

CS141: Intermediate Data Structures and Algorithms

Greedy Algorithms

Amr Magdy

Activity Selection Problem

- ▶ Given a set of activities $S = \{a_1, a_2, \dots, a_n\}$ where each activity i has a start time s_i and a finish time f_i , where $0 \leq s_i < f_i < \infty$.
- ▶ An activity a_i happens in the half-open time interval $[s_i, f_i)$.

Activity Selection Problem

- ▶ Given a set of activities $S = \{a_1, a_2, \dots, a_n\}$ where each activity i has a start time s_i and a finish time f_i , where $0 \leq s_i < f_i < \infty$.
- ▶ An activity a_i happens in the half-open time interval $[s_i, f_i)$.
- ▶ Activities compete on a single resource, e.g., CPU

Activity Selection Problem

- ▶ Given a set of activities $S = \{a_1, a_2, \dots, a_n\}$ where each activity i has a start time s_i and a finish time f_i , where $0 \leq s_i < f_i < \infty$.
- ▶ An activity a_i happens in the half-open time interval $[s_i, f_i)$.
- ▶ Activities compete on a single resource, e.g., CPU
- ▶ Two activities are said to be **compatible** if they **do not overlap**.

Activity Selection Problem

- ▶ Given a set of activities $S = \{a_1, a_2, \dots, a_n\}$ where each activity i has a start time s_i and a finish time f_i , where $0 \leq s_i < f_i < \infty$.
- ▶ An activity a_i happens in the half-open time interval $[s_i, f_i)$.
- ▶ Activities compete on a single resource, e.g., CPU
- ▶ Two activities are said to be **compatible** if they **do not overlap**.
- ▶ The problem is to find a **maximum-size compatible subset**, i.e., a one with the maximum number of activities.

Example

a3[0,6)

a10[2,14)

a1[1,4)

a9[8,12)

a5[3,9)

a4[5,7)

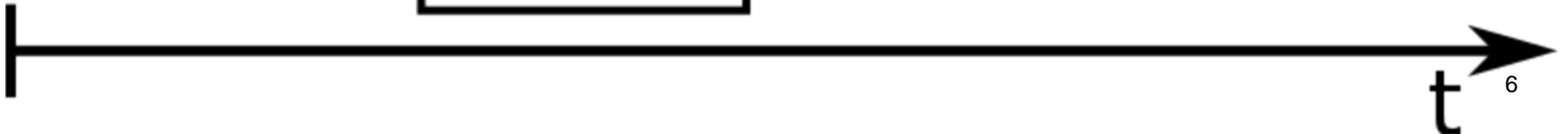
a8[8,11)

a2[3,5)

a7[6,10)

a11[12,16)

a6[5,9)



A Compatible Set

a3[0,6)

a10[2,14)

a1[1,4)

a9[8,12)

a5[3,9)

a4[5,7)

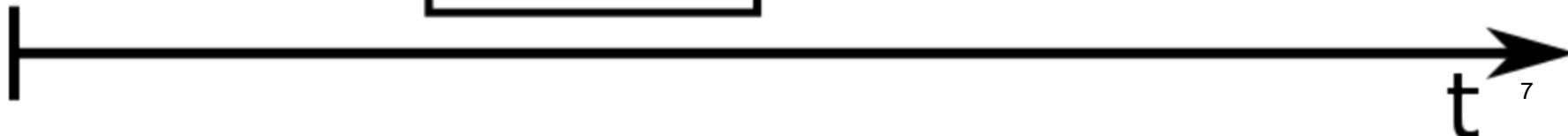
a8[8,11)

a2[3,5)

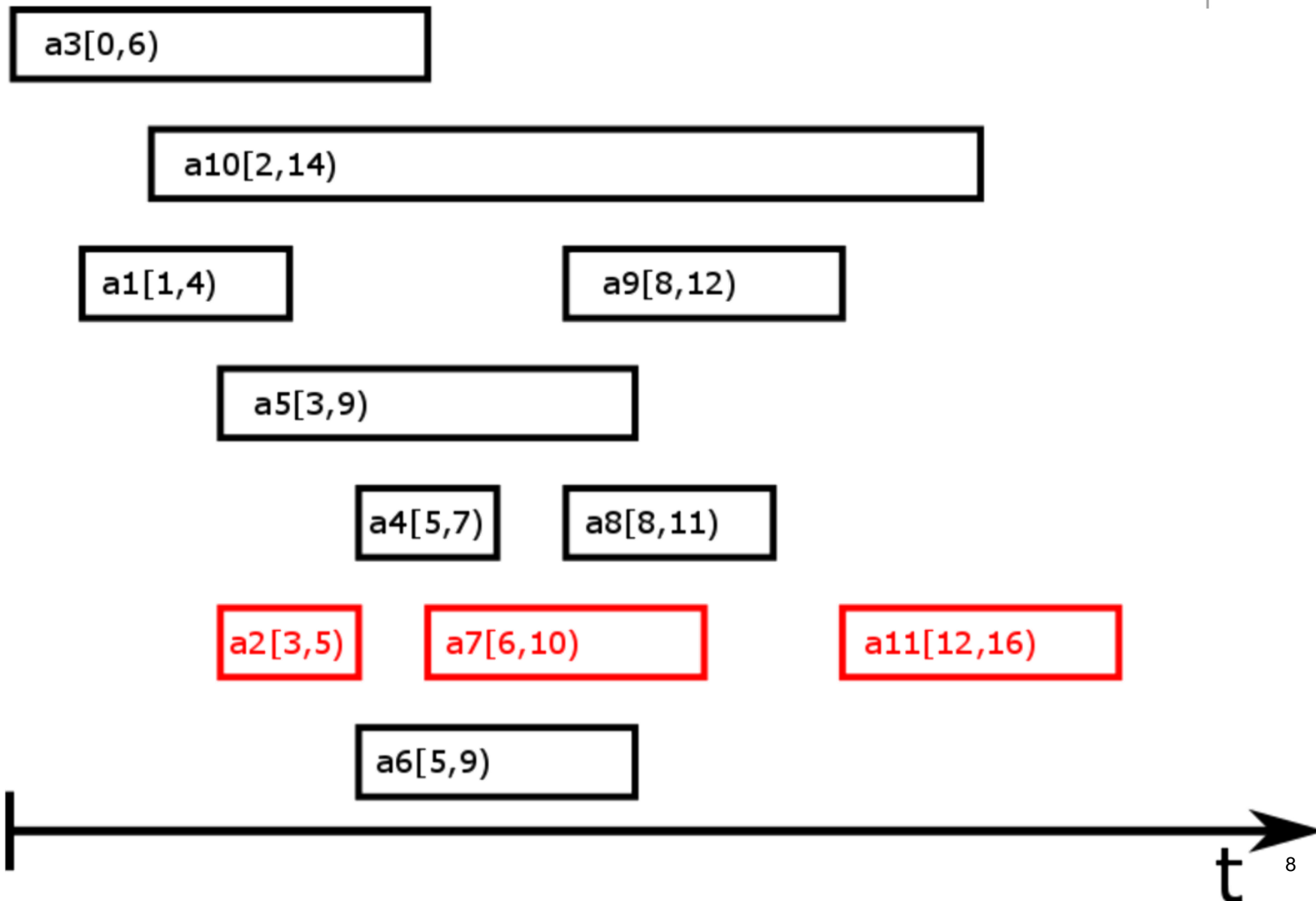
a7[6,10)

a11[12,16)

