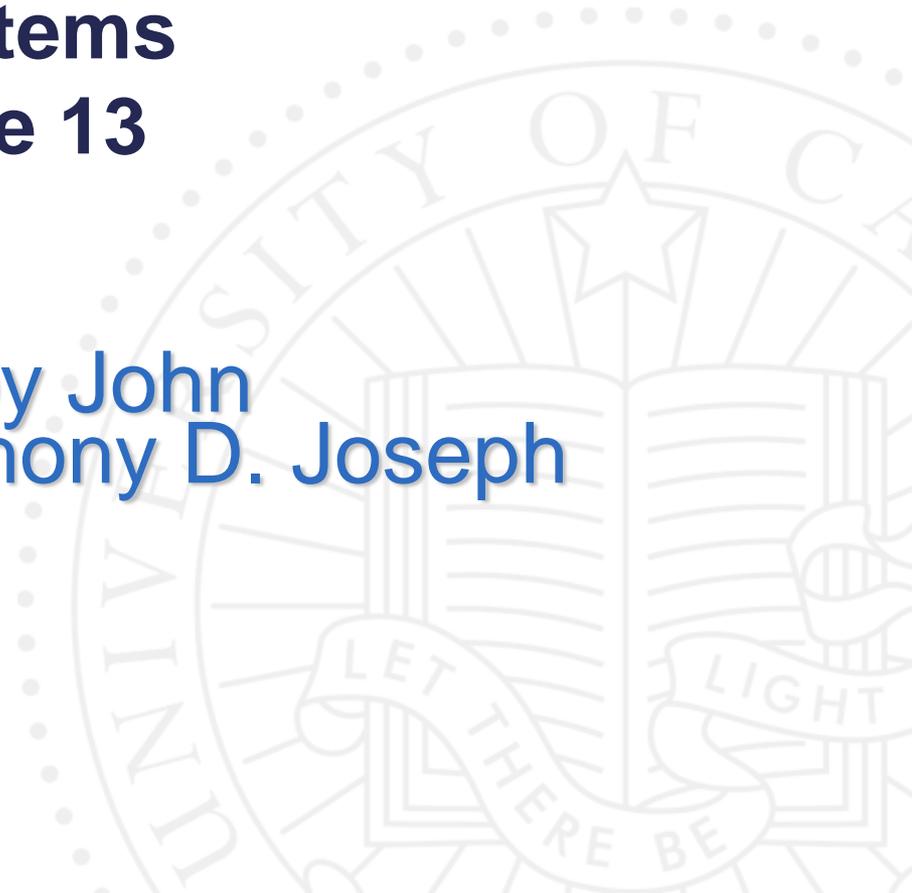


Filesystems

Lecture 13

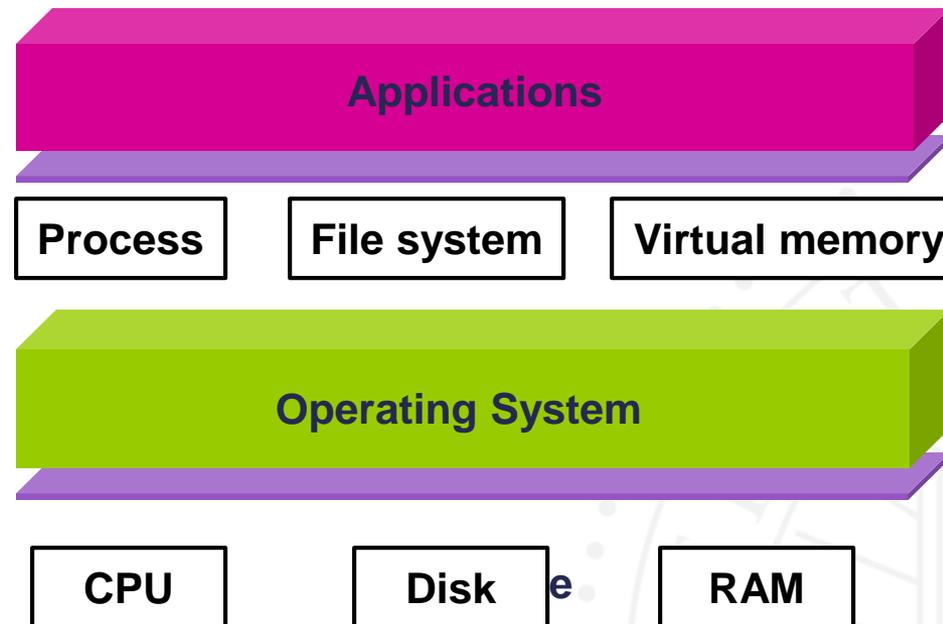
Credit: some slides by John Kubiatoicz and Anthony D. Joseph



