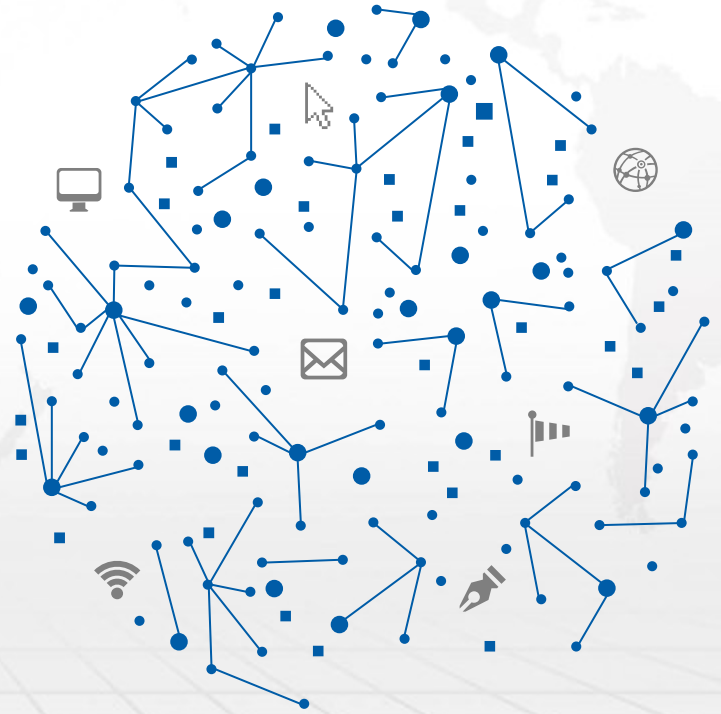


Challenges of managing LiDAR data, point cloud data

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What are “Challenges” of managing LiDAR data?

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1. Acquisition

How to acquire a huge amount of data, useful data?

2. Storage

How to store them so that we can query them within a short time?

3. Utilization

How to analyze and visualize the data?

A faint, light gray world map is visible in the background of the slide. The word "Paper" is centered in the upper left quadrant, flanked by horizontal dashed lines with diamond-shaped ends.

Paper

"Dictionary compression in point cloud data management."

Pavlovic, Mirjana, et al.

Proceedings of the 25th ACM SIGSPATIAL International Conference on Advances in Geographic Information Systems. 2017.

Overview



- 1 Research Backgrounds
- 2 Proposed Methods
- 3 Experimental Evaluation
- 4 Conclusion



Research Backgrounds

Dictionary-Based Compression

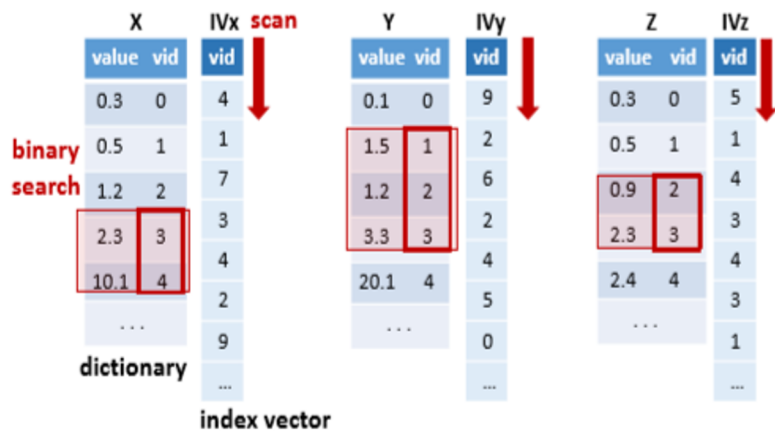


Figure 1: An example of range query execution over a dictionary-based representation of point cloud data.

