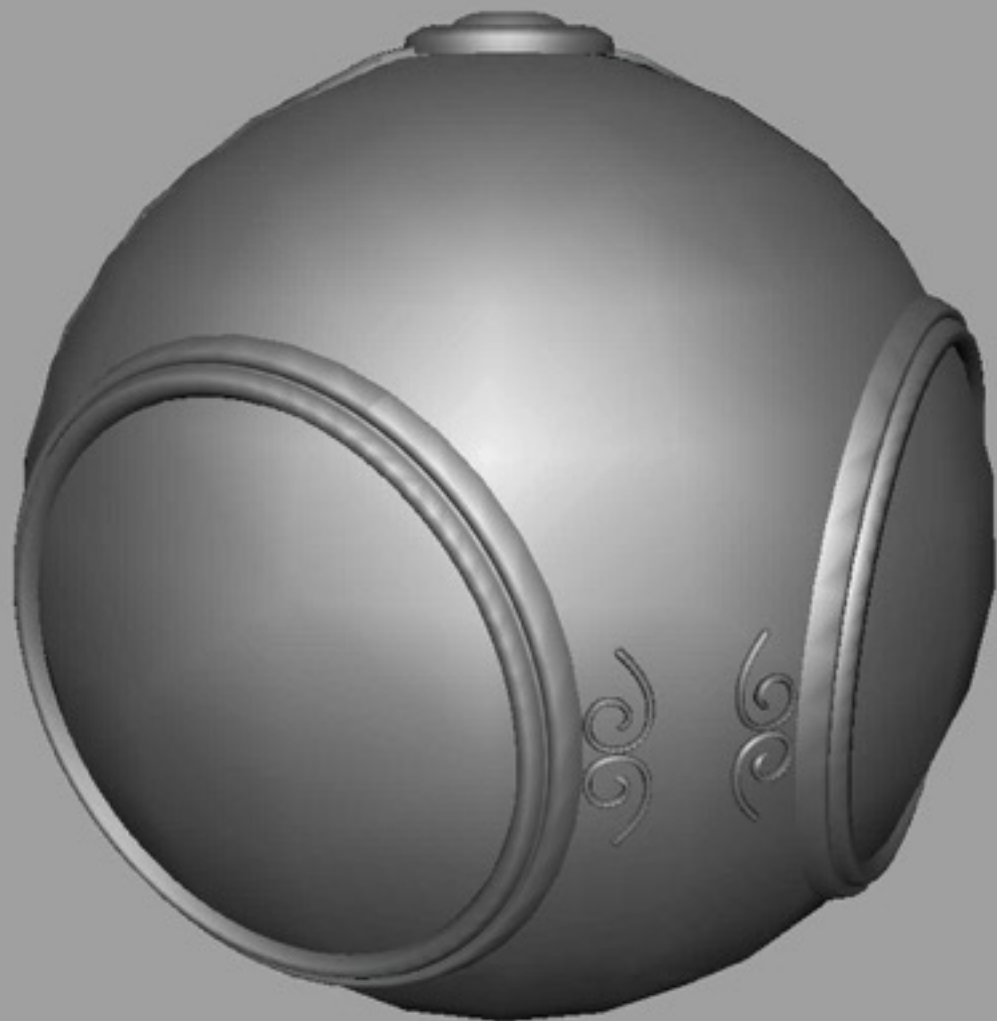
# Use texture mapping to increase realism through detail



This image is just 8 polygons!



[Angel and Shreiner]



No texture



With texture

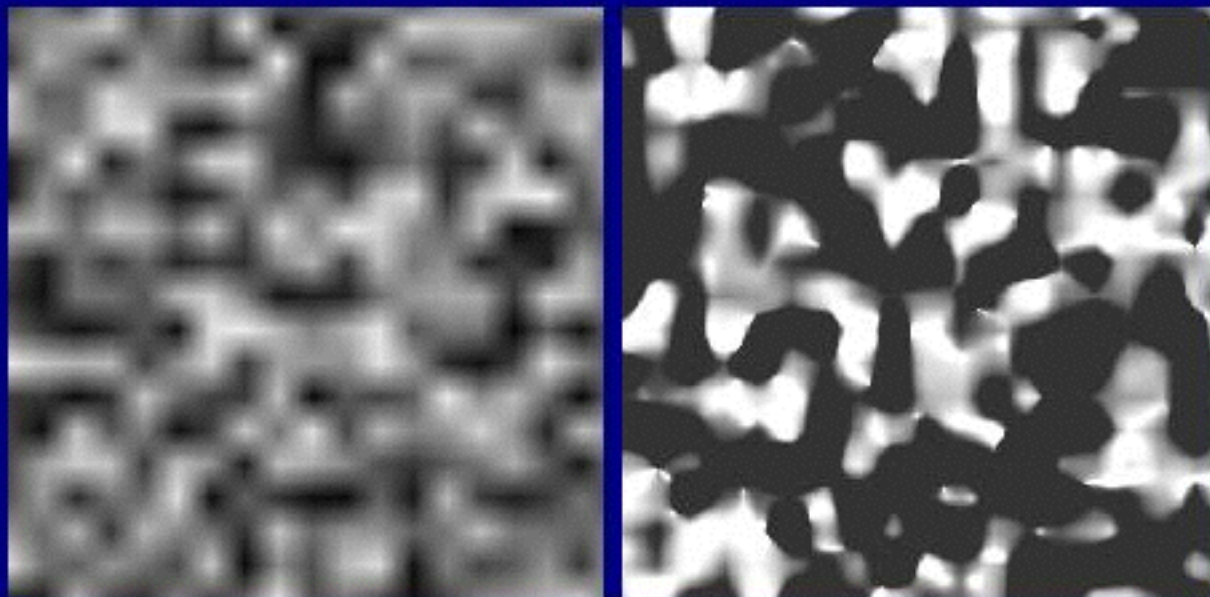
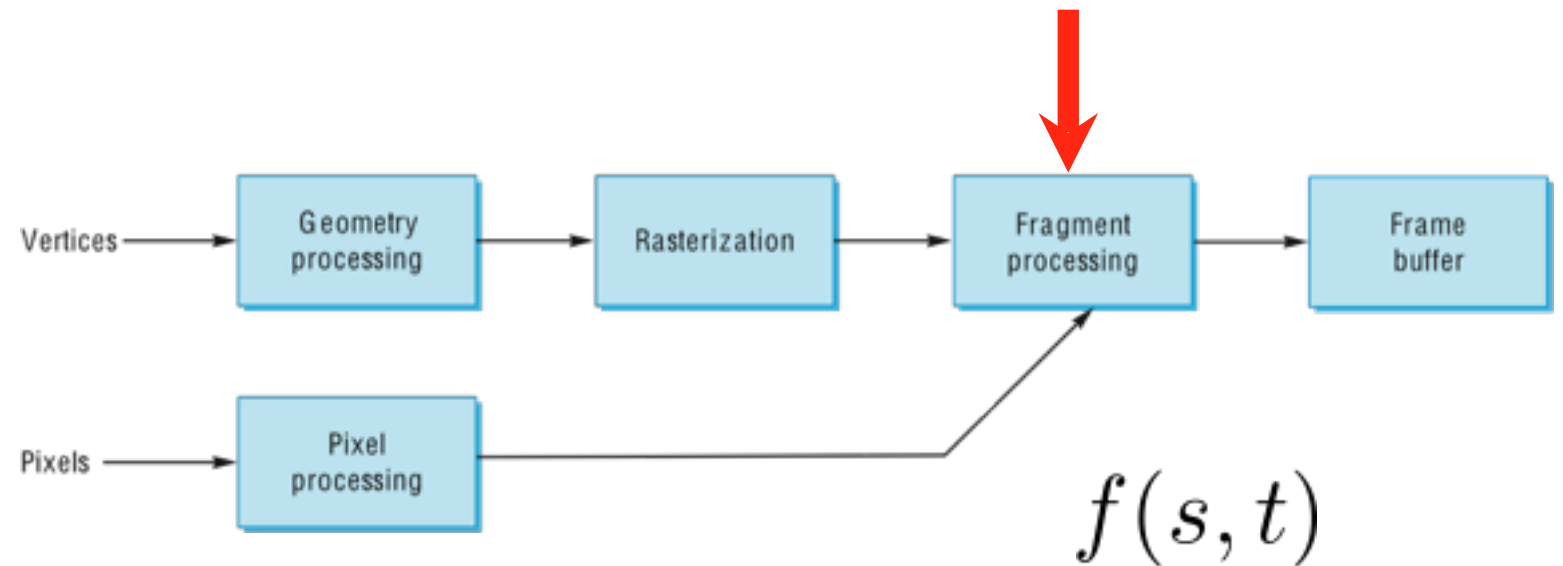




Pixar - Toy Story



# Store 2D images in buffers and lookup pixel reflectances



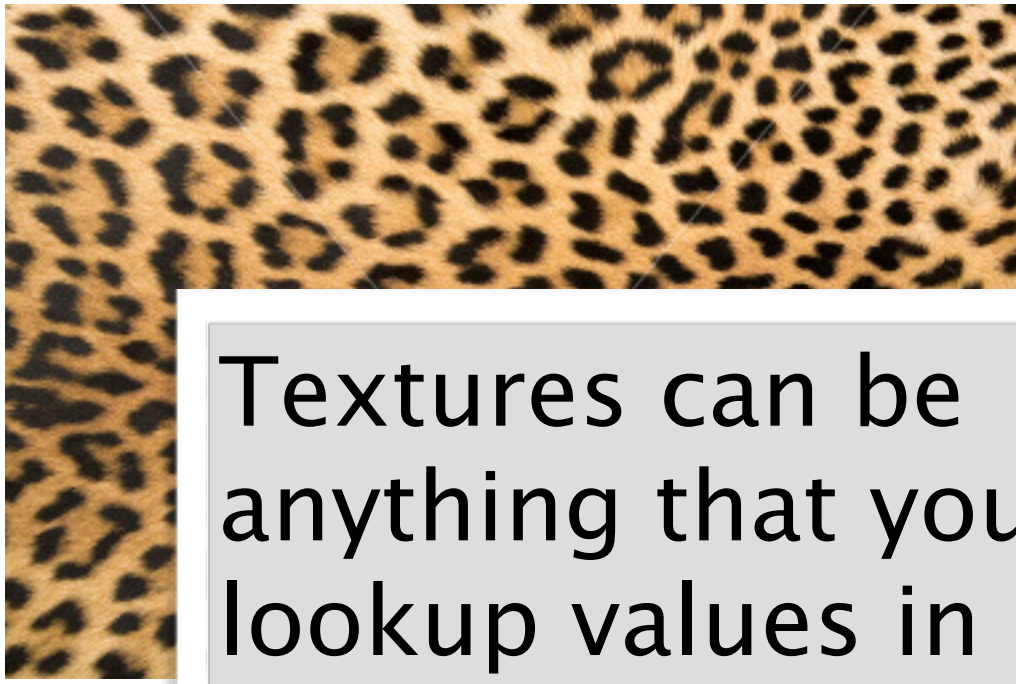
procedural



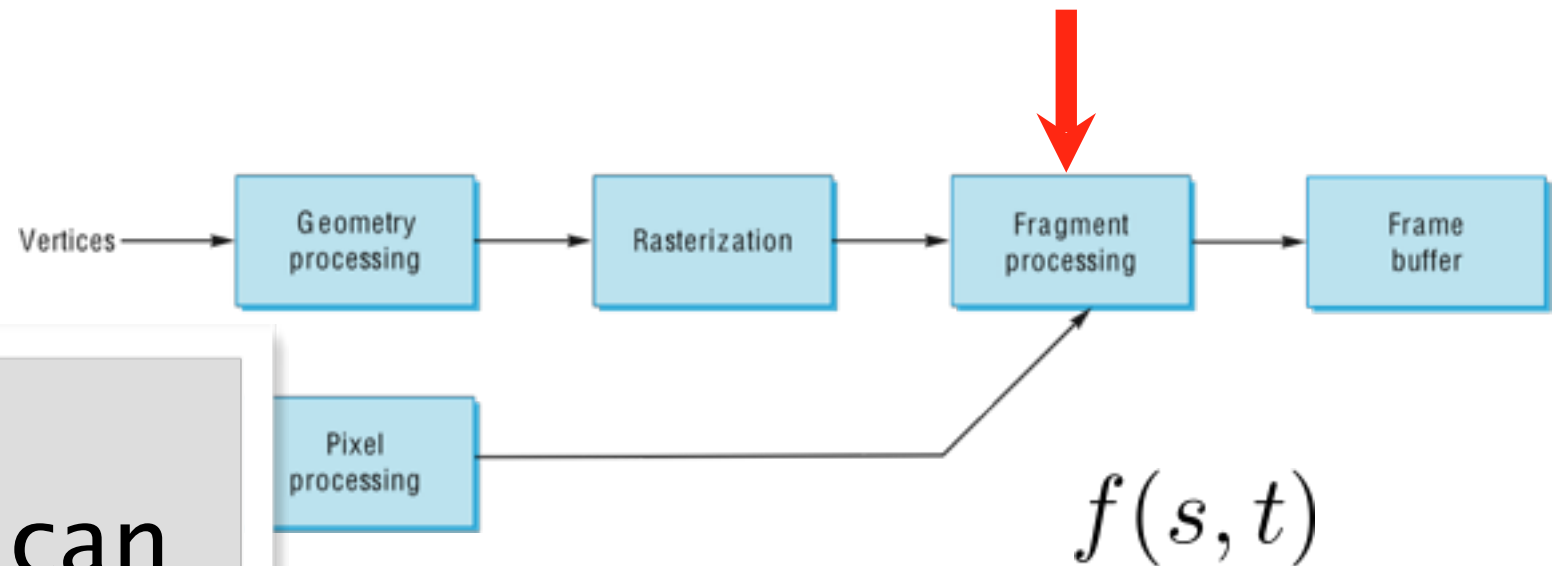
photo



# Store 2D images in buffers and lookup pixel reflectances



Textures can be anything that you can lookup values in — photo, procedurally generated, or even a function that computes a value on the fly.



photo

procedural

# 3D solid textures

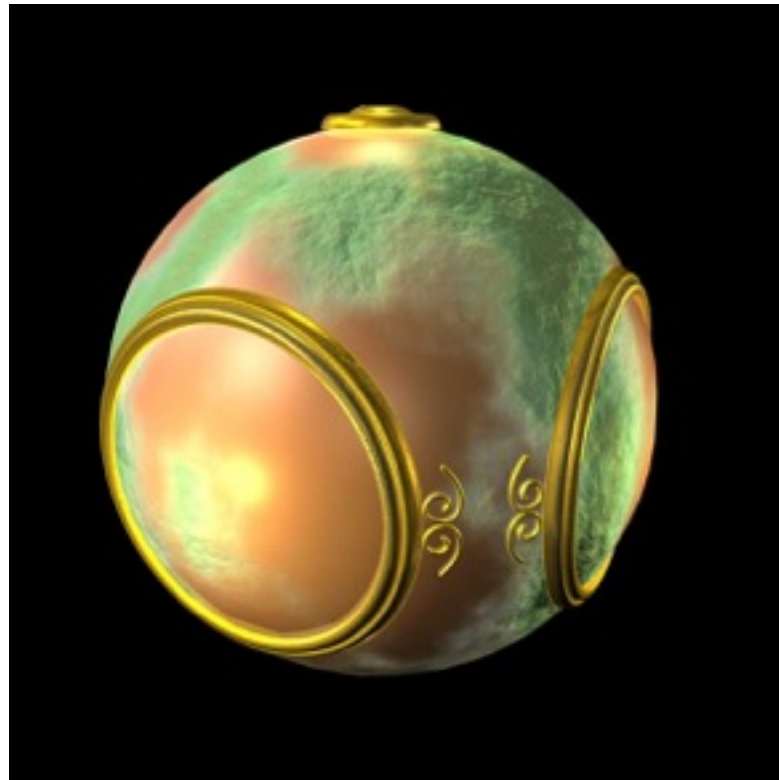


[Dong et al., 2008]

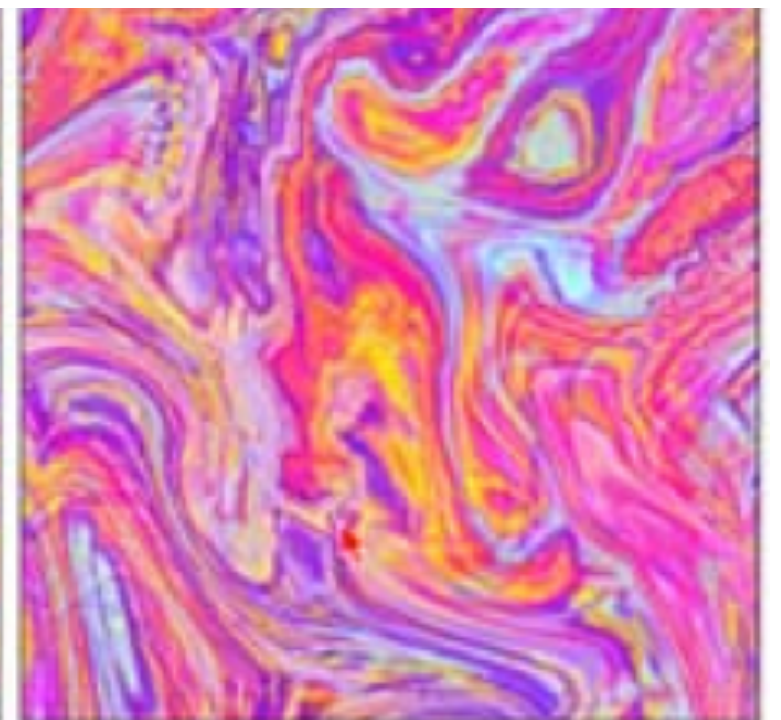
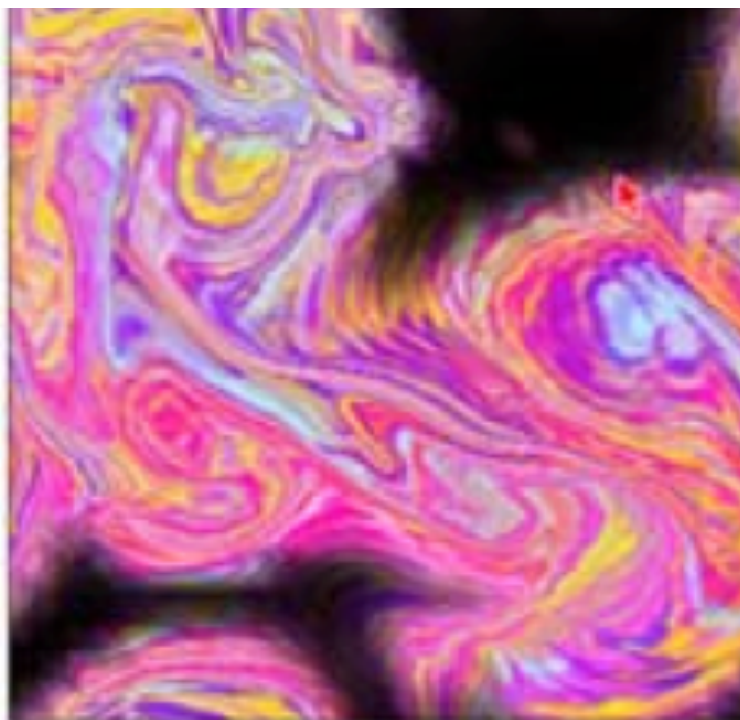


# Other uses of textures...

Light maps  
Shadow maps  
Environment  
maps  
Bump maps  
Opacity maps  
Animation

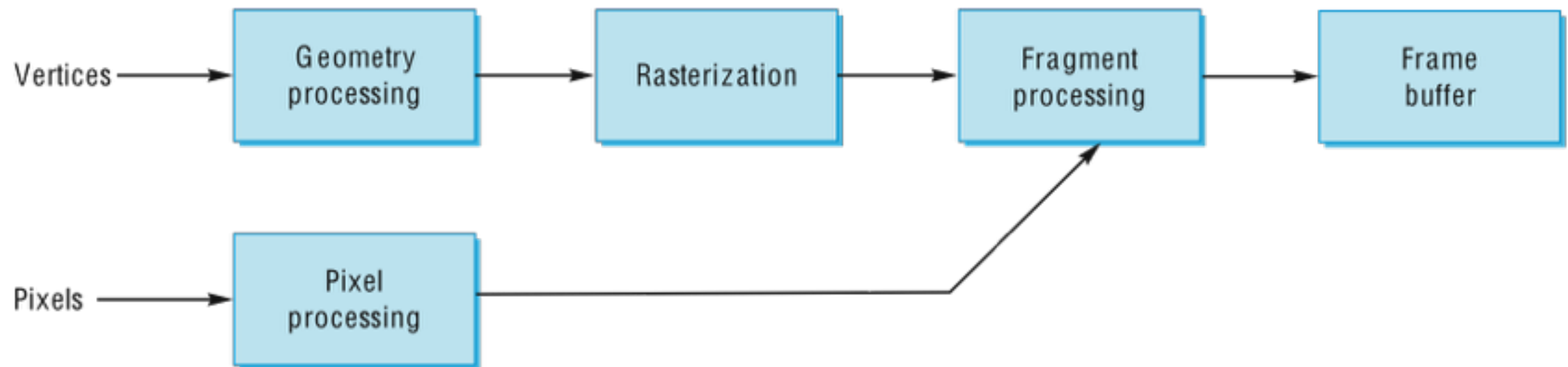


[Angel and Shreiner]



[Stam 99]

