



# HETEROREFACTOR: Refactoring for Heterogeneous Computing with FPGA

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VLSI architecture,  
synthesis & technology



**SEAL**  
Software Evolution & Analysis Laboratory



The 42<sup>nd</sup> International Conference on Software Engineering  
**ICSE 2020**



# HETEROREFACTOR: Refactoring for Heterogeneous Computing with FPGA



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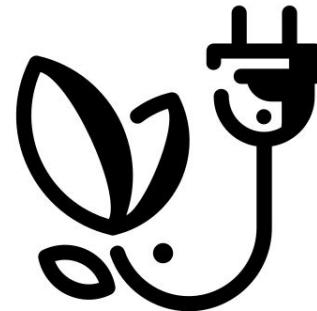
Miryung Kim



# FPGA\*-based Acceleration



Fast



Efficient

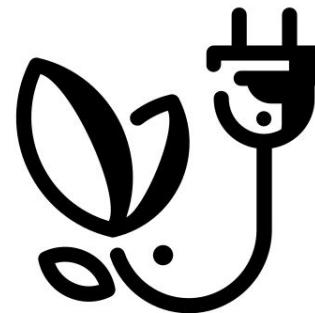
\* FPGA: Field Programmable Gate Array



# FPGA\*-based Acceleration



Fast



Efficient



Effort

\* FPGA: Field Programmable Gate Array



# Evolution of Programming Model

typeless.

registers.

instructions.

goto-style control.

```
module vecdot(a, b, c, clk, rst);
    input [67:0] a, b;
    output [16:0] c;
    reg [5:0] s; reg [16:0] prod [0:7]; ...
    always @(posedge clk or posedge rst)
        if (!rst) begin
            if (s == 6'b000001)
                prod[0] = a[...] * b[...]; prod[1] =...
                s = 6'b00010;
            else if (s == 6'b000010)
                reg1 = prod[0] + prod[1] + prod[2];
                s = 6'b00100; // goto L00100;
            else if (s == 6'b00100)
                reg1 = reg1 + prod[3] + prod[4];
                s = 6'b01000;
            else ... ;
        ...
    endmodule
```

Verilog  
HDL\*

\* HDL: Hardware Description Language



# Evolution of Programming Model

typed.

auto schedule.

auto resource.

auto optimization.

```
fpga_float<8,15> vecdot(  
    fpga_float<8,15> a[],  
    fpga_float<8,15> b[],  
    fpga_int<31> n) {  
    for (fpga_int<31> i = 0; i < n; i++)  
        sum += a[i] * b[i];  
    return sum;  
}
```

Merlin  
HLS\*,  
etc.

\* HLS: High-Level Synthesis



# Programming Challenges

bit-width.

```
fpga_float<8,15> vecdot(  
    fpga_float<8,15> a[],  
    fpga_float<8,15> b[],  
    fpga_int<31> n) {  
    for (fpga_int<31> i = 0; i < n; i++)  
        sum += a[i] * b[i];  
    return sum;  
}  
bitwidth = 31  
waste scarce  
memory!
```

Merlin  
HLS\*,  
etc.

FPGA memory:  
< 100 MB

\* HLS: High-Level Synthesis



# Programming Challenges

bit-width.

floating-point precision.

```
fpga_float<8,15> vecdot(  
    fpga_float<8,15> a[],  
    fpga_float<8,15> b[],  
    fpga_int<31> n) {  
    for (fpga_int<31> i = 0; i < n; i++)  
        sum += a[i] * b[i];  
    return sum;  
}
```

*exponent 8 bits  
fraction 15 bits*

*memory?  
precision?*

Merlin  
HLS\*,  
etc.

\* HLS: High-Level Synthesis



# Programming Challenges

4 errors in 14 lines of code

bit-width.

floating-point precision.

recursive data structure.

nested pointers

```
struct Node {  
    Node *left, *right;  
    int val; };  
  
void init(Node **root) {  
    *root = (Node *)malloc(sizeof(Node)); }  
  
void insert(Node **root, int *arr);  
void delete_tree(Node *root) {  
    // ... free(root); }  
void traverse(Node *curr) {  
    if (curr == NULL) return;  
    int ret = visit(curr->val);  
  
    traverse(curr->left);  
    traverse(curr->right);  
}
```

Merlin  
HLS\*,  
etc.

\* HLS: High-Level Synthesis



# Programming Challenges

4 errors in 14 lines of code

bit-width.

floating-point precision.

recursive data structure.

nested pointers

dynamic mem mgmt

```
struct Node {  
    Node *left, *right;  
    int val; };  
  
void init(Node **root) {  
    *root = (Node *)malloc(sizeof(Node)); }  
  
void insert(Node **root, int *arr);  
void delete_tree(Node *root) {  
    // ... free(root); }  
void traverse(Node *curr) {  
    if (curr == NULL) return;  
    int ret = visit(curr->val);  
  
    traverse(curr->left);  
    traverse(curr->right);  
}
```

preallocated  
size?

Merlin  
HLS\*,  
etc.

\* HLS: High-Level Synthesis



# Programming Challenges

4 errors in 14 lines of code

bit-width.

floating-point precision.

recursive data structure.

nested pointers

dynamic mem mgmt

pointer operations

```
struct Node {  
    Node *left, *right;  
    int val; };  
  
void init(Node **root) {  
    *root = (Node *)malloc(sizeof(Node)); }  
  
void insert(Node **root, int *arr);  
void delete_tree(Node *root) {  
    // ... free(root); }  
void traverse(Node *curr) {  
    if (curr == NULL) return;  
    int ret = visit(curr->val);  
  
    traverse(curr->left);  
    traverse(curr->right);  
}
```

preallocated  
size?

Merlin  
HLS\*,  
etc.

\* HLS: High-Level Synthesis



# Programming Challenges

4 errors in 14 lines of code

bit-width.

floating-point precision.

recursive data structure.

nested pointers

dynamic mem mgmt

pointer operations

recursion functions

```
struct Node {  
    Node *left, *right;  
    int val; };  
  
void init(Node **root) {  
    *root = (Node *)malloc(sizeof(Node)); }  
  
void insert(Node **root, int *arr);  
void delete_tree(Node *root) {  
    // ... free(root); }  
void traverse(Node *curr) {  
    if (curr == NULL) return;  
    int ret = visit(curr->val);  
  
    traverse(curr->left);  
    traverse(curr->right);  
}
```

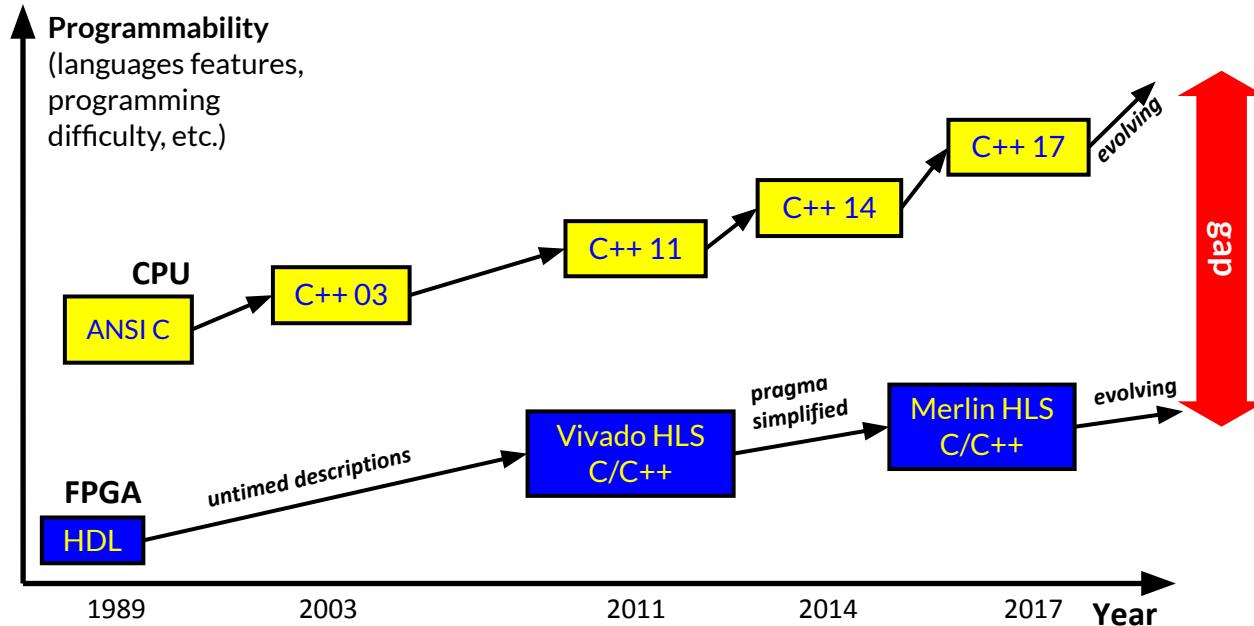
preallocated  
size?