Advantages: encode the data using information that is not stored in the actual datafile we are

How to optimize?

challenges: waste computational resources (it does not leverage the spatial properties of data)

Dictionary-Based Compression

Dictionary Compression in Point Cloud Data Management

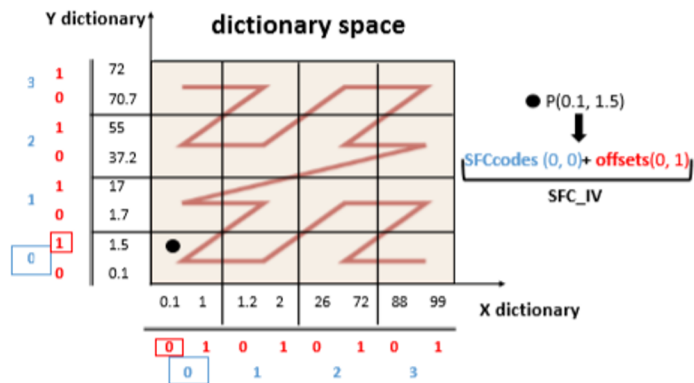
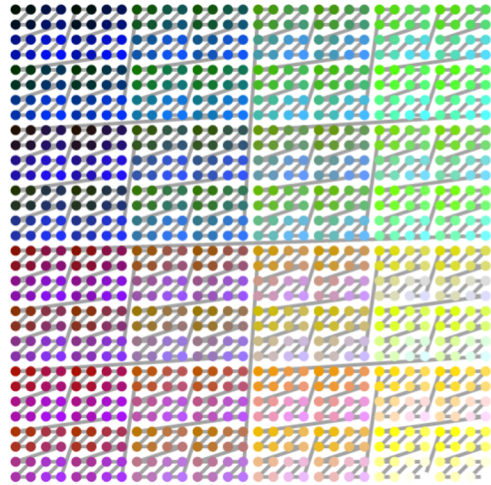


Figure 2: Dictionary space, 2D illustration.

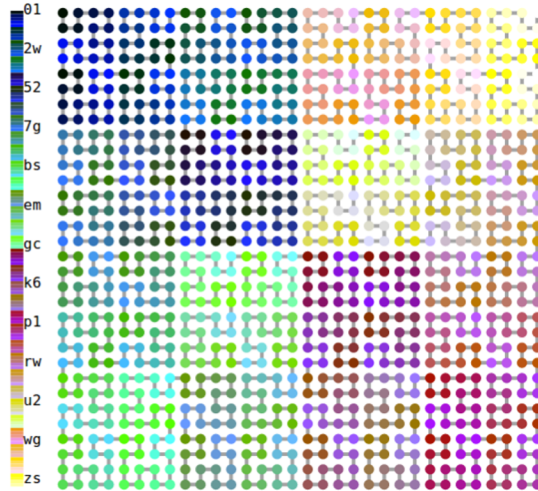
How to optimize: restrict a search range in singular index structure (this does not increase the data access patterns)

Space-filling Curves

MORTON CURVE in a grid of 1024 cells



HILBERT CURVE in a grid of 1024 cells



Advantages: transforms data from a multi- dimensional to a one-dimensional domain using SFC to impose a total, 1 D order by visiting all the points in a d-dimensional grid exactly once.

Space-filling Curves

Step1

Partition the dataset's universe with a uniform grid and assign to each cell a value on the space-filling curve



1

SFC order reorganizes data (three steps)

Step2

Assign SFC code to every point cloud entry according to the grid cell they belong to, where multiple point cloud entries can map to the same SFC code value curve



2

Step3

Sort the points based on the assigned SFC code

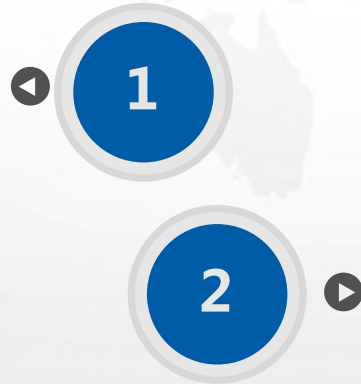


3

Space-filling Curves

Step 1

Transform a query to the 1D domain according to the SFC-order and perform binary search on the SFC codes data structure based on the transformed ranges



Range query execution order (two steps)

Step 2

As a SFC code is assigned per cell and not per point basis, all the points whose SFC code matches the result of the binary search have to be additionally checked whether they belong to the query range in order to remove false positives.