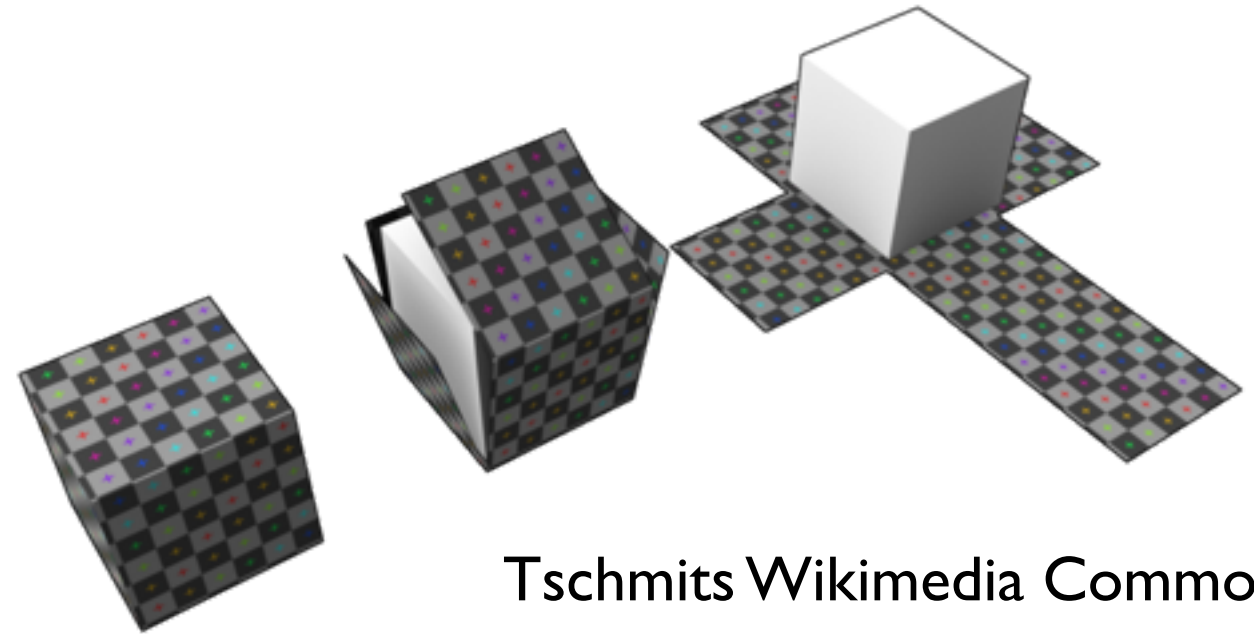
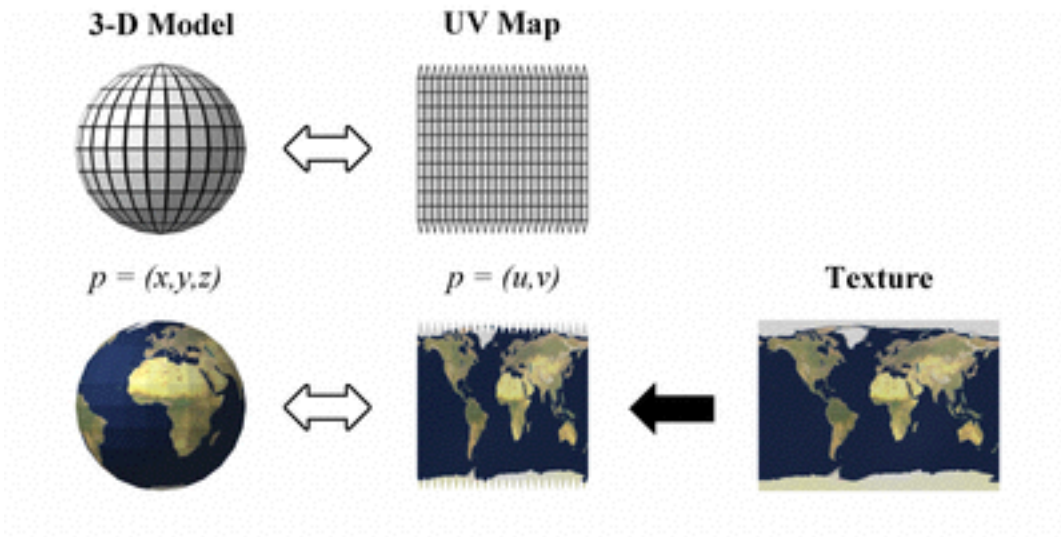
# Texture mapping in the OpenGL pipeline



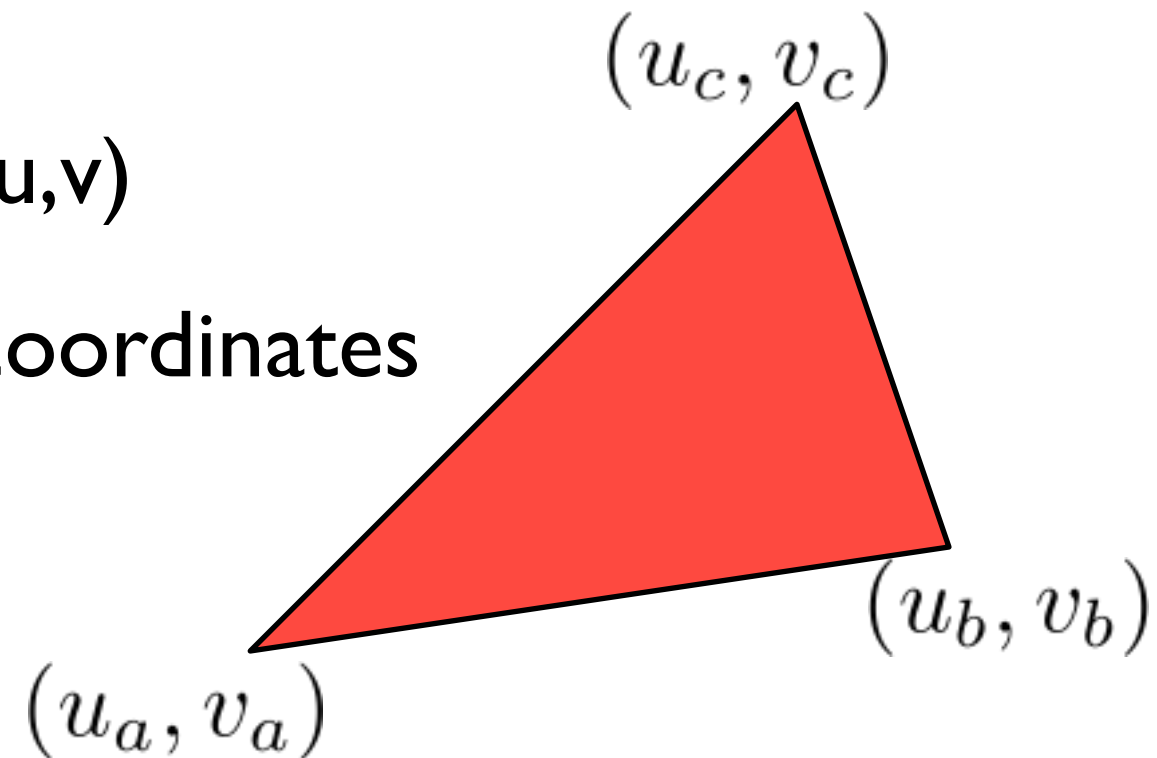
- Geometry and pixels have separate paths through pipeline
- meet in **fragment processing** - where textures are applied
- texture mapping applied at end of pipeline - efficient since relatively few polygons get past clipper

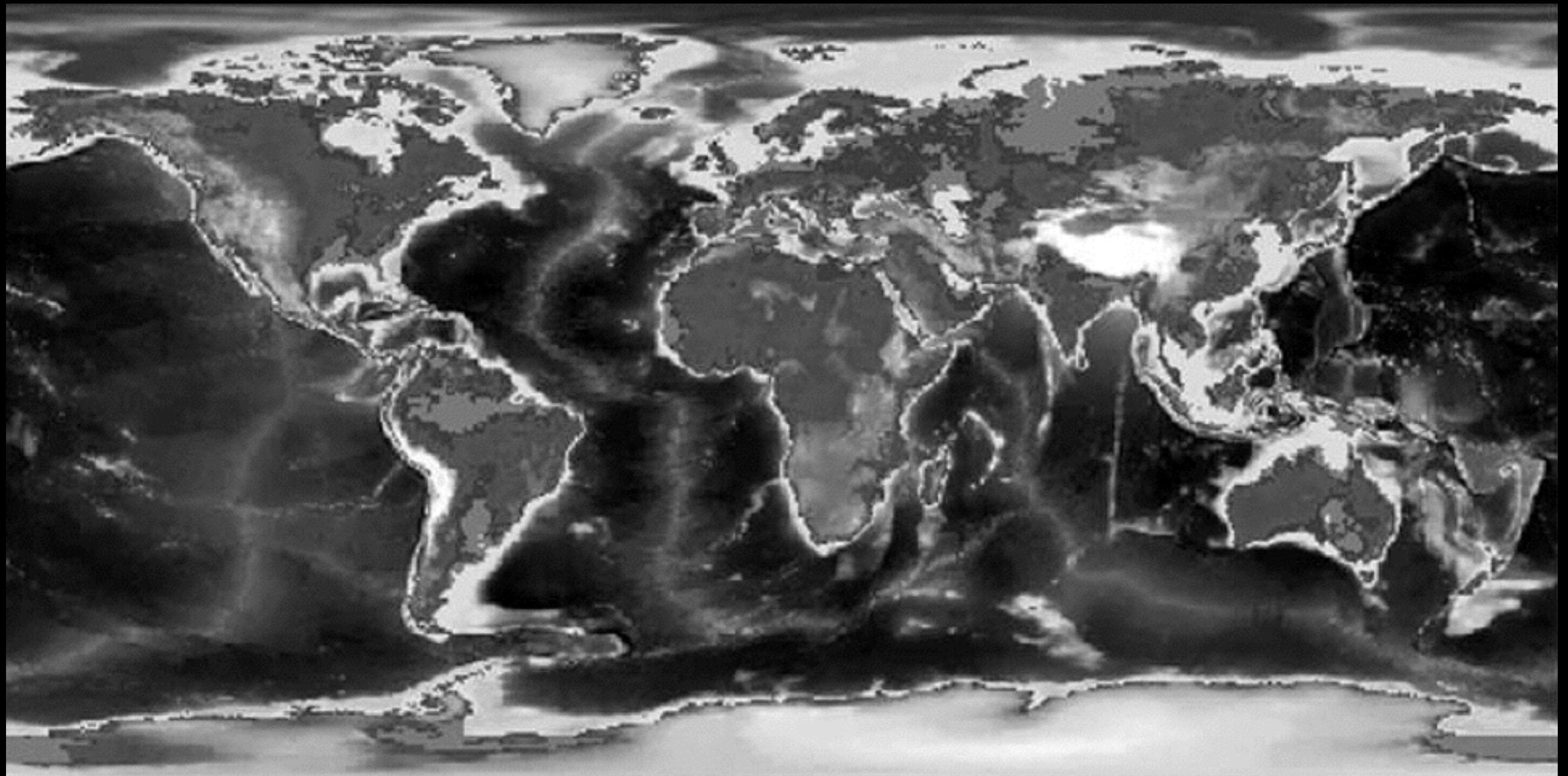
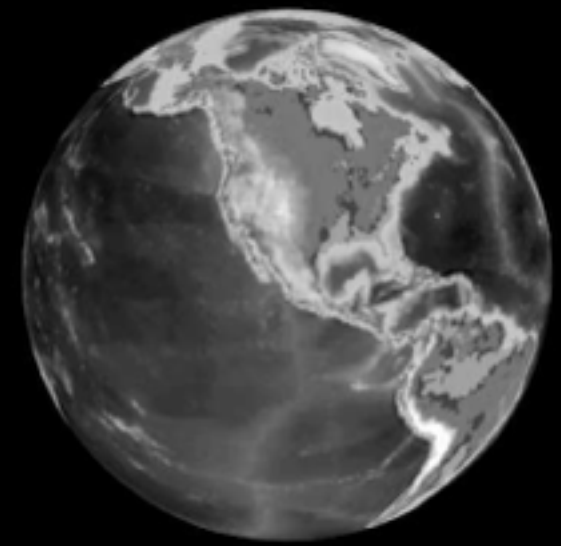


# uv Mapping



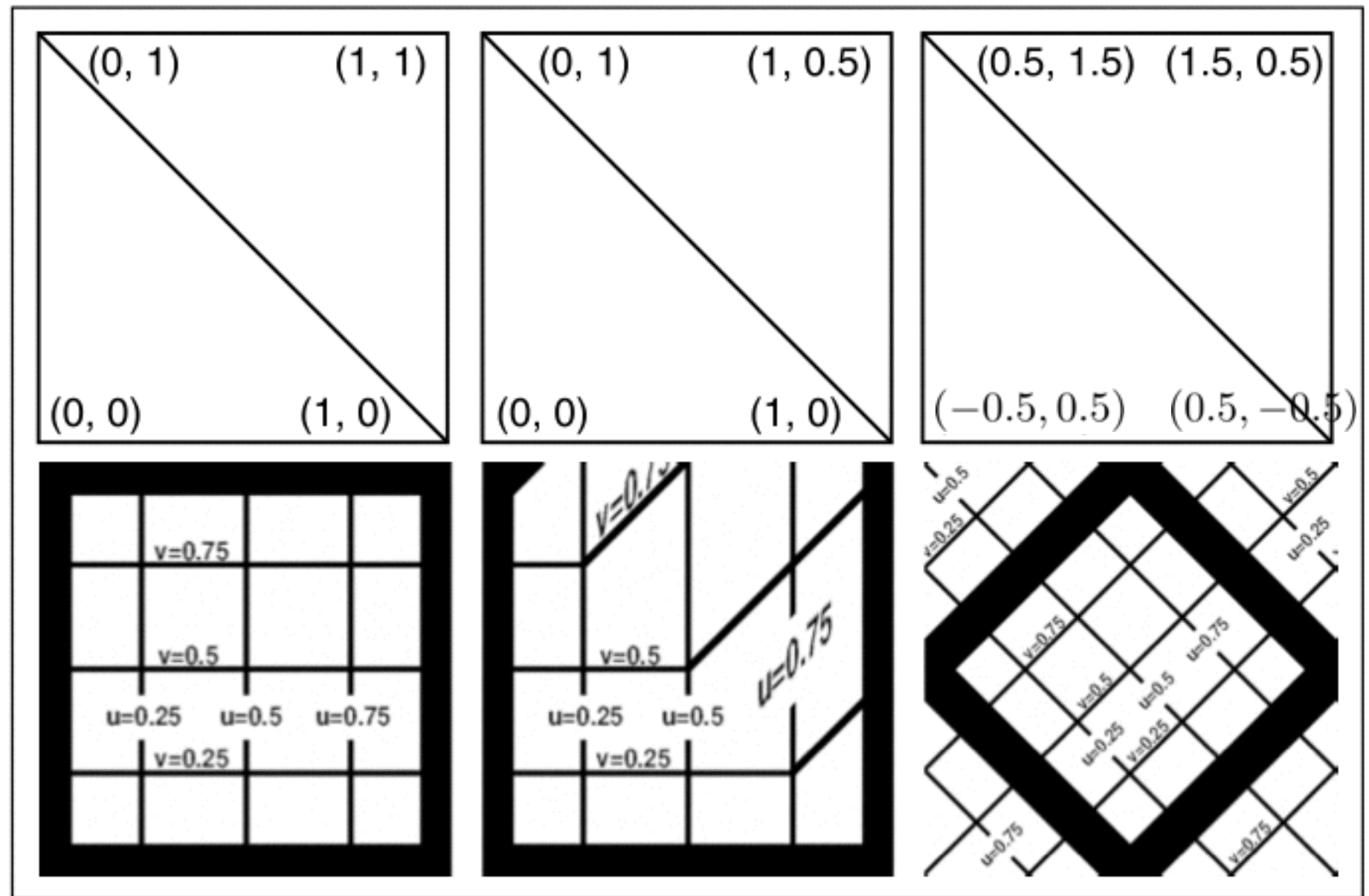
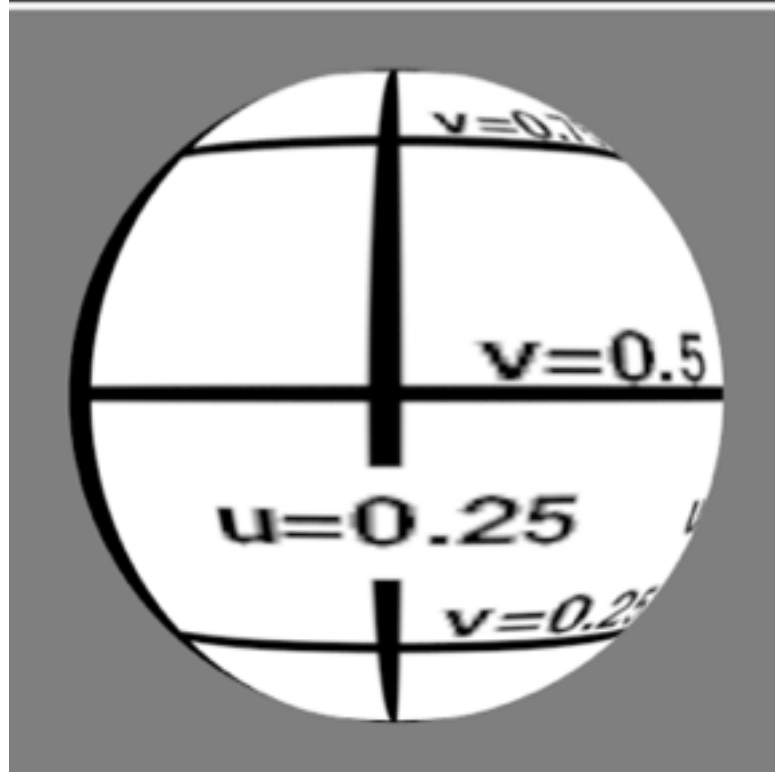
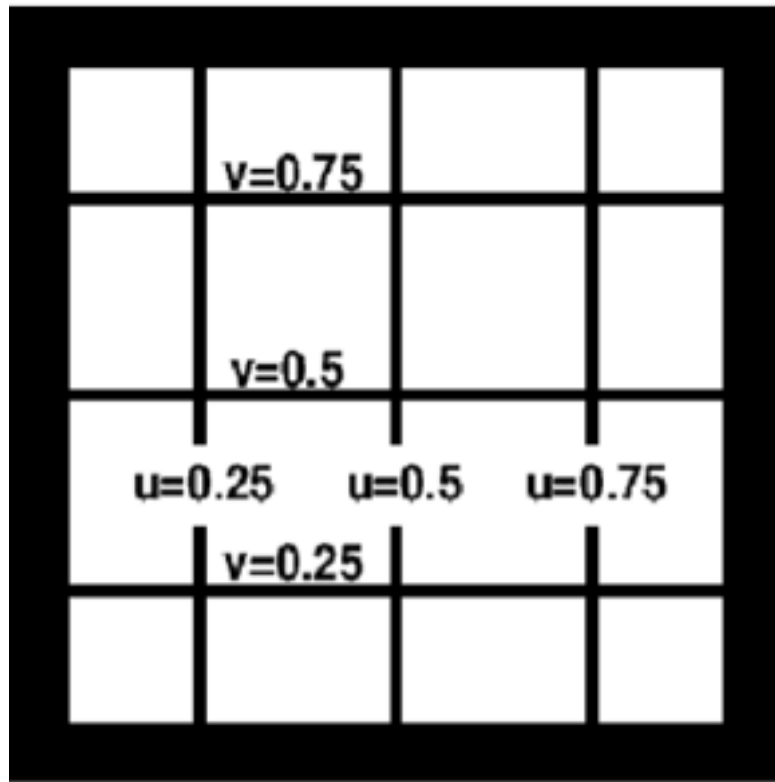
- 2D texture is parameterized by (u,v)
- Assign polygon vertices texture coordinates
- Interpolate within polygon





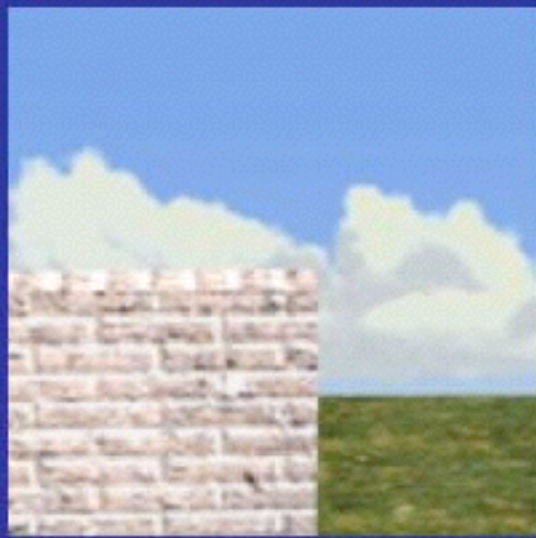
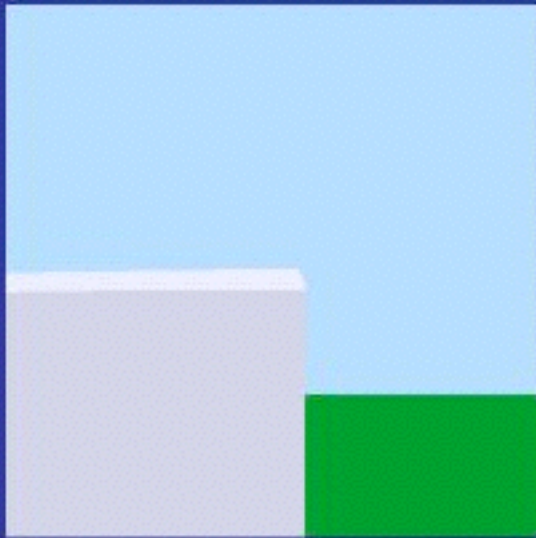


# Texture Calibration



# The major issues in texture mapping...

- What should the actual mapping be?