Merlin  
HLS\*,  
etc.

\* HLS: High-Level Synthesis



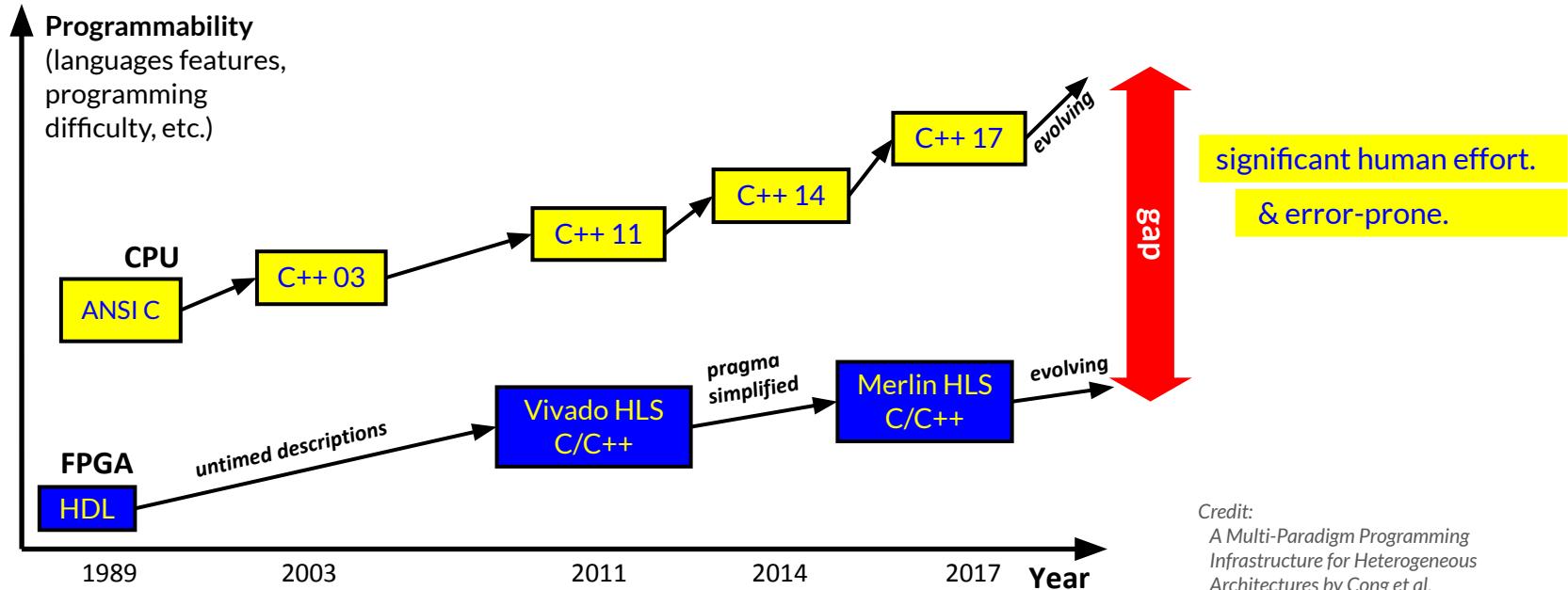
# Evolution of Programming Model



Credit:  
A Multi-Paradigm Programming  
Infrastructure for Heterogeneous  
Architectures by Cong et al.