Today and some of next class

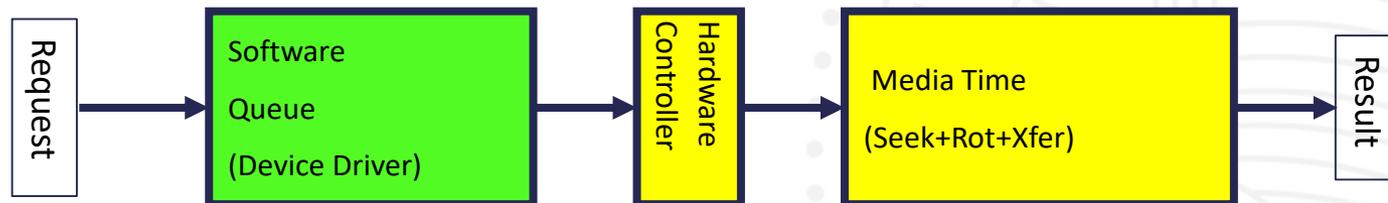
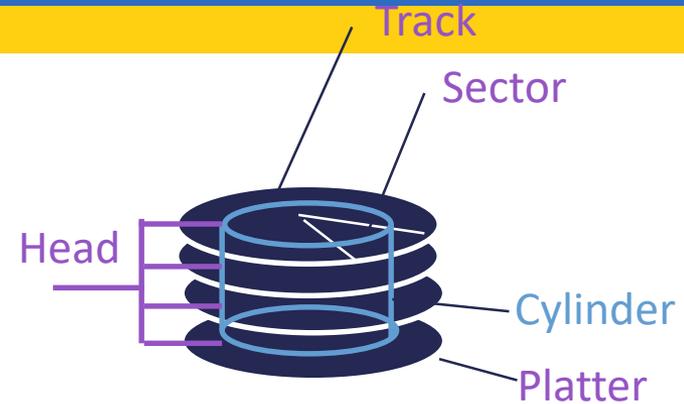
- › Overview of file systems
- › Papers on basic file systems
 - › [A Fast File System for UNIX](#)
Marshall Kirk McKusick, William N. Joy, Samuel J. Leffler and Robert S. Fabry. Appears in *ACM Transactions on Computer Systems (TOCS)*, Vol. 2, No. 3, August 1984, pp 181-197
 - › Log Structured File Systems (LFS), Ousterhout and Rosenblum
- › System design paper and system analysis paper

OS Abstractions



Review: Magnetic Disk Characteristic

- › Cylinder: all the tracks under the head at a given point on all surface
- › Read/write data is a three-stage process:
 - › Seek time: position the head/arm over the proper track (into proper cylinder)
 - › Rotational latency: wait for the desired sector to rotate under the read/write head
 - › Transfer time: transfer a block of bits (sector) under the read-write head
- › **Disk Latency = Queuing Time + Controller time + Seek Time + Rotation Time + Xfer Time**



- › **Highest Bandwidth:**
 - › Transfer large group of blocks sequentially from one track