easy: flat surface

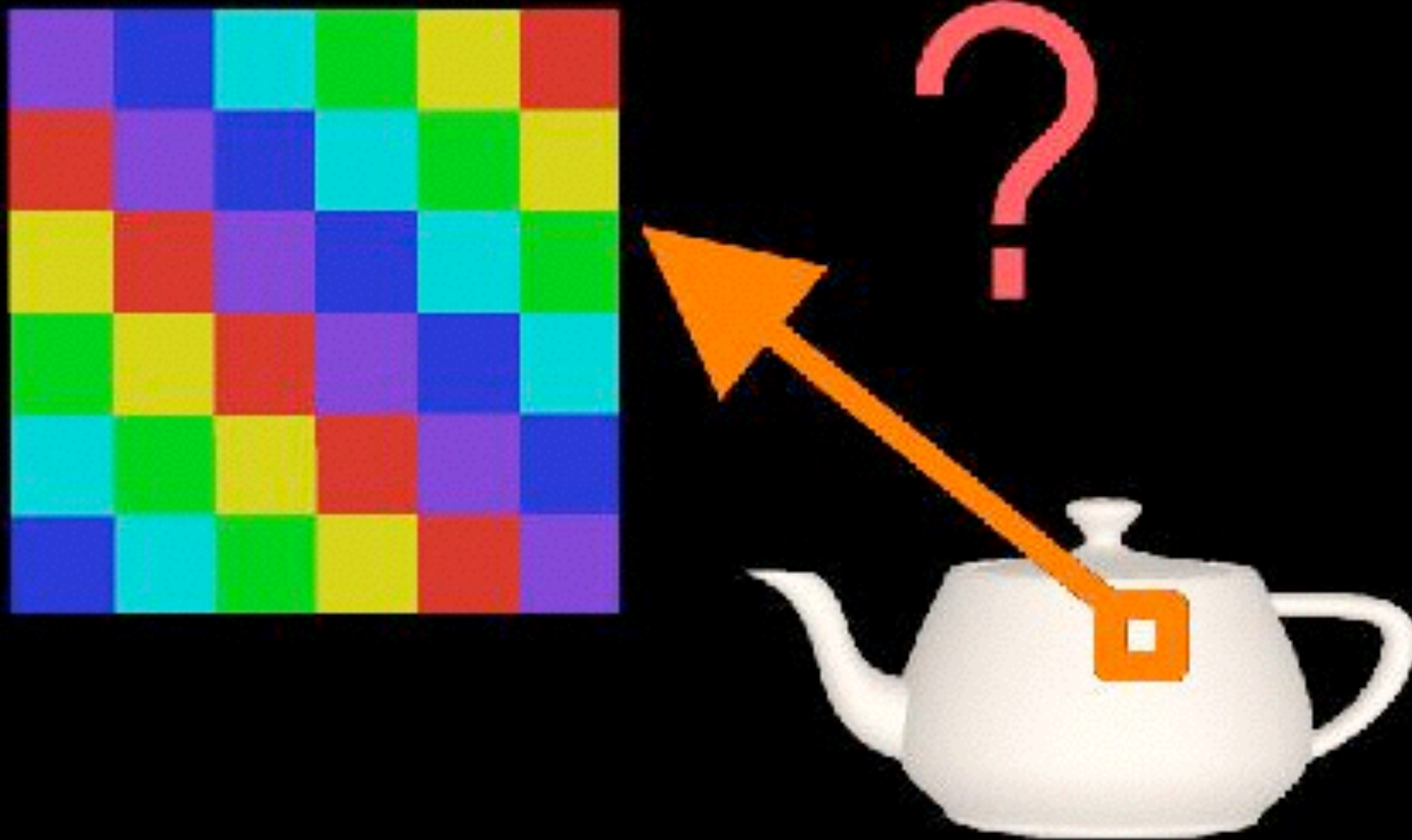


harder: curved surface

[Rosalee Wolfe]

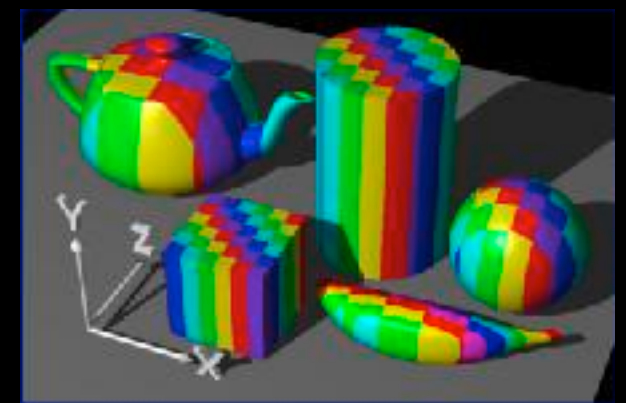
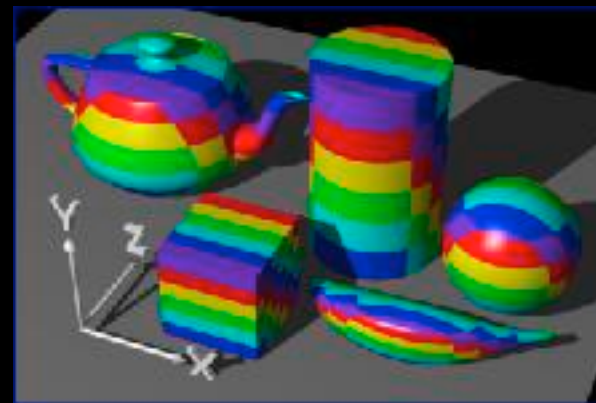
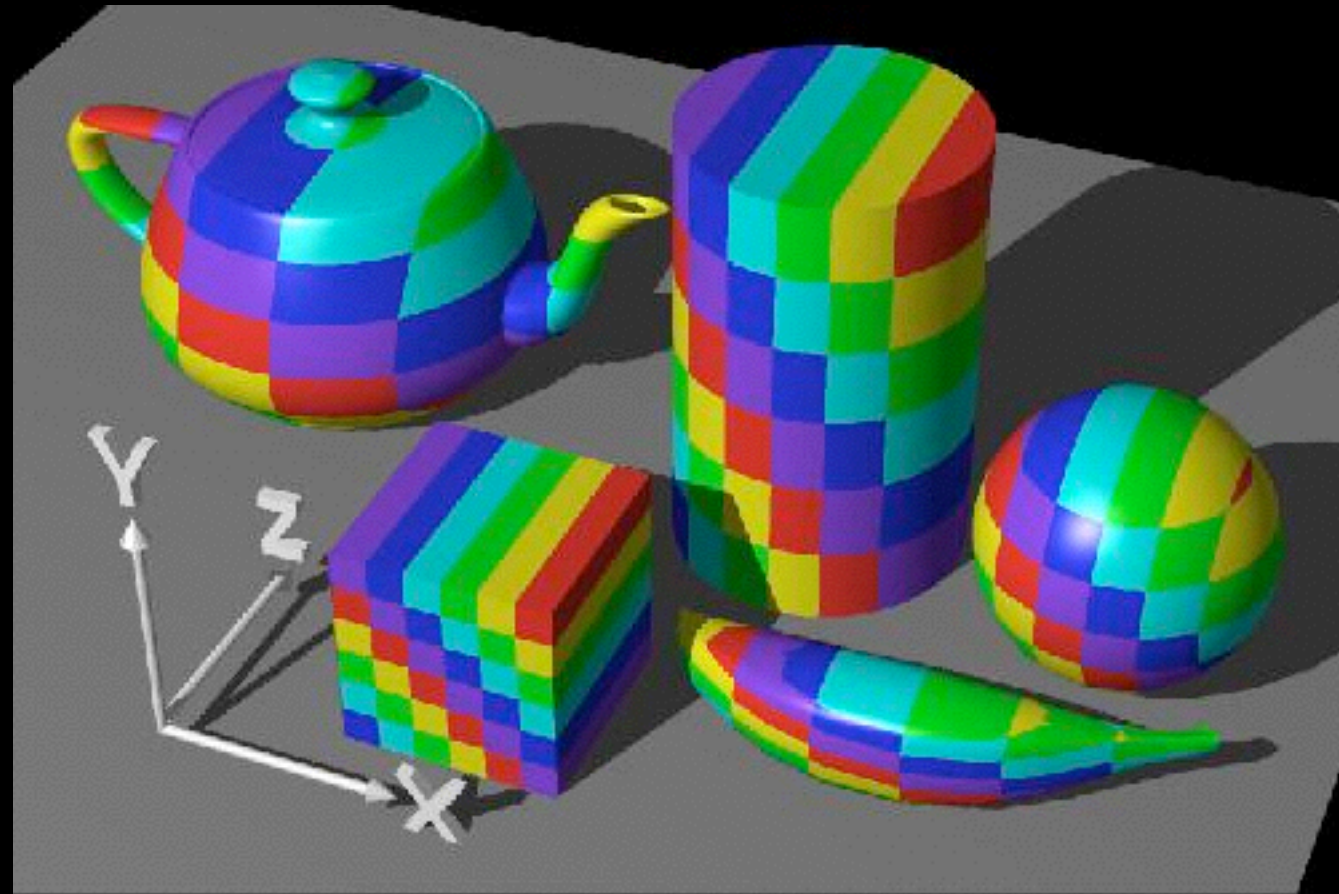
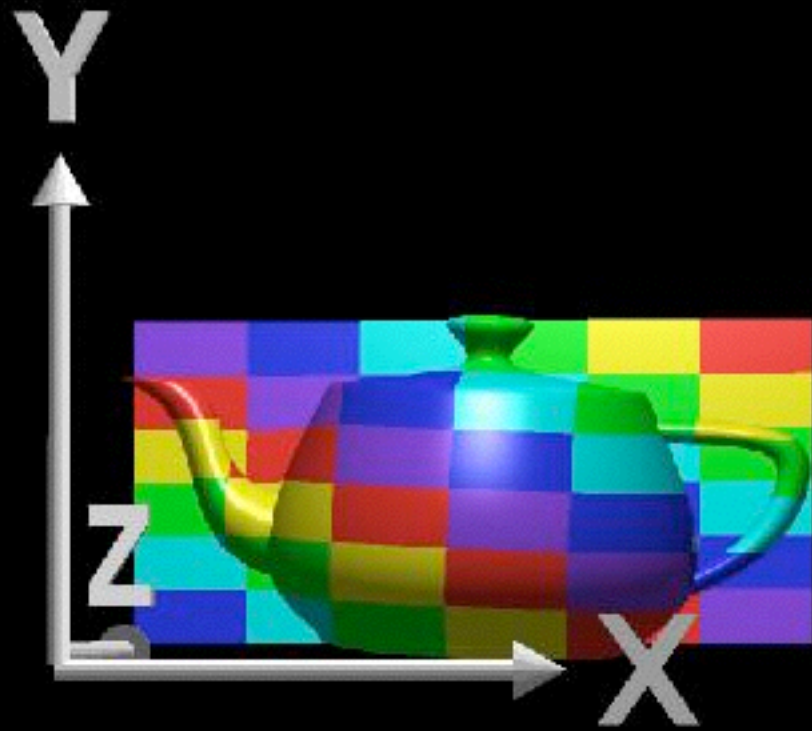


Given a point on the object  $(x,y,z)$ , what point  $(u,v)$  in the texture we use?



# Example: planar mapping

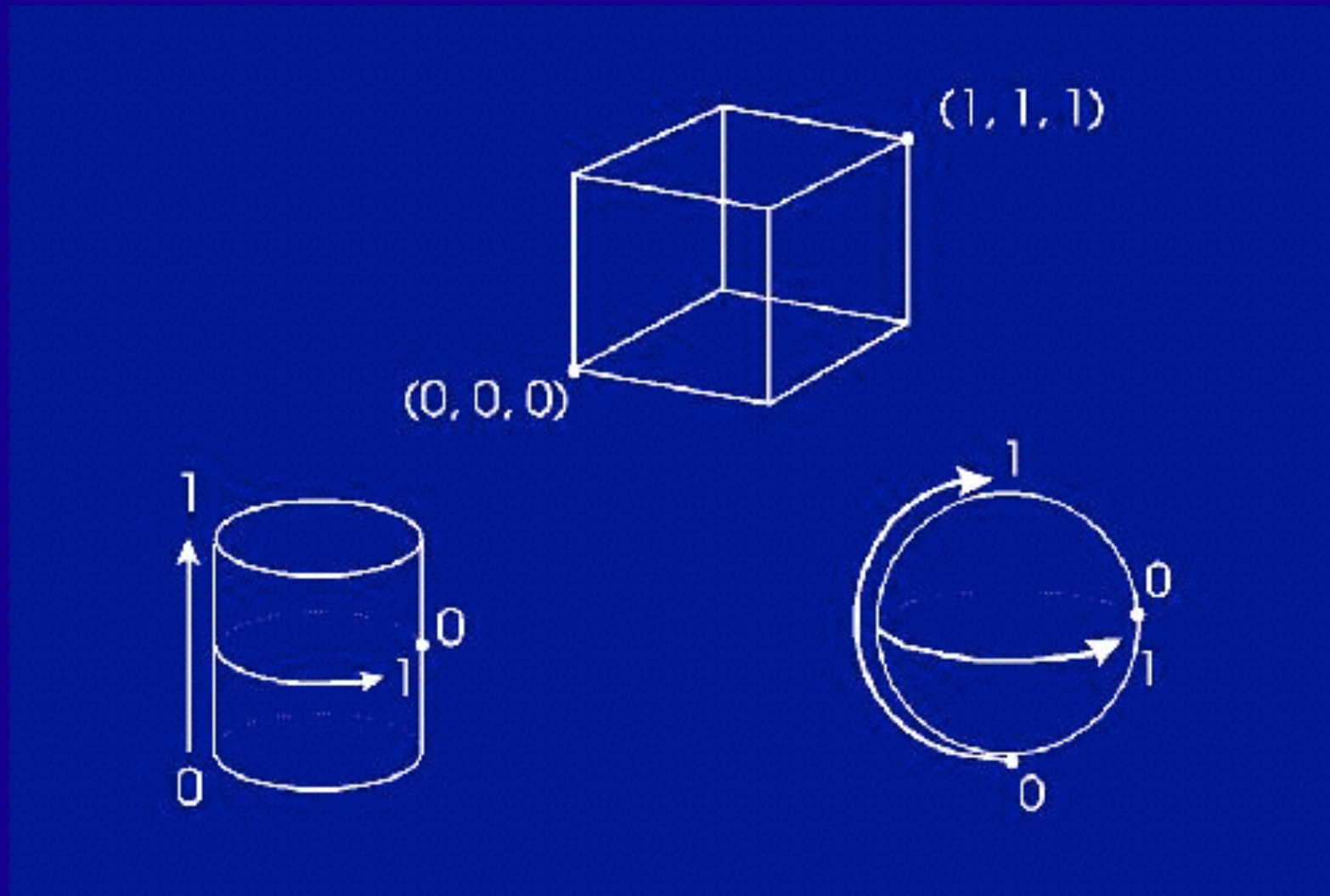
[Rosalee Wolfe]





# Intermediate surfaces

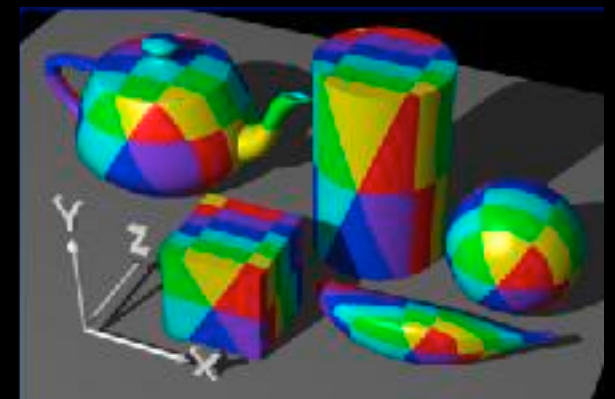
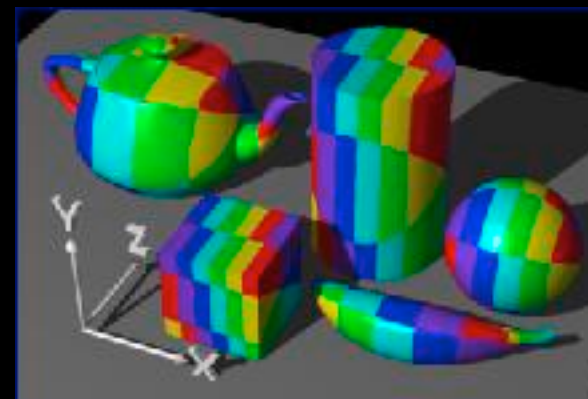
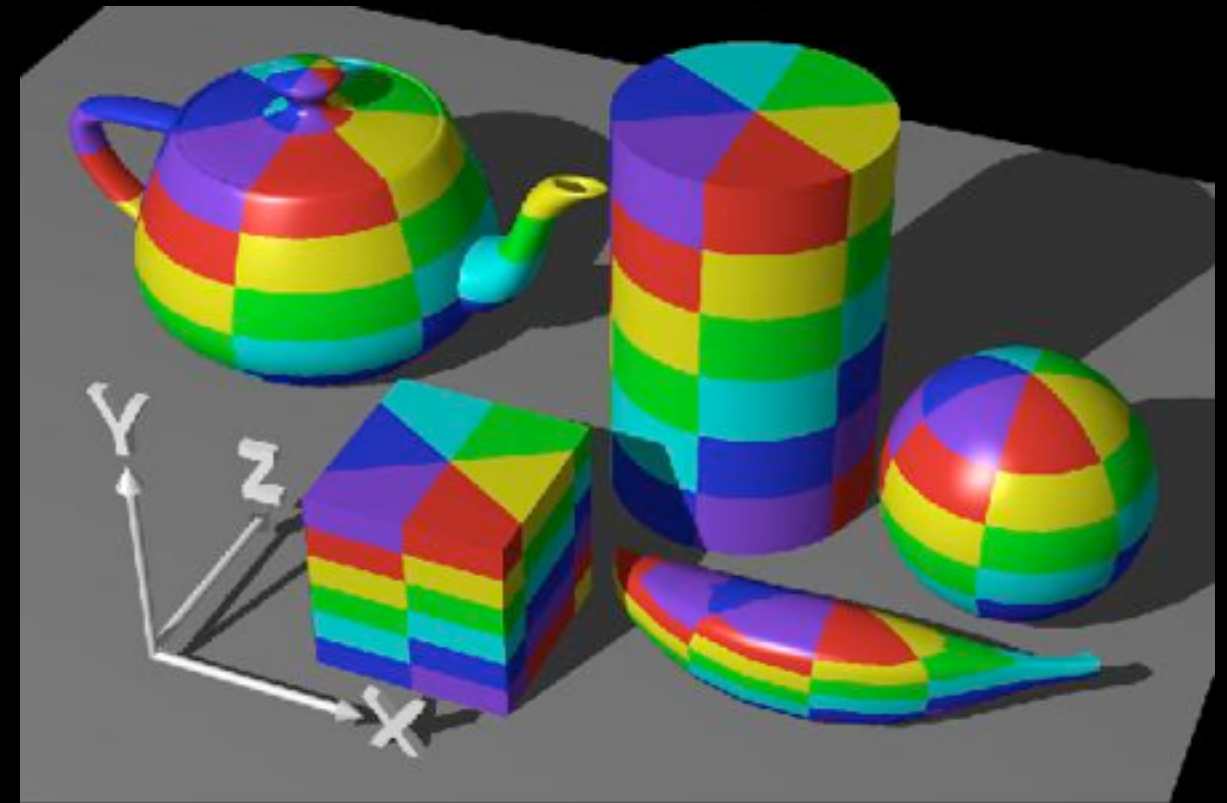
First map the texture to a simpler, intermediate surface



# Cylindrical mapping

$$(x,y,z) \rightarrow (\text{theta}, h) \rightarrow (u,v)$$

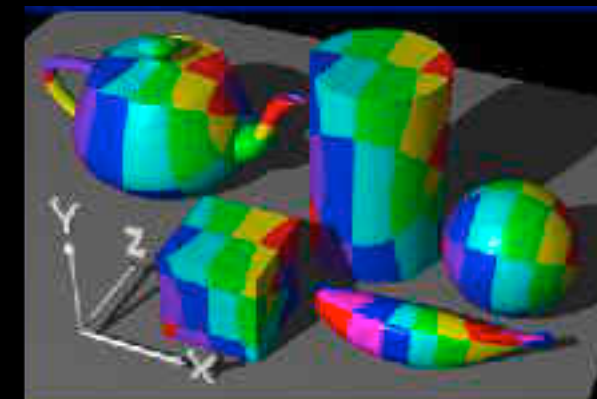
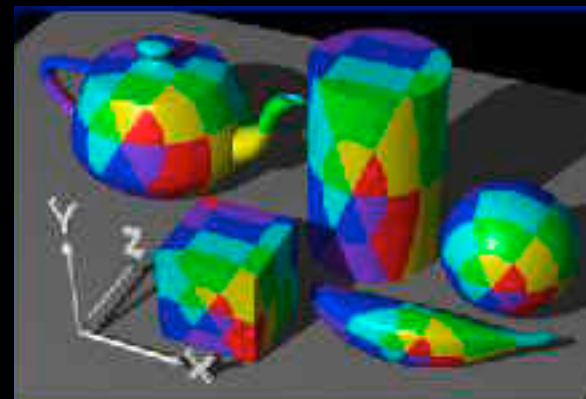
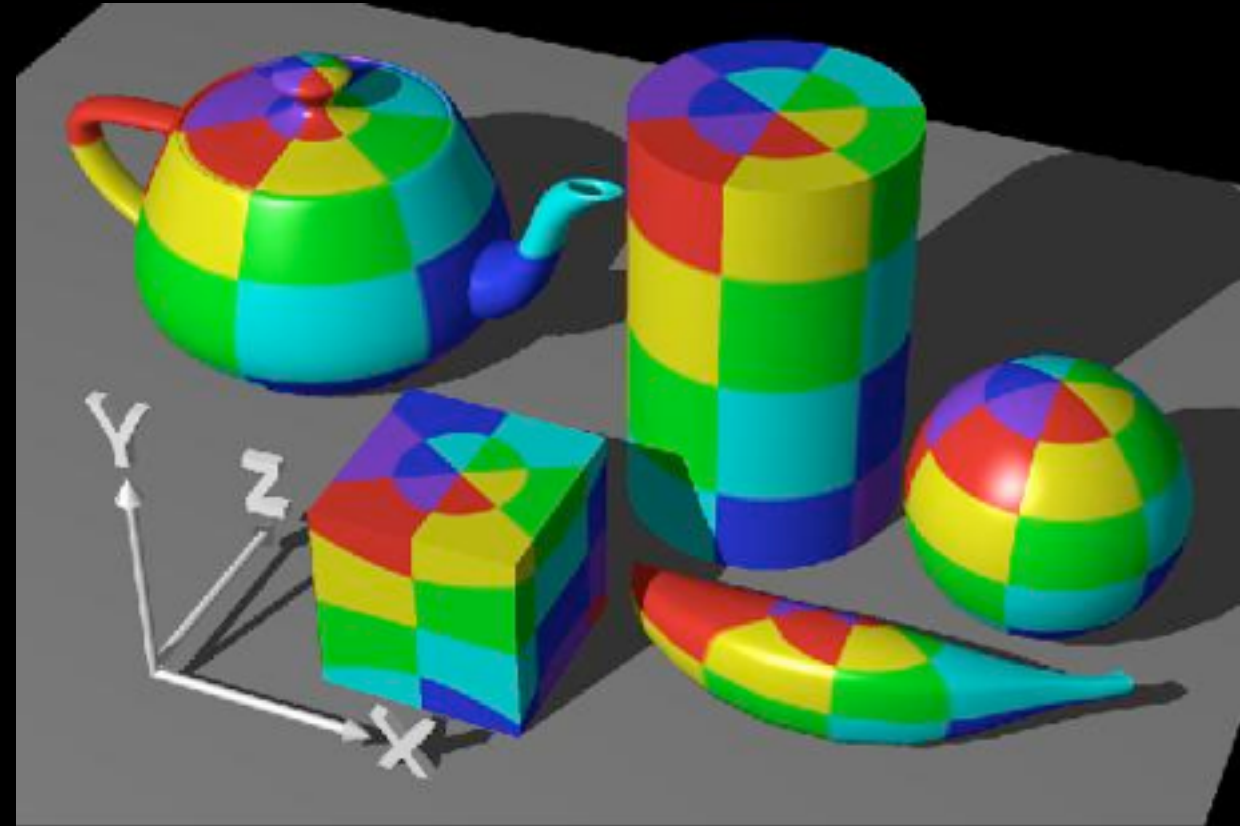
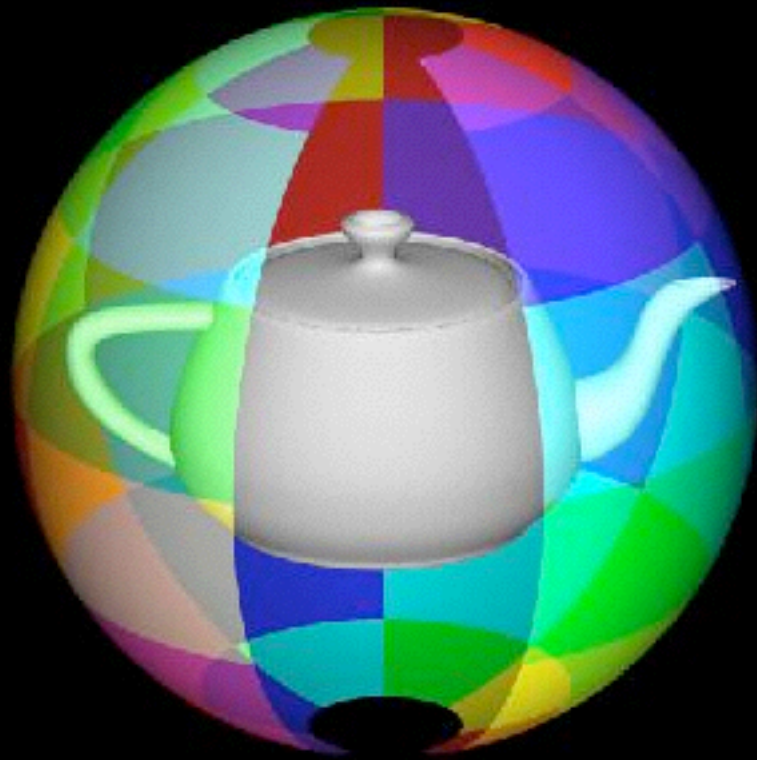
[Rosalee Wolfe]