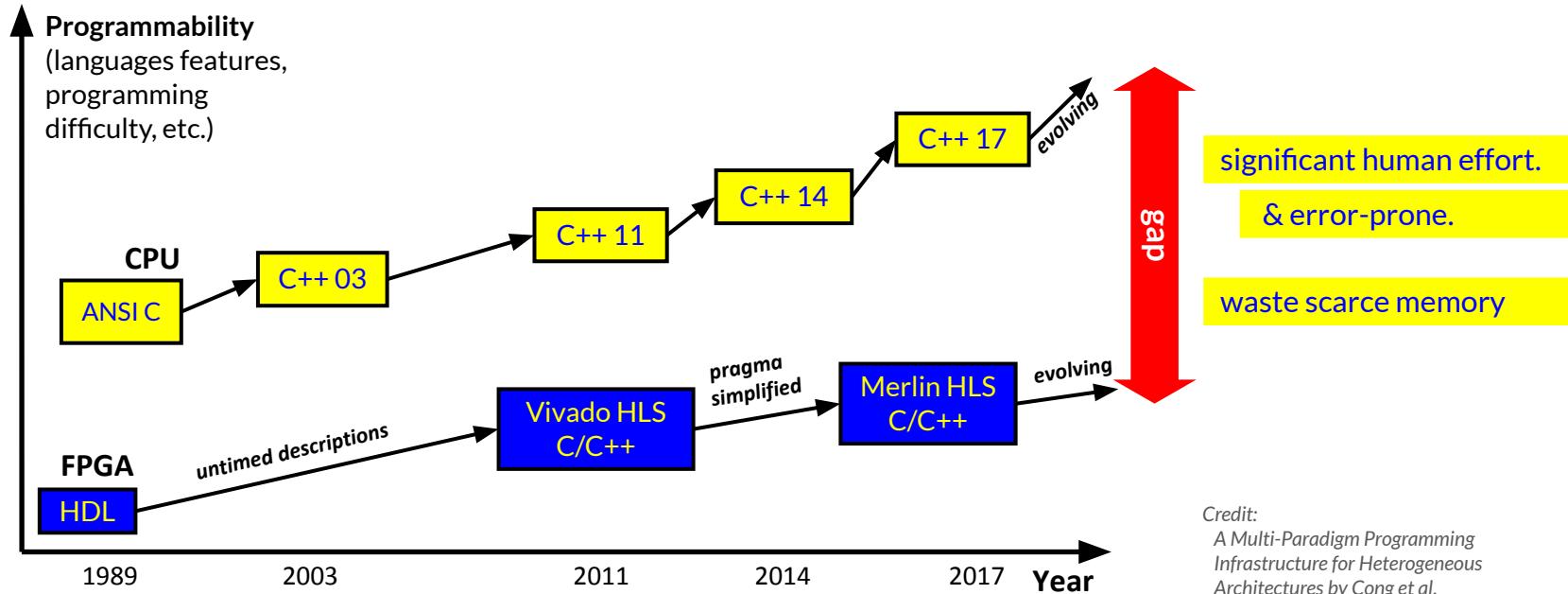


# Evolution of Programming Model





# Evolution of Programming Model



I want it to **run!**

---

I want it to run **efficiently!**

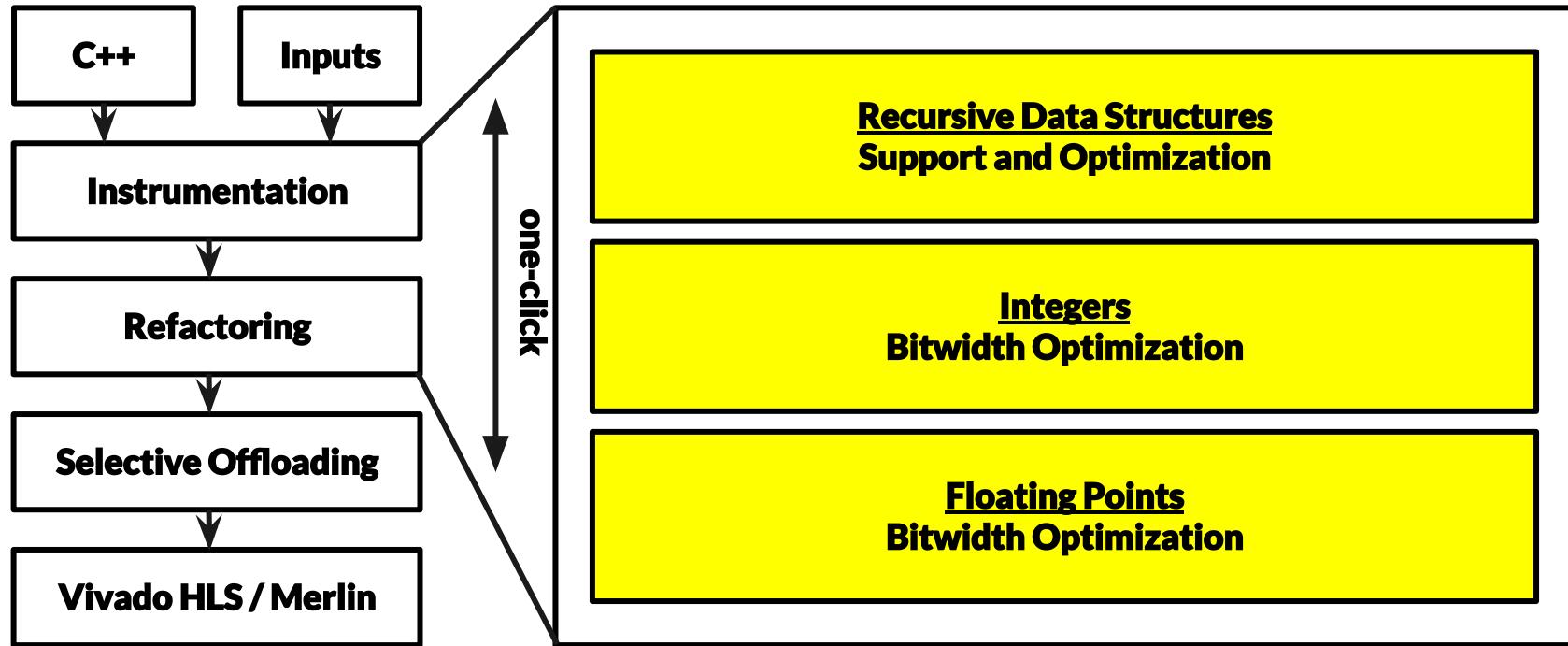
---

# Automation!

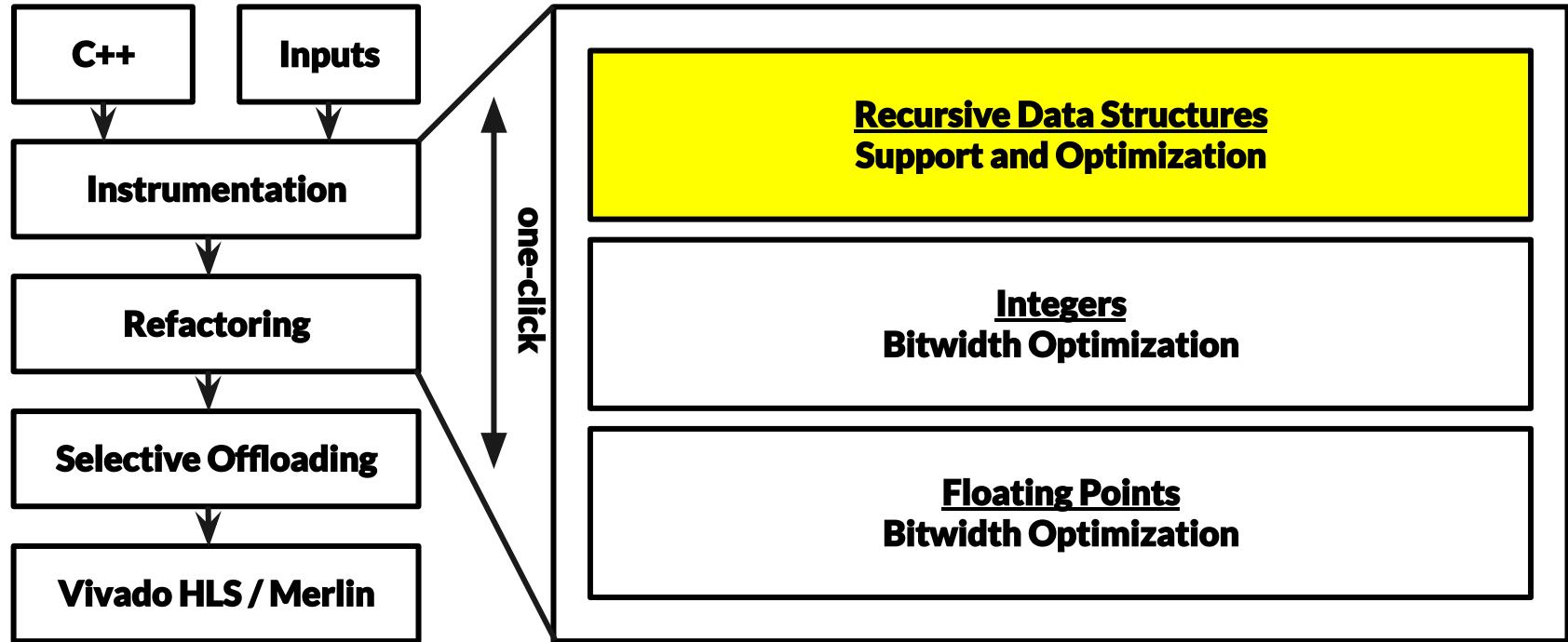




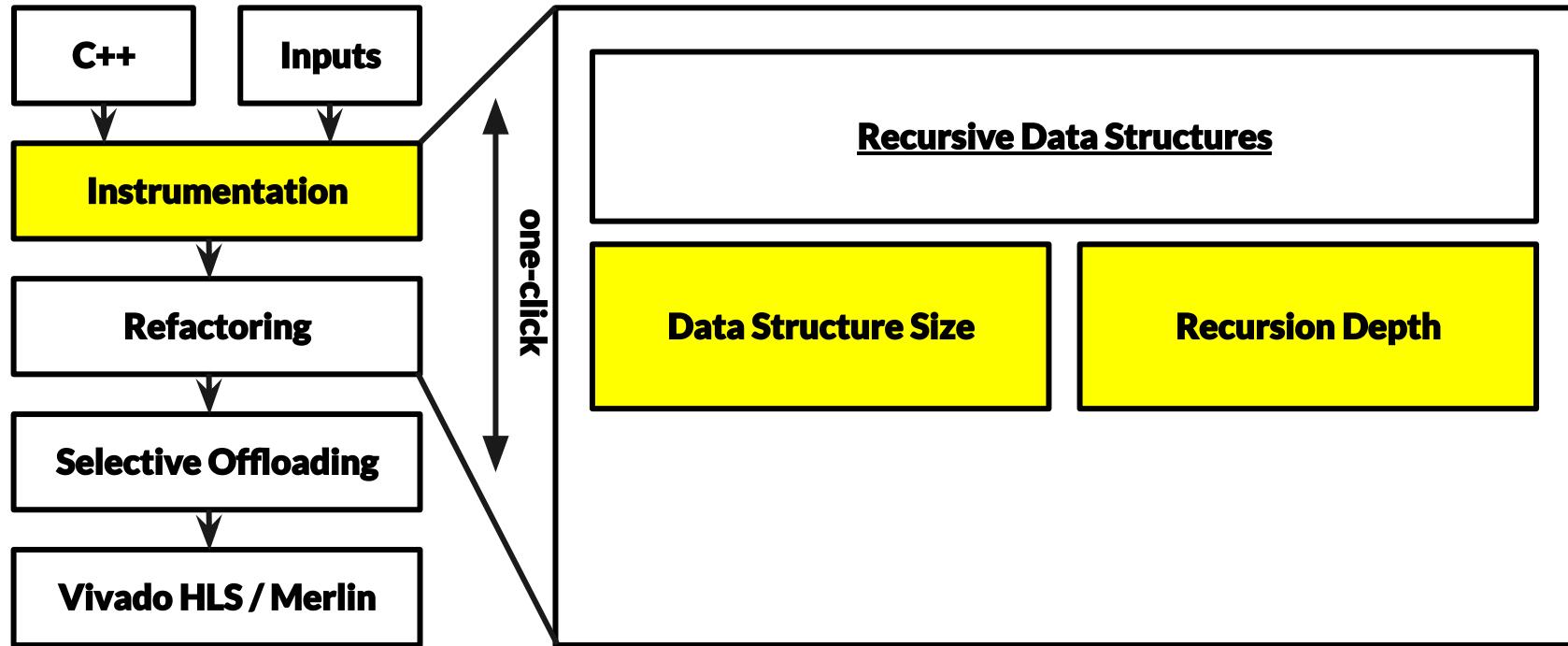
# HETEROREFACTOR Approach Overview



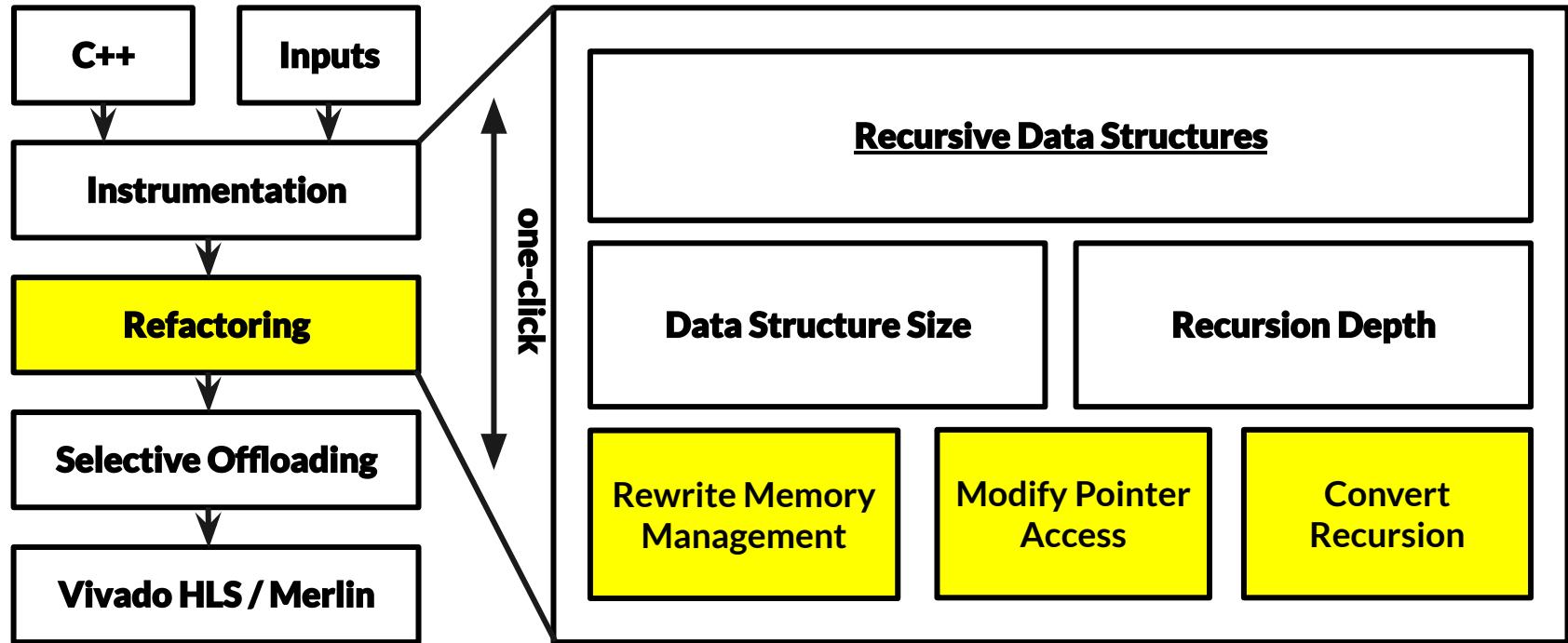
# Part 1. Recursive Data Structures



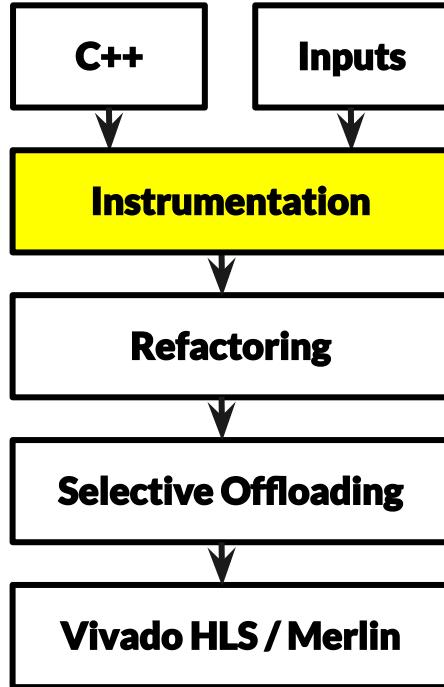
# Recursive: Instrumentation



# Recursive: Refactoring



# Recursive: Example Program



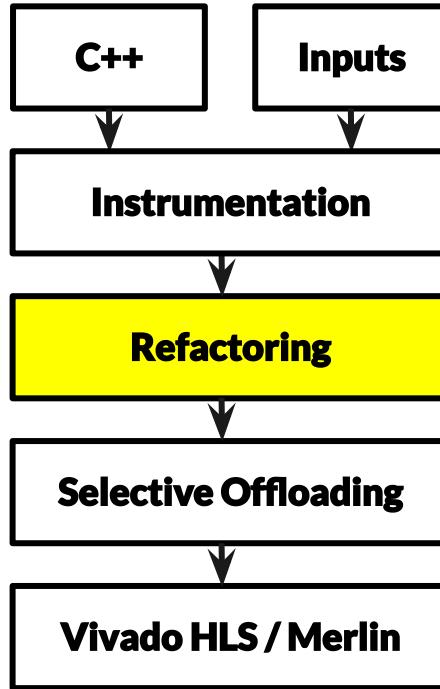
```
void init(Node **root) {
    *root = (Node *)malloc(sizeof(Node)); }

void delete_tree(Node *root) { // ...
    free(root); }

void traverse(Node *curr) { // entry