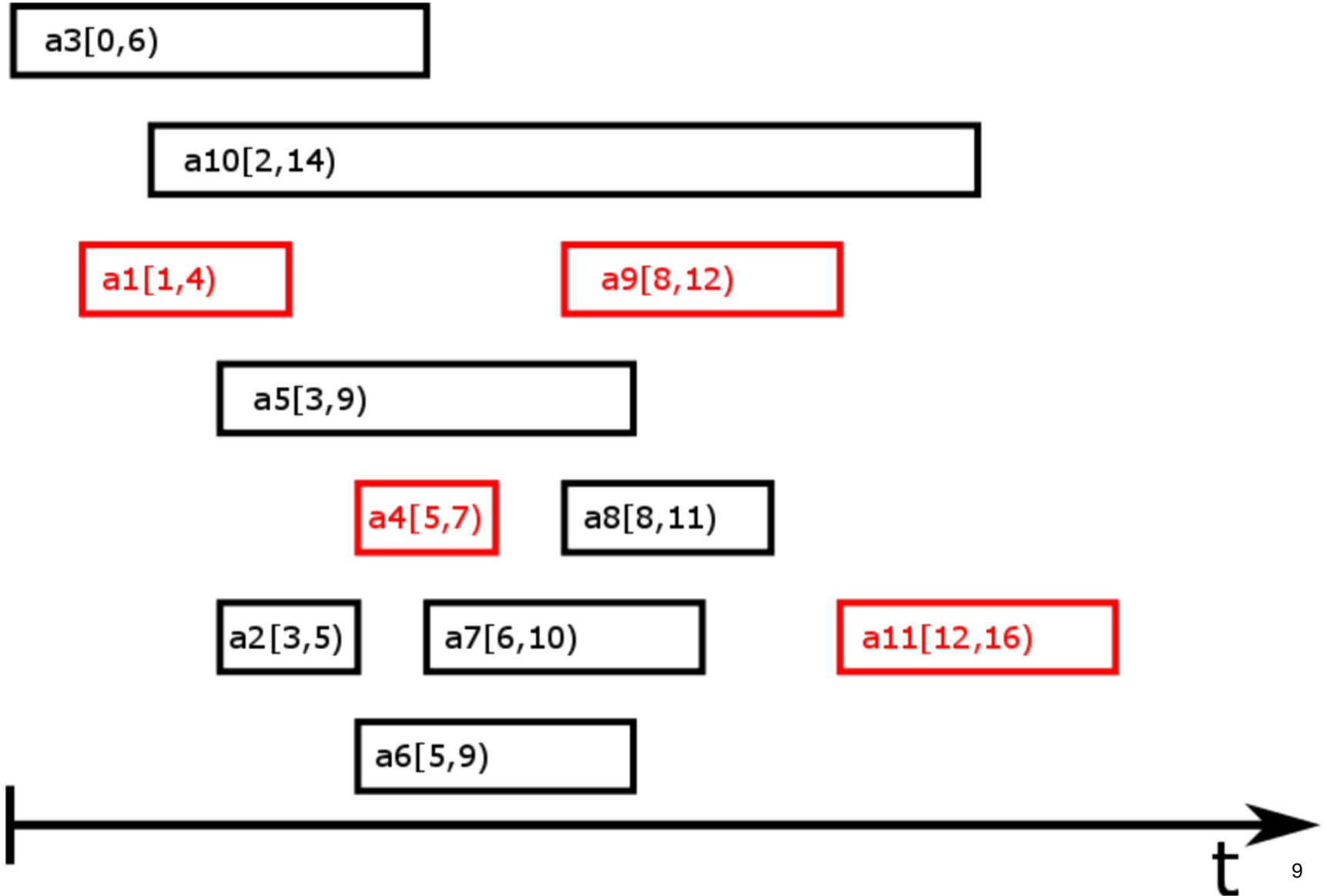
a6[5,9)