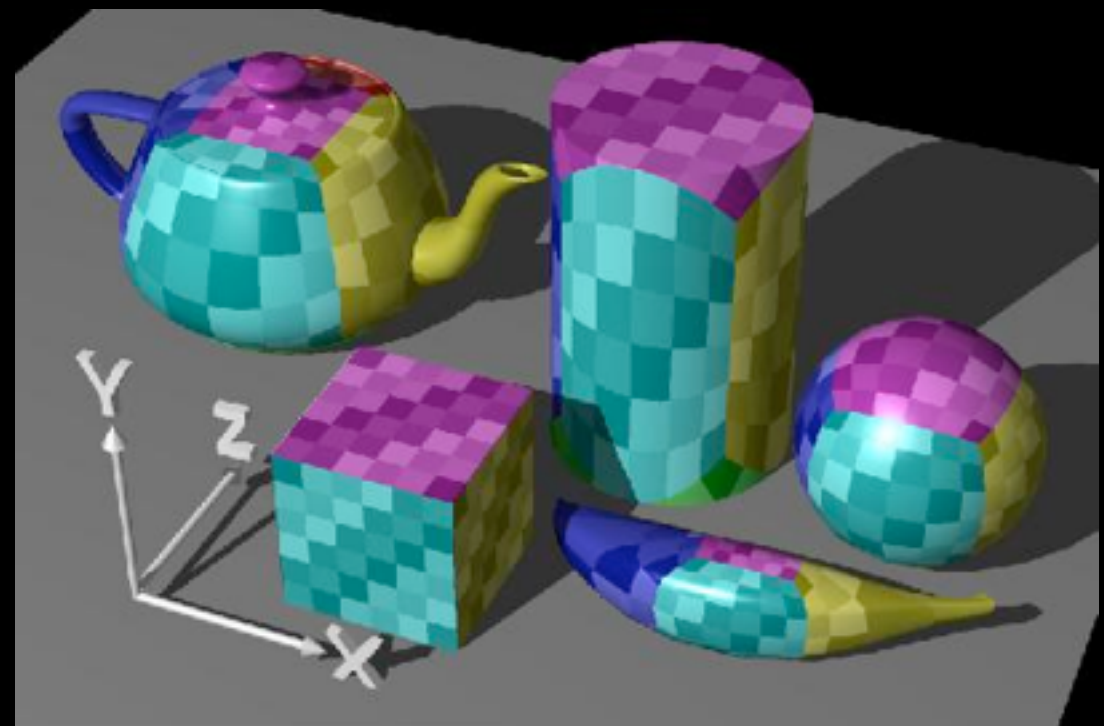
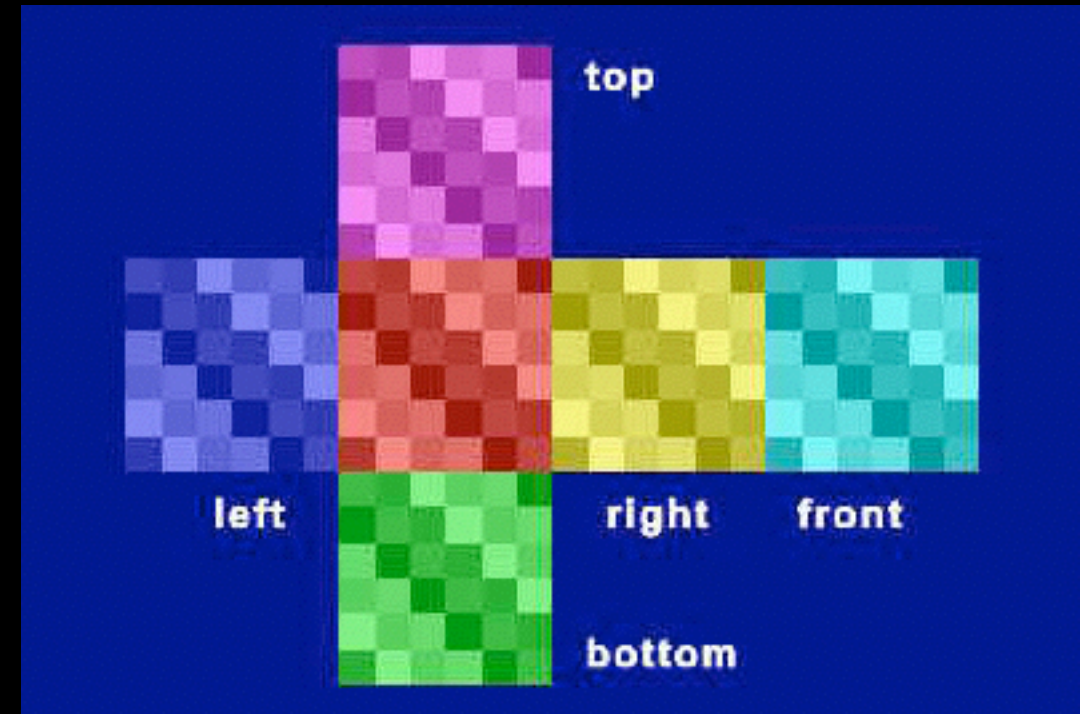
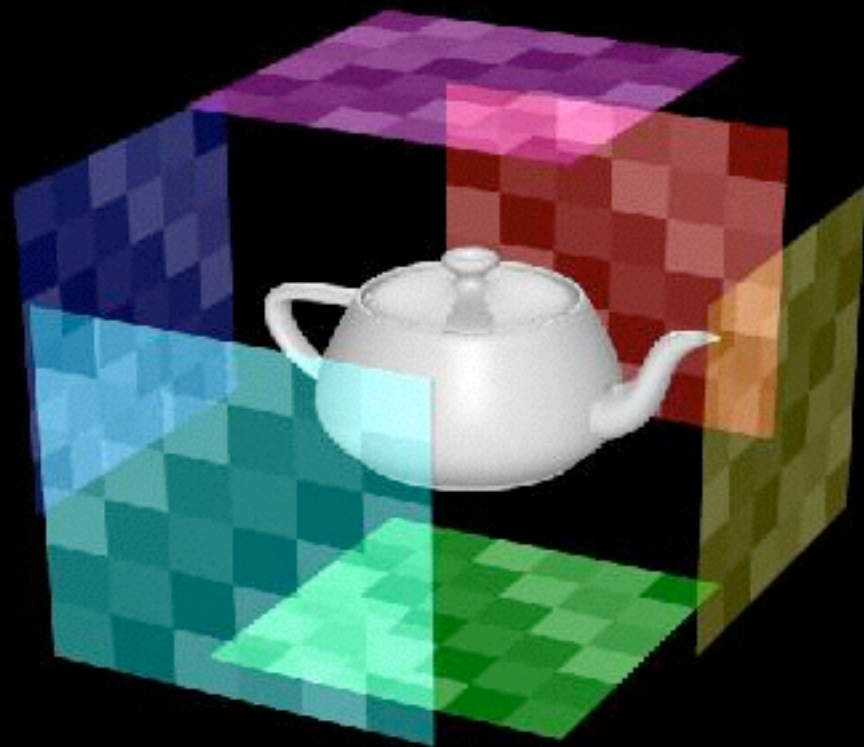
# Spherical Mapping

$(x,y,z) \rightarrow (\text{latitude}, \text{longitude})$   
 $\rightarrow (u,v)$



# Box Mapping

[Rosalee Wolfe]





# How do we map between intermediate and actual objects?



**position**



**surface normal**



**from centroid**



**reflection**

# How do we map between intermediate and actual objects?

[Rosalee Wolfe]



position



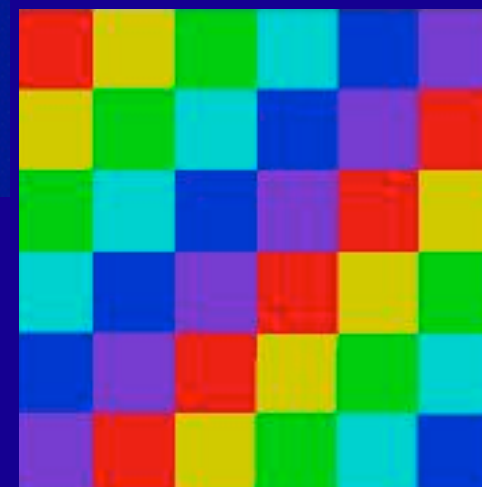
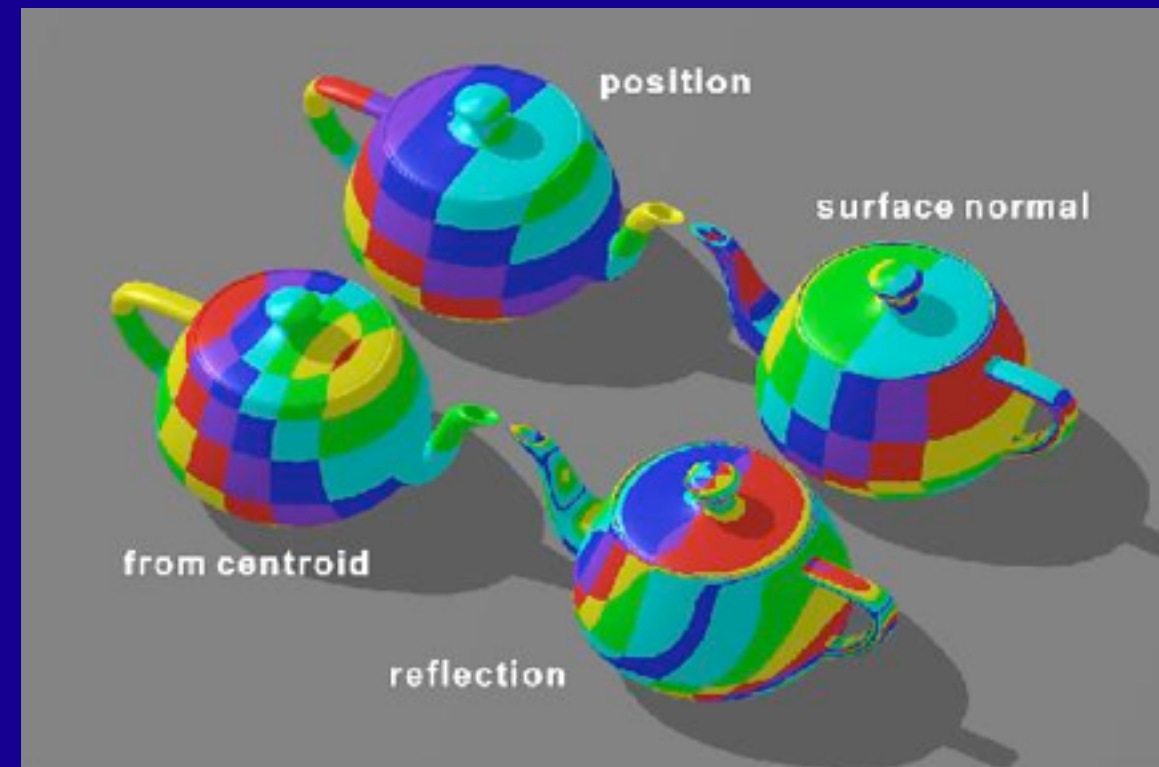
surface normal



from centroid

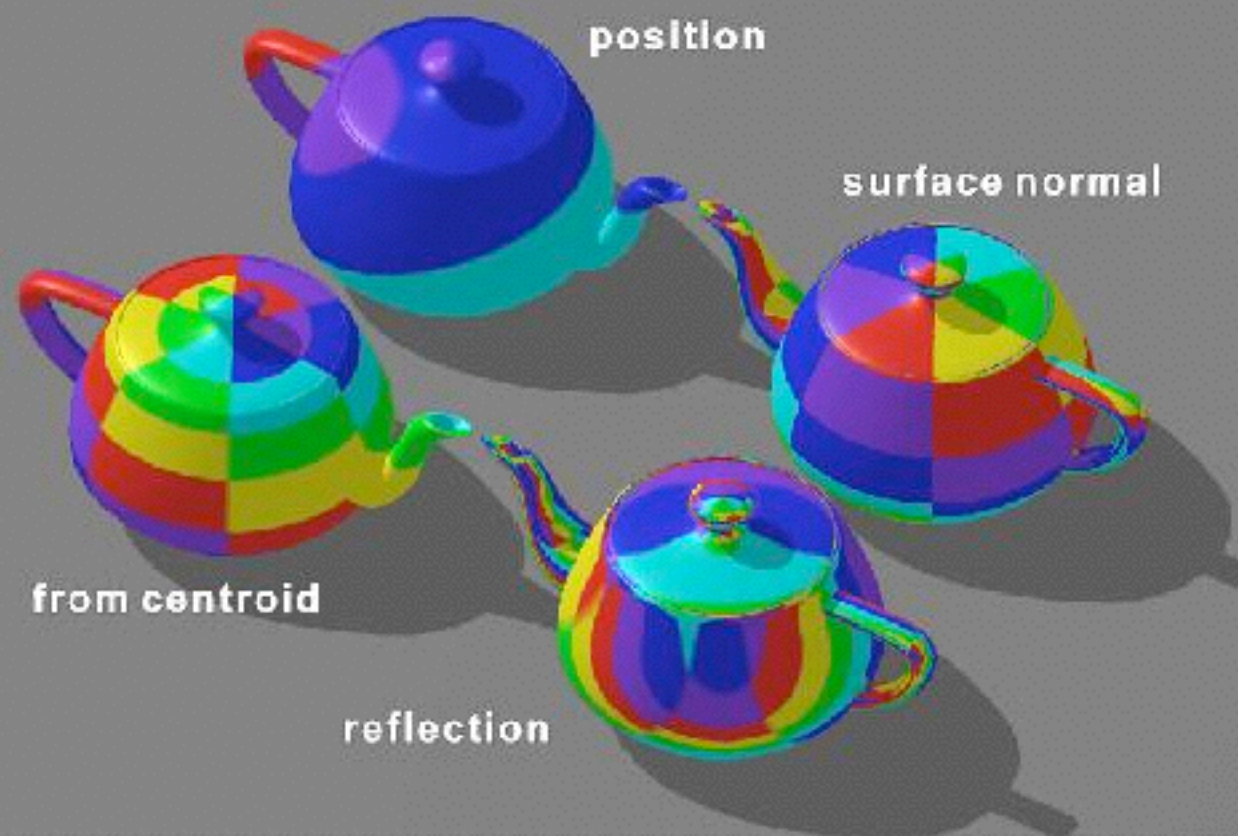


reflection

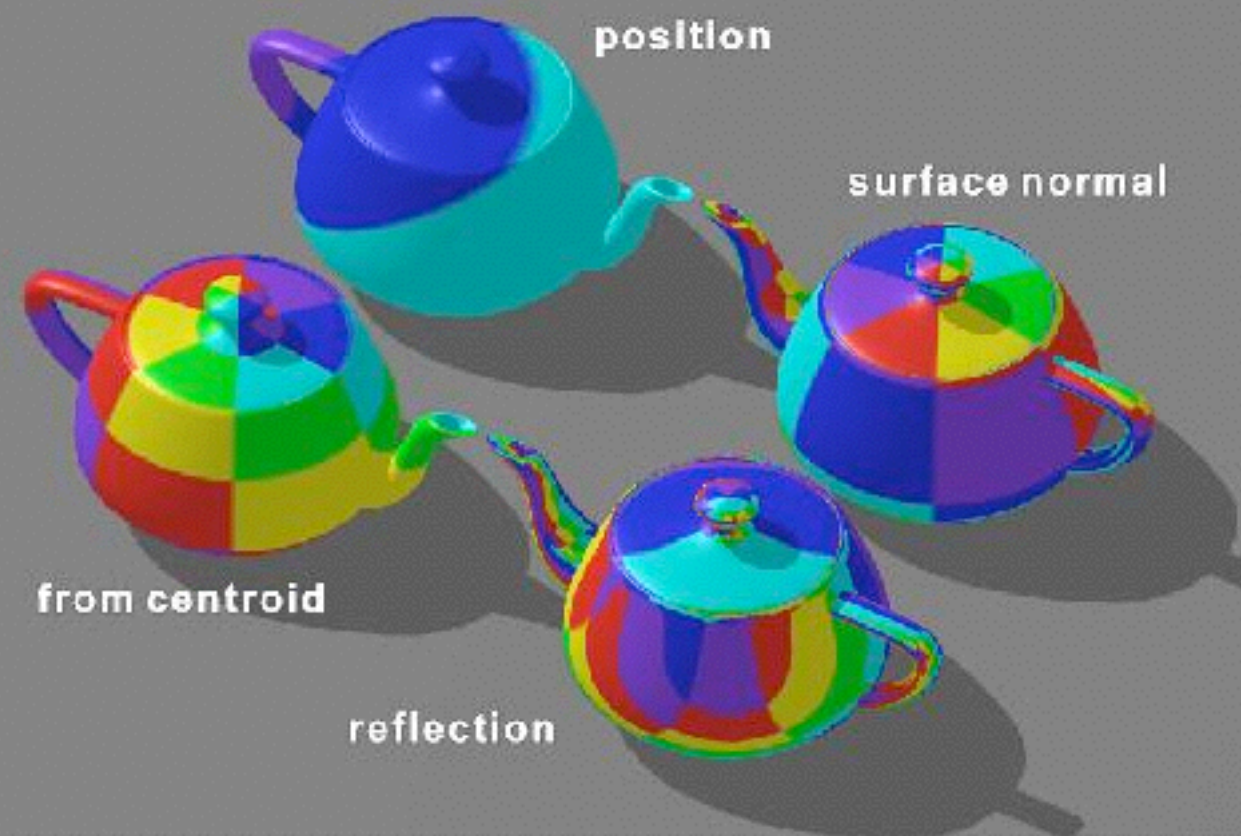


What intermediate shape was used here?