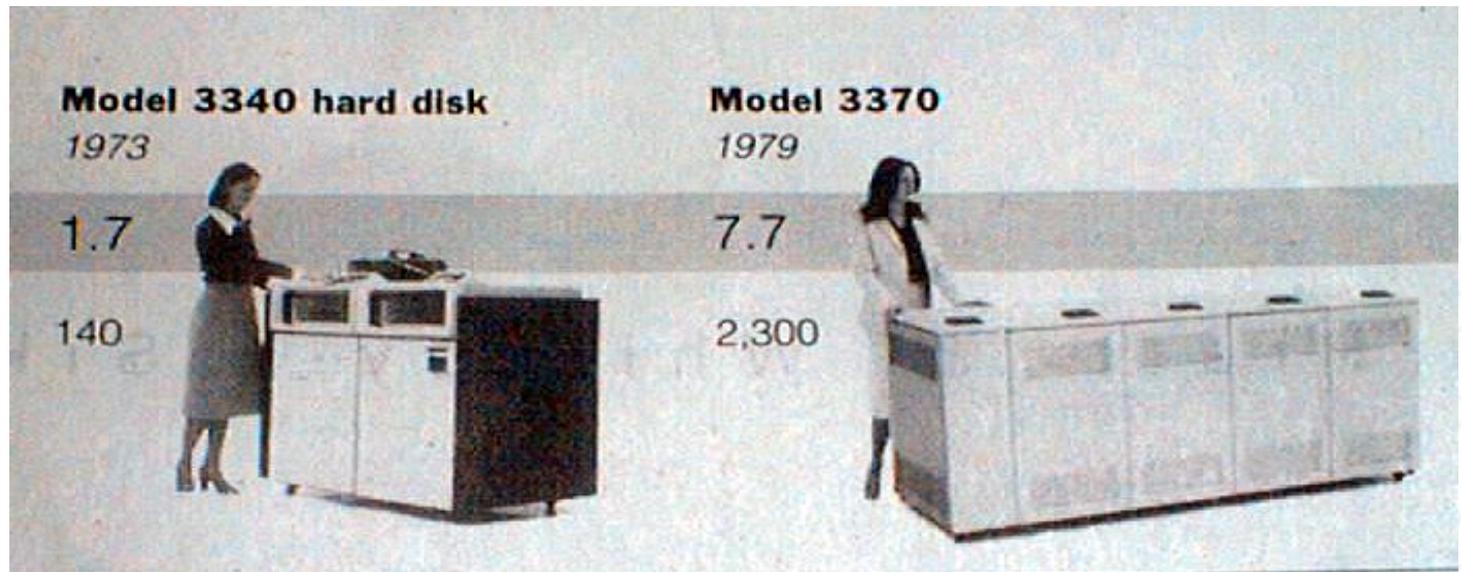
Historical Perspective

- › 1956 IBM Ramac — early 1970s Winchester
 - › Developed for mainframe computers, proprietary interfaces
 - › Steady shrink in form factor: 27 in. to 14 in.
- › Form factor and capacity drives market more than performance
- › 1970s developments
 - › 5.25 inch floppy disk formfactor (microcode into mainframe)
 - › Emergence of industry standard disk interfaces
- › Early 1980s: PCs and first generation workstations
- › Mid 1980s: Client/server computing
 - › Centralized storage on file server
 - › accelerates disk downsizing: 8 inch to 5.25
 - › Mass market disk drives become a reality
 - › industry standards: SCSI, IPI, IDE
 - › 5.25 inch to 3.5 inch drives for PCs, End of proprietary interfaces
- › 1990s: Laptops => 2.5 inch drives
- › 2000s: Shift to perpendicular recording
 - › 2007: Seagate introduces 1TB drive
 - › 2009: Seagate/WD introduces 2TB drive
- › 2014: Seagate announces 8TB drives

Disk History

Data
density
Mbit/sq. in.

Capacity of
Unit Shown
Megabytes

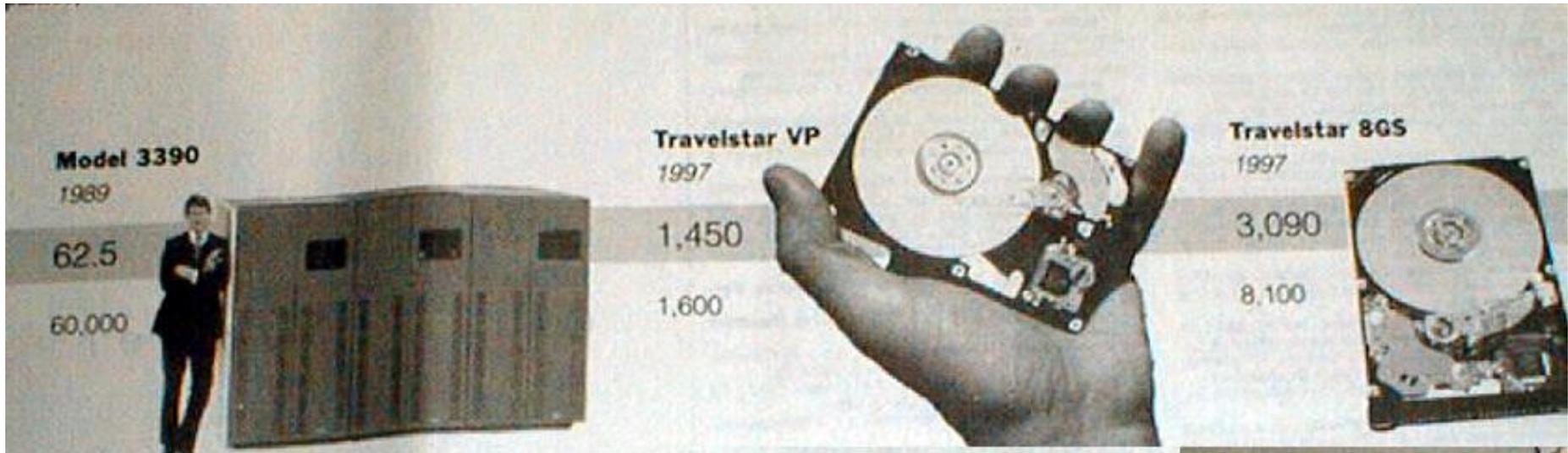


1973:
1.7 Mbit/sq. in
140 MBytes

1979:
7.7 Mbit/sq. in
2,300 MBytes

source: *New York Times*, 2/23/98, page C3,
“Makers of disk drives crowd even more data into even smaller spaces”

Disk History



1989:
63 Mbit/sq. in
60,000 MBytes

1997:
1450 Mbit/sq. in
2300 MBytes

1997:
3090 Mbit/sq. in
8100 MBytes

*source: New York Times, 2/23/98, page C3,
"Makers of disk drives crowd even more data into even smaller spaces"*