    if (curr == NULL)
        return;
    int ret = visit(curr->val);
    traverse(curr->left);
    traverse(curr->right); // return
}

// top-level function
float kernel(float input[], int n) {
    float value = computation(float(..), ..);
}
```

# Refactoring Rule 1: Rewrite Mem. Mgmt.



```
void init(Node **root) {  
    *root = (Node *)malloc(sizeof(Node)); }
```

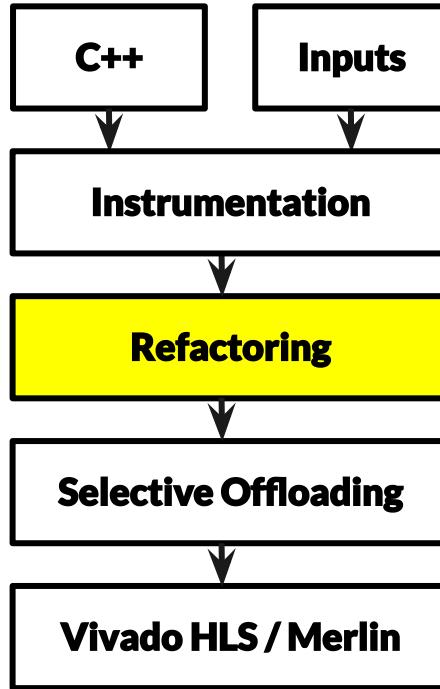
```
void delete_tree(Node *root) { // ...  
    free(root); }
```

---

```
void init(Node_ptr *root) {  
    *root = (Node_ptr)Node_malloc(sizeof(Node)); }
```

```
void delete_tree(Node_ptr root) { // ...  
    Node_free(root); }
```

# Refactoring Rule 1: Rewrite Mem. Mgmt.



```
void init(Node **root) {  
    *root = (Node *)malloc(sizeof(Node)); }
```