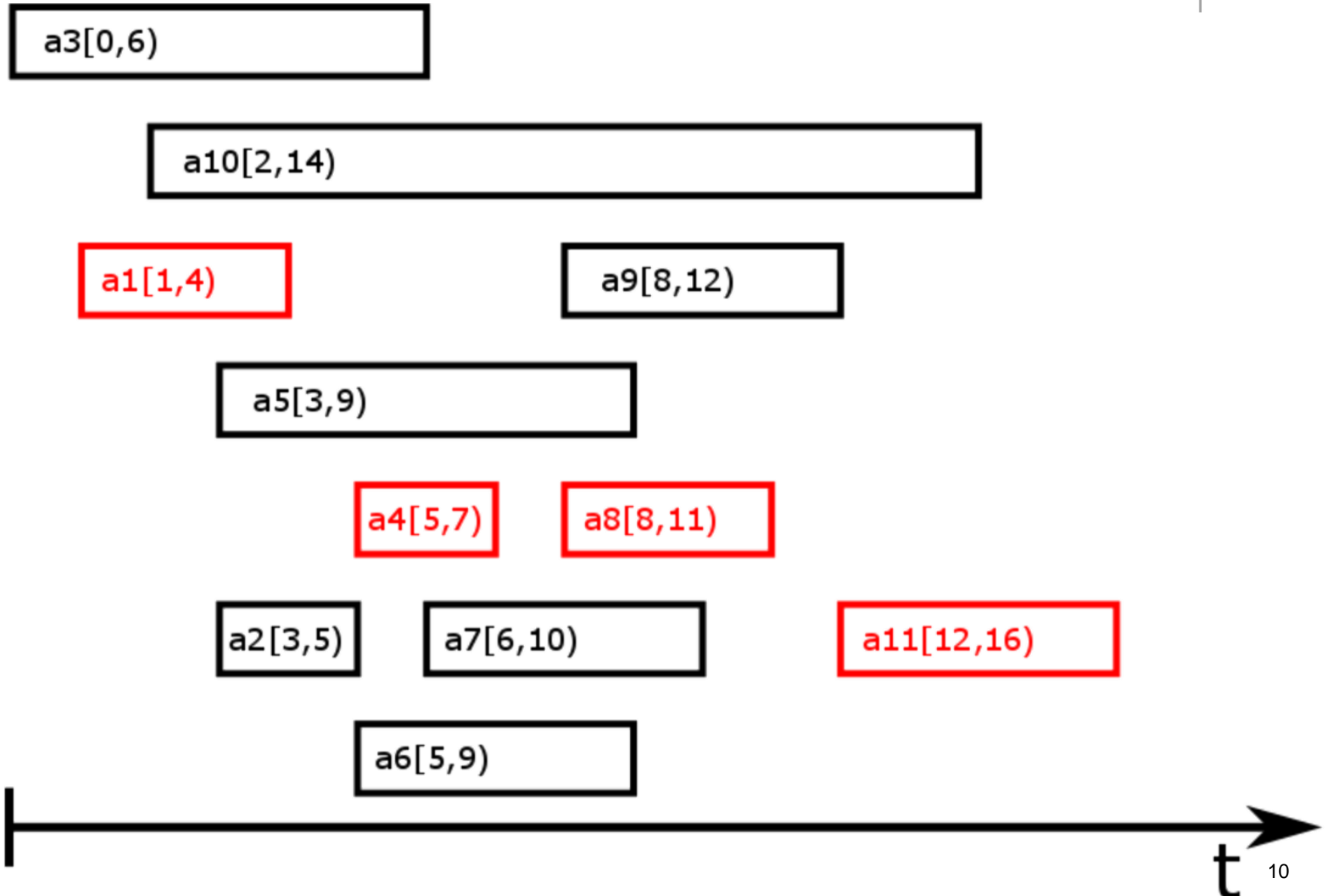
A Better Compatible Set



An Optimal Solution



Another Optimal Solution



Activity Selection Problem



- › Solution algorithm?
 - › Brute force (naïve): all possible combinations $\rightarrow O(2^n)$
 - › Can we do better?
 - › Divide line for D&C is not clear

Activity Selection Problem

- Solution algorithm?
 - Brute force (naïve): all possible combinations $\rightarrow O(2^n)$
 - Can we do better?
 - Divide line for D&C is not clear

- Does the problem have optimal substructure?
 - i.e., the optimal solution of a bigger problem has optimal solutions for subproblems

Activity Selection Problem

- > Does the problem have optimal substructure?
 - > i.e., the optimal solution of a bigger problem has optimal solutions for subproblems

- > Assume A is an optimal solution for S
 - > Is $A' = A - \{a_i\}$ an optimal solution for $S' = S - \{a_i$ and its incompatible activities}?
 - > If A' is not an optimal solution, then there an optimal solution A'' for S' so that $|A''| > |A'|$
 - > Then $B = A'' \cup \{a_i\}$ is a solution for S , $|B| = |A''| + 1$, $|A| = |A'| + 1$
 - > Then $|B| > |A|$, i.e., $|A|$ is not an optimal solution, **contradiction**
 - > Then A' must be an optimal solution for S'

Activity Selection Problem

- > Does the problem have optimal substructure?
 - > i.e., the optimal solution of a bigger problem has optimal solutions for subproblems

- > Assume A is an optimal solution for S
 - > Is $A' = A - \{a_i\}$ an optimal solution for $S' = S - \{a_i$ and its incompatible activities}?
 - > If A' is not an optimal solution, then there an optimal solution A'' for S' so that $|A''| > |A'|$
 - > Then $B = A'' \cup \{a_i\}$ is a solution for S , $|B| = |A''| + 1$, $|A| = |A'| + 1$
 - > Then $|B| > |A|$, i.e., $|A|$ is not an optimal solution, **contradiction**
 - > Then A' must be an optimal solution for S'

- > Proof by contradiction
 - > Assume the opposite of your goal
 - > Given that prove a contradiction, then your goal is proved

Activity Selection Problem



- › What does having optimal substructure means?
 - › We can solve smaller problems, then expand to larger
 - › Similar to dynamic programming

Activity Selection Problem

- › What does having optimal substructure means?
 - › We can solve smaller problems, then expand to larger
 - › Similar to dynamic programming
- › Instead, can we a **greedy** choice?
 - › i.e., take the best choice so far, reduce the problem size, and solve a subproblem later

Activity Selection Problem

- ▶ What does having optimal substructure means?
 - ▶ We can solve smaller problems, then expand to larger
 - ▶ Similar to dynamic programming
- ▶ Instead, can we a **greedy** choice?
 - ▶ i.e., take the best choice so far, reduce the problem size, and solve a subproblem later
- ▶ Greedy choices
 - ▶ Longest first
 - ▶ Shortest first
 - ▶ Earliest start first
 - ▶ Earliest finish first
 - ▶ ...?