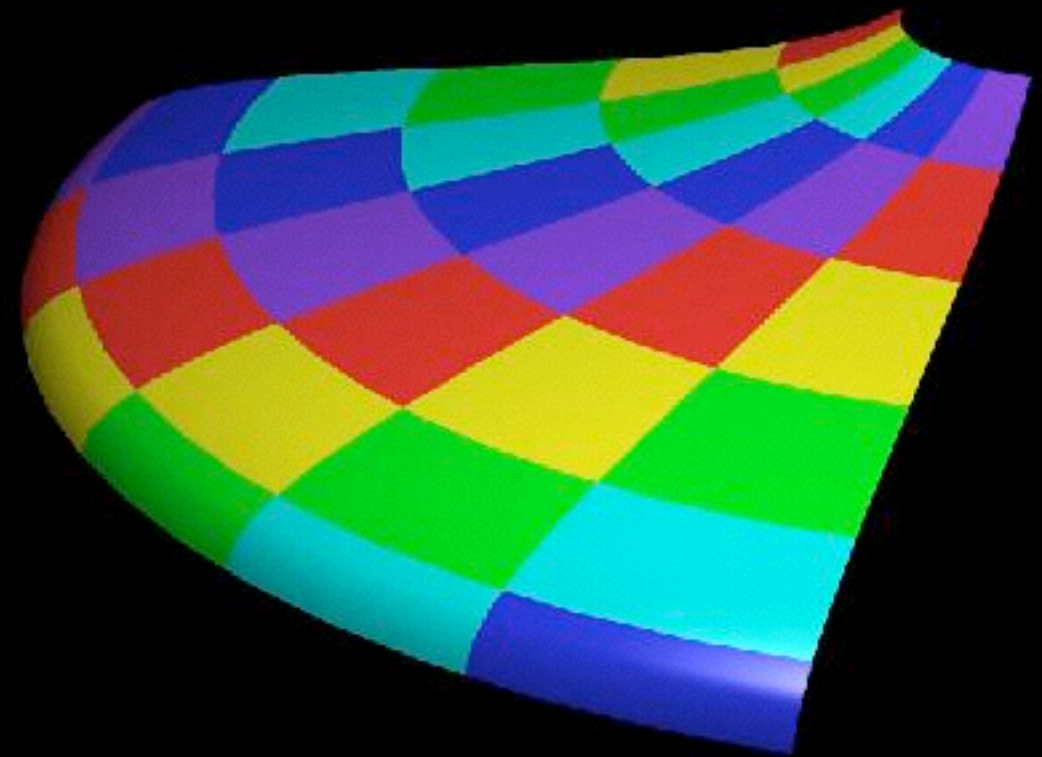
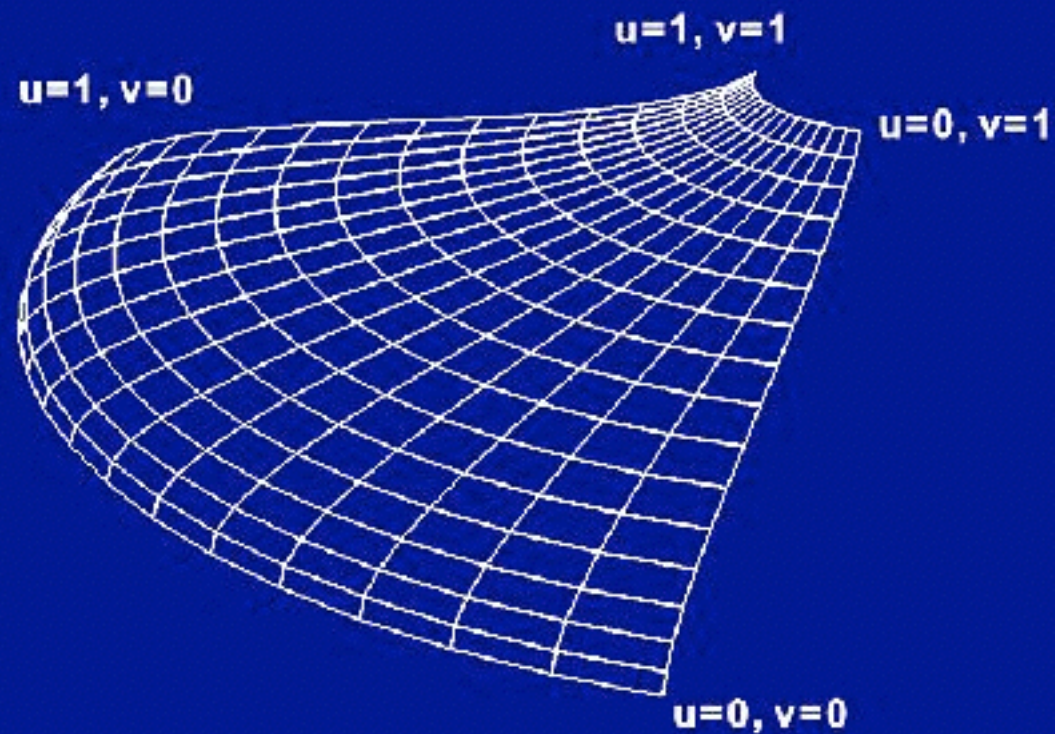


Cylindrical

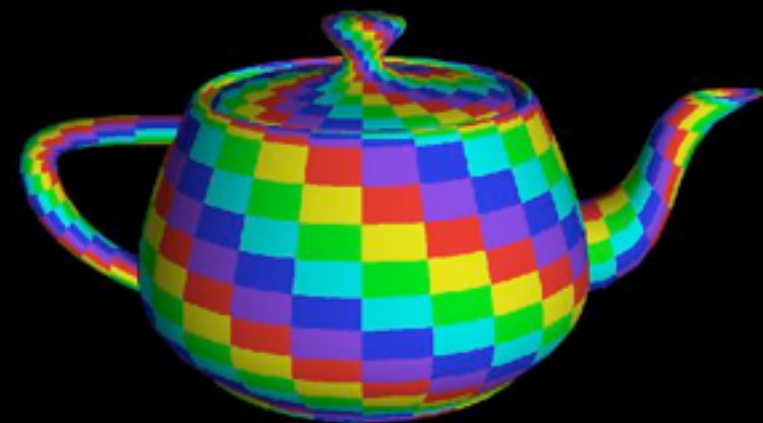


Spherical

# Parametric Surfaces



32 parametric patches





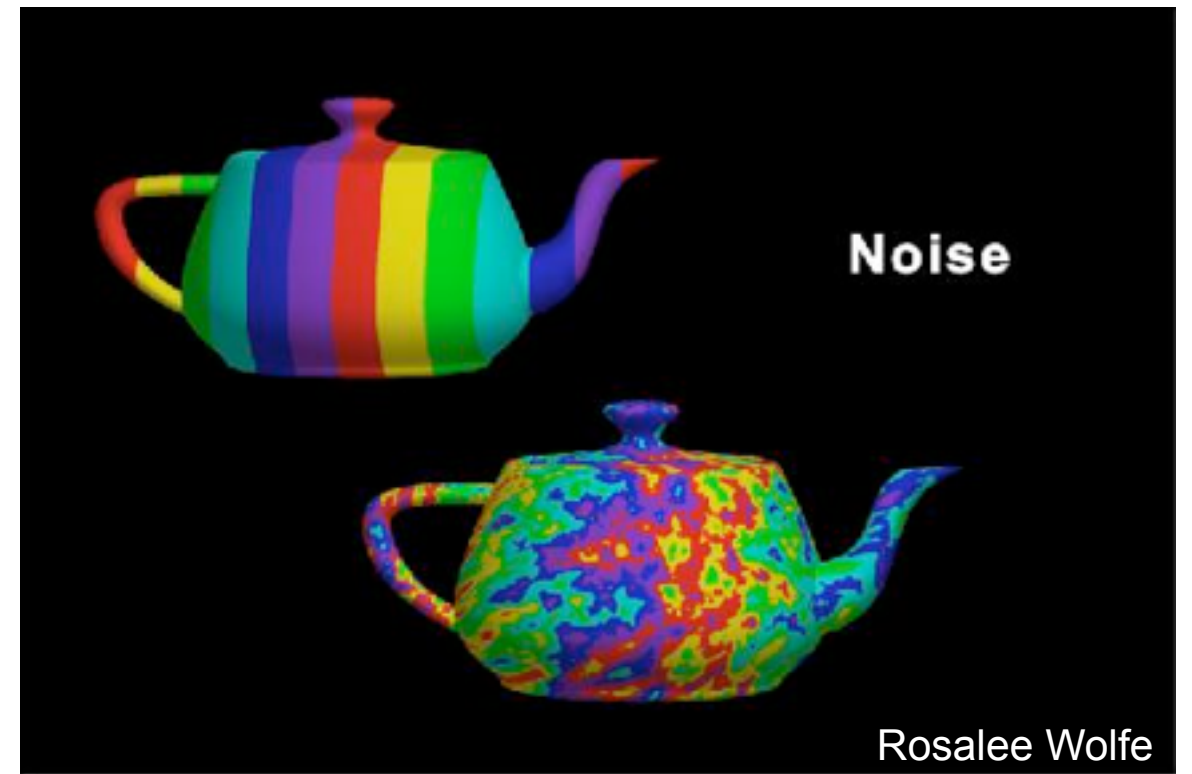
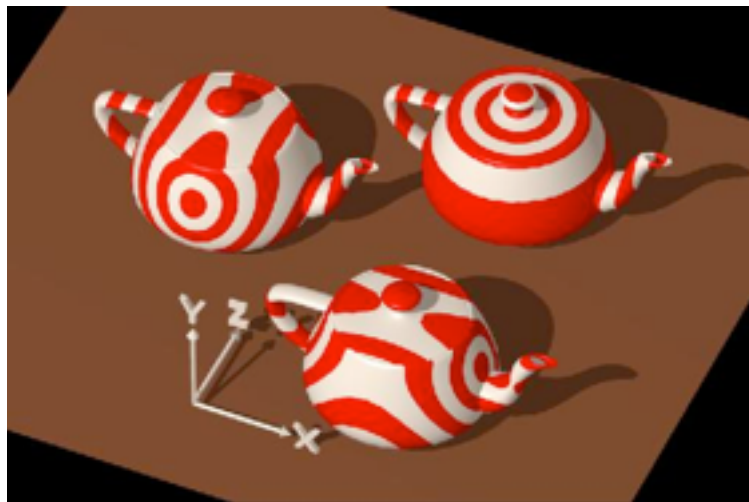
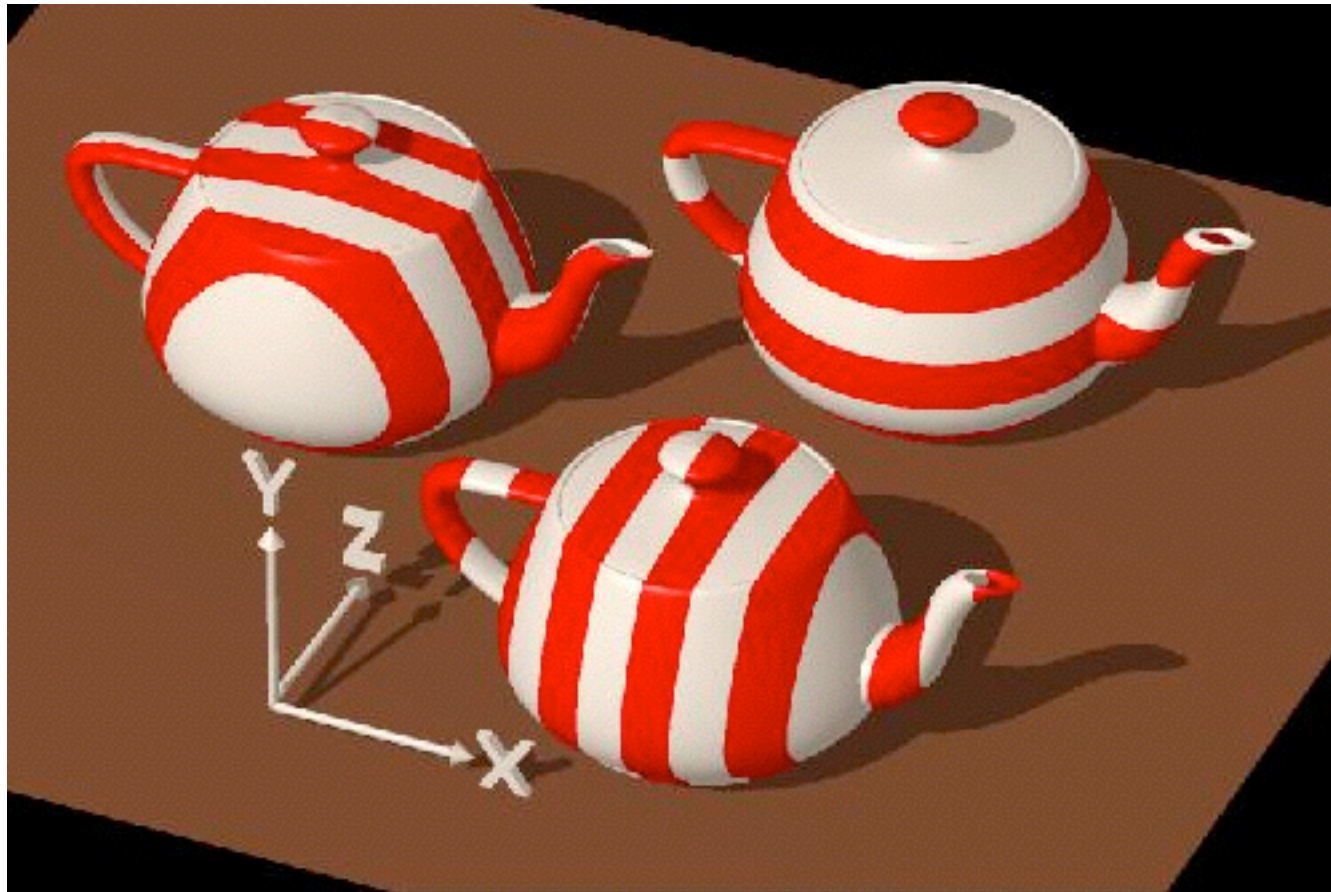
# 3D solid textures



[Dong et al., 2008]

can map object  $(x,y,z)$  directly to texture  $(u,v,w)$

# Procedural textures



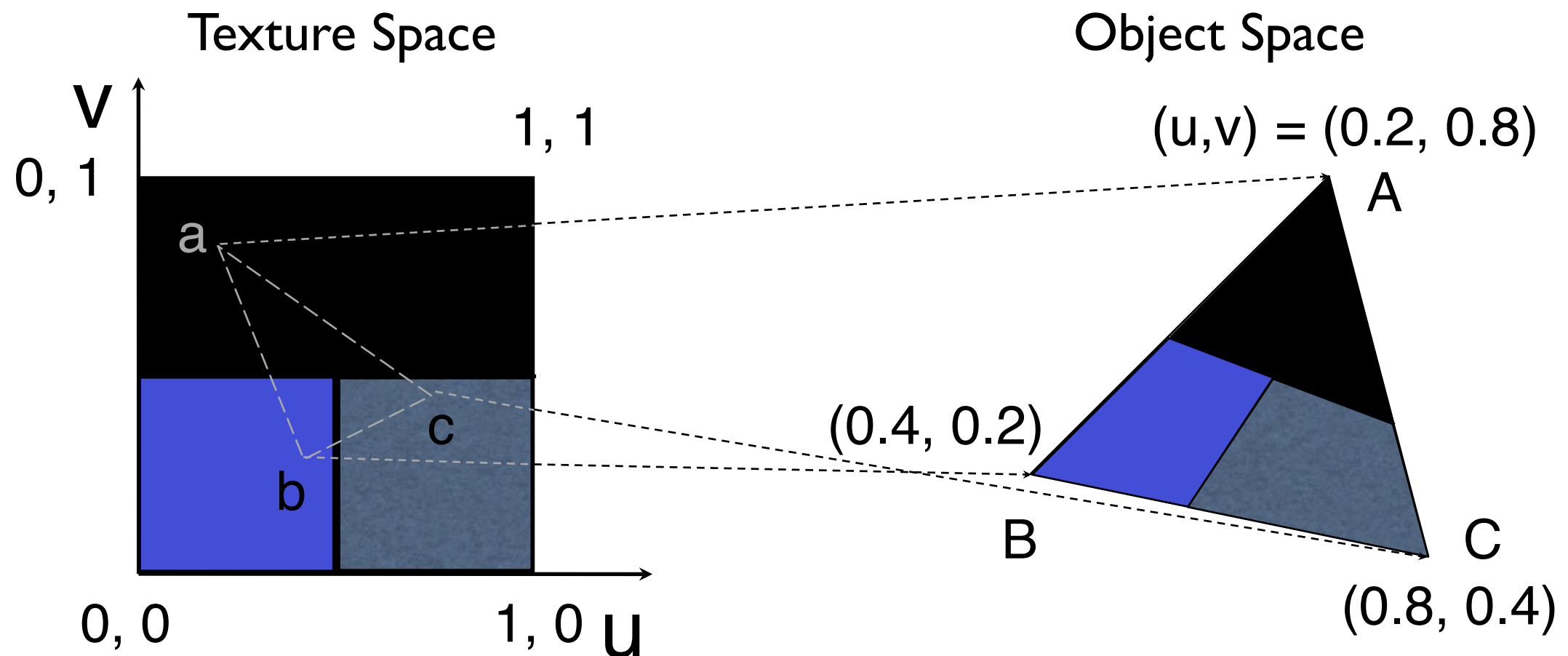
e.g., Perlin noise



# Triangles

# Texturing triangles

- Store  $(u,v)$  at each vertex
- interpolate inside triangles using barycentric coordinates





# Texturing triangles

- Store (u,v) at each vertex
- interpolate inside triangles using barycentric coordinates

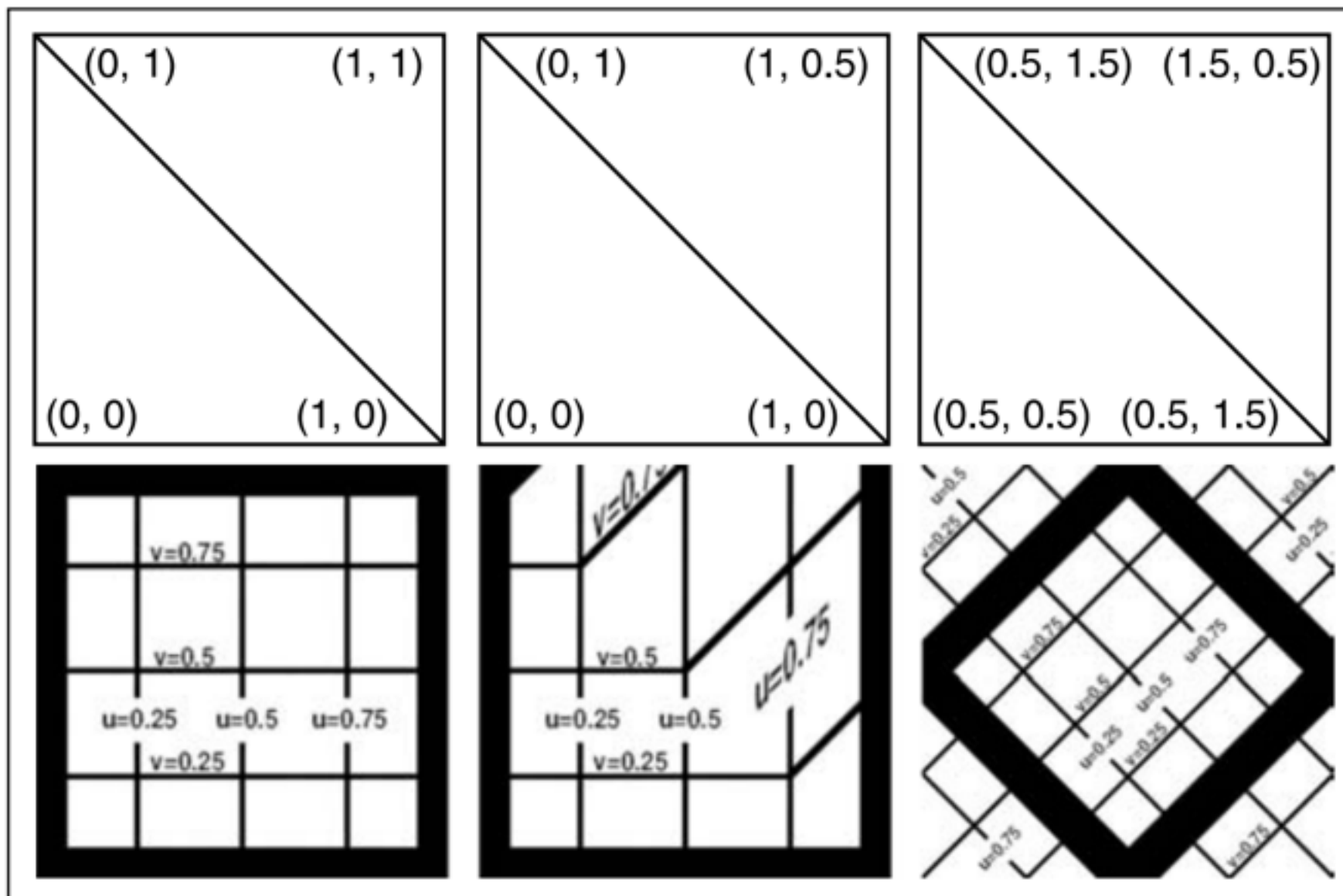
$$\mathbf{p}(\beta, \gamma) = \mathbf{a} + \beta(\mathbf{b} - \mathbf{a}) + \gamma(\mathbf{c} - \mathbf{a}).$$

$$u(\beta, \gamma) = u_a + \beta(u_b - u_a) + \gamma(u_c - u_a),$$

$$v(\beta, \gamma) = v_a + \beta(v_b - v_a) + \gamma(v_c - v_a).$$

# Texturing triangles

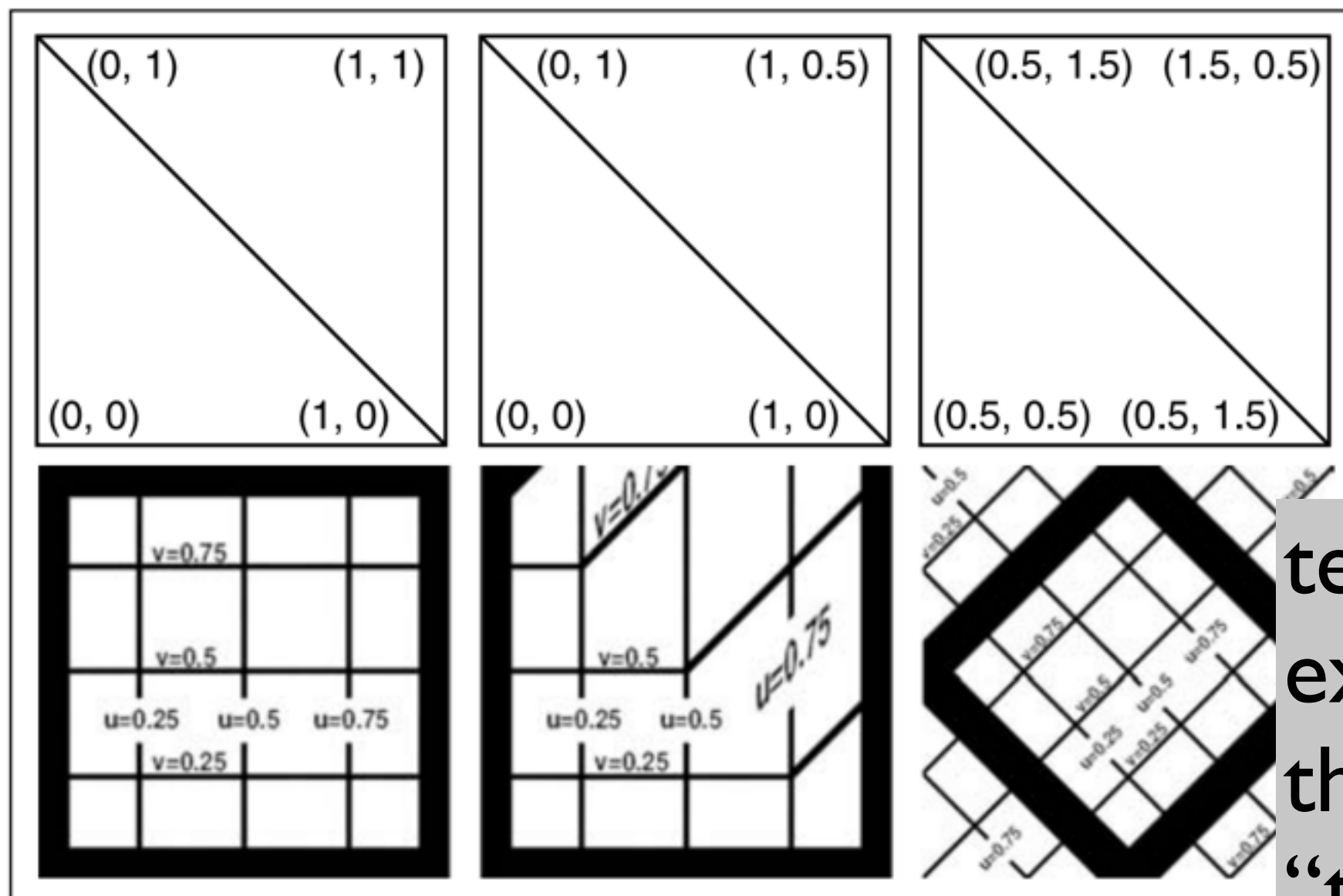
Choice of  $(u,v)$  makes big difference