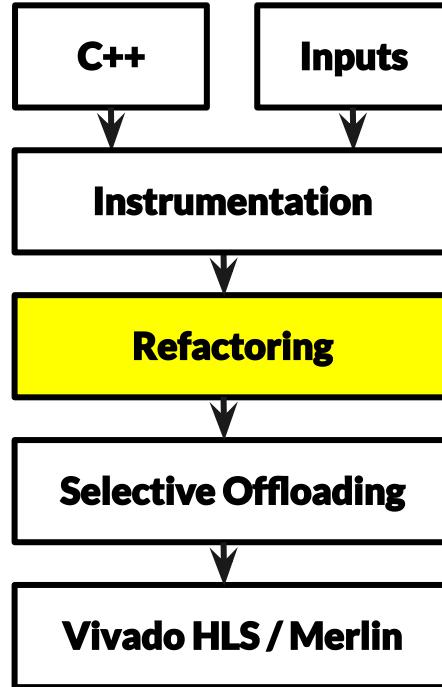
```
void delete_tree(Node *root) { // ...  
    free(root); }
```

---

```
void init(Node_ptr *root) {  
    *root = (Node_ptr)Node_malloc(sizeof(Node)); }
```

```
void delete_tree(Node_ptr root) { // ...  
    Node_free(root); }
```

# Refactoring Rule 2: Rewrite Pointer Access

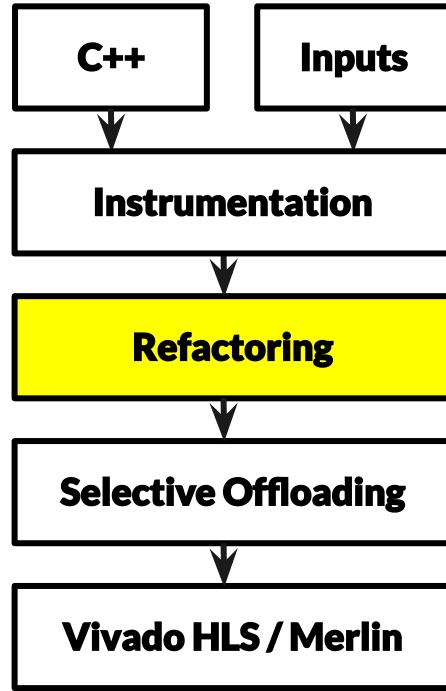


```
void traverse(Node_ptr curr) {  
    if (curr == NULL) return;  
    int ret = visit(curr->val);  
    traverse(curr->left);  
    traverse(curr->right); }
```

---

```
Node Node_arr[NODE_ARR_SIZE];  
void traverse(Node_ptr curr) {  
    if (curr == NULL) return;  
    int ret = visit(Node_arr[curr].val);  
    traverse(Node_arr[curr].left);  
    traverse(Node_arr[curr].right); }
```

# Refactoring Rule 3: Convert Recursion

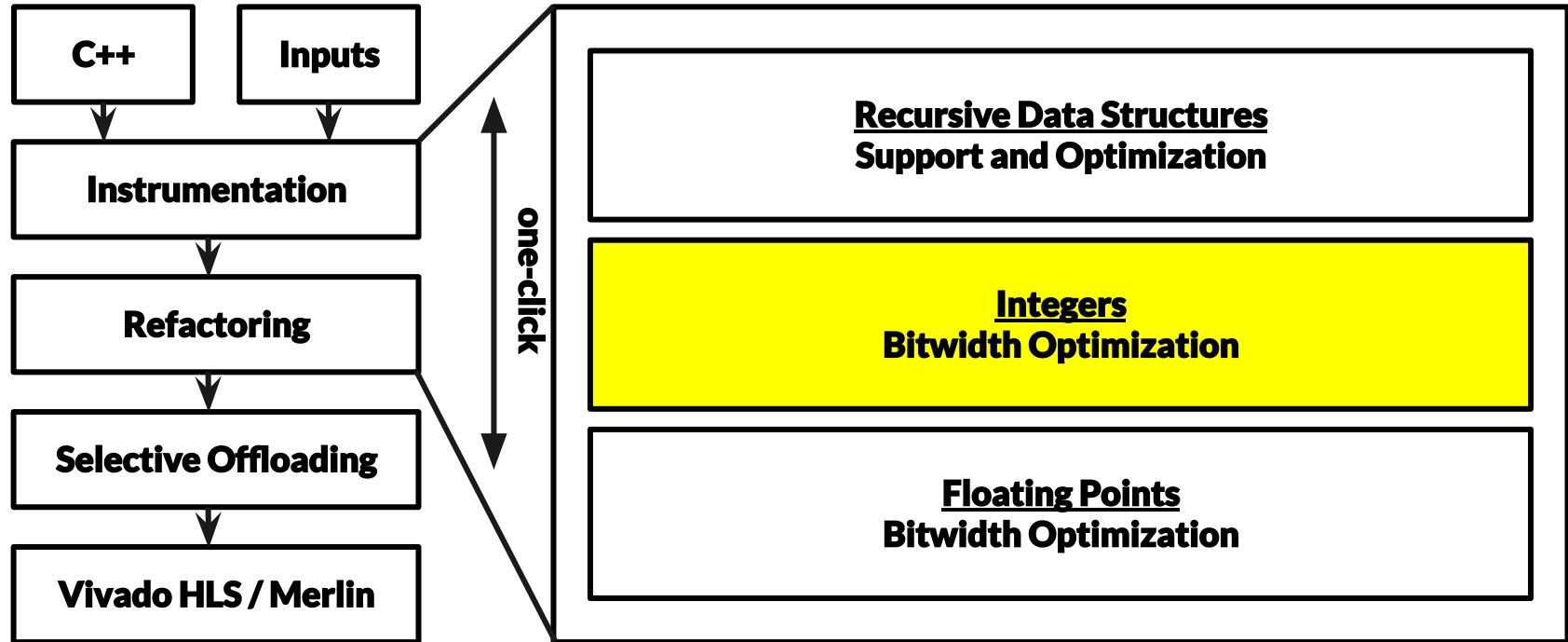


```
void traverse(Node_ptr curr) {
    traverse(Node_arr[curr].left);
    traverse(Node_arr[curr].right); }
```

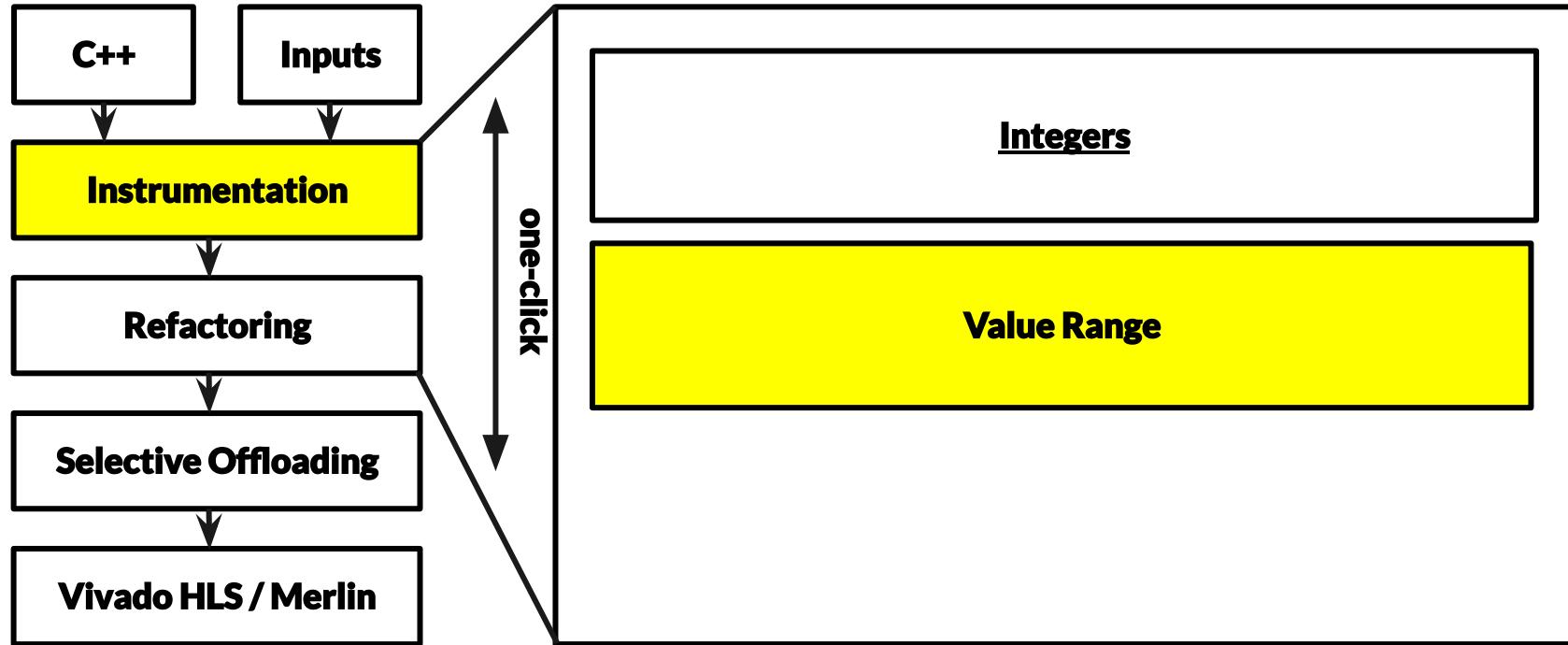
---

```
void traverse_converted(Node_ptr curr) {
    stack<context> s(STACK_SIZE);
    while (!s.empty()) {
        context c = s.pop();
        goto c.location;
    L0:
        // traverse(Node_arr[curr].left);
        c.location = L1;
        s.push(c);
        s.push({curr: Node_arr[curr].left});
        continue;
    L1:
        // ...
    }
}
```