Activity Selection Problem

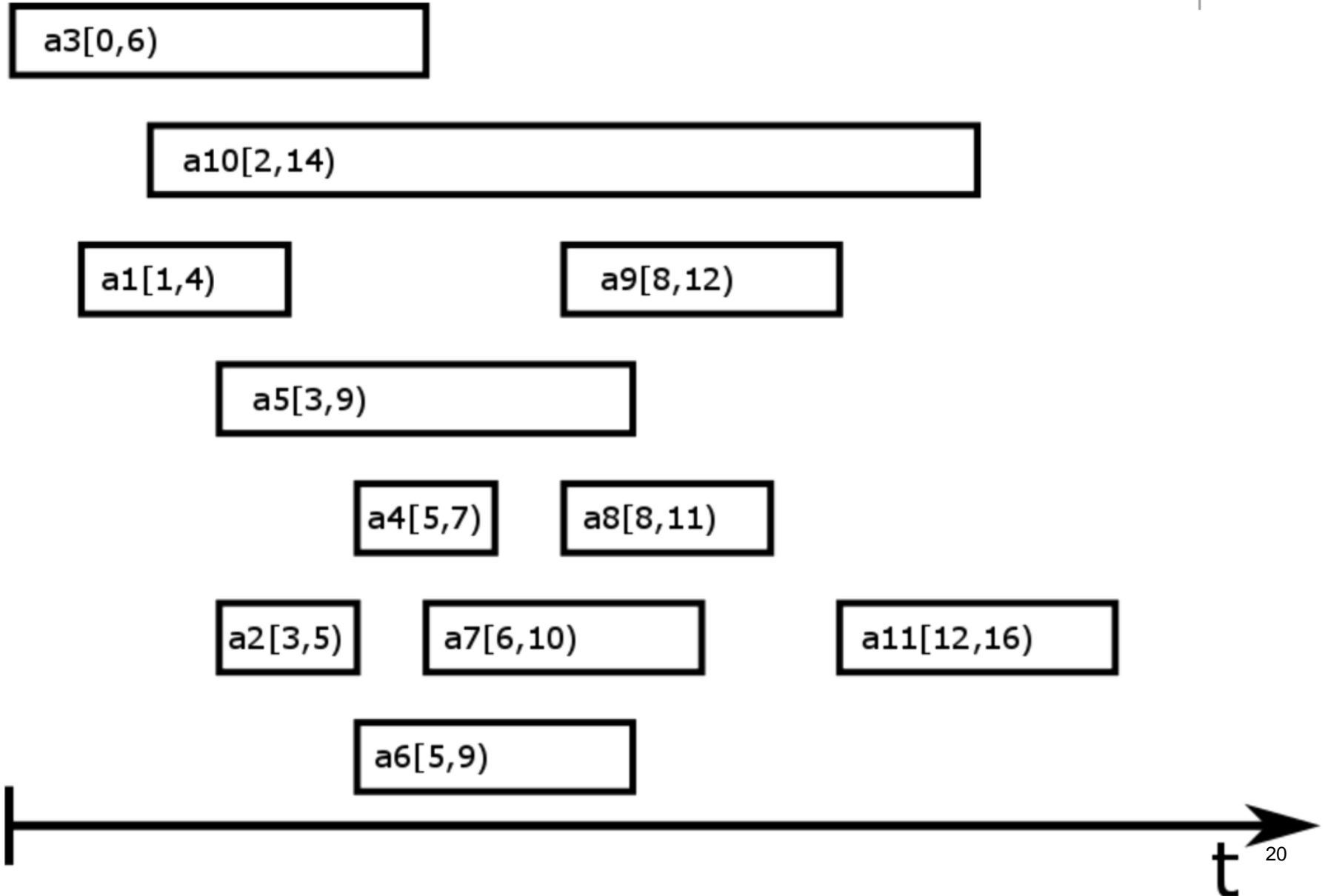


- ▶ Greedy choice: earliest finish first
 - ▶ Why? It leaves as much resource as possible for other tasks

Activity Selection Problem

- › Greedy choice: earliest finish first
 - › Why? It leaves as much resource as possible for other tasks
- › Solution:
 - › Include earliest finish activity a_m in solution A
 - › Remove all a_m 's incompatible activities
 - › Repeat for the remaining earliest finish activity

Activity Selection Problem: Greedy Solution



Activity Selection Problem: Greedy Solution

a3[0,6)

a10[2,14)

a1[1,4)

a9[8,12)

a5[3,9)

a4[5,7)

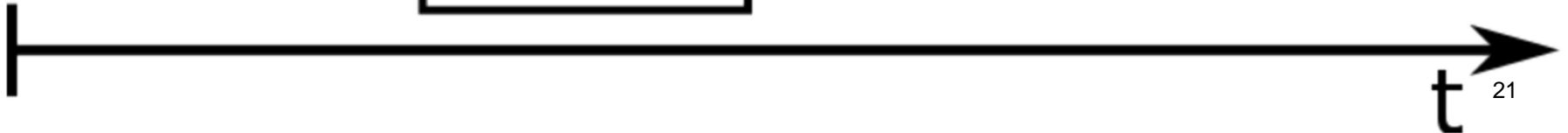
a8[8,11)

a2[3,5)

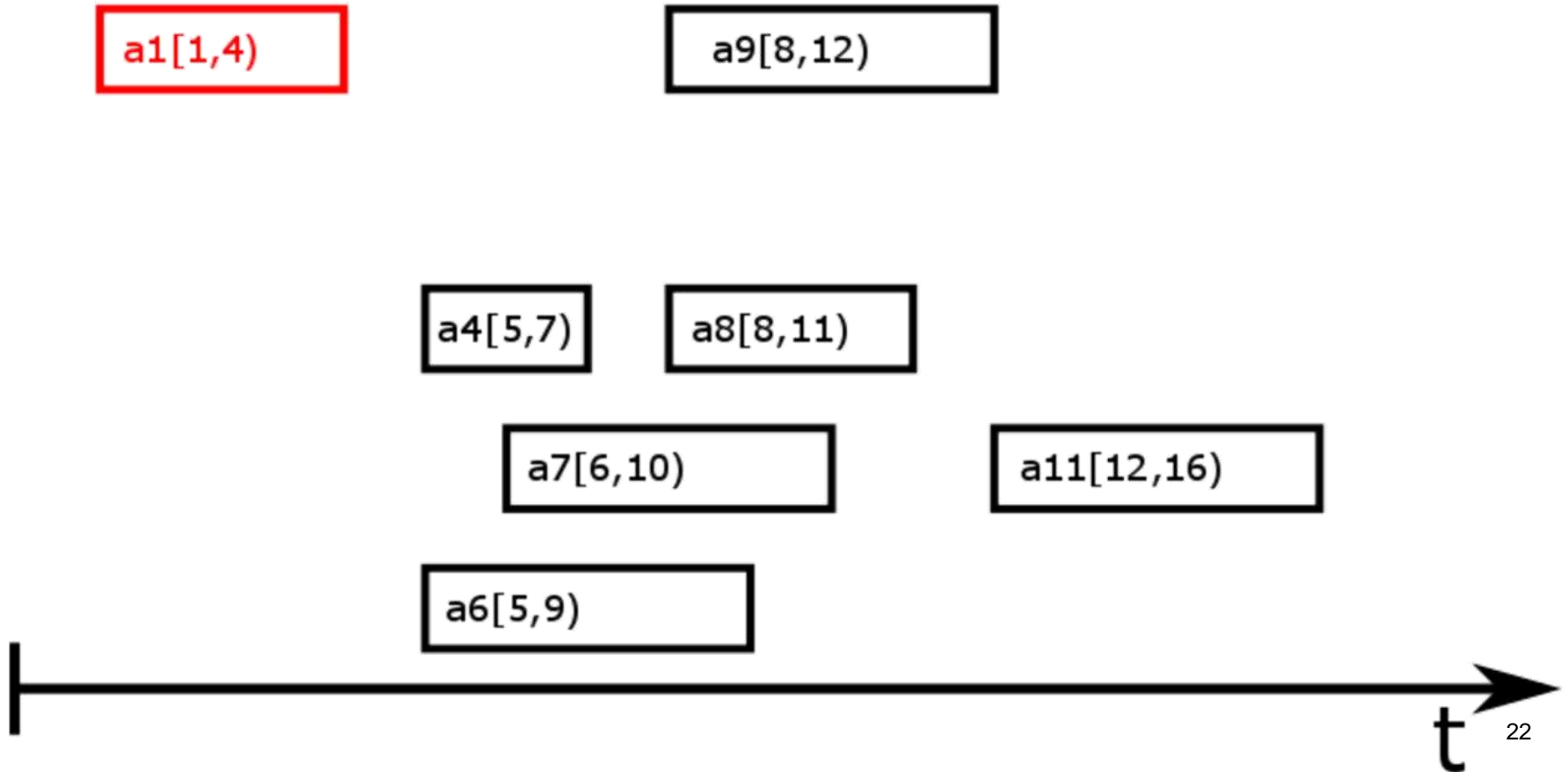
a7[6,10)