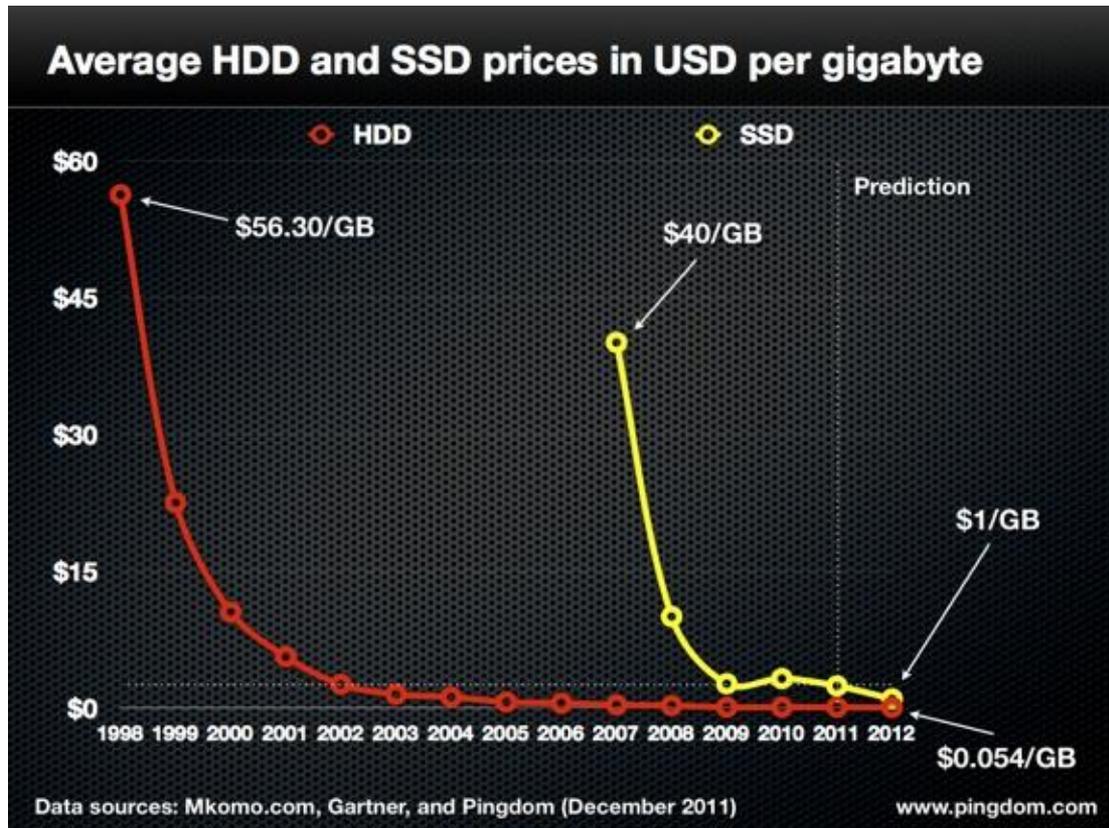
Recent: Seagate Enterprise (2015)

- › 10TB! 800 Gbits/inch²
- › 7 (3.5") platters, 2 heads each
- › 7200 RPM, 8ms seek latency
- › 249/225 MB/sec read/write transfer rates
- › 2.5million hours MTBF
- › 256MB cache
- › \$650



Contrarian View

- › FFS doesn't matter in 2012!



- › What about Journaling? Is it still relevant?

60 TB SSD (\$20,000)



Storage Performance & Price

	Bandwidth (sequential R/W)	Cost/GB	Size
HDD	50-100 MB/s	\$0.05-0.1/GB	2-4 TB
SSD ¹	200-500 MB/s (SATA) 6 GB/s (PCI)	\$1.5-5/GB	200GB-1TB
DRAM	10-16 GB/s	\$5-10/GB	64GB-256GB

¹<http://www.fastestssd.com/featured/ssd-rankings-the-fastest-solid-state-drives/>

BW: SSD up to x10 than HDD, DRAM > x10 than SSD

Price: HDD x30 less than SSD, SSD x4 less than DRAM

File system abstractions

- › How do users/user programs interact with the file system?
 - › Files
 - › Directories
 - › Links
 - › Protection/sharing model
- › Accessed and manipulated by a virtual file system set of system calls
- › File system implementation:
 - › How to map these abstractions to the storage devices
 - › Alternatively, how to implement those system calls

File system basics

- › Virtual file system abstracts away concrete file system implementation
 - › Isolates applications from details of the file system
- › Linux vfs interface includes:
 - › `creat(name)`
 - › `open(name, how)`
 - › `read(fd, buf, len)`
 - › `write(fd, buf, len)`
 - › `sync(fd)`
 - › `seek(fd, pos)`
 - › `close(fd)`
 - › `unlink(name)`

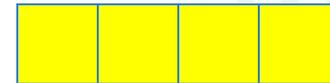


Disk Layout Strategies

- › Files span multiple disk blocks
- › How do you find all of the blocks for a file?