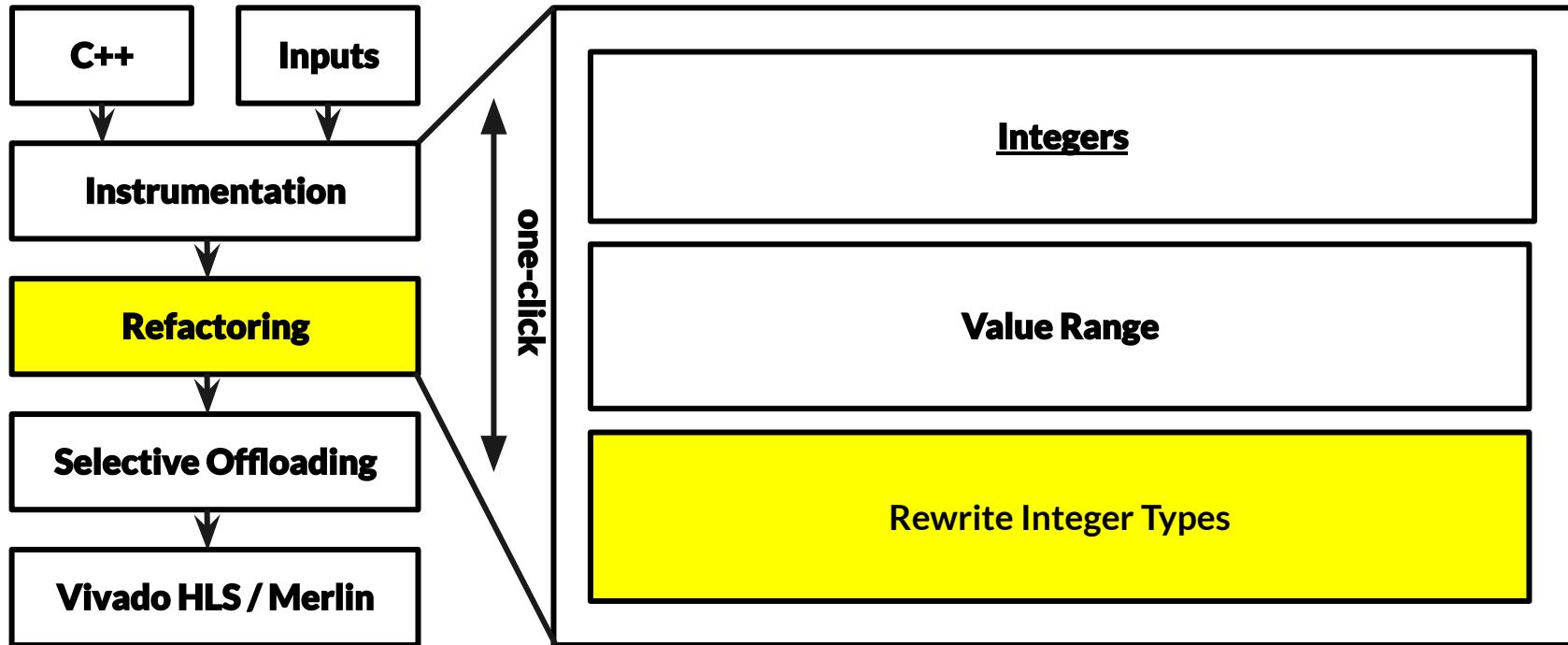
## Part 2. Integer Bitwidth Optimization



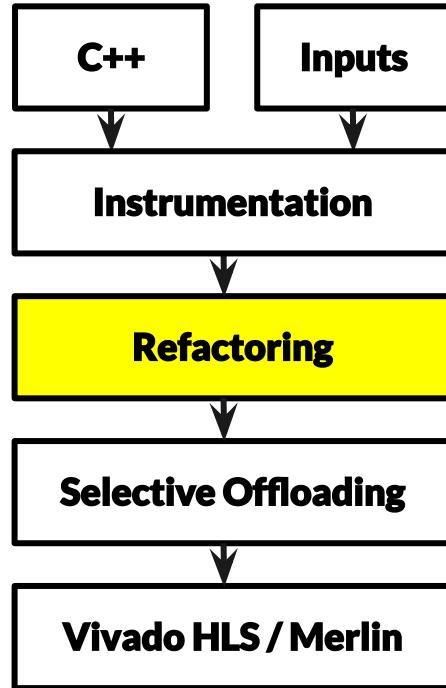
# Integers: Kvasir-based Instrumentation