a11[12,16)

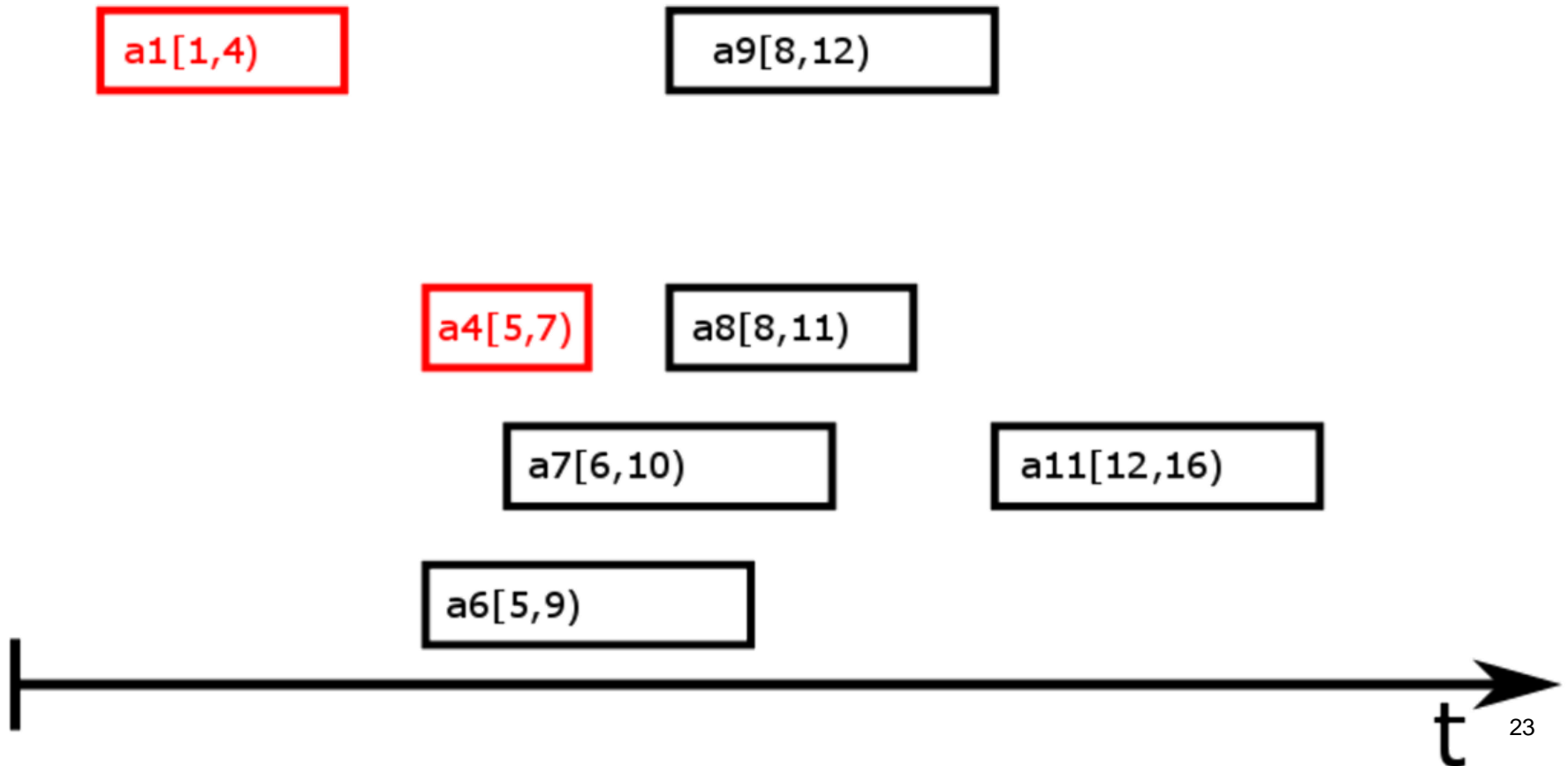
a6[5,9)