Space-filling Curves



Challenge:
the SFC codes structure requires
additional storage resources. (hurts
space efficiency)

Space-filling Curves Dictionary-based Compression

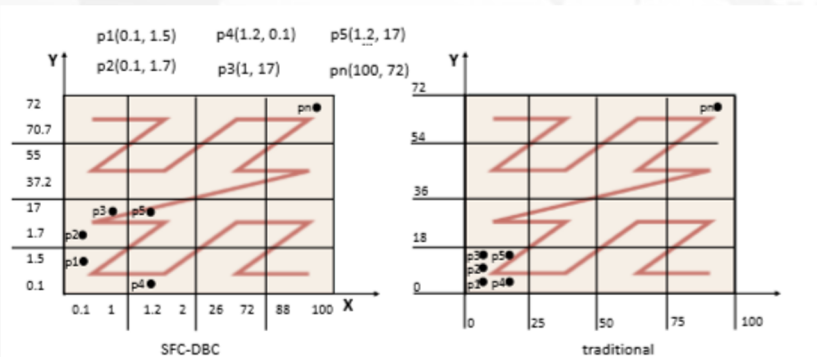


Figure 3: SFC-DBC (data-oriented) and SFC-based (space-oriented) partitioning strategy.

Advantages: SFC-DBC combines DBC with SFC order to ensure space efficiency and preserve spatial proximity, thus optimizing for query execution



Proposed Method

Space-filling Curves Dictionary-based Compression

1. producing a 3D dictionary space and a grid on top of it

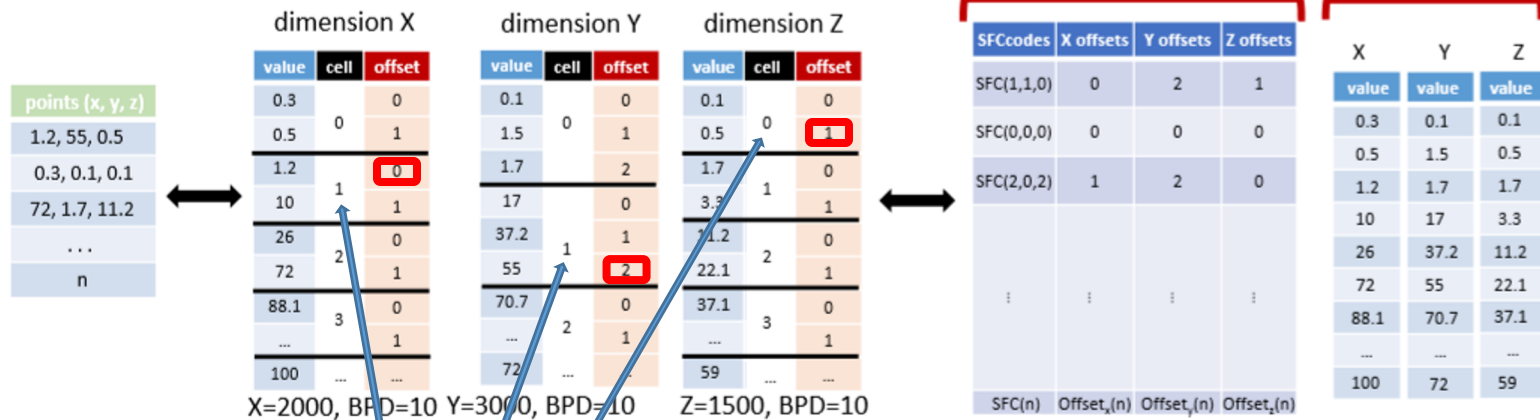


Figure 4: Point cloud data organized according to SFC-DBC Encoding.

2. Assign a SFC code to every point according to the dictionary cells they belong to

3. Additionally store the position of the point within the cells

4. Once the final structures are produced, we sort them according to the assigned SFC code

Query Execution

First step:
Produce a candidate result set.

Algorithm 1: Query Execution: produce candidate results set

Input: q : range query - defined with two coordinates

Output: $minDQ$, $maxDQ$: min and max position in dictionary
that corresponds to query range

Output: $candidateSet$: candidate result set

//transforms query to 1D:

for $d = 0$ **to** $dimensions$ **do**

$minDQ[d] = binaryS(dictionary[d], q.low[d])$

$maxDQ[d] = binaryS(dictionary[d], q.high[d])$

end

$qSFCcodes = calcSFCcode(q, minDQ, maxDQ)$

$candidateSet = binaryS(qSFCcodes, SFCcodes)$

return $candidateSet$

Query Execution

Second step:

Produce the final result set.