1. Contiguous allocation

- › Like memory
- › Fast, simplifies directory access
- › Inflexible, causes fragmentation, needs compaction



2. Linked structure

- › Each block points to the next, directory points to the first
- › Bad for random access patterns

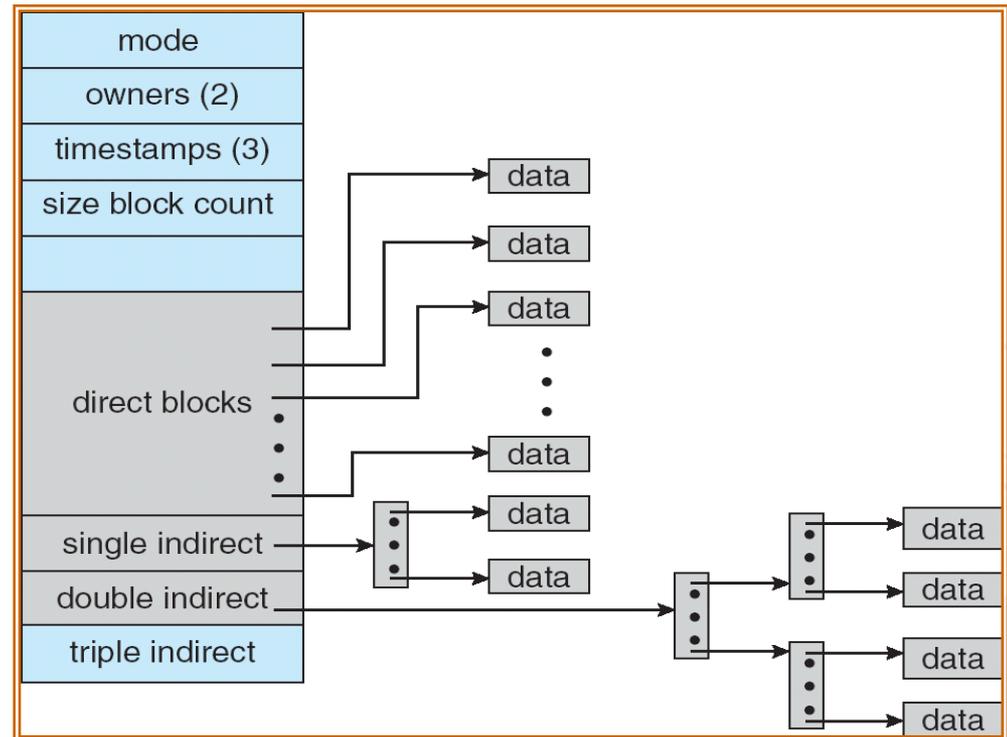


3. Indexed structure (indirection, hierarchy)

- › An “index block” contains pointers to many other blocks
- › Handles random better, still good for sequential
- › May need multiple index blocks (linked together)

Zooming in on i-node

- › i-node: structure for per-file metadata (unique per file)
 - › contains: ownership, permissions, timestamps, about 10 data-block pointers
 - › i-nodes form an array, indexed by “i-number” – so each i-node has a unique i-number
 - › Array is explicit for FFS, implicit for LFS (its i-node map is cache of i-nodes indexed by i-number)



- › Indirect blocks:
 - › i-node only holds a small number of data block pointers (direct pointers)
 - › For larger files, i-node points to an indirect block containing 1024 4-byte entries in a 4K block
 - › Each indirect block entry points to a data block
 - › Can have multiple levels of indirect blocks for even larger files

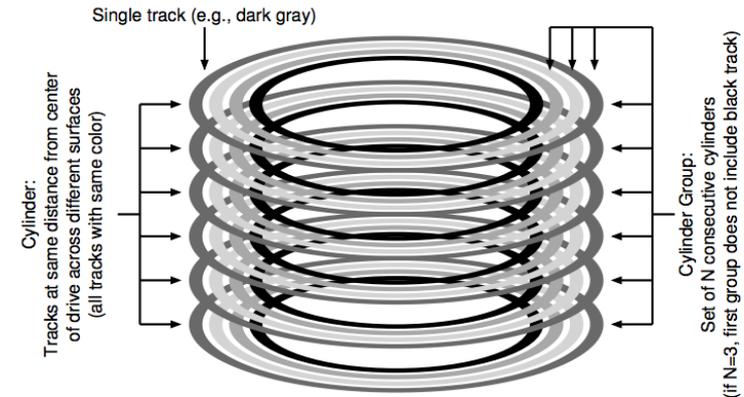
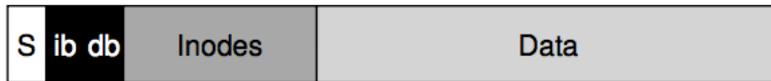
Unix Inodes and Path Search

- › Unix Inodes are **not** directories
- › Inodes describe where on disk the blocks for a file are placed
 - › Directories are files, so inodes also describe where the blocks for directories are placed on the disk
- › Directory entries map file names to inodes
 - › To open “/one”, use Master Block to find inode for “/” on disk
 - › Open “/”, look for entry for “one”
 - › This entry gives the disk block number for the inode for “one”
 - › Read the inode for “one” into memory
 - › The inode says where first data block is on disk
 - › Read that block into memory to access the data in the file
- › This is why we have *open* in addition to *read* and *write*

FFS – what's wrong with original unix FS?