# Texturing triangles

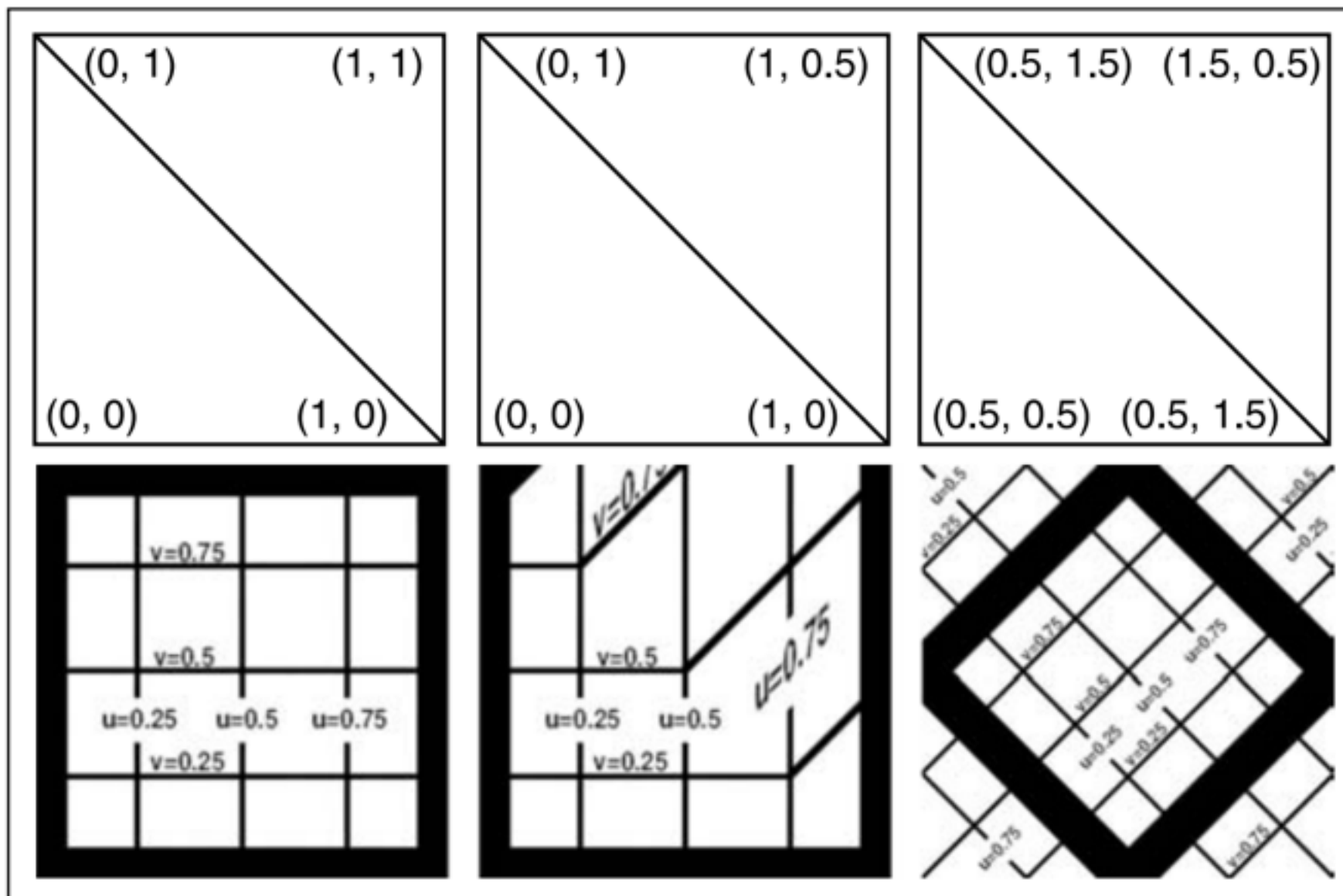
Choice of  $(u,v)$  makes big difference



texture  
extended  
through  
“tiling”

# Texturing triangles

Choice of  $(u,v)$  makes big difference

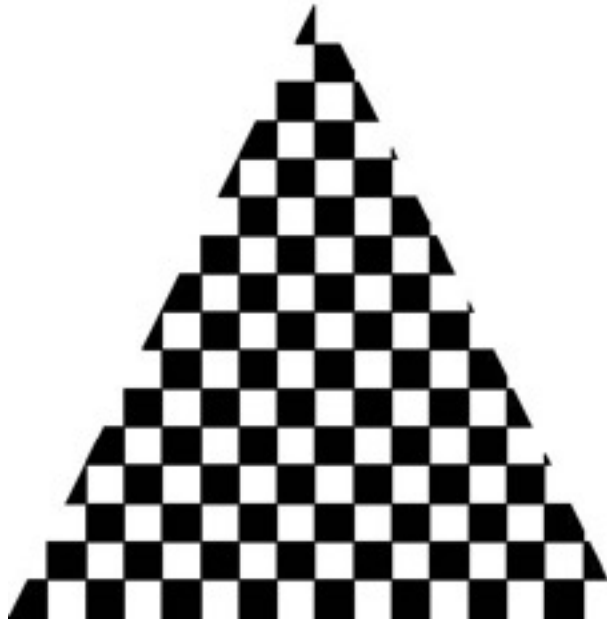




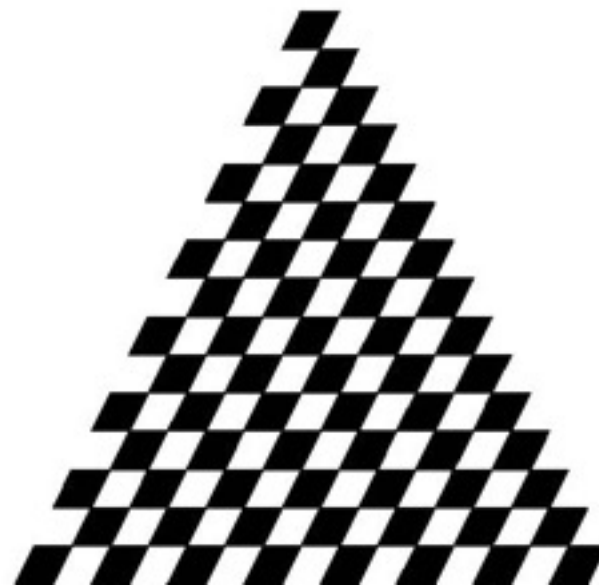
# Textures in OpenGL

```
glTexCoord* ()
```

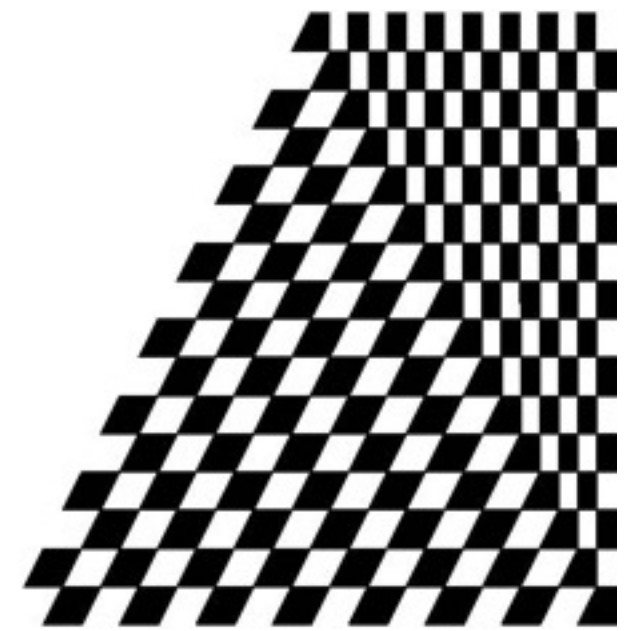
- Assign (u,v) to vertices
- OpenGL then uses interpolation for triangle interior



good selection  
of tex coordinates

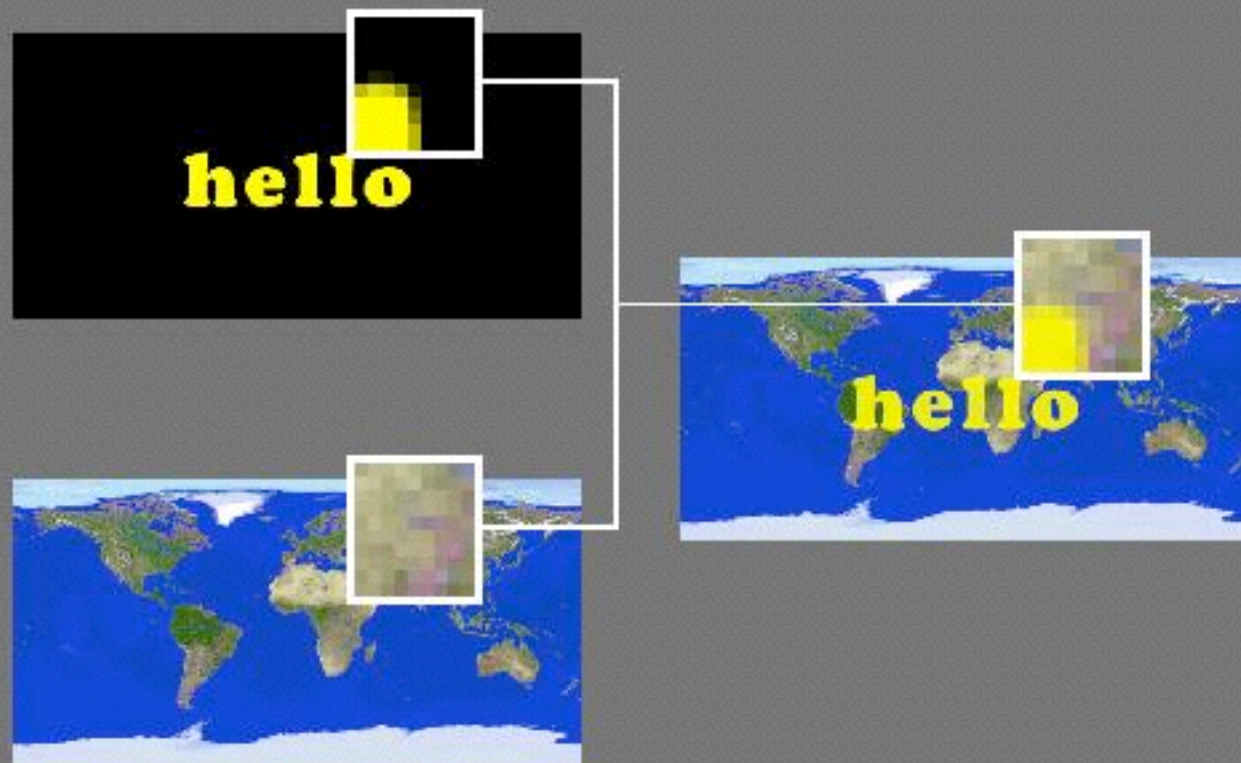
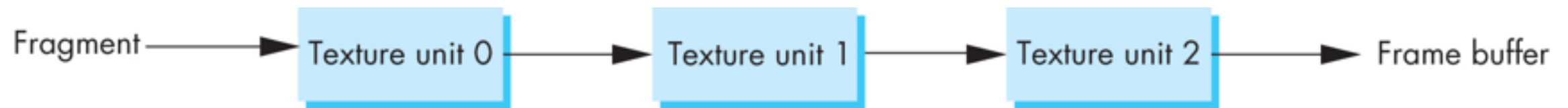


poor selection  
of tex coordinates



texture stretched  
over trapezoid  
showing effects of  
bilinear interpolation

# Multitexturing

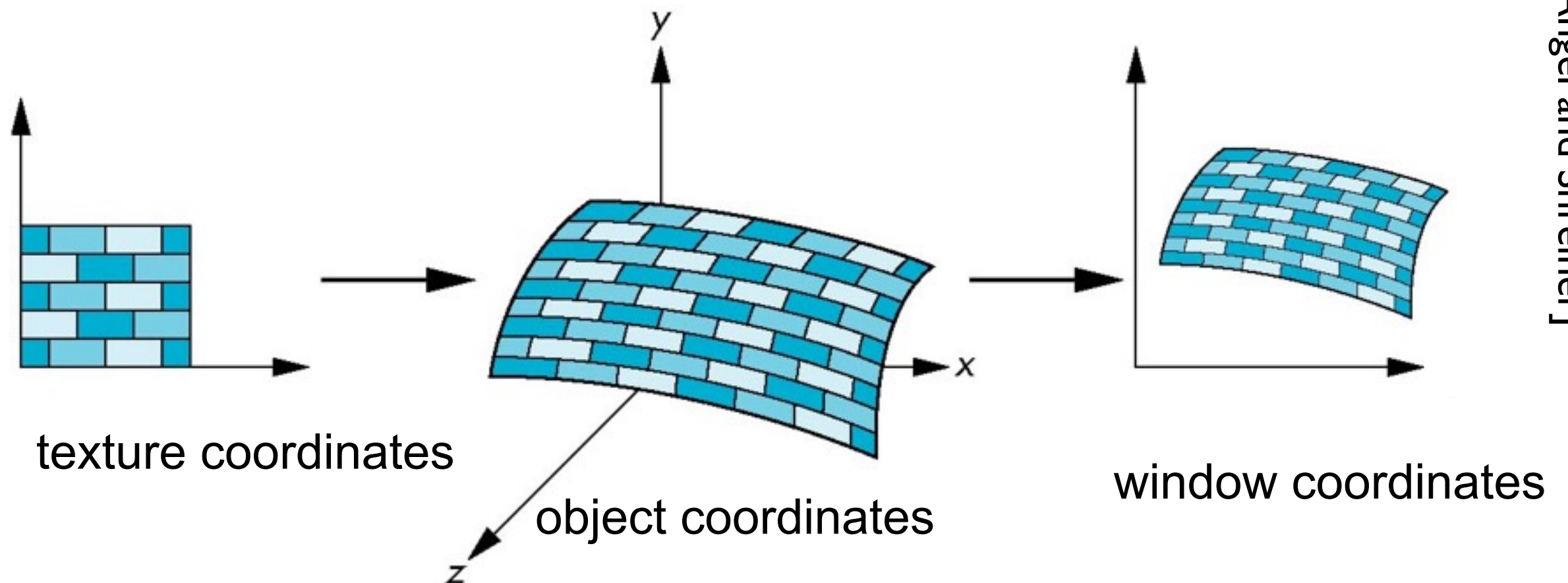
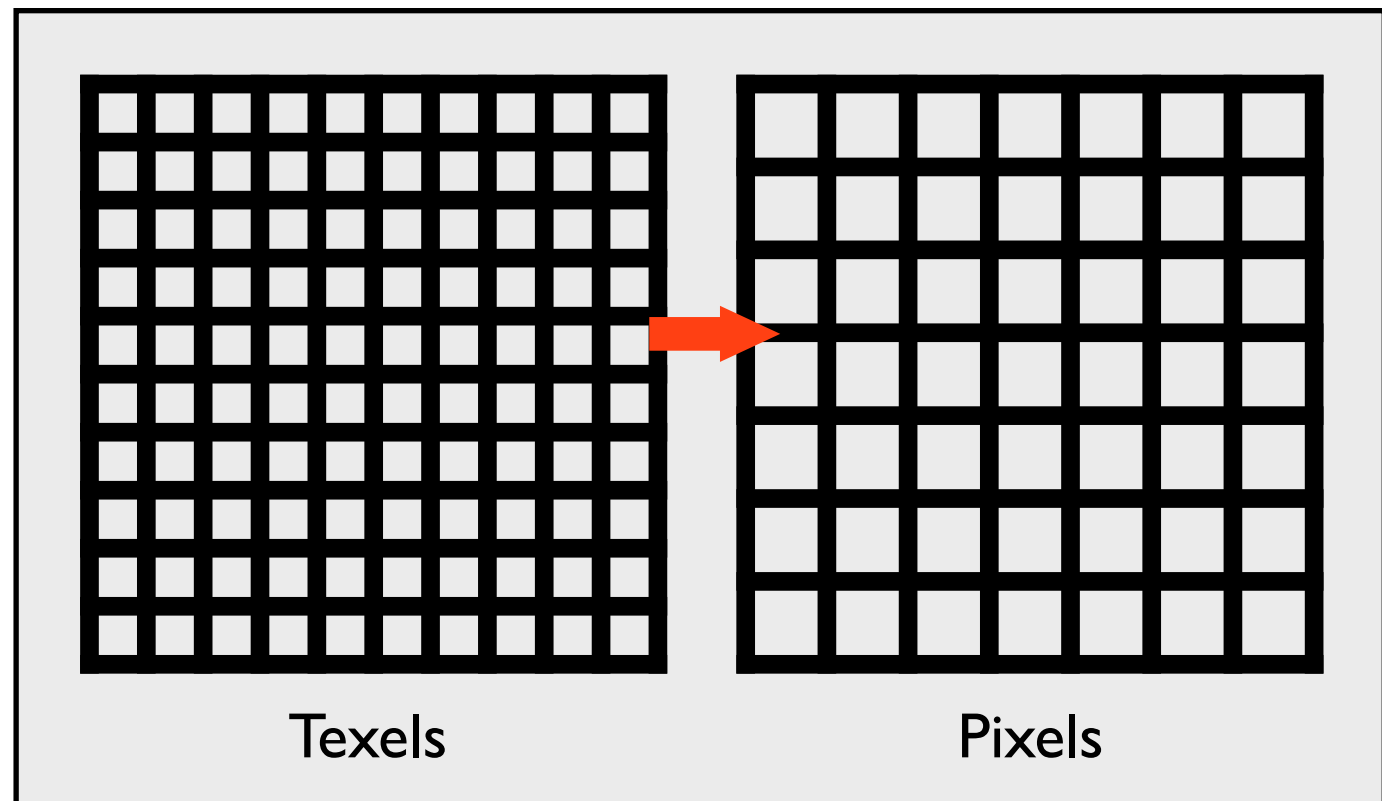


Rosalee Wolfe



# Texture Sampling

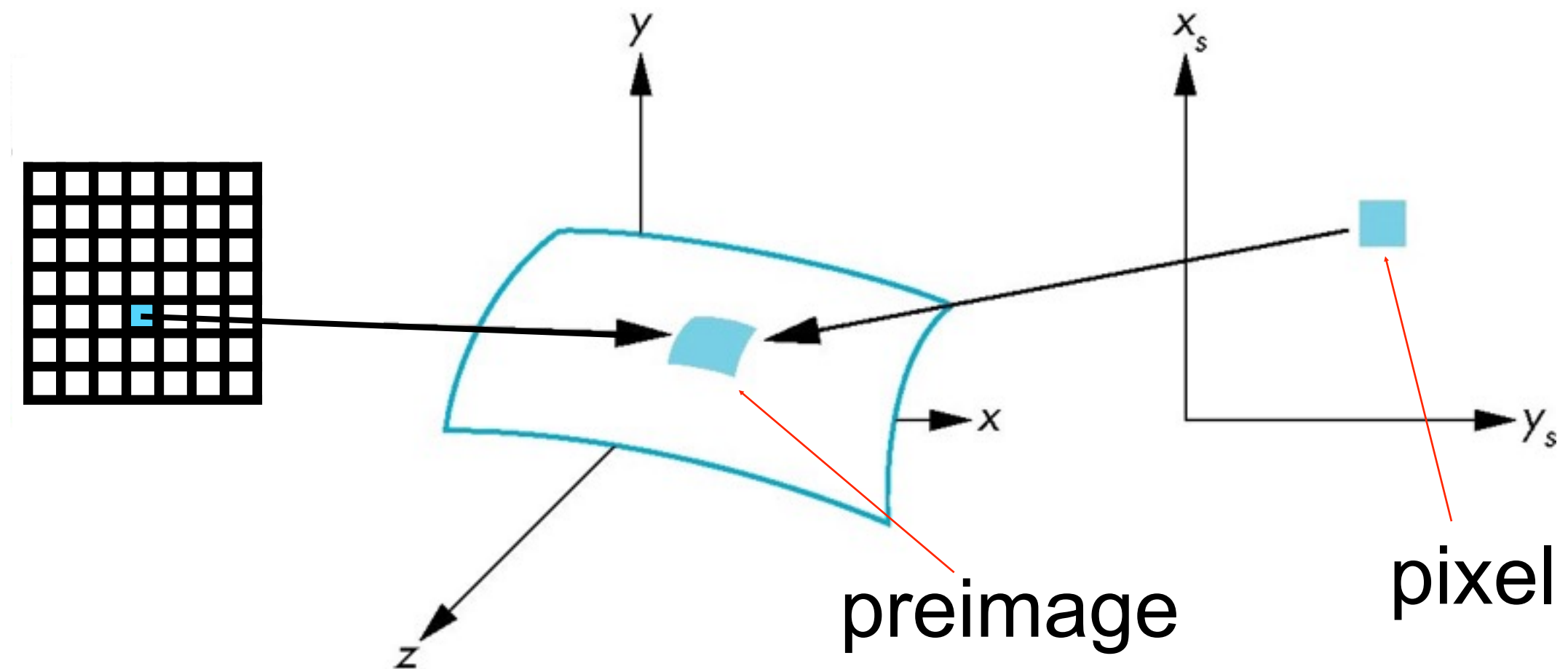
# Texture Mapping



[Angel and Shreiner]