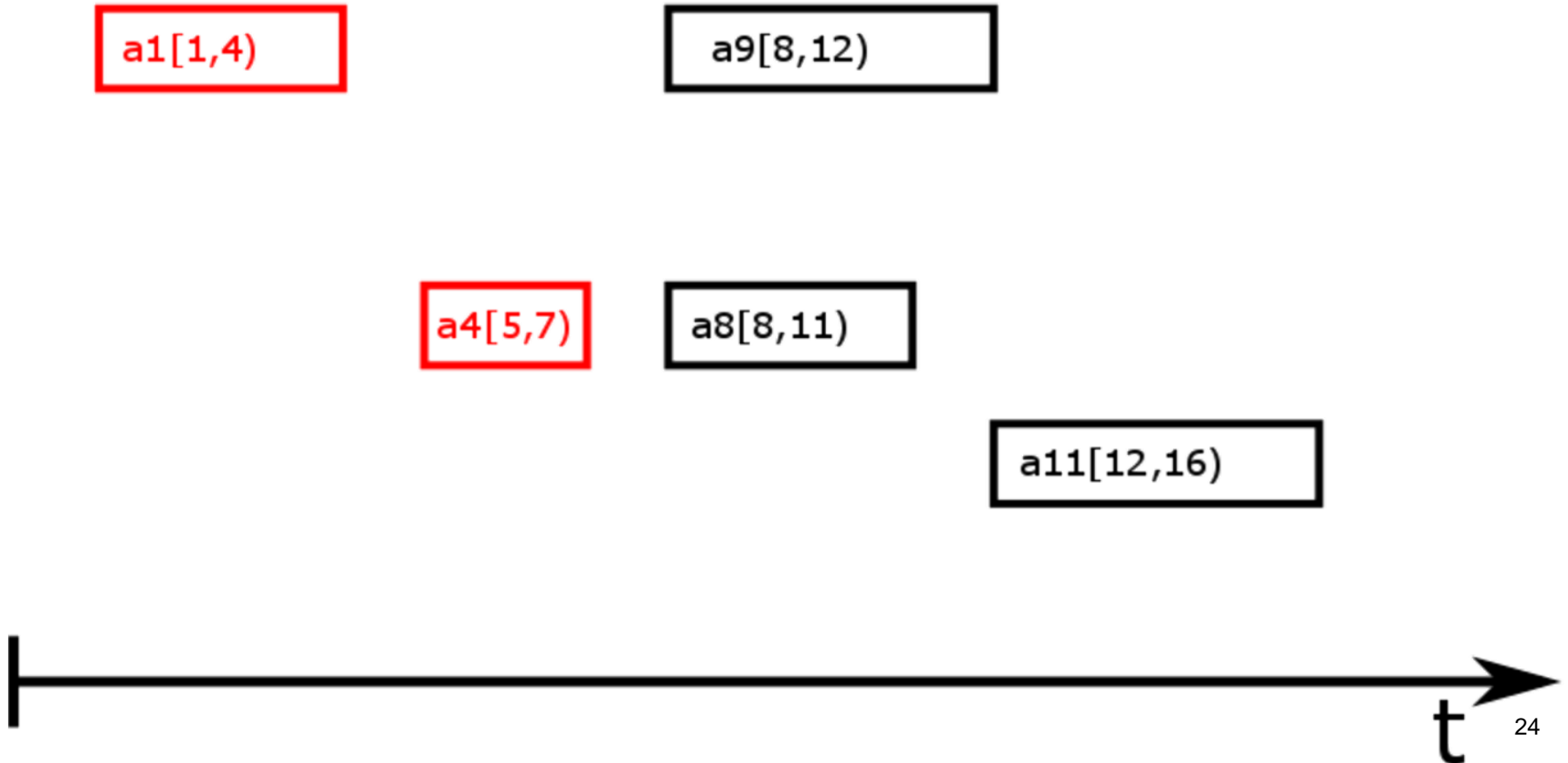
Activity Selection Problem: Greedy Solution



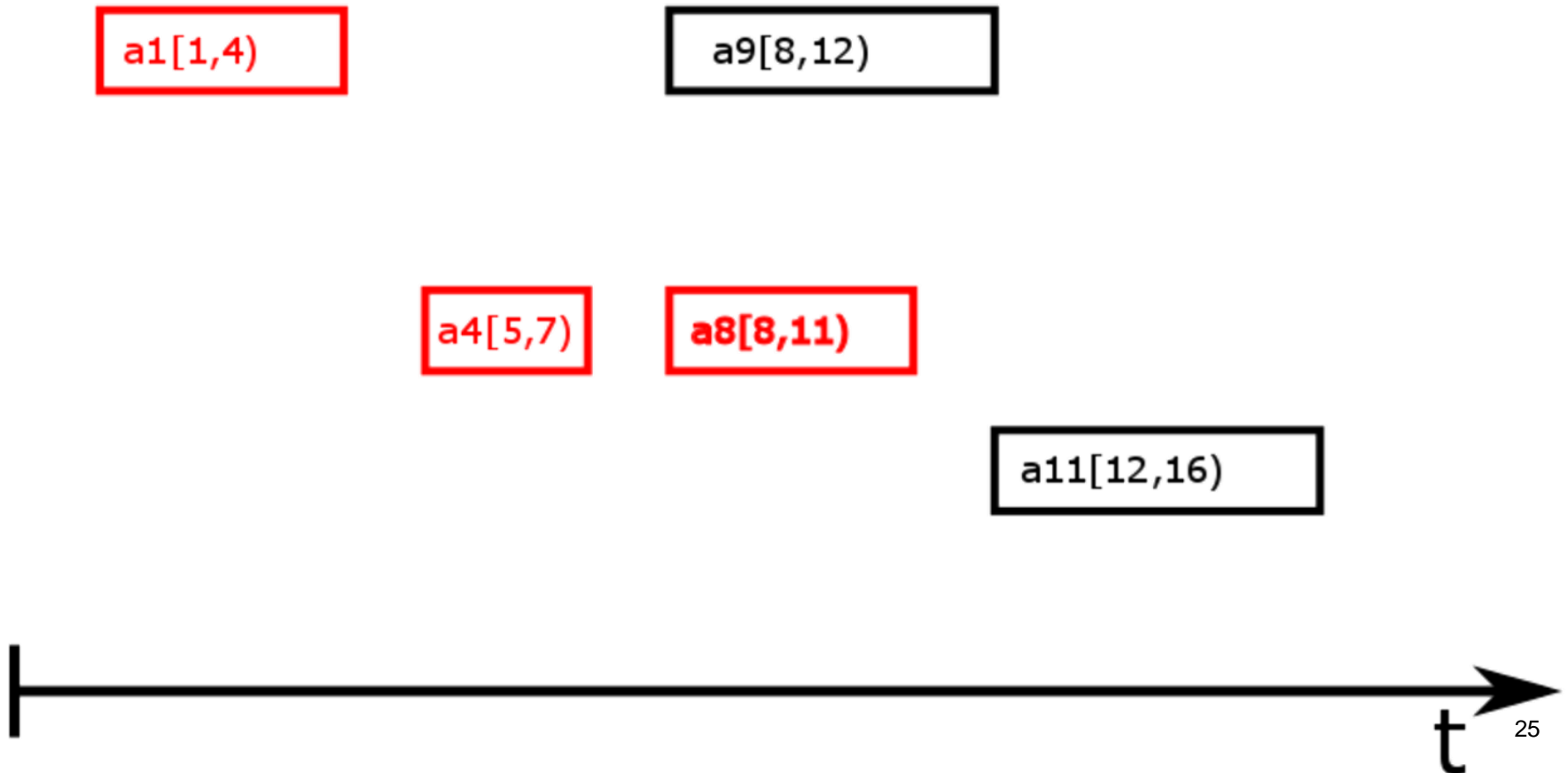
Activity Selection Problem: Greedy Solution



