#### Math 142-2, Midterm

Name: \_\_\_\_\_ ID: \_\_\_\_\_

#### Problem 1

Consider a damped spring given by the equation mx'' + cx'|x'| + kx = 0.

- (a) Show that total energy can never increase. Can it decrease?
- (b) Why is  $c(x')^2$  not used for the damping term?
- (c) What are the units of c?

# Problem 1 (continued)

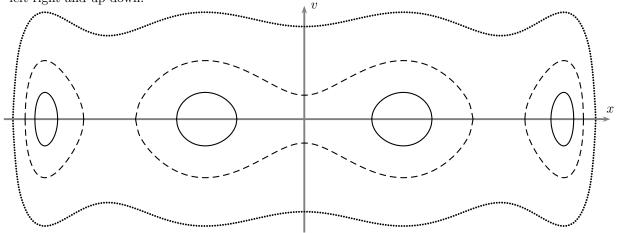
Consider a damped spring given by the equation mx'' + cx'|x'| + kx = 0.

(d) Determine using linearized stability analysis whether the system is stable, unstable, or neutrally stable.

(e) Is the system stable, unstable, or neutrally stable? Why?

#### Problem 2

Consider the ODE mx'' = f(x) for a particle, where the force f(x) has the potential energy function  $\phi(x)$ . Below is part of the phase plane diagram for the resulting ODE. The phase plane is symmetrical left-right and up-down.

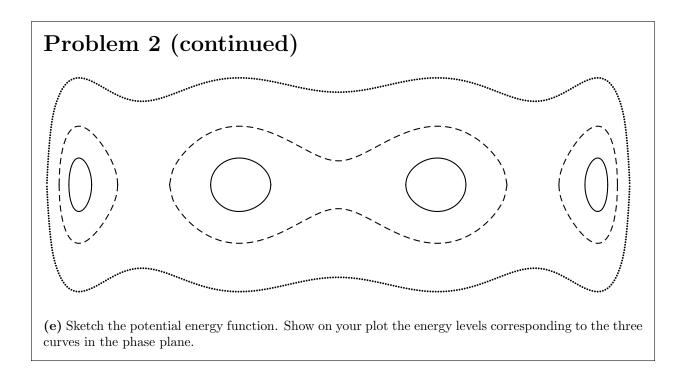


(a) The phase plane shows three energy levels: dotted, dashed, and solid. Which of these corresponds to the highest energy level? Which corresponds to the lowest energy level?

(b) On the phase plane diagram above, mark the stable equilibria with " $\bullet$ " and the unstable equilibria with " $\circ$ ".

(c) On the phase plane diagram above, sketch the curves whose energy matches the energy of the unstable equilibria. These energy curves may contain more than one piece; be sure to sketch all of them.

(d) Put arrows on all of the curves (including the ones you drew in part (c)) to show the trajectories.

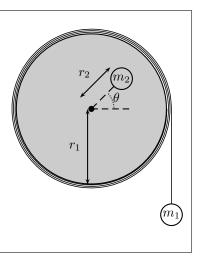


### Problem 3

A pulley of radius  $r_1$  has wrapped around it a long cable with an object of mass  $m_1$  hanging from it. Another object of mass  $m_2$  is attached to the pulley at a distance of  $r_2$  from the pulley's center. Let  $\theta$  be the polar angle the attached mass. Assume the cable is arbitrarily long.

- (a) What is the potential energy of the system (in terms of  $\theta$ )?
- (b) What is the total energy of the system (in terms of  $\theta$  and  $\dot{\theta}$ )?
- (c) Show that this system obeys the ODE

 $(m_1r_1^2 + m_2r_2^2)\ddot{\theta} + r_2m_2g\cos\theta + r_1m_1g = 0.$ 



## Problem 3 (continued)

(d) If  $m_2 < M_e$ , for some critical mass  $M_e$ , then this system has no equilibria. Find  $M_e$ .

(e) If  $m_2 < M_e$ , describe qualitatively the dynamical behavior of the system.