- › Original UNIX FS was simple and elegant, but slow
- › Could only achieve about 20 KB/sec/arm; ~2% of 1982 disk bandwidth
- › Problems:
 - › Blocks too small
 - › 512 bytes (matched sector size)
 - › Consecutive blocks of files not close together
 - › Yields random placement for mature file systems
 - › i-nodes far from data
 - › All i-nodes at the beginning of the disk, all data after that
 - › i-nodes of directory not close together
 - › no read-ahead
 - › Useful when sequentially reading large sections of a file

FFS Changes -- Locality is important



- › Aspects of new file system:
 - › 4096 or 8192 byte block size (why not larger?)
 - › large blocks and small fragments
 - › disk divided into cylinder groups
 - › each contains superblock, i-nodes, bitmap of free blocks, usage summary info
 - › Note that i-nodes are now spread across the disk:
 - › Keep i-node near file, i-nodes of a directory together (shared fate)
 - › Cylinder groups ~ 16 cylinders, or 7.5 MB
 - › Cylinder headers spread around so not all on one platter

FFS Locality Techniques

› Goals

- › Keep directory within a cylinder group, spread out different directories
- › Allocate runs of blocks within a cylinder group, every once in a while switch to a new cylinder group (jump at 1MB)

› Layout policy: global and local

- › Global policy allocates files & directories to cylinder groups – picks “optimal” next block for block allocation
- › Local allocation routines handle specific block requests – select from a sequence of alternative if need to

FFS Results

- › 20-40% of disk bandwidth for large reads/writes
- › 10-20x original UNIX speeds
- › Size: 3800 lines of code vs. 2700 in old system
- › 10% of total disk space unusable (except at 50% performance price)
- › Could have done more; later versions do
- › Watershed moment for OS designers— File system matters

FFS Summary

- › 3 key features:
 - › Parameterize FS implementation for the hardware it's running on
 - › Measurement-driven design decisions
 - › Locality “wins”
- › Major flaws:
 - › Measurements derived from a single installation
 - › Ignored technology trends
- › A lesson for the future: don't ignore underlying hardware characteristics
- › Contrasting research approaches: improve what you've got vs. design something new

File operations still expensive

- › How many operations (seeks) to create a new file?
 - › New file, needs a new inode
 - › But at least a block of data too
 - › Check and update the inode and data bitmap (eventually have to be written to disk)
 - › Not done yet – need to add it to the directory (update the directory inode and the directory data block – may need to split if its full)...
 - › Whew!! How does all of this even work?
- › So what is the advantage?
 - › Not removing any operations
 - › Seeks are just shorter...

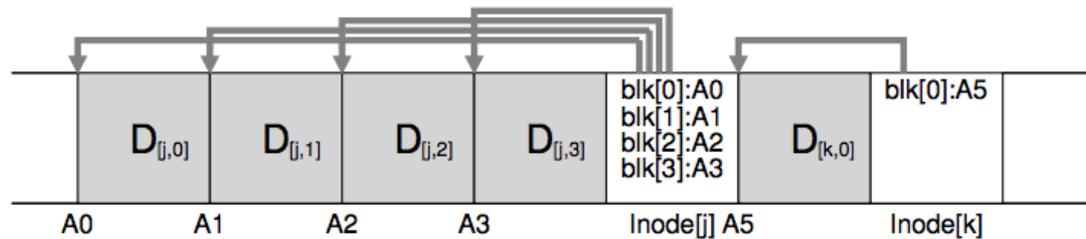
Log-Structured/Journaling File System

- › Radically different file system design
- › Technology motivations:
 - › CPUs outpacing disks: I/O becoming more-and-more of a bottleneck
 - › Large RAM: file caches work well, making most disk traffic writes
- › Problems with (then) current file systems:
 - › Lots of little writes
 - › Synchronous: wait for disk in too many places – makes it hard to win much from RAIDs, too little concurrency
 - › 5 seeks to create a new file: (rough order)
 1. file i-node (create)
 2. file data
 3. directory entry
 4. file i-node (finalize)
 5. directory i-node (modification time)
 6. (not to mention bitmap updates)

LFS Basic Idea

- › Log all data and metadata with efficient, large, sequential writes
 - › Do not update blocks in place – just write new versions in the log
- › Treat the log as the truth, but keep an index on its contents
- › Not necessarily good for reads, but trends help
 - › Rely on a large memory to provide fast access through caching
- › Data layout on disk has “temporal locality” (good for writing), rather than “logical locality” (good for reading)
 - › Why is this a better? Because caching helps reads but not writes!