# Integers: Refactoring



# Refactoring Rule: Modify Integer Type



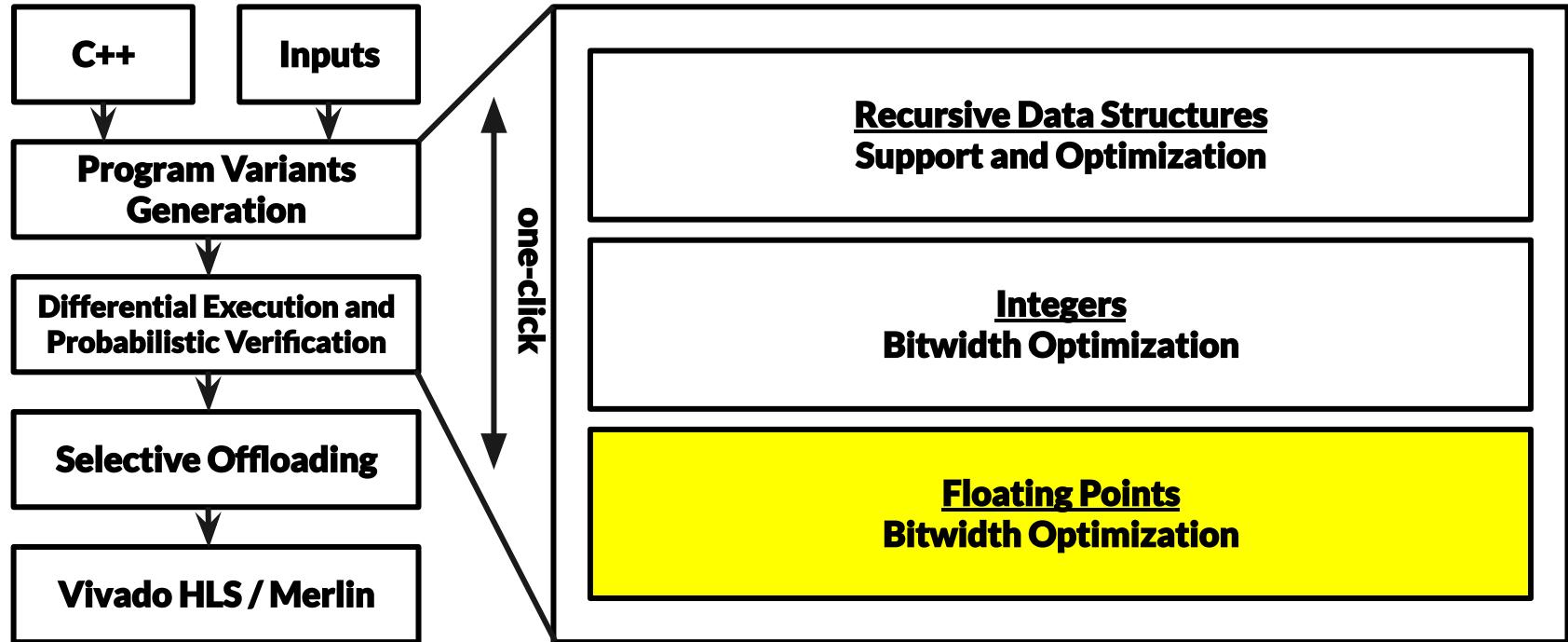
```
Node Node_arr[NODE_ARR_SIZE];
void init(Node_ptr *root) {
    *root = (Node_ptr)Node_malloc(sizeof(Node)); }

void delete_tree(Node_ptr root) { // ...
    Node_free(root); }

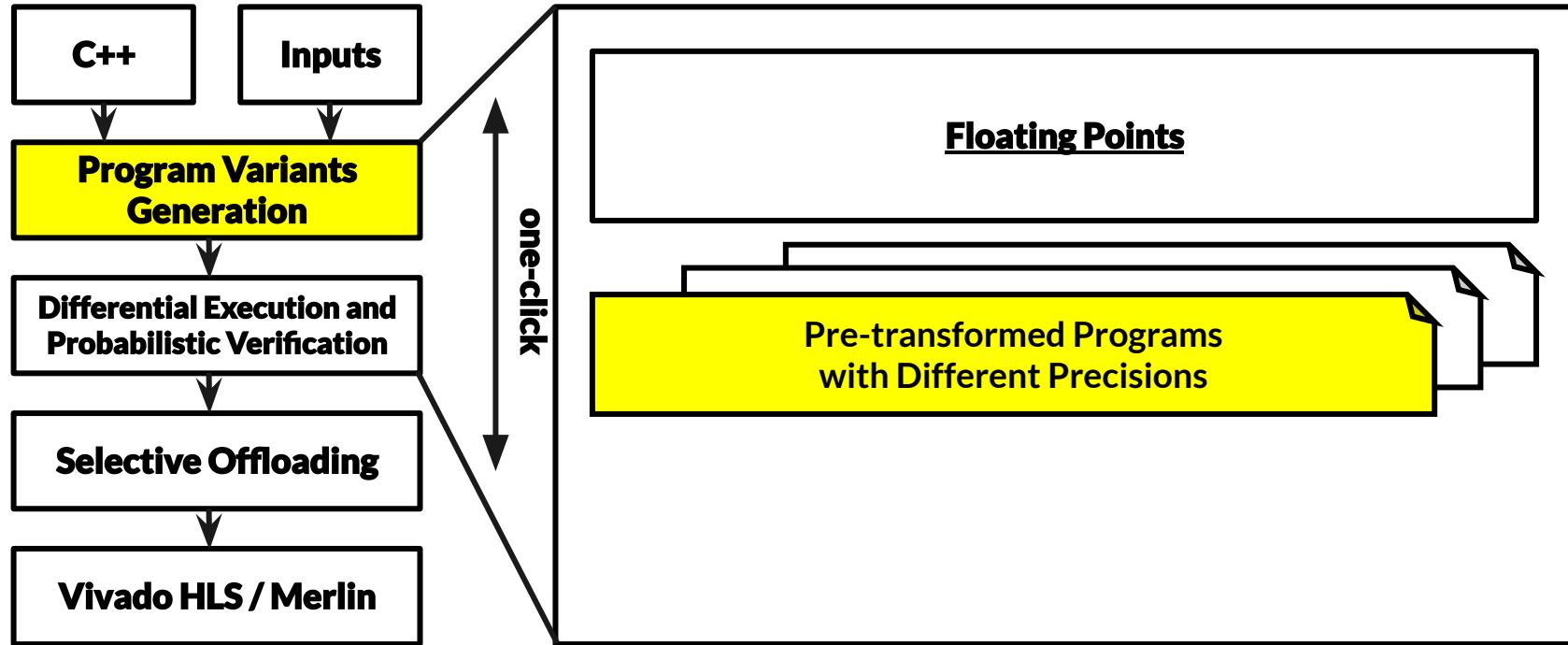
void traverse(Node_ptr curr) {
    if (curr == NULL) return;
// @invariants(ret[21,255])
// int ret = visit(Node_arr[curr].val);
fpga_uint<8> ret = visit(Node_arr[curr].val);
    traverse(Node_arr[curr].left);
    traverse(Node_arr[curr].right); }

float kernel(float input[], int n) {
    float value = computation(float(..), ..);
}
```

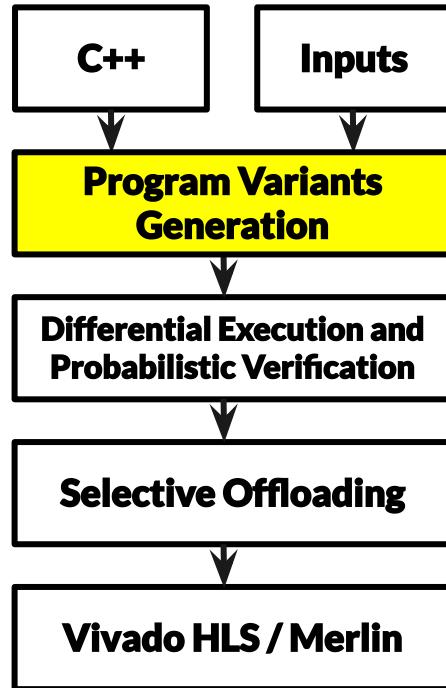
# Part 3. Floating Point Tuning



# Floating Points: Program Variants Generation



# Floating Points: Program Variants Generation



```
float kernel(float input[], int n) {  
    float value = computation(float(..), ..);  
}
```

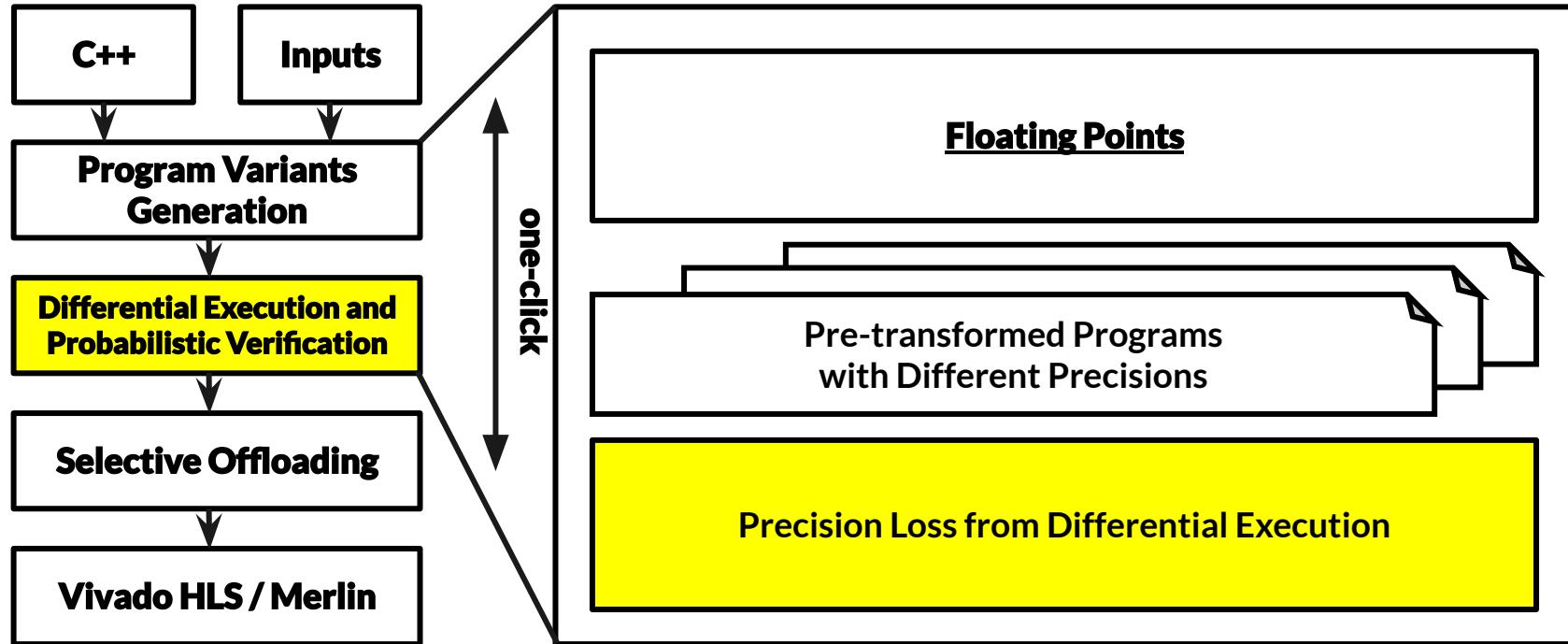
---

```
float low_bit(float input[], int n) {  
    fpga_float<8,16> value =  
        computation(fpga_float<8,16>(..), ..);  
}
```