Activity Selection Problem: Greedy Solution



Activity Selection Problem: Greedy Solution



Activity Selection Problem: Greedy Solution

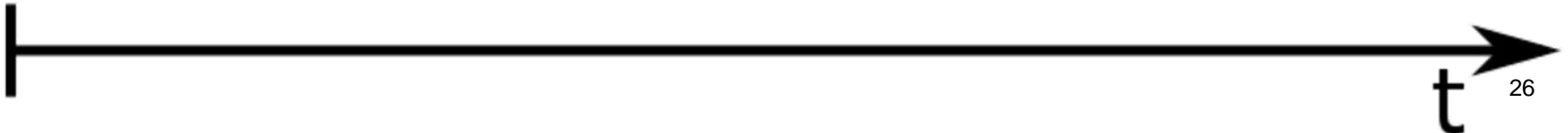


$a_1[1,4)$

$a_4[5,7)$

$a_8[8,11)$

$a_{11}[12,16)$



Activity Selection Problem: Greedy Solution

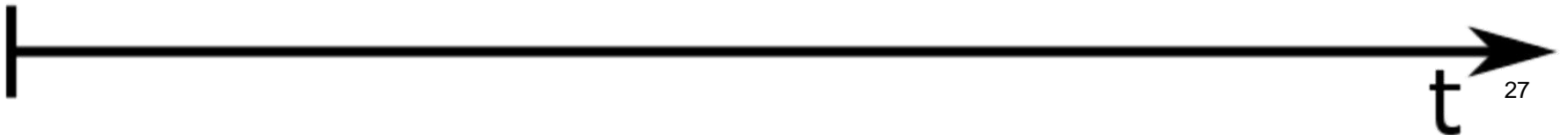


$a_1[1,4)$

$a_4[5,7)$

$a_8[8,11)$

$a_{11}[12,16)$



Activity Selection Problem



- › Pseudo code?

Activity Selection Problem

› Pseudo code?

```
findMaxSet(Array a, int n)
```

```
{
```

```
    - Sort "a" based on earliest finish time
```

```
    - result  $\leftarrow$  {}
```

```
    - for i = 1 to n
```

```
        validAi = true
```

```
        for j = 1 to result.size
```

```
            if (a[i] is incompatible with result[j])
```

```
                validAi = false
```

```
        if (validAi)
```

```
            result  $\leftarrow$  result  $\cup$  a[i]
```

```
    - return result
```

```
}
```

Activity Selection Problem



- › Is greedy choice is enough to get optimal solution?

Activity Selection Problem

- › Is greedy choice is enough to get optimal solution?
- › Greedy choice property
 - › Prove that if a_m has the earliest finish time, it must be included in some optimal solution.

Activity Selection Problem

- › Is greedy choice is enough to get optimal solution?
- › Greedy choice property
 - › Prove that if a_m has the earliest finish time, it must be included in some optimal solution.
- › Assume a set S and a solution set A , where $a_m \notin A$
 - › Let a_j is the activity with the earliest finish time in A (not in S)
 - › Compose another set $A' = A - \{a_j\} \cup \{a_m\}$
 - › A' still have all activities disjoint (as a_m has the global earliest finish time and A activities are already disjoint), and $|A'|=|A|$
 - › Then A' is an optimal solution
 - › Then a_m is always included in an optimal solution

Elements of a Greedy Algorithm



1. Optimal Substructure
2. Greedy Choice Property

Greedy vs. Dynamic Programming



- › Solving the bigger problem include
One choice (greedy) vs Multiple possible choices

Greedy vs. Dynamic Programming



- › Solving the bigger problem include

One choice (greedy)

vs

Multiple possible choices



One subproblem



A lot of overlapping subproblems

Greedy vs. Dynamic Programming



- › Solving the bigger problem include
One choice (greedy) vs Multiple possible choices

One subproblem A lot of overlapping subproblems
- › Both have optimal substructure