Basic idea

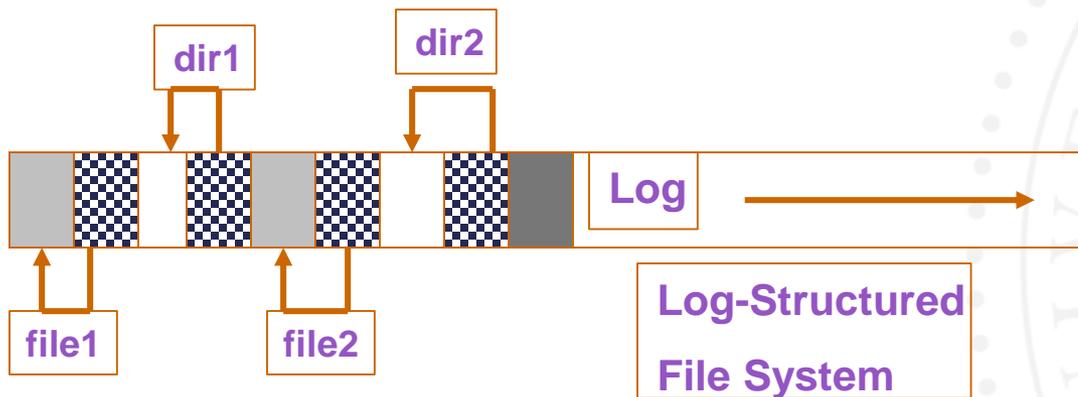
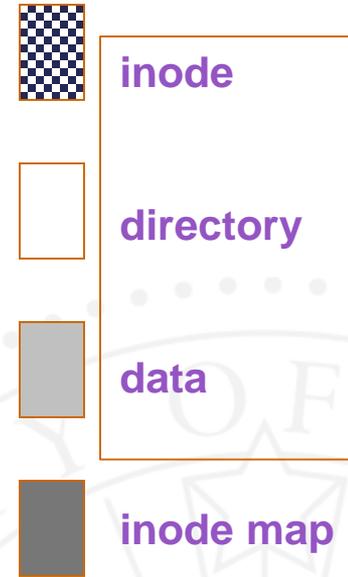
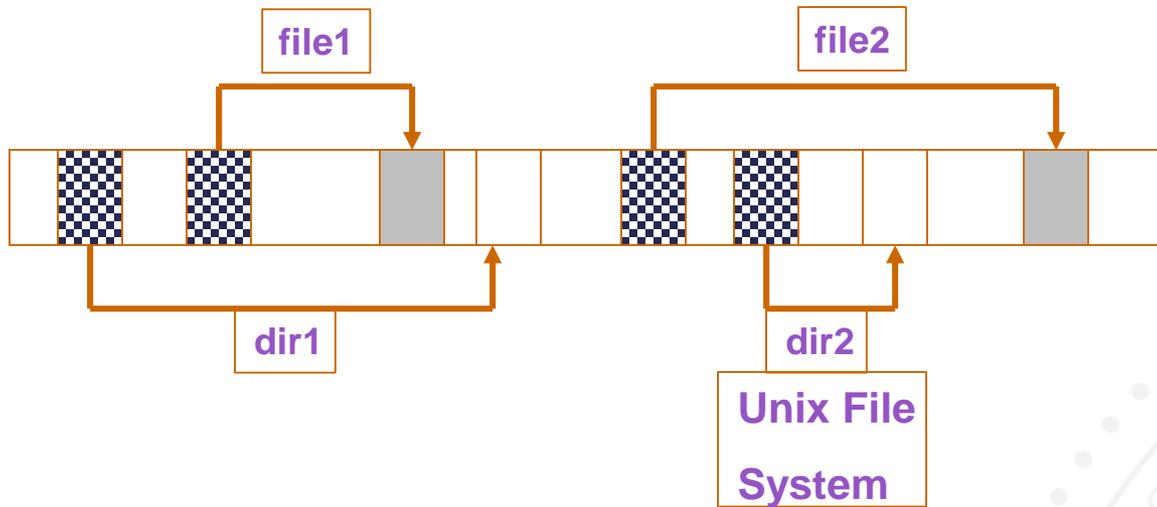


- › We buffer all updates, and write them together in one big sequential write
 - › Good for the disk
 - › Example above, writes to two different files were written together (along with the new version of i-node) in one write
 - › How much should we buffer?
 - › What happens if too much? If too little?
- › But how do we find a file??
 - › All problems in CS solved with another level of indirection ☺

Devil is in the details

- › Two potential problems:
 - › Log retrieval on cache misses – how do we find the data?
 - › Wrap-around: what happens when end of disk is reached?
 - › No longer any big, empty runs available
 - › How to prevent fragmentation?

