

# CS 153

# Design of Operating Systems

Fall 19

Lecture 8: Deadlock

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# Deadlock – the deadly embrace!

- Synchronization – we can easily shoot ourselves in the foot
  - ◆ Incorrect use of synchronization can block all processes
  - ◆ You have likely been intuitively avoiding this situation already
- Consider: threads that use multiple critical sections/need different resources
  - ◆ If one thread tries to access a resource that a second thread holds, and vice-versa, they can never make progress
- We call this situation **deadlock**, and we'll look at:
  - ◆ Definition and conditions necessary for deadlock
  - ◆ Representation of deadlock conditions
  - ◆ Approaches to dealing with deadlock

# Deadlock Definition

- Deadlock is a problem that can arise:
  - ◆ When threads/processes compete for access to limited resources
  - ◆ When threads/processes are incorrectly synchronized
- Definition:
  - ◆ Deadlock exists among a set of threads if every thread is waiting for an event that can be caused only by another thread in the set

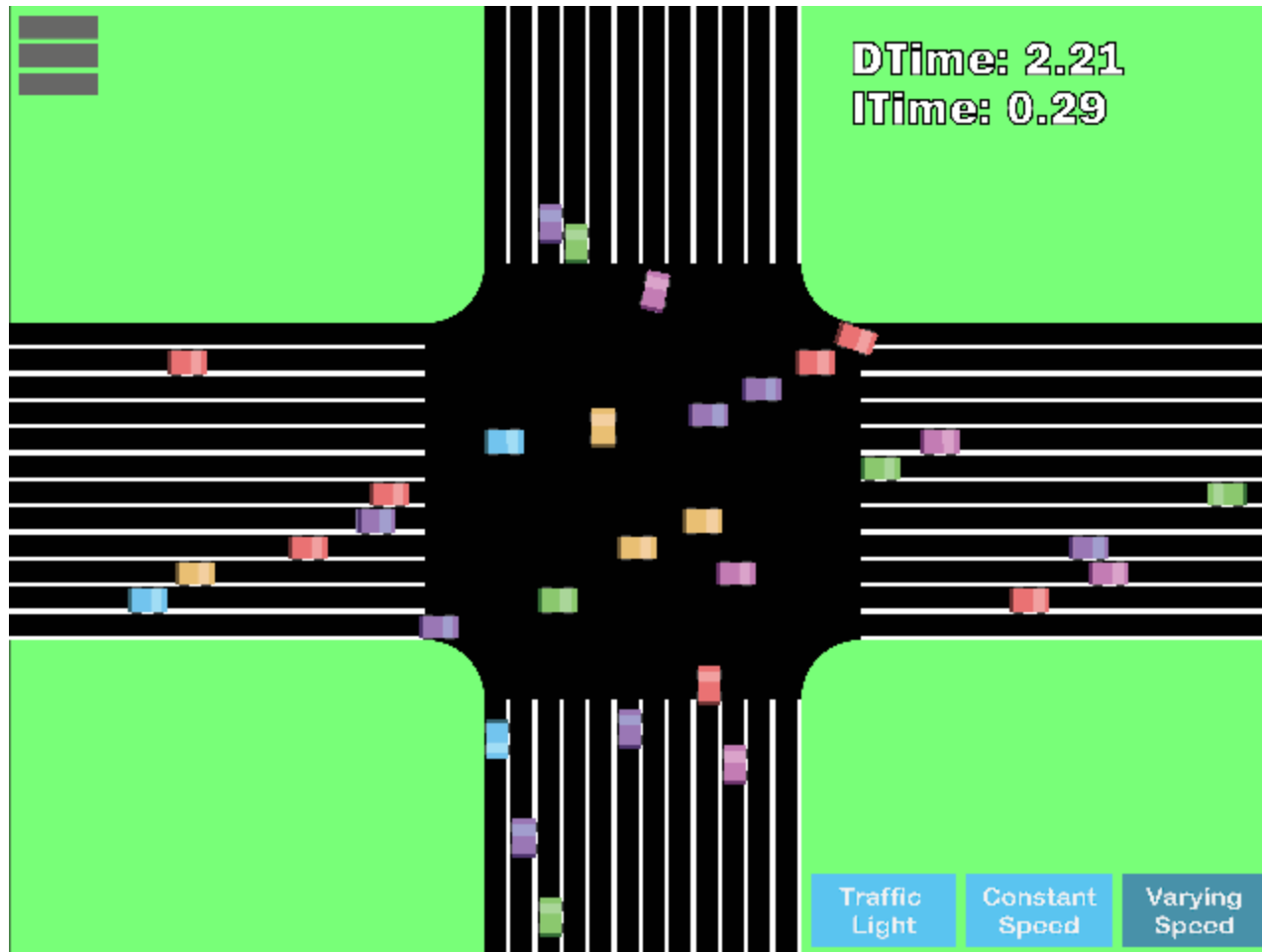
## Thread 1

```
lockA->Acquire();  
...  
lockB->Acquire();
```