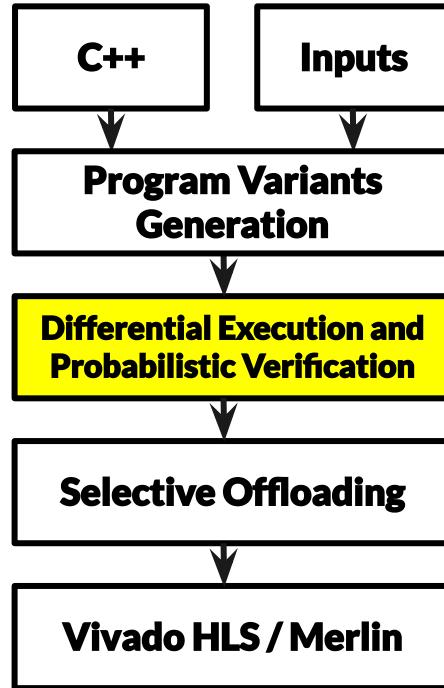
```
float high_bit(float input[], int n) {  
    fpga_float<8,23> value =  
        computation(fpga_float<8,23>(..), ..);  
}
```

**fpga\_float<Exponent, Fraction>** to customize FP precision  
\* note: fpga\_float<8,23> is 32 bit float type, fpga\_float<5,16> uses 22 bits in total

# Floating Points: Differential Execution



# Floating Points: Differential Execution

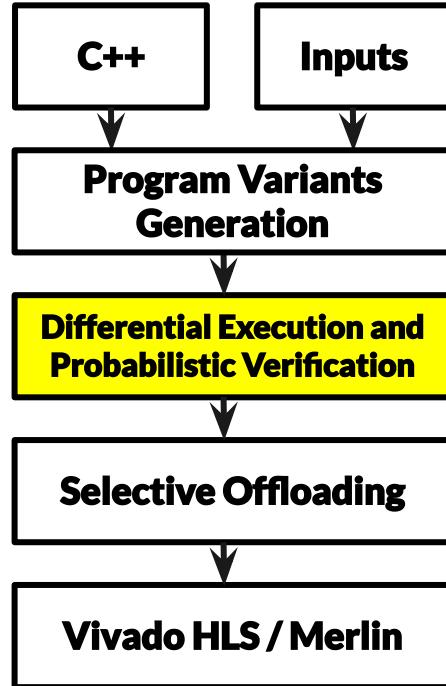


```
float kernel(float input[], int n) {
    float value = computation(float(..), ..);
}

float low_bit(float input[], int n) {
    fpga_float<8,16> value =
        computation(fpga_float<8,16>(..), ..);
}
float high_bit(float input[], int n) {
    fpga_float<8,23> value =
        computation(fpga_float<8,23>(..), ..);
}

void verification() {
    float diff = high_bit(..) - bit_ver(..);
    if (diff > epsilon) // failed sample
}
```

# Floating Points: Probabilistic Verification



```
void verification() {  
    float diff = high_ver(..) - low_ver(..);  
    if (diff > epsilon) // failed sample  
}
```

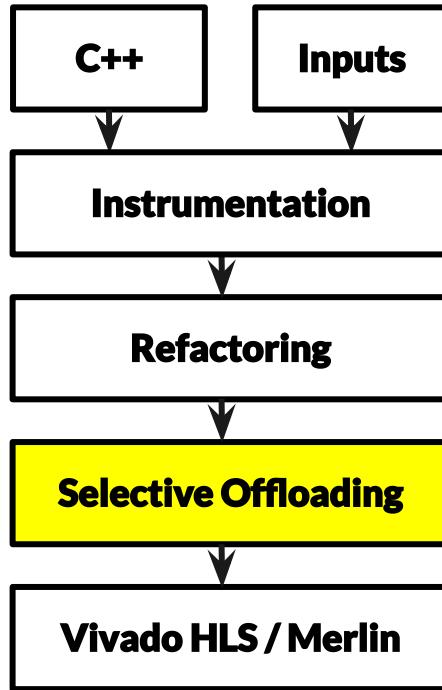
Use **Hoeffding's inequality** [1] to calculate the number of samples to meet the required confidence level: alpha.

$$n \geq \ln(2/\alpha)/(2\epsilon^2)$$

[1] Hoeffding, Wassily (1963). "Probability inequalities for sums of bounded random variables"



# Guard Checking



- Input check on host and intermediate check on device
- Send a signal to the host to indicate **fallback** when:
  - Recursive programs: stack overflow, memory failure
  - Integers: overflow
- The host **restart computation on CPU.**
- Guarantees **correctness** while boosting performance.



# Evaluation: Coding Effort

| ID / Program  | Orig. Chars | Manual Chars | Δ Chars | Orig. LOC | Manual LOC | Δ LOC | Auto. LOC |
|---------------|-------------|--------------|---------|-----------|------------|-------|-----------|
| R1/A.-C.      | 5673        | 8776         | 35%     | 190       | 291        | 33%   | 557       |
| R2/DFS        | 2236        | 5699         | 61%     | 86        | 198        | 57%   | 464       |
| R3/L. List    | 3061        | 6686         | 54%     | 131       | 235        | 44%   | 329       |
| R4/M. Sort    | 3267        | 9124         | 64%     | 128       | 342        | 63%   | 390       |
| R5/Strassen's | 10026       | 40971        | 76%     | 342       | 735        | 53%   | 1006      |
| Geomean       |             |              | 56%     |           |            | 49%   |           |

49%  
reduction  
in LOC



# Evaluation: Resource Reduction

Recursive Data Structures\*

Integer

Floating-point

**83% 42%**

reduction increase  
in BRAM in Fmax

**22% 21%**

reduction reduction  
in FF in LUT

**61% 39%**

reduction reduction  
in FF in LUT

**41% 52%**

reduction increase  
in BRAM in DSP

**50%**

increase  
in DSP

\* assuming a typical size of 2k,  
+ a conservative size of 16k



# Acknowledgement

- Intel/NSF CAPA grant
- CRISP, one of six centers in JUMP, a SRC program
- NSF grants: CCF-1764077, CCF-1527923, CCF-1723773
- Center for Domain-Specific Computing (CDSC)
  - Xilinx and VMWare.
- ONR grant: N00014-18-1-2037
- Samsung grant
- Guy Van den Broeck, Brett Chalabian, Todd Millstein,  
Peng Wei, Cody Hao Yu, Janice Wheeler



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University of California, Los Angeles

\*Equal co-first authors in alphabetical order



- We adapt and expand **automated refactoring** to heterogeneous computing with FPGA.
- **HETEROREFACTOR** provides a novel, end-to-end solution that combines:
  - **dynamic invariant analysis** for identifying common-case.
  - **kernel refactoring** to enhance HLS synthesizability and to reduce memory usage.
  - **selective offloading** with guard checking to guarantee correctness.
- The proposed combination is unique to the best of our knowledge.