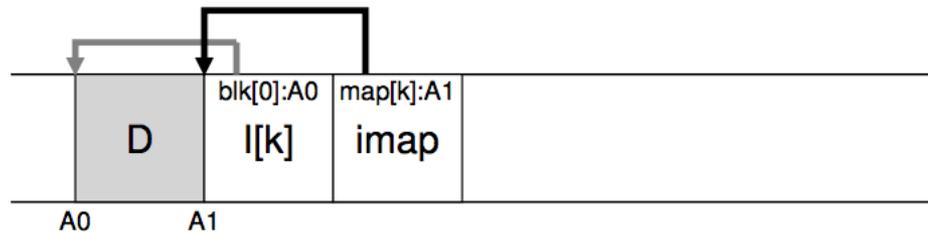
LFS vs. UFS



Blocks written to create two 1-block files: dir1/file1 and dir2/file2, in UFS and

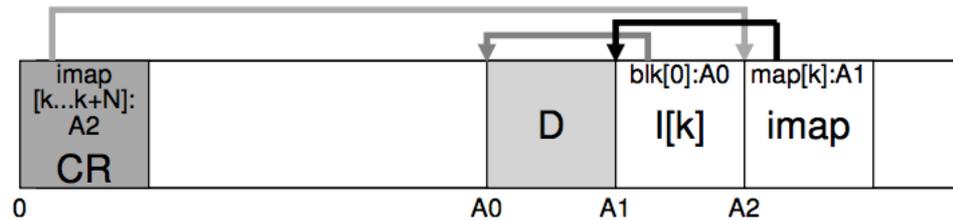
LFS

i-node map



- › A map keeping track of the location of i-nodes
- › Anytime an i-node is written to disk, the imap is updated
 - › But is that any better? In a second
- › Most of the time the imap is in memory, so access is fast
- › Updated imap is saved as part of the log!
 - › but how do we find it!

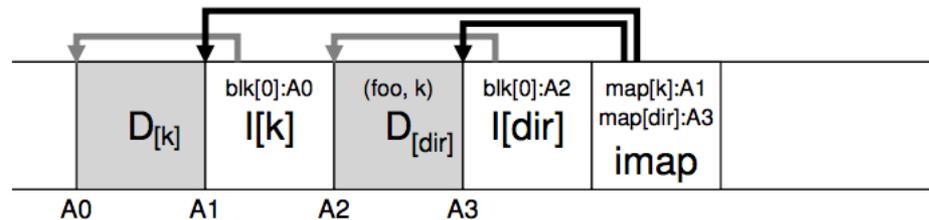
Final piece to the solution



- > Checkpoint region is written to point to the location of the imap
 - > Also serves as an indicator of a stable point in the file system for crash recovery

- > So, to read a file from LFS:
 - > Read the CR, use it to read and cache the imap
 - > After that, it is identical to FFS
 - > Are reads fast?

What about directories?



- › When a file is updated, its inode changes (new copy)
 - › We need to update the directory inode (also creating a copy)
 - › We need to update its parent directory
- › Ugh....what to do?
 - › Inode map helps with that too – just keep track of inode number and resolve it through inode map

LFS Disk Wrap-Around/Garbage collection

- › Compact live info to open up large runs of free space
 - › Problem: long-lived information gets copied over-and-over
- › Thread log through free spaces
 - › Problem: disk fragments, causing I/O to become inefficient again
- › Solution: *segmented log*
 - › Divide disk into large, fixed-size segments
 - › Do compaction within a segment; thread between segments
 - › When writing, use only clean segments (i.e. no live data)
 - › Occasionally clean segments: read in several, write out live data in compacted form, leaving some fragments free
 - › Try to collect long-lived info into segments that never need to be cleaned
 - › Note there is not free list or bit map (as in FFS), only a list of clean segments

LFS Segment Cleaning

- › Which segments to clean?
 - › Keep estimate of free space in each segment to help find segments with lowest utilization
 - › Always start by looking for segment with utilization=0, since those are trivial to clean...
 - › If utilization of segments being cleaned is U:
 - › write cost = (total bytes read & written)/(new data written) = $2/(1-U)$ (unless U is 0)
 - › write cost increases as U increases: U = .9 => cost = 20!
 - › Need a cost of less than 4 to 10; => U of less than .75 to .45
- › How to clean a segment?
 - › Segment summary block contains map of the segment
 - › Must list every i-node and file block
 - › For file blocks you need {i-number, block #}
 - › Through i-map you check if this block is still being used for the (i-number, block #)

Is this a good paper?

- › What were the authors' goals?
- › What about the evaluation/metrics?
- › Did they convince you that this was a good system/approach?
- › Does the system/approach meet the "Test of Time" challenge?
- › How would you review this paper today?