# Point Sampling

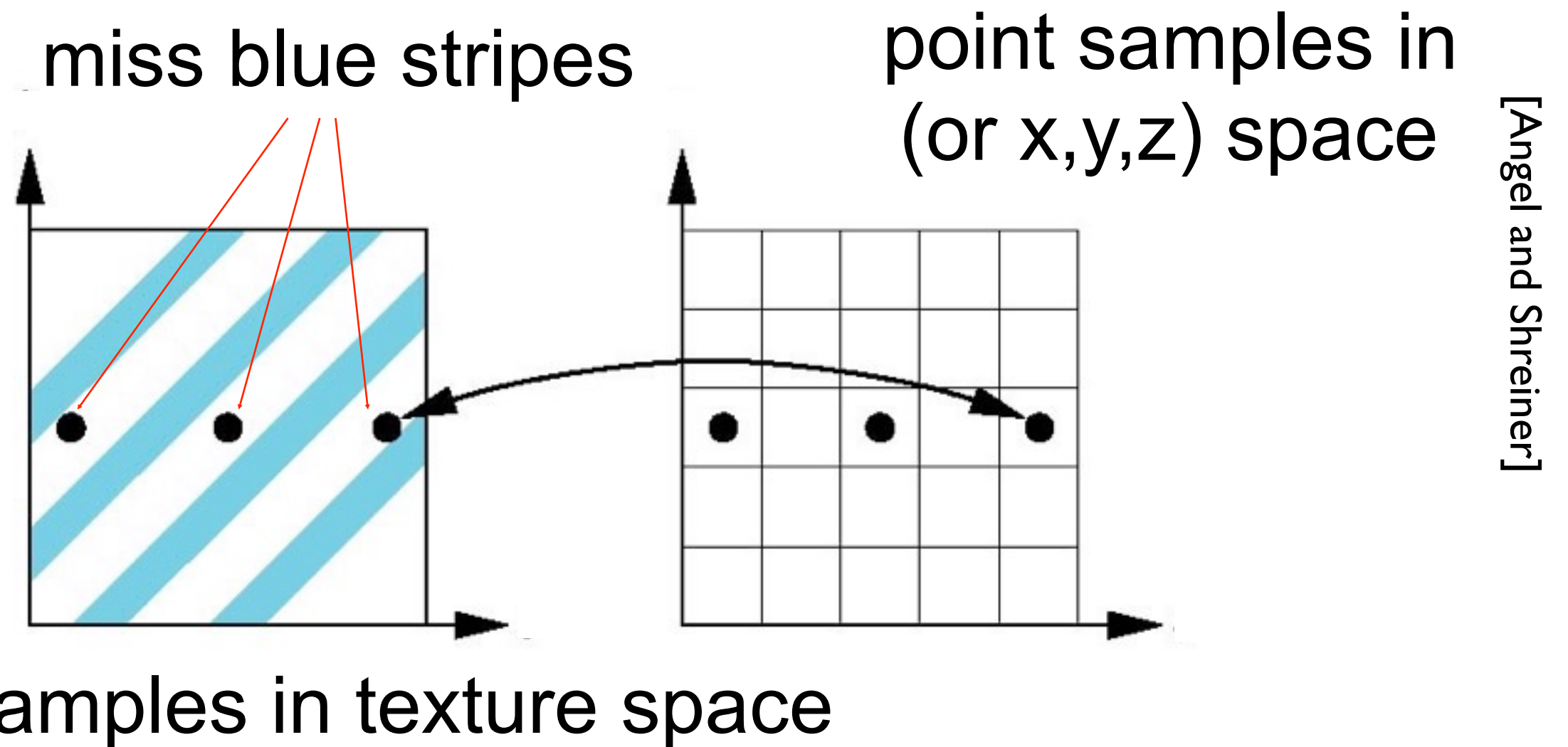
Map back to texture image and use the nearest texel





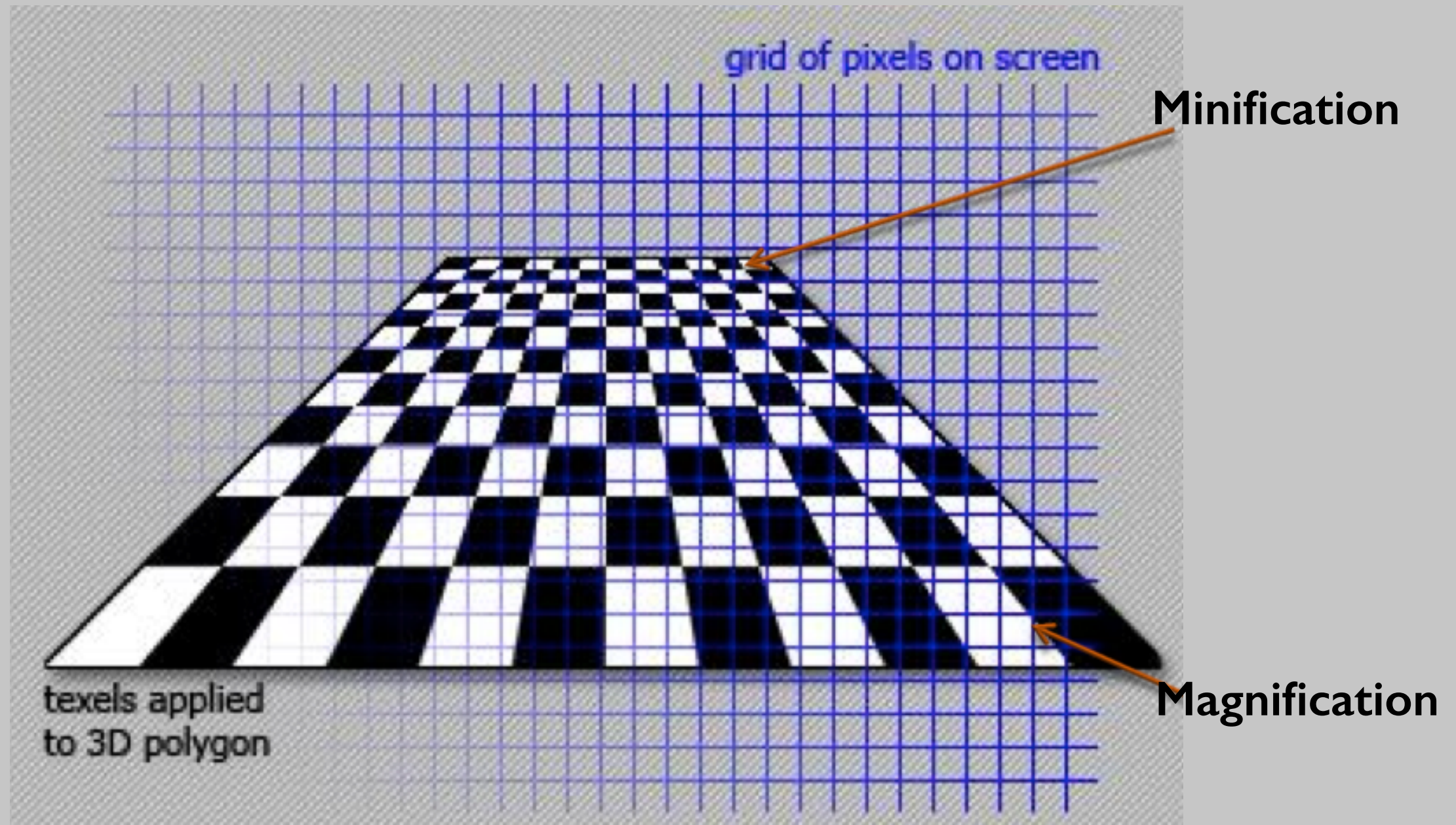
# Aliasing

**Point sampling** of the texture can lead to aliasing artifacts



[Angel and Shreiner]

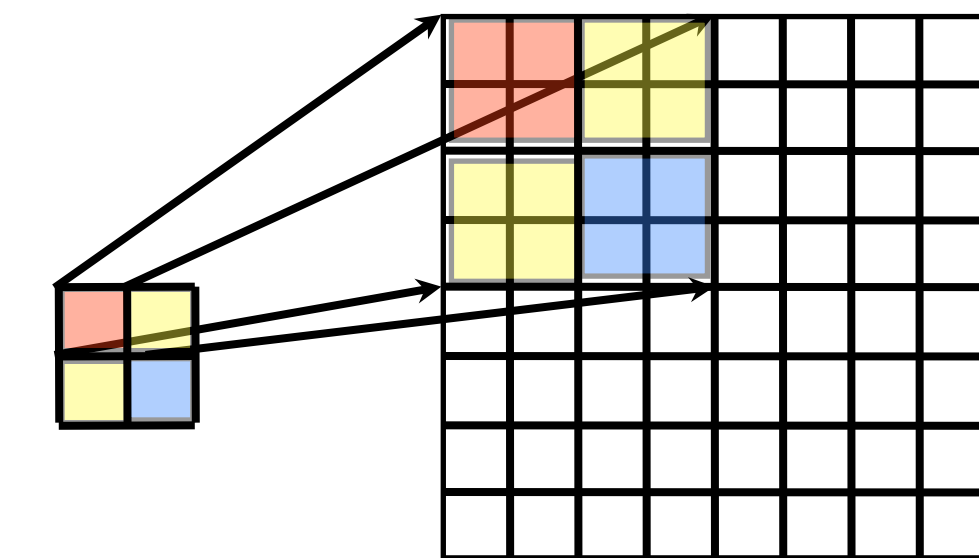
# Magnification and Minification



# Magnification and Minification

More than one texel can cover a pixel (*minification*) or more than one pixel can cover a texel (*magnification*)

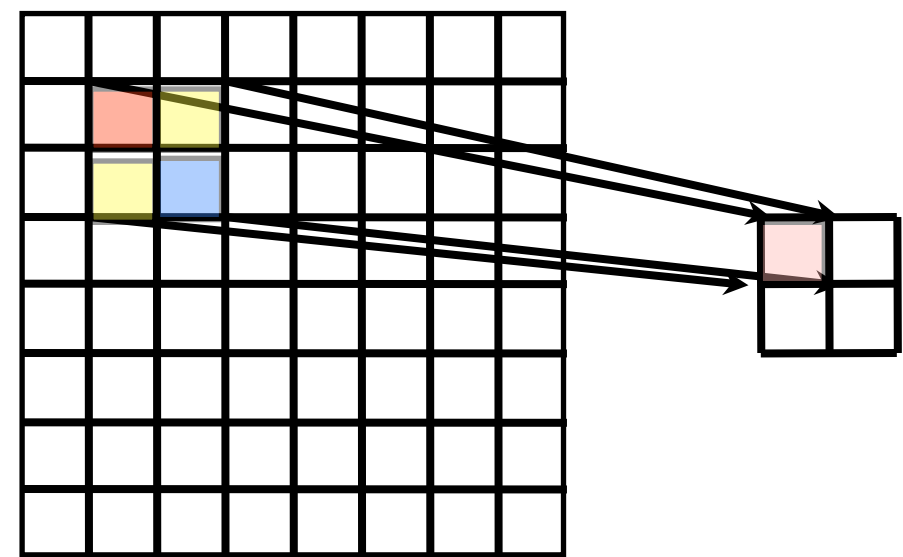
Can use point sampling (nearest texel) or linear filtering (2 x 2 filter) to obtain texture values



Texture

Pixels

**Magnification**



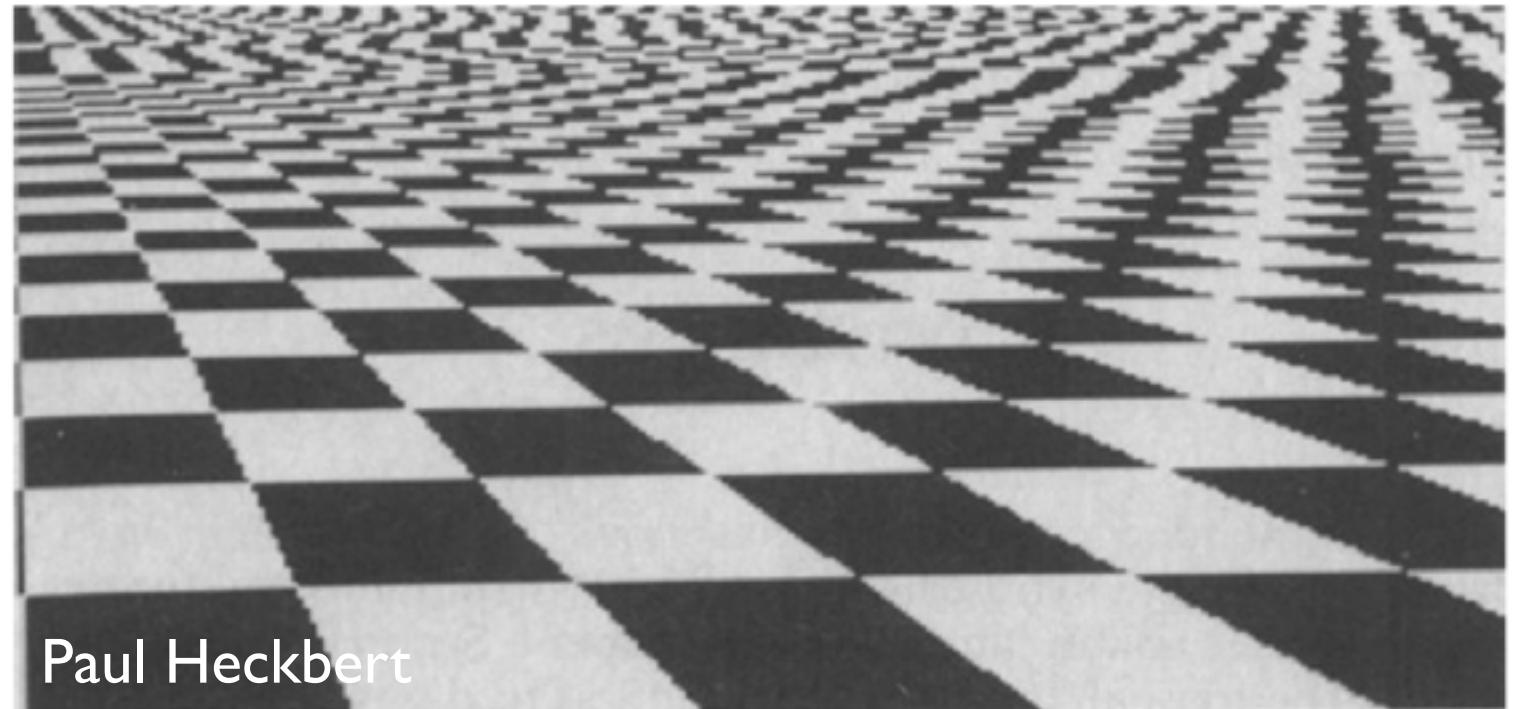
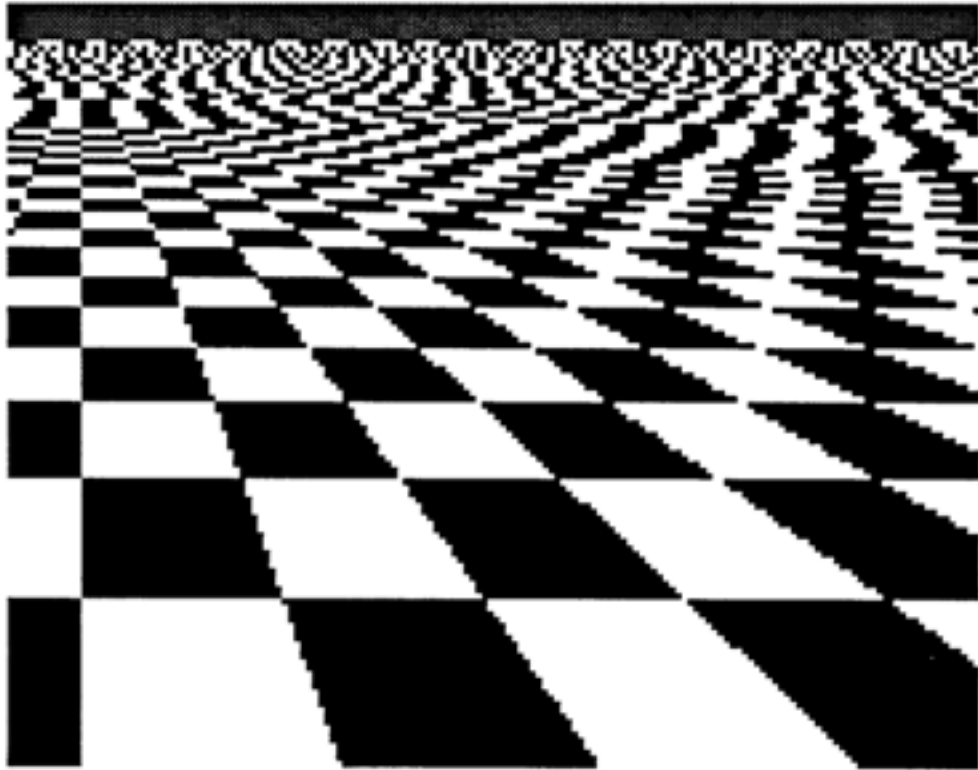
Texture