## Thread 2

```
lockB->Acquire();  
...  
lockA->Acquire();
```

# Real example!



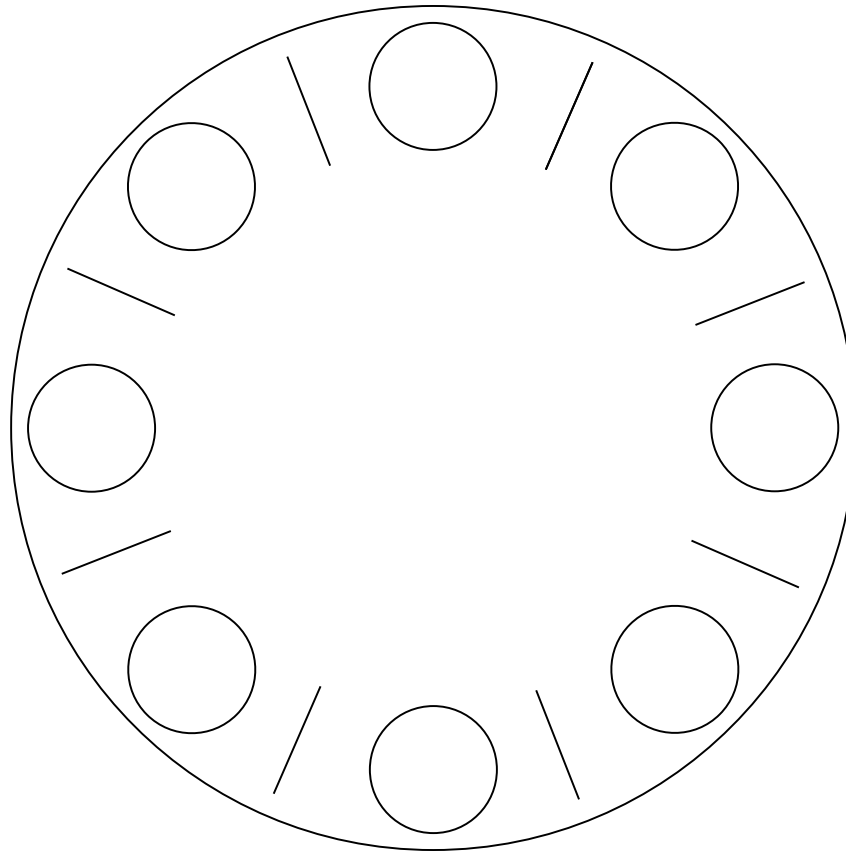
# Real example!



# Conditions for Deadlock

- Deadlock can exist if and only if the following four conditions hold **simultaneously**:
  1. **Mutual exclusion** – At least one resource must be held in a non-sharable mode
  2. **Hold and wait** – There must be one process holding one resource and waiting for another resource
  3. **No preemption** – Resources cannot be preempted (critical sections cannot be aborted externally)
  4. **Circular wait** – There must exist a set of threads  $[T_1, T_2, T_3, \dots, T_n]$  such that  $T_1$  is waiting for  $T_2$ ,  $T_2$  for  $T_3$ , etc.

# Dining Lawyers



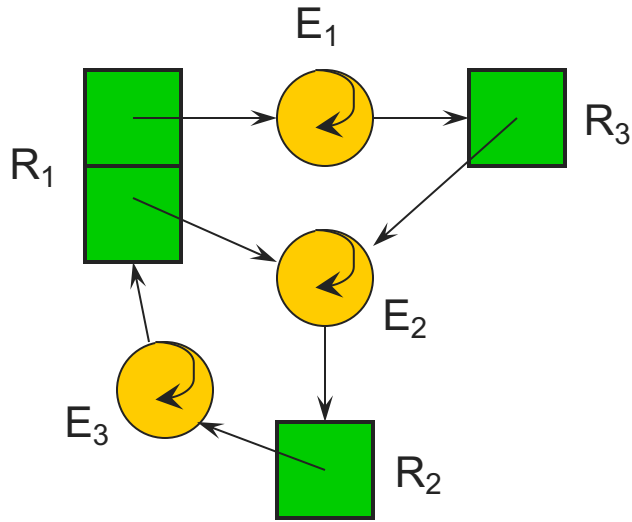
**Each lawyer needs two chopsticks to eat.  
Each grabs chopstick on the right first.**

