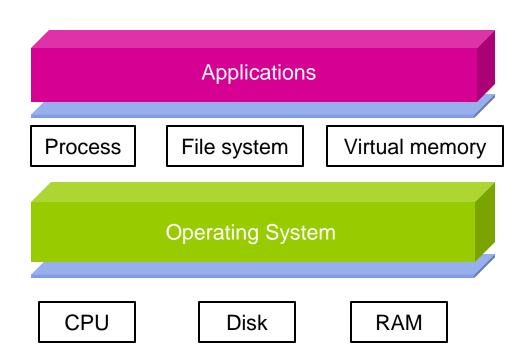


CS 202 Advanced Operating System

Process

OS Abstractions





Today, we start discussing the first abstraction that enables us to virtualize (i.e., share) the CPU – processes!

The Process



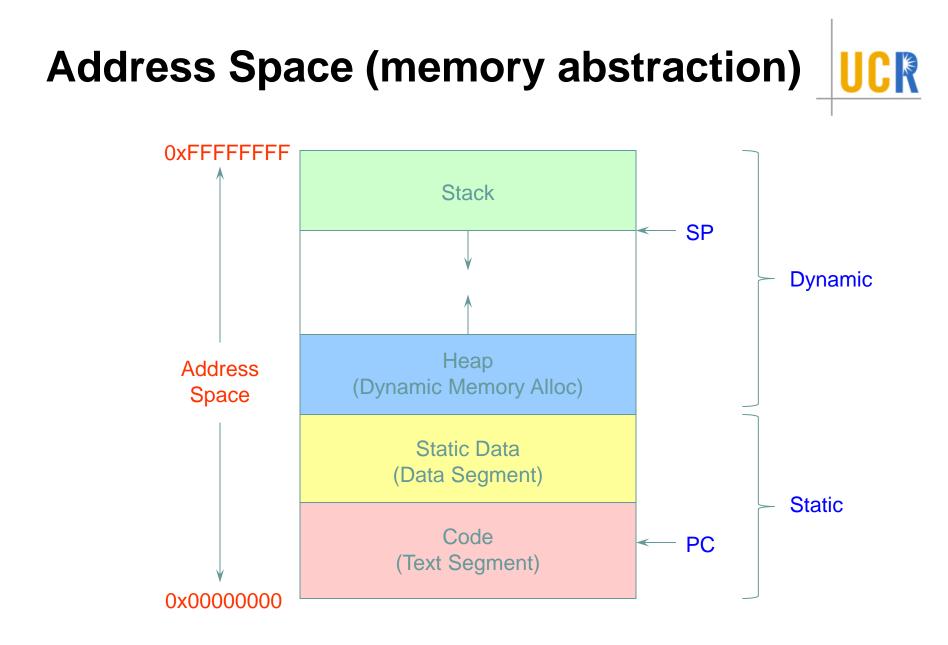
- The process is the OS abstraction for execution
 - > It is the unit of execution
 - It is the unit of scheduling
- > A process is a program in execution
 - Programs are static entities with the potential for execution
 - Process is the animated/active program
 - > Starts from the program, but also includes dynamic state
 - As the representative of the program, it is the "owner" of other resources (memory, files, sockets, ...)
- > How does the OS implement this abstraction?
 - How does it share the CPU?

Process Components



- A process contains all the state for a program in execution
 - An address space containing
 - > Static memory:
 - > The code and input data for the executing program
 - > Dynamic memory:
 - > The memory allocated by the executing program
 - > An execution stack encapsulating the state of procedure calls
 - > Control registers such as the program counter (PC)
 - > A set of general-purpose registers with current values
 - > A set of operating system resources
 - > Open files, network connections, etc.