Time consuming:

scan offsets + decoding SFCcode

Algorithm 2: Query Execution: produce final results set

Input: q : range query - defined with two coordinates

Input: candidateSet: candidate result set

Input: minDQ, maxDQ: min and max position in dictionary that corresponds to query range

Input: EPC: number of entries per cell, d - dimension

Output: pOut: point cloud result set

```
for  $i = \text{value in candidateSet}$  do
   $\text{cell\_id} = \text{decode}(\text{SFCCodes}[i], d)$ 
   $\text{base} = \text{cell\_id} * \text{EPC}[d]$ 
  //retrieve the positions of the points for the given SFCcode
   $\langle \text{inputMin}, \text{inputMax} \rangle = \text{mapSFCCodeToInputPosition}(i)$ 
  //enclosedByQuery condition
  if  $\text{minDQ}[d] < \text{base}$  AND  $(\text{base} + \text{EPC}[d]) < \text{maxDQ}[d]$ 
    then
      |  $\text{pOut.setRange}(\text{inputMin}, \text{inputMax})$ 
      | continue
    end
  //not enclosedByQuery - retrieve offsets
  for  $j = \text{inputMin}; j < \text{inputMax}$  do
    | position = base + offsets[j];
    | if  $\text{minDQ} < \text{position} < \text{maxDQ}$  then
    | |  $\text{pOut.set}(j)$ 
    | end
  end
end
return pOut
```

Analyze

Space requirements

Assume each dictionary in 3d space has the same length

Traditional DBC: $3 \times (DS \times de + n \times \log_2 DS)$

SFC-DBC: $3 \times (DS \times de + n \times \log_2 \lceil DS / 2^{BPD} \rceil + \#SFCcode \times BPD)$

DS: the number of entries

de: the size of an entry

n: the number of points

$\log_2 DS$: the number of bits per Index Vector entry

BPD : the number of bits assigned per dimension

#SFC-code : represents the number of distinct SFCcode values



Experimental Evaluation

Experiment Environment

Hardware Configuratio

SuSE Linux Enterprise Server 12
SP1 machine
4 Intel Xeon CPU E7-4880v2
processors at 2.50GHz and 512GB
of RAM
Each processor has 15 cores with
private L1 (32KB) and L2 (256KB)
caches, as well as 37,5MB of
shared L3 cache.

1

SAP HANA

HANA is an in-memory database
that offers the possibility to store
data in either a row-oriented or a
column-oriented fashion.

2

Experiment Environment

Dataset

1. AHN2 dataset
2. Senatsverwaltung für Wirtschaft, Technologie und Forschung" and "Europäischer Fonds für regionale Entwicklung (EFRE)" provided the dataset that are generated by using dense image matching.