Pixels

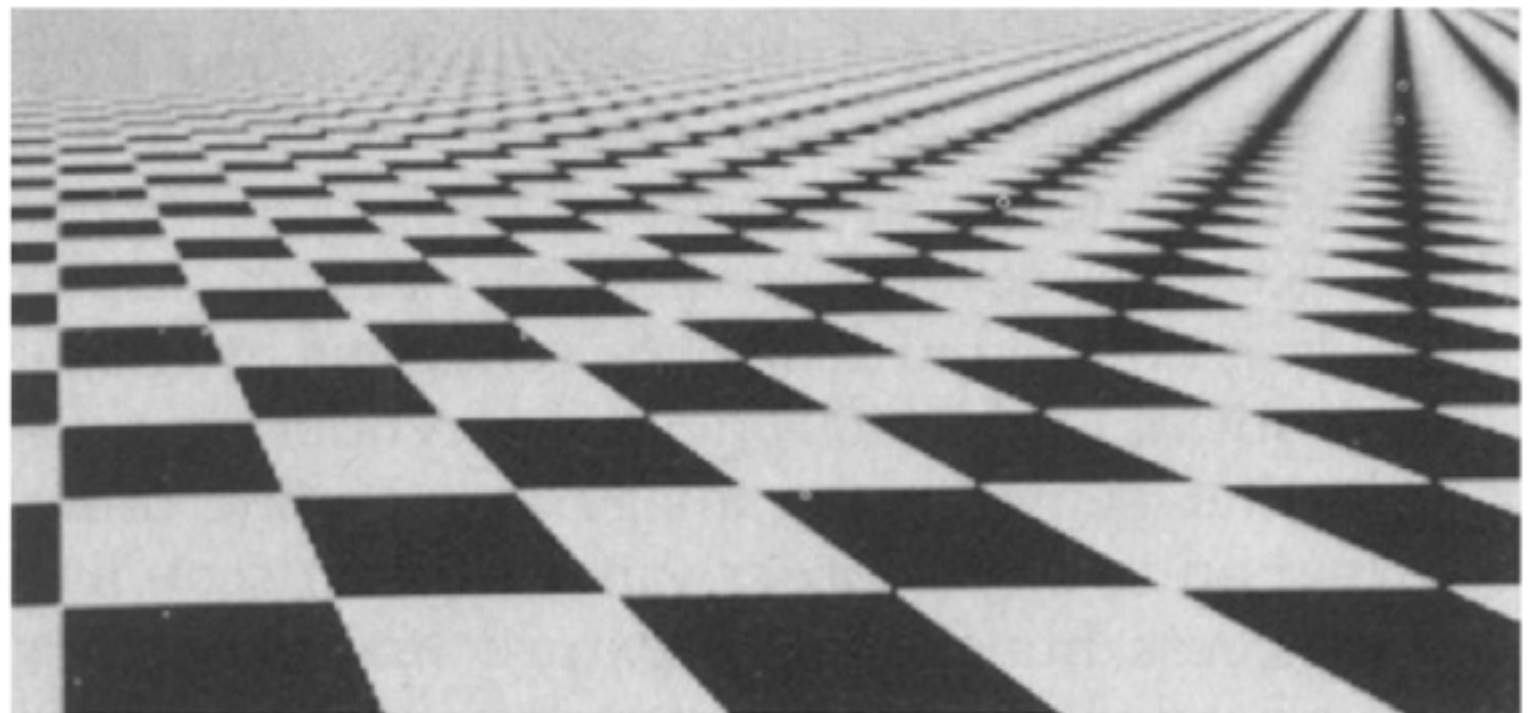
**Minification**



# Aliasing artifacts

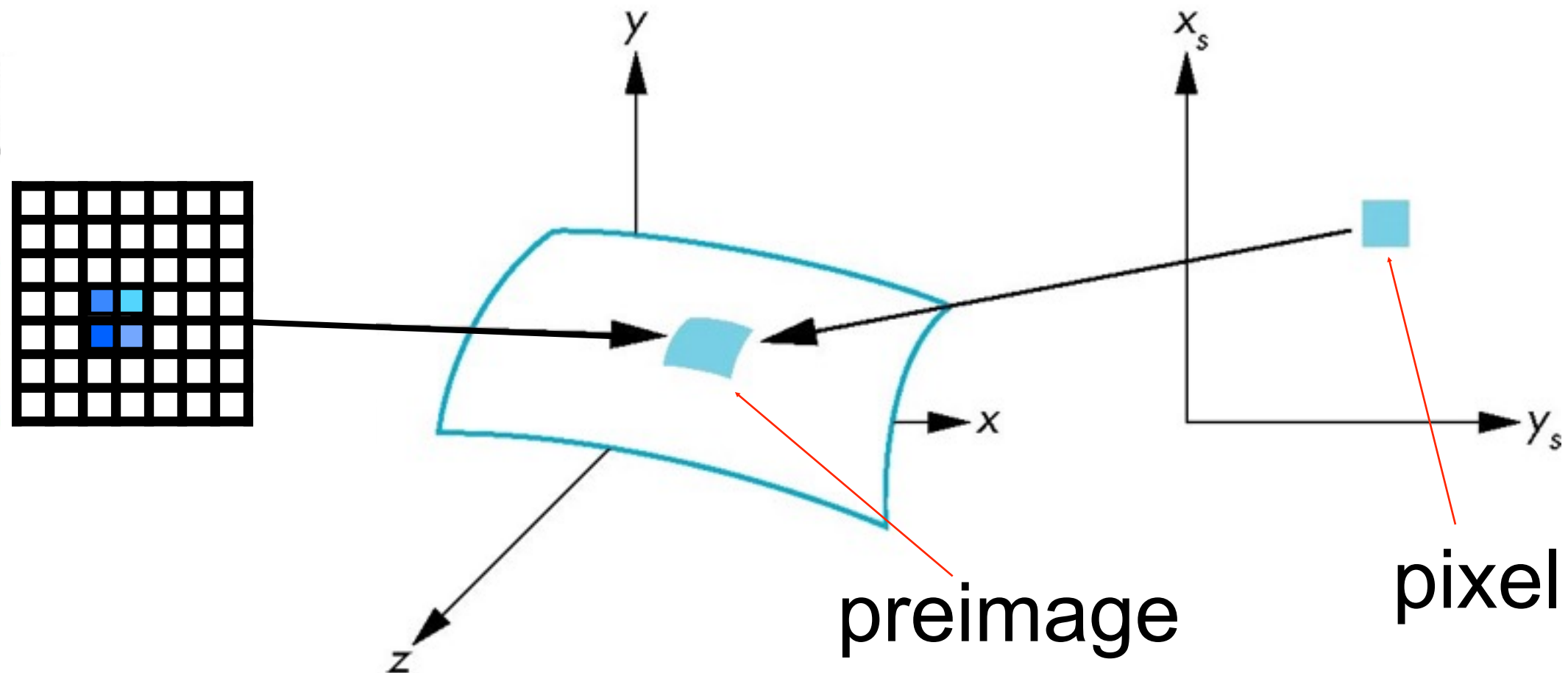


We apply **filtering** to  
reduce aliasing  
artifacts

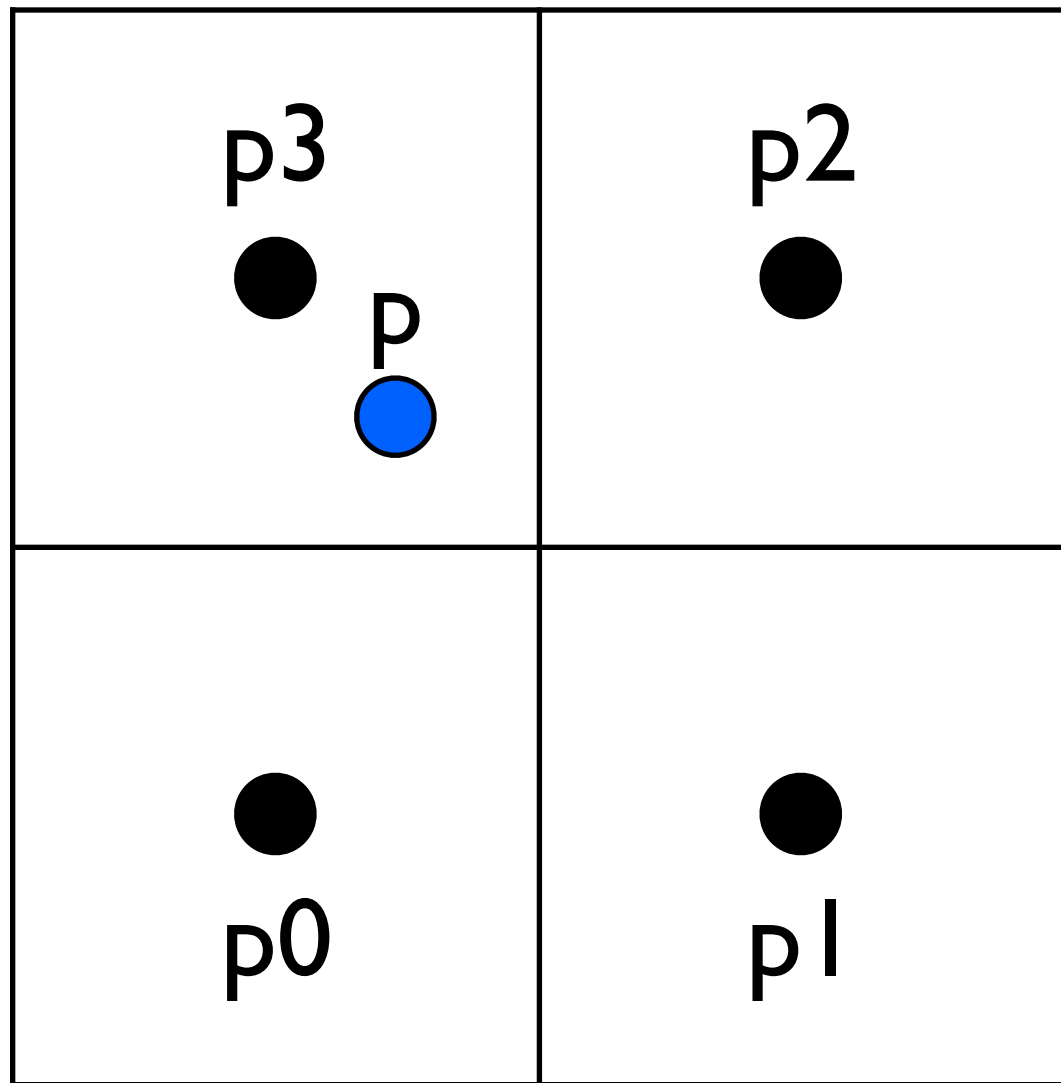


# Area Averaging

A better but slower option is to use **area averaging**



# Use bilinear filtering



$p = ?$



nearest  
neighbor



bilinear

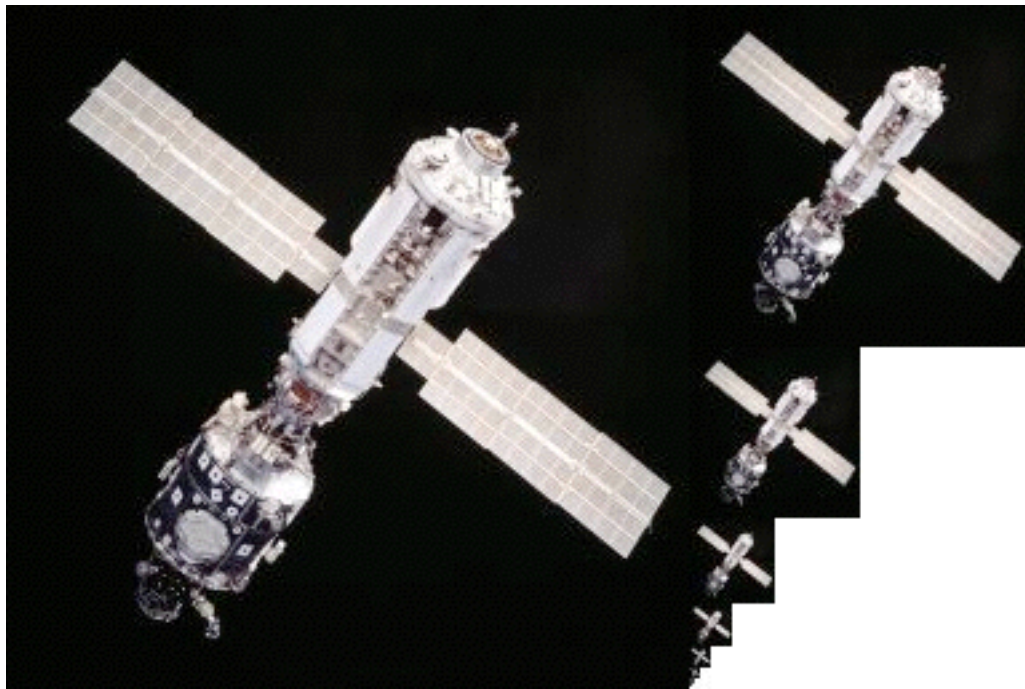


Wikipedia  
bicubic

mitigate magnification artifacts



# Mipmapping



Togikun, Wikimedia Commons

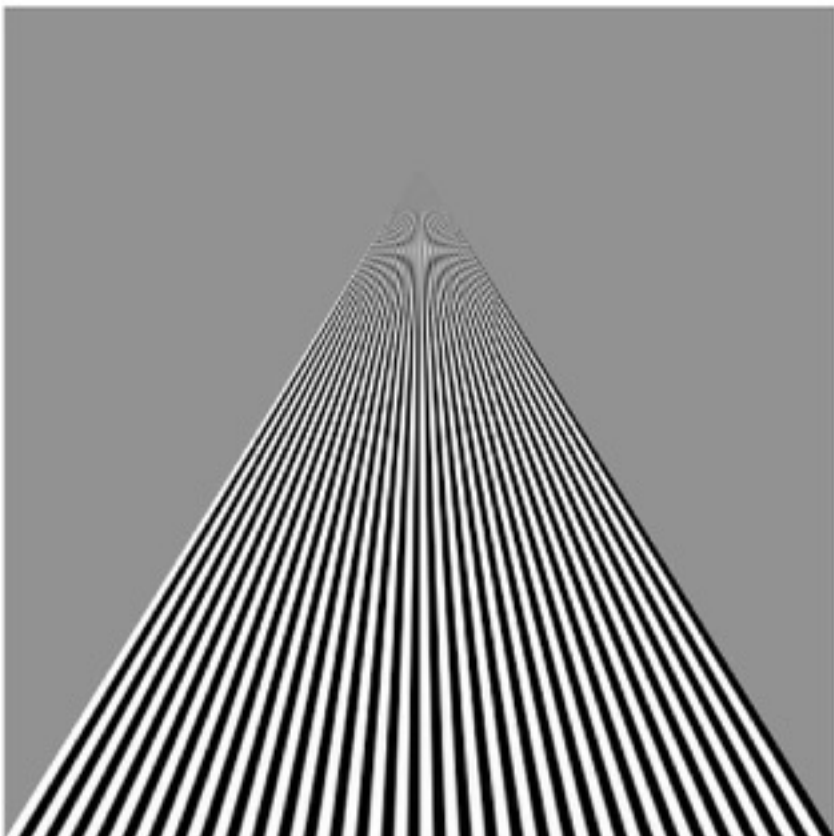
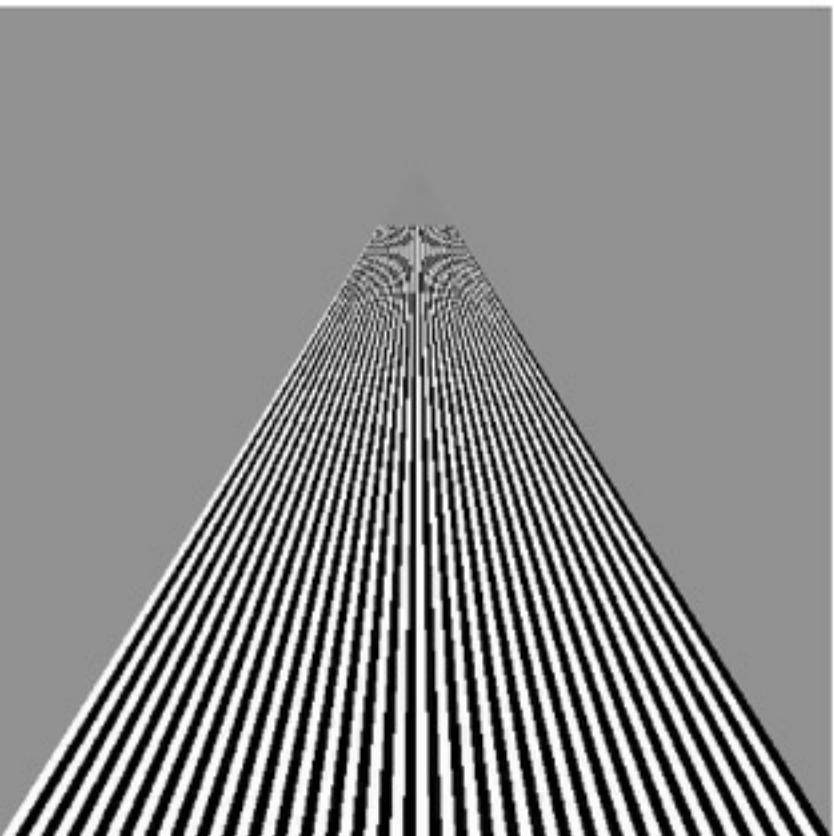
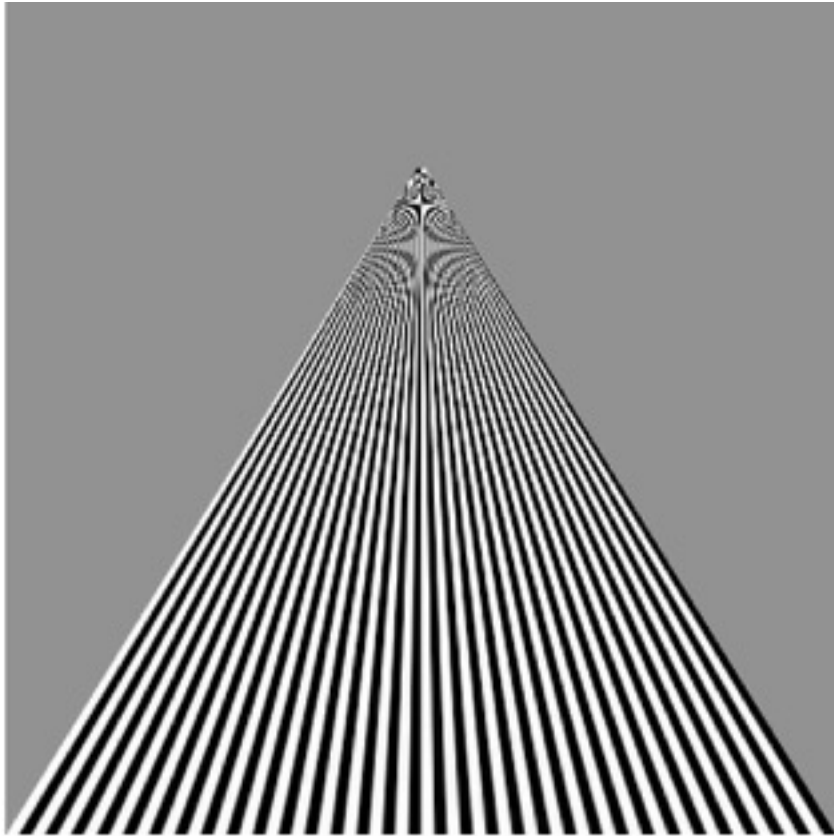
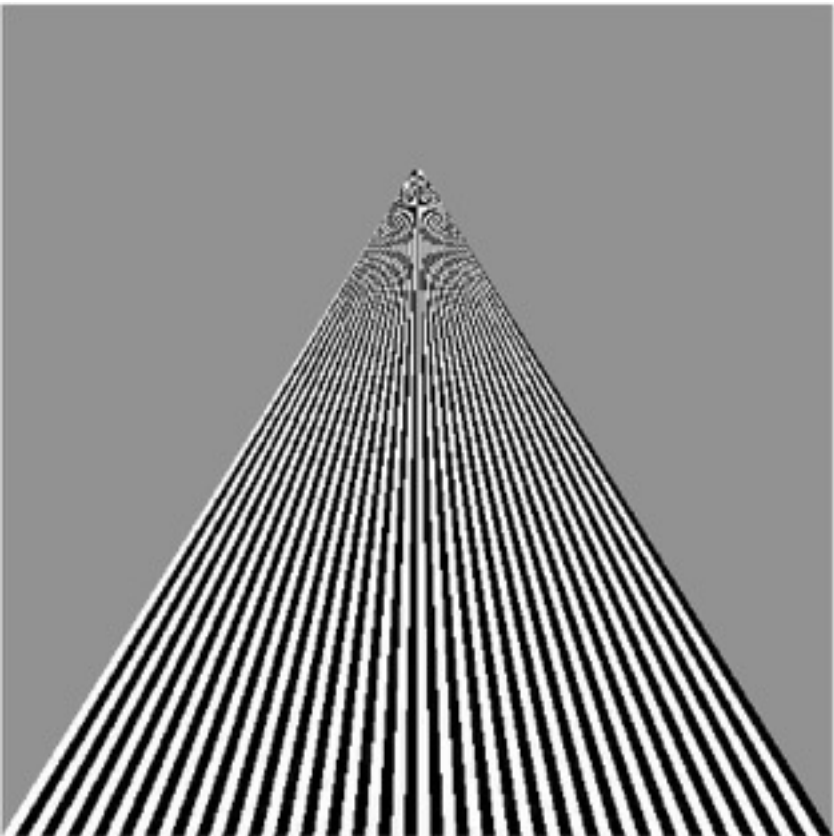
128×128, 64×64, 32×32, 16×16, 8×8, 4×4, 2×2, 1×1

Reduce minification artifacts

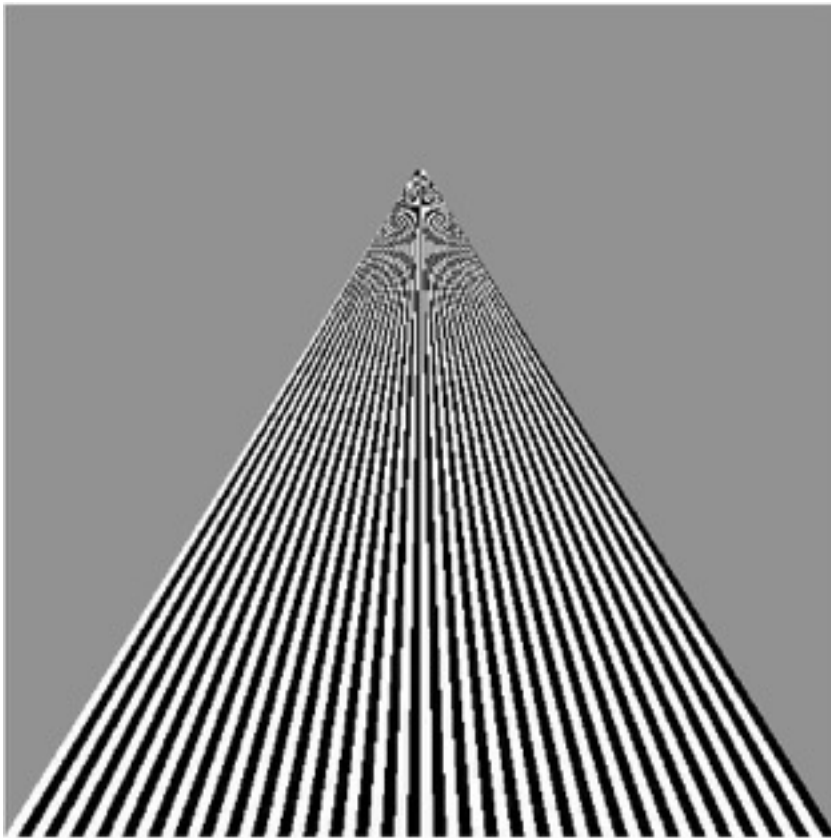
Prefilter the texture to obtain reduced resolutions

Requires 1/3 more space

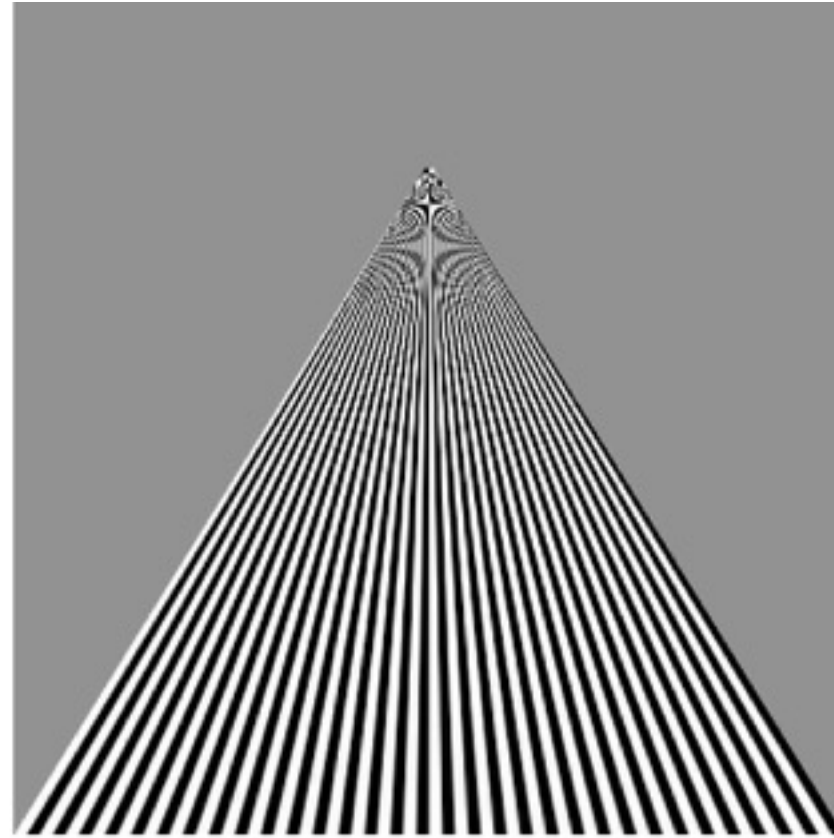
Get a texture hierarchy indexed by level



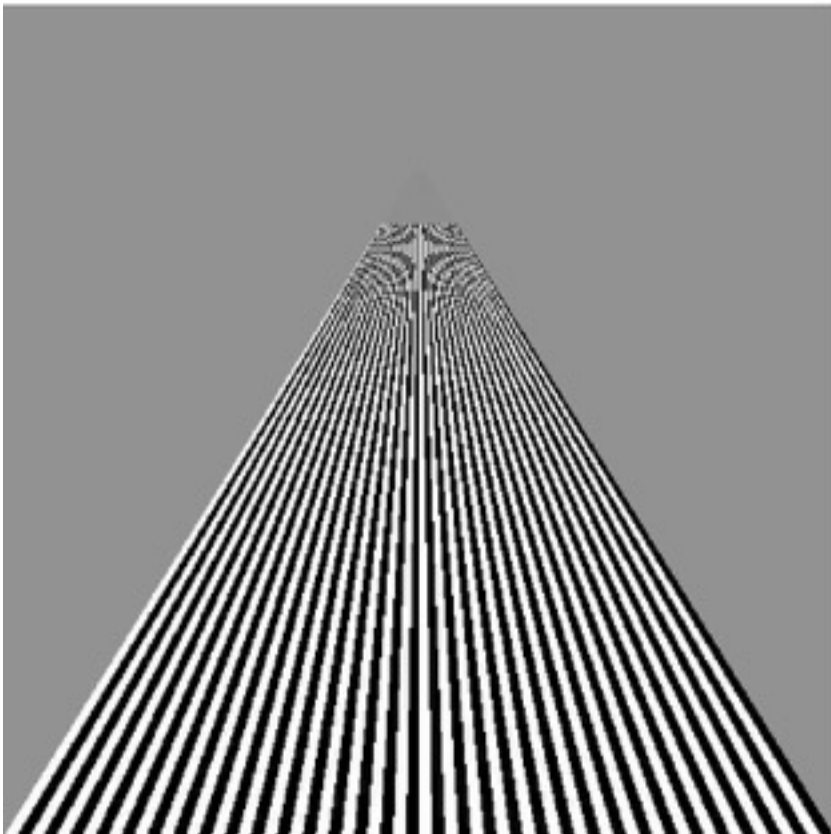
point  
sampling



linear  
filtering  
[Angel and Shreiner]



mipmapped  
point  
sampling



mipmapped  
linear  
filtering