A process is named using its process ID (PID)



Process Execution State



- A process is born, executes for a while, and then dies
- The process execution state that indicates what it is currently doing
 - Running: Executing instructions on the CPU
 - > It is the process that has control of the CPU
 - > How many processes can be in the running state simultaneously?
 - Ready: Waiting to be assigned to the CPU
 - Ready to execute, but another process is executing on the CPU
 - > Waiting: Waiting for an event, e.g., I/O completion
 - > It cannot make progress until event is signaled (disk completes)

Execution state (cont'd)



- As a process executes, it moves from state to state
 - > Unix "ps -x": STAT column indicates execution state

PROCESS STATE CODES

Here are the different values that the s, stat and state output specifiers (header "S

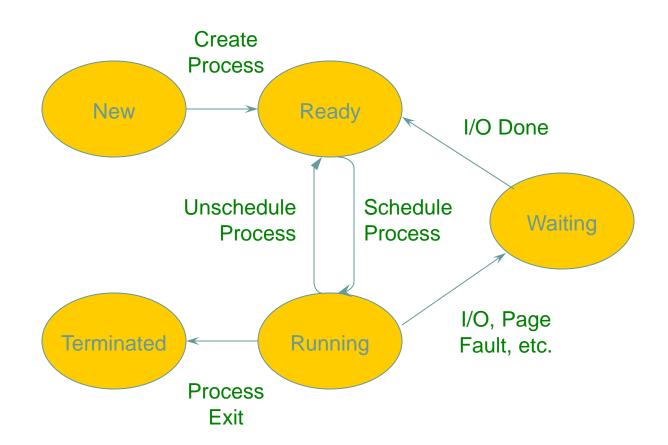
- D uninterruptible sleep (usually IO)
- R running or runnable (on run queue)
- S interruptible sleep (waiting for an event to complete)
- T stopped, either by a job control signal or because it is being traced.
- W paging (not valid since the 2.6.xx kernel)
- X dead (should never be seen)
- Z defunct ("zombie") process, terminated but not reaped by its parent.

For BSD formats and when the stat keyword is used, additional characters may be displ

- < high-priority (not nice to other users)
- N low-priority (nice to other users)
- L has pages locked into memory (for real-time and custom IO)
- s is a session leader
- is multi-threaded (using CLONE_THREAD, like NPTL pthreads do)
- + is in the foreground process group.

Execution State Graph





How does the OS support this model?



We will discuss three issues:

- 1. How does the OS represent a process in the kernel?
 - The OS data structure representing each process is called the Process Control Block (PCB)
- 2. How do we pause and restart processes?
 - ² We must be able to save and restore the full machine state

3. How do we keep track of all the processes in the system?

A lot of queues!

PCB Data Structure



- > PCB also is where OS keeps all of a process' hardware execution state when the process is not running
 - Process ID (PID)
 - > Execution state
 - > Hardware state: PC, SP, regs
 - > Memory management
 - Scheduling
 - Accounting
 - > Pointers for state queues
 - > Etc.
- This state is everything that is needed to restore the hardware to the same configuration it was in when the process was switched out of the hardware

Xv6 struct proc



enum procstate { UNUSED, EMBRYO, SLEEPING, RUNNABLE, RUNNING, ZOMBIE };

```
// Per-process state
struct proc {
  uint sz:
  pde_t* pgdir;
 char *kstack;
  enum procstate state; // Process state
  volatile int pid;
  struct proc *parent; // Parent process
  struct trapframe *tf;
  struct context *context;
  void *chan;
  int killed:
  struct file *ofile[NOFILE]; // Open files
  struct inode *cwd; // Current directory
  char name[16];
};
```

- // Size of process memory (bytes)
- // Linear address of proc's pgdir
- // Bottom of kernel stack for this process
- // Process ID
- // Trap frame for current syscall
- // Switch here to run process
- // If non-zero, sleeping on chan
- // If non-zero, have been killed

- // Process name (debugging)

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How to pause/restart processes?