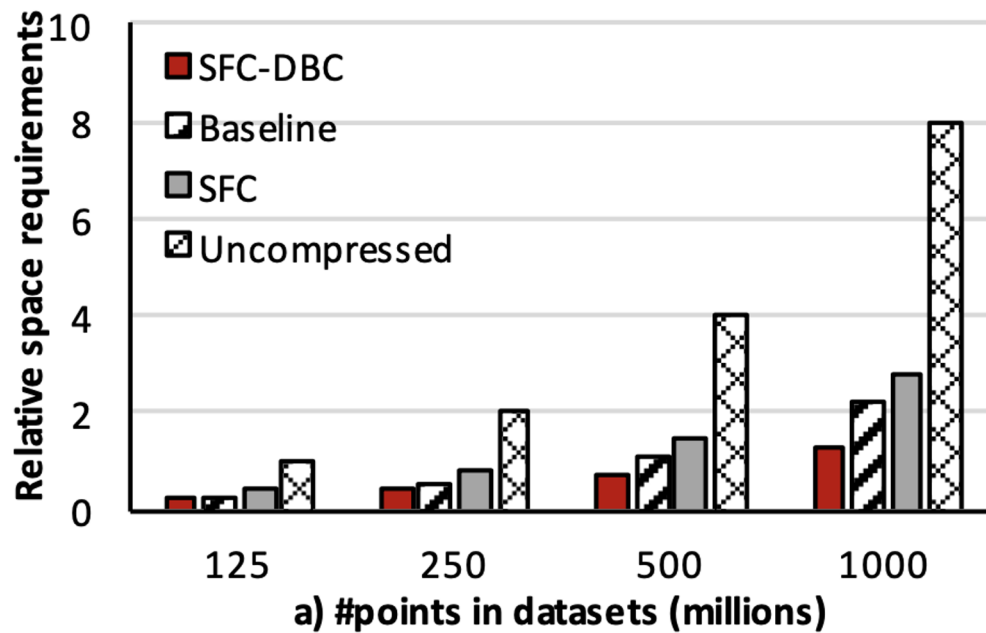
1

Query

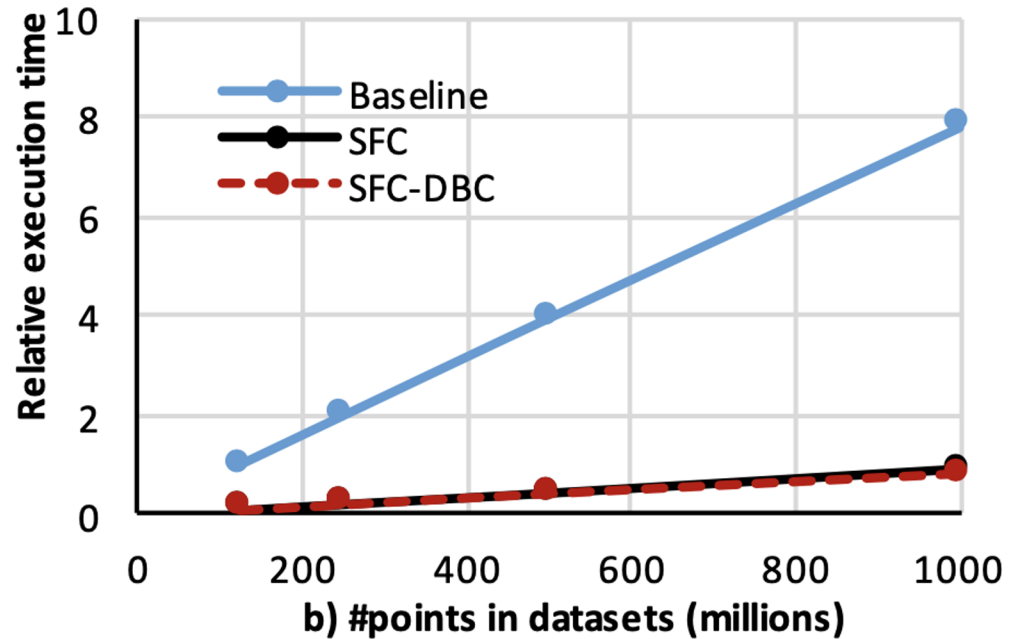
one hundred 2D and 3D range queries that follow uniform distribution.