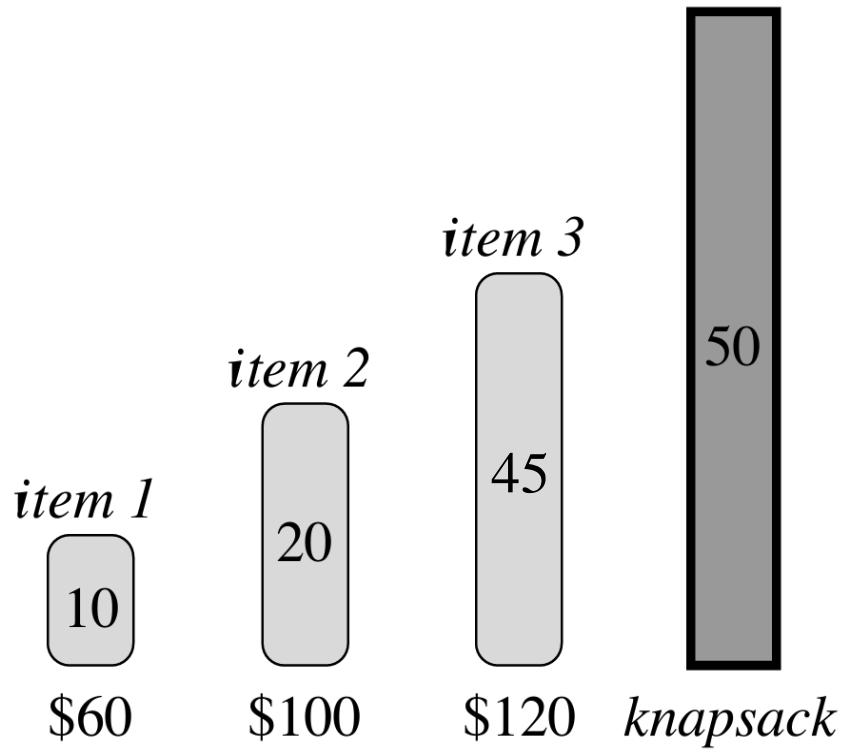
Greedy vs. Dynamic Programming



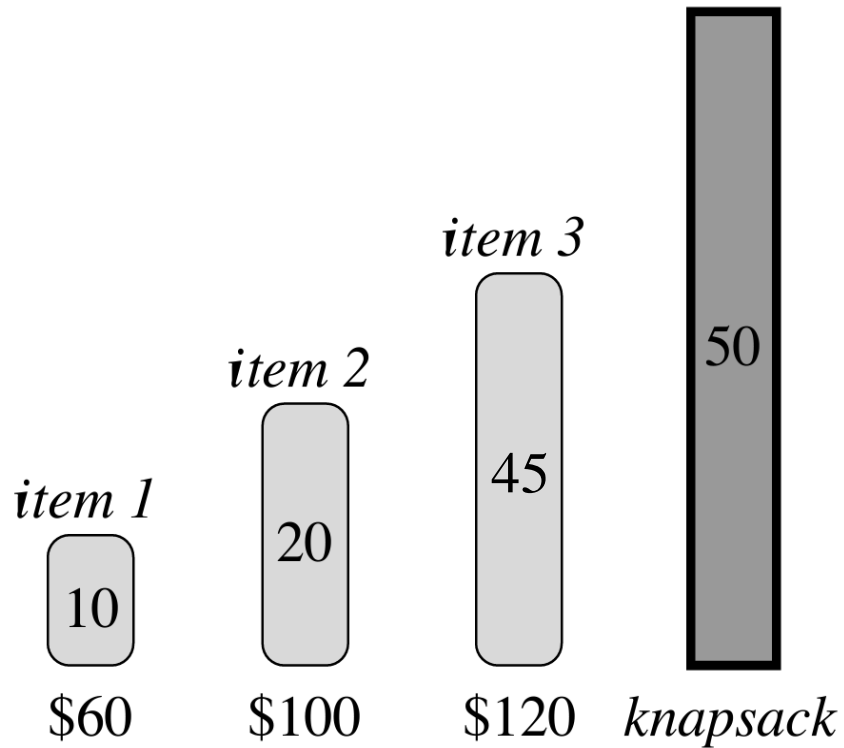
- › Solving the bigger problem include
One choice (greedy) vs Multiple possible choices
↓
One subproblem vs A lot of overlapping subproblems
- › Both have optimal substructure
- › Elements:

Greedy	DM
Optimal substructure	Optimal substructure
Greedy choice property	Overlapping subproblems

Knapsack Problem

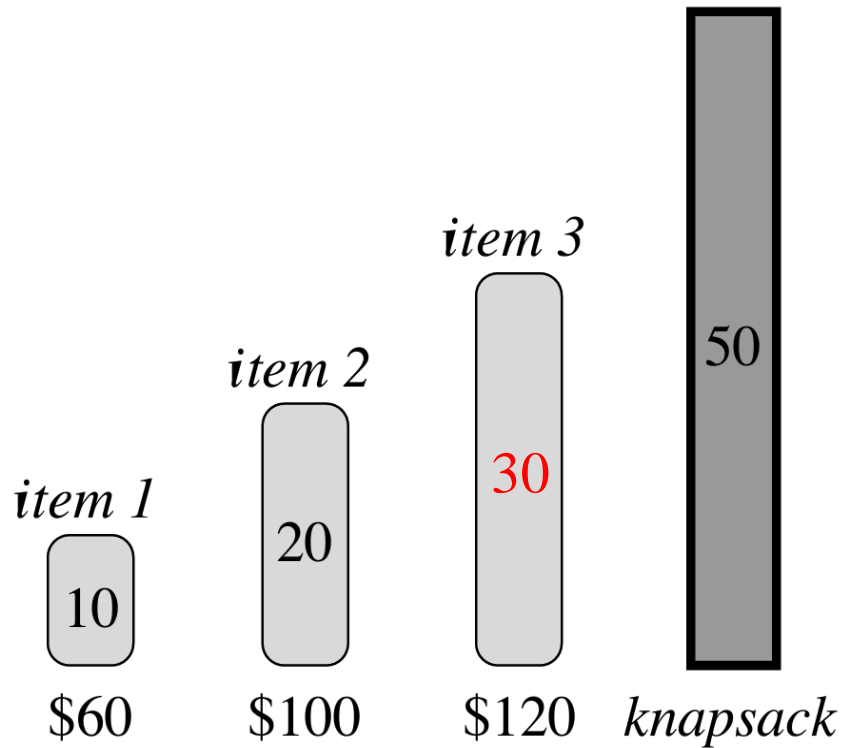


Knapsack Problem



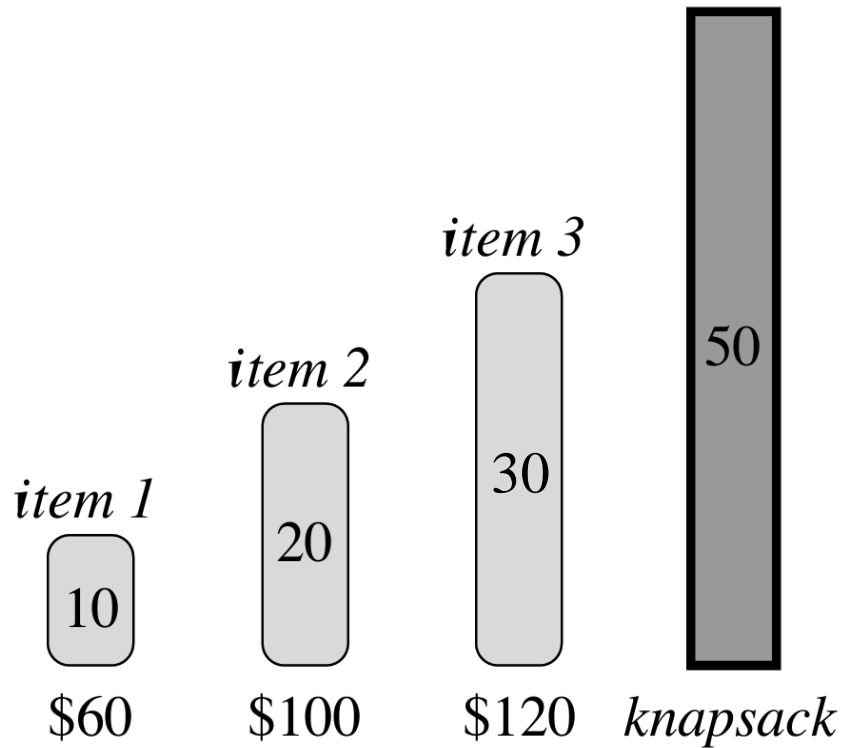
- 0-1 Knapsack: Each item either included or not
- Greedy choices:
 - Take the most valuable → Does not lead to optimal solution
 - Take the most valuable per unit → Works in this example

Knapsack Problem