- When a process is running, its dynamic state is in memory and some hardware registers
 - Hardware registers include Program counter, stack pointer, control registers, data registers, ...
 - > To be able to stop and restart a process, we need to completely restore this state
- When the OS stops running a process, it saves the current values of the registers (usually in PCB)
- When the OS restarts executing a process, it loads the hardware registers from the stored values in PCB
- Changing CPU hardware state from one process to another is called a context switch
 - > This can happen 100s or 1000s of times a second!

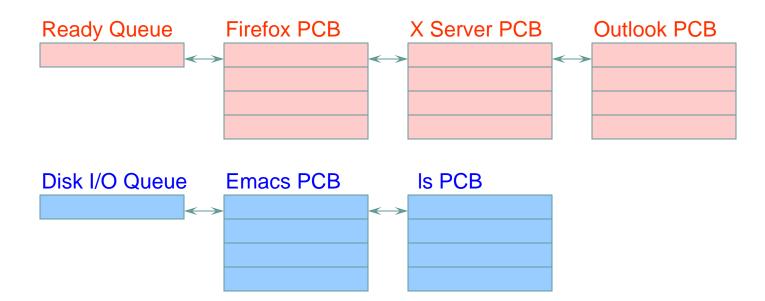
How does the OS track processes?



- The OS maintains a collection of queues that represent the state of all processes in the system
- > Typically, the OS at least one queue for each state
 - > Ready, waiting, etc.
- Each PCB is queued on a state queue according to its current state
- As a process changes state, its PCB is unlinked from one queue and linked into another

State Queues





Console Queue

Sleep Queue

.

There may be many wait queues, one for each type of wait (disk, console, timer, network, etc.)

Process system call API



- > Process creation: how to create a new process?
- Process termination: how to terminate and clean up a process
- Coordination between processes
 - Wait, waitpid, signal, inter-process communication, synchronization
- > Other
 - > E.g., set quotas or priorities, examine usage, ...

Process Creation



- > A process is created by another process
 - > Why is this the case?
 - Parent is creator, child is created (Unix: ps "PPID" field)
 - > What creates the first process (Unix: init (PID 0 or 1))?
- In some systems, the parent defines (or donates) resources and privileges for its children
 - Unix: Process User ID is inherited children of your shell execute with your privileges
- After creating a child, the parent may either wait for it to finish its task or continue in parallel (or both)

Process Creation: Windows



- The system call on Windows for creating a process is called, surprisingly enough, CreateProcess: BOOL CreateProcess (char *prog, char *args) (simplified)
- > CreateProcess
 - Creates and initializes a new PCB
 - > Creates and initializes a new address space
 - > Loads the program specified by "prog" into the address space
 - > Copies "args" into memory allocated in address space
 - Initializes the saved hardware context to start execution at main (or wherever specified in the file)
 - > Places the PCB on the ready queue

Process Creation: Unix



- In Unix, processes are created using fork() int fork()
- > fork()
 - Creates and initializes a new PCB
 - > Creates a new address space
 - Initializes the address space with a copy of the entire contents of the address space of the parent
 - Initializes the kernel resources to point to the resources used by parent (e.g., open files)
 - > Places the PCB on the ready queue
- Fork returns twice
 - > Returns the child's PID to the parent, "0" to the child

fork()



```
int main(int argc, char *argv[])
{
  char *name = argv[0];
  int child pid = fork();
  if (child pid == 0) {
      printf("Child of %s is %d\n", name, getpid());
      return 0;
  } else {
      printf("My child is %d\n", child pid);
      return 0;
  }
}
```

What does this program print?