2

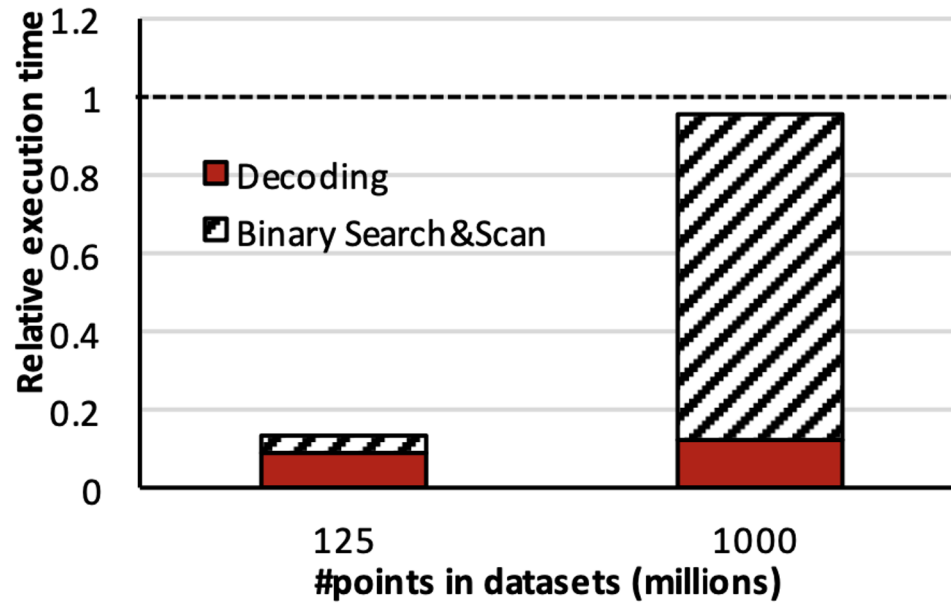
Space Requirements



Query Performance



Query Performance



Impact of Skew

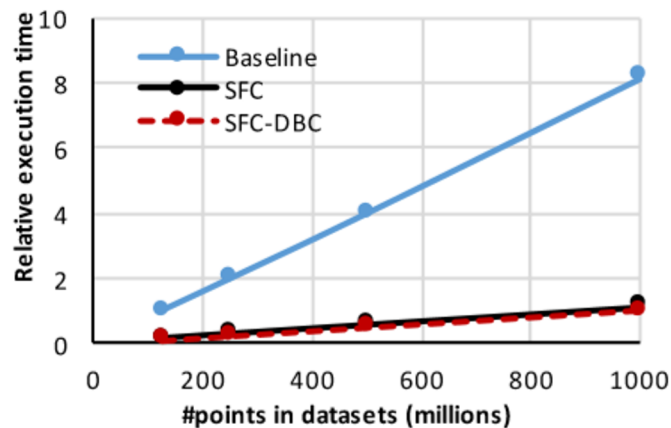
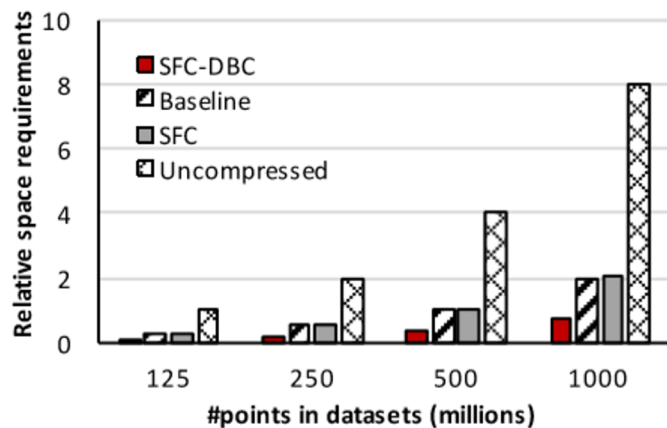


Figure 9: The impact of skew: space requirements and query execution time.

Impact of Filtering

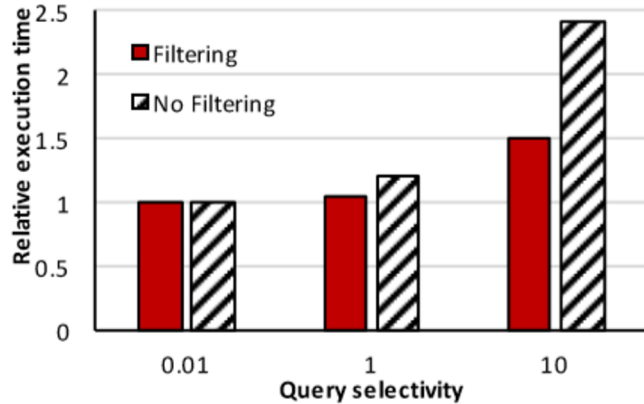


Figure 11: SFC-DBC: impact of filtering.

The relative execution time for the SFC-DBC approach, when enable and disable filtering

The filtering step significantly improves the execution time for low selectivity queries, considering that it filters more data (e.g., the improvement in the execution time is 38% for 10% selectivity)

Filtering does not have a significant impact on performance when executing high selectivity queries (e.g., for 0.01% selectivity queries the improvement in the execution time is 0.6%).



Conclusions

Conclusion

Executing existing data management solutions face two challenges: time and space efficiency.

SFC-DBC employs dictionary-based compression in the spatial data management domain, enhancing it with indexing capabilities without introducing additional storage overhead, thus solve the two problems.

The image features a light gray world map in the upper half, centered on the Atlantic Ocean. Below the map is a perspective grid of thin gray lines that recedes into the distance. The text "Thanks for listening!" is centered in the middle of the image in a bold, blue, sans-serif font.

Thanks for listening!