# Lets get formal for a minute

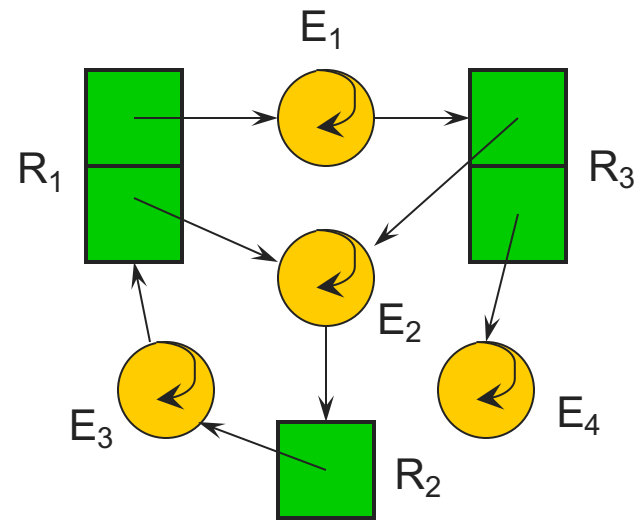
- Deadlock can be described using a resource allocation graph (RAG)
- The RAG consists of a set of vertices  $E=\{E_1, E_2, \dots, E_n\}$  of entities and  $R=\{R_1, R_2, \dots, R_m\}$  of resources
  - ◆ A directed edge from a entity to a resource,  $E_i \rightarrow R_i$ , means that  $E_i$  has requested  $R_j$
  - ◆ A directed edge from a resource to a entity,  $R_i \rightarrow E_i$ , means that  $R_j$  has been allocated to  $E_i$
  - ◆ Each resource has a fixed number of units
- If the graph has no cycles, deadlock **cannot exist**
- If the graph has a cycle, deadlock **may exist**



# RAG Example



**A cycle...and  
deadlock!**



**Same cycle...but no  
deadlock. Why?**

# A Simpler Way

- If all resources are **single unit** and all processes make single requests, then we can represent the resource state with a simpler waits-for graph (WFG)
- The WFG consists of a set of vertices  $E = \{E_1, E_2, \dots, E_n\}$  of entities
  - ◆ A directed edge  $E_i \rightarrow E_j$  means that  $E_i$  has requested a resource that  $E_j$  currently holds
- If the graph has no cycles, deadlock **cannot exist**
- If the graph has a cycle, deadlock **exists**

# In Practice

- Resources are usually synchronization primitives
  - ◆ Locks, semaphores, ...
- Entities are usually threads, but could also be processes

# Dealing with Deadlock

- There are four approaches for dealing with deadlock:
  - ◆ **Ignore it** – how lucky do you feel?
  - ◆ **Prevention** – make it impossible for deadlock to happen
  - ◆ **Avoidance** – control allocation of resources
  - ◆ **Detection and Recovery** – look for a cycle in dependencies

# Deadlock Prevention

- Prevention – Ensure that at least one of the necessary conditions cannot happen
  - ◆ Mutual exclusion
    - » Make resources sharable (not generally practical)
  - ◆ Hold and wait
    - » Process/thread cannot hold one resource when requesting another
  - ◆ Preemption
    - » OS can preempt resource (costly)
  - ◆ Circular wait
    - » Impose an ordering (numbering) on the resources and request them in order (**popular implementation technique**)

# Deadlock Prevention

- One shot allocation: ask for all your resources in one shot; no more resources can be requested
  - ◆ What ingredient does this prevent?
  - ◆ Comments?
- Preemption
  - ◆ Nice: Give up a resource if what you want is not available
  - ◆ Aggressive: steal a resource if what you want is not available
- Hierarchical allocation:
  - ◆ Assign resources to classes
  - ◆ Can only ask for resources from a higher number class than what you hold now

# Deadlock Avoidance

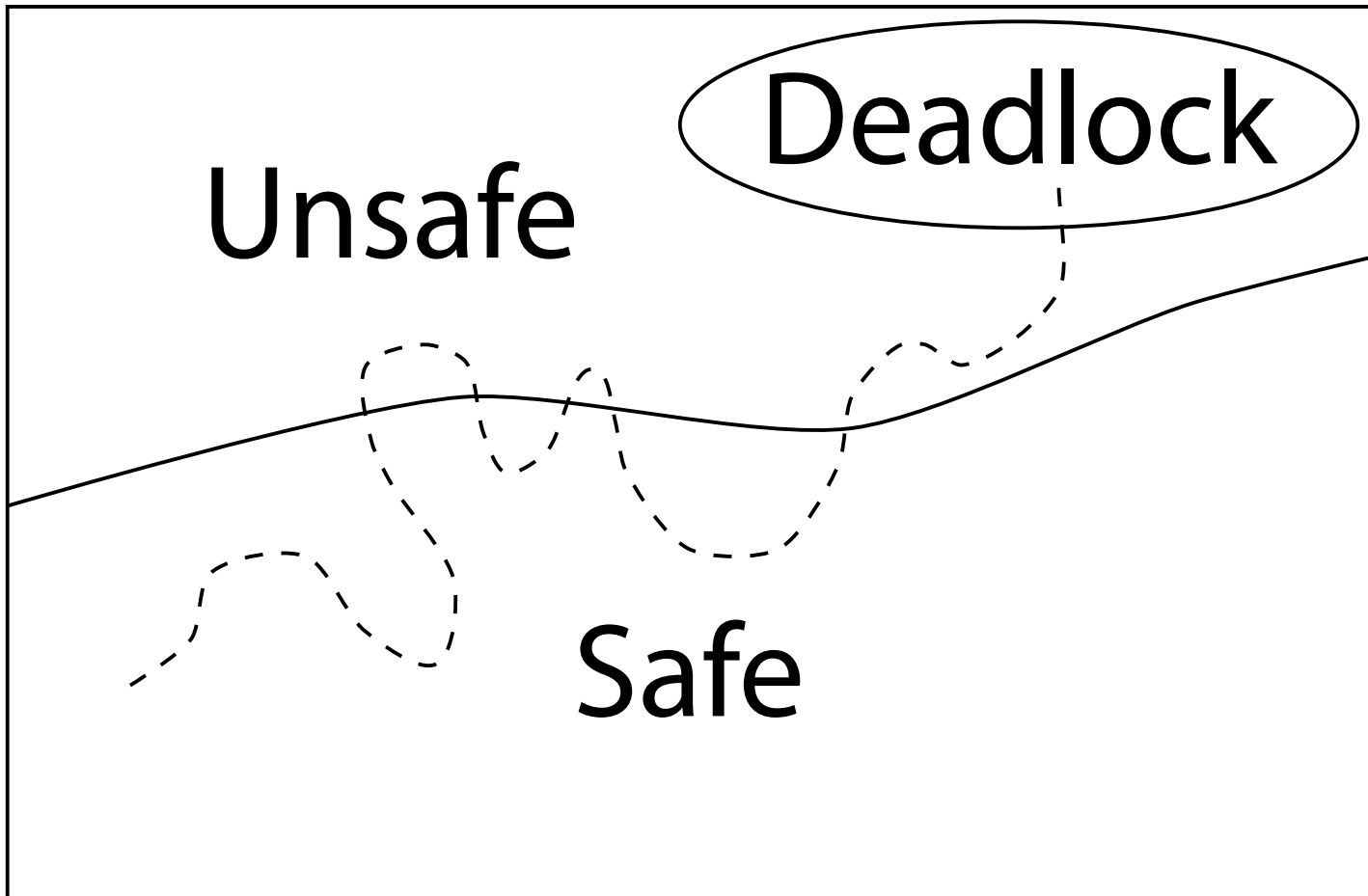
- Prevention can be too conservative – can we do better?
- Avoidance
  - ◆ Provide information in advance about what resources will be needed by processes
  - ◆ System only grants resource requests if it knows that deadlock cannot happen
  - ◆ Avoids circular dependencies
- Tough
  - ◆ Hard to determine all resources needed in advance
  - ◆ Good theoretical problem, not as practical to use

# Banker's Algorithm

- The Banker's Algorithm is the classic approach to deadlock avoidance for resources with multiple units
  1. Assign a **credit limit** to each customer (process)
    - » Maximum credit claim must be stated in advance
  2. Reject any request that leads to a **dangerous state**
    - » A dangerous state is one where a sudden request by any customer for the full credit limit could lead to deadlock
    - » A recursive reduction procedure recognizes dangerous states
  3. In practice, the system must keep resource usage well below capacity to maintain a **resource surplus**
    - » Rarely used in practice due to low resource utilization

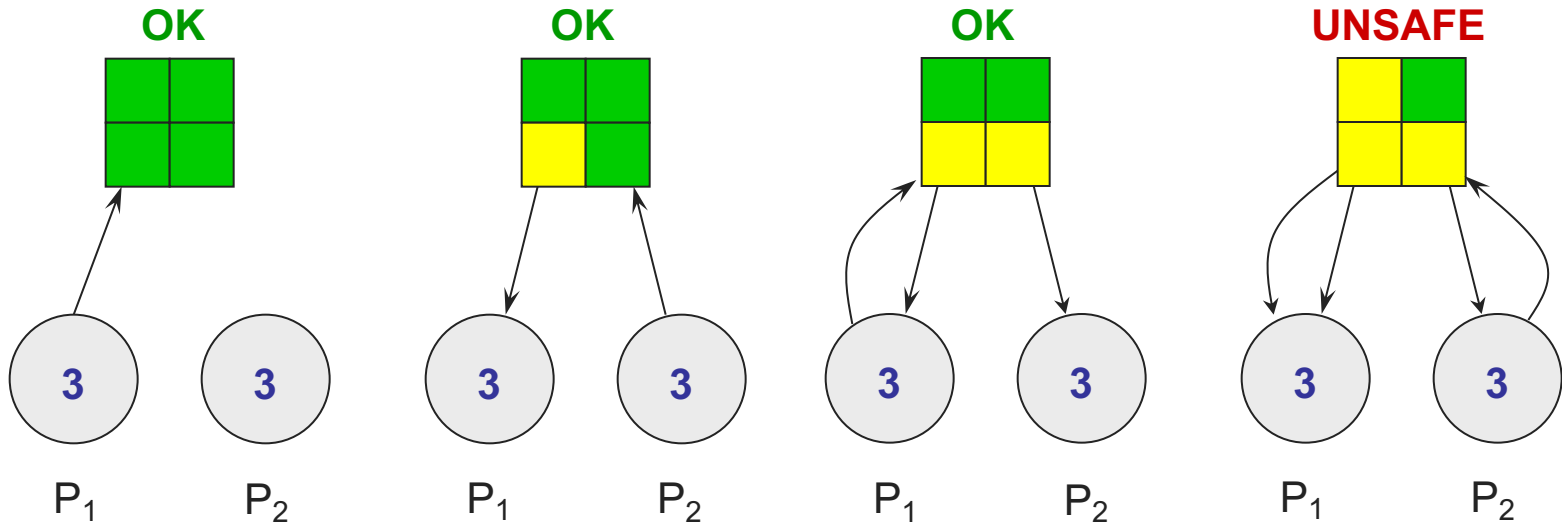


# Possible System States



# Banker's Algorithm Simplified

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# Detection and Recovery

- Detection and recovery
  - ◆ If we don't have deadlock prevention or avoidance, then deadlock may occur
  - ◆ In this case, we need to detect deadlock and recover from it
- To do this, we need two algorithms
  - ◆ One to determine whether a deadlock has occurred
  - ◆ Another to recover from the deadlock
- Possible, but expensive (time consuming)
  - ◆ Implemented in VMS
  - ◆ Run detection algorithm when resource request times out

# Deadlock Detection

- Detection
  - ◆ Traverse the resource graph looking for cycles
  - ◆ If a cycle is found, preempt resource (force a process to release)
- Expensive
  - ◆ Many processes and resources to traverse
- Only invoke detection algorithm depending on
  - ◆ How often or likely deadlock is
  - ◆ How many processes are likely to be affected when it occurs

# Deadlock Recovery

Once a deadlock is detected, we have two options...

## 1. Abort processes

- ◆ Abort all deadlocked processes
  - » Processes need to start over again
- ◆ Abort one process at a time until cycle is eliminated
  - » System needs to rerun detection after each abort

## 2. Preempt resources (force their release)

- ◆ Need to select process and resource to preempt
- ◆ Need to rollback process to previous state
- ◆ Need to prevent starvation

# Deadlock Summary

- Deadlock occurs when threads/processes are waiting on each other and cannot make progress
  - ◆ Cycles in Wait For Graph (WFG)
- Deadlock requires four conditions
  - ◆ Mutual exclusion, hold and wait, no resource preemption, circular wait
- Four approaches to dealing with deadlock:
  - ◆ **Ignore it** – Living life on the edge
  - ◆ **Prevention** – Make one of the four conditions impossible
  - ◆ **Avoidance** – Banker's Algorithm (control allocation)
  - ◆ **Detection and Recovery** – Look for a cycle, preempt or abort