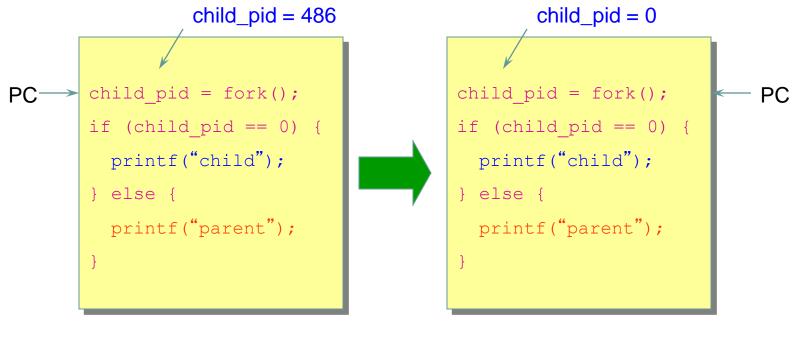
Example Output



[well ~]\$ gcc t.c [well ~]\$./a.out My child is 486 Child of a.out is 486



Duplicating Address Spaces

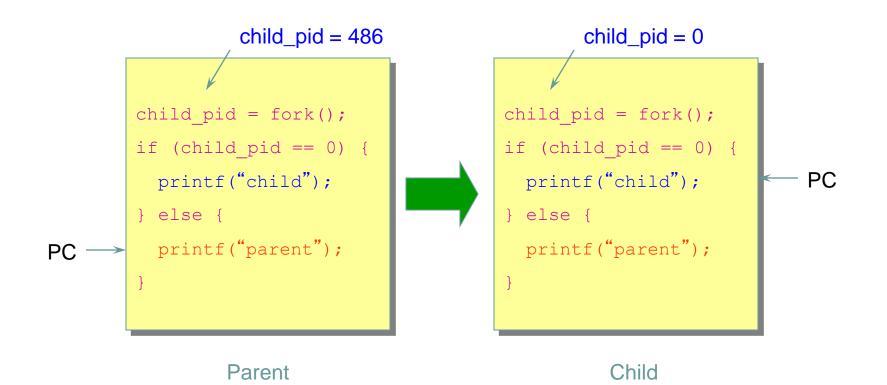


Parent

Child

Divergence





Example Continued



[well ~]\$ gcc t.c [well ~]\$./a.out My child is 486 Child of a.out is 486 [well ~]\$./a.out Child of a.out is 498 My child is 498

Why is the output in a different order?

Why fork()?



- Very useful when the child...
 - Is cooperating with the parent
 - Relies upon the parent's data to accomplish its task
- > Example: Web server

```
while (1) {
    int sock = accept();
    if ((child_pid = fork()) == 0) {
        Handle client request
    } else {
        Close socket
    }
}
```

Process Creation: Unix (2)



Wait a second. How do we actually start a new program?

int exec(char *prog, char *argv[])

- > exec()
 - > Stops the current process
 - Loads the program "prog" into the process' address space
 - > Initializes hardware context and args for the new program
 - > Places the PCB onto the ready queue
 - > Note: It **does not** create a new process
- > What does it mean for exec to return?
- > What does it mean for exec to return with an error?

Process Termination



- All good processes must come to an end. But how?
 - Unix: exit(int status), NT: ExitProcess(int status)
- > Essentially, free resources and terminate
 - Terminate all threads (next lecture)
 - > Close open files, network connections
 - Allocated memory (and VM pages out on disk)
 - > Remove PCB from kernel data structures, delete
- Note that a process does not need to clean up itself
 - OS will handle this on its behalf

wait() a second...



- Often it is convenient to pause until a child process has finished
 - > Think of executing commands in a shell
- > Use wait() (WaitForSingleObject)
 - Suspends the current process until a child process ends
 - waitpid() suspends until the specified child process ends
- > Wait has a return value...what is it?
- > Unix: Every process must be reaped by a parent
 - > What happens if a parent process exits before a child?
 - > What do you think is a "zombie" process?

Unix Shells

}



```
while (1) {
  char *cmd = read command();
  int child pid = fork();
  if (child pid == 0) {
      Manipulate STDIN/OUT/ERR file descriptors for pipes,
      redirection, etc.
      exec(cmd);
      panic("exec failed");
  } else {
      if (!(run in background))
             waitpid(child pid);
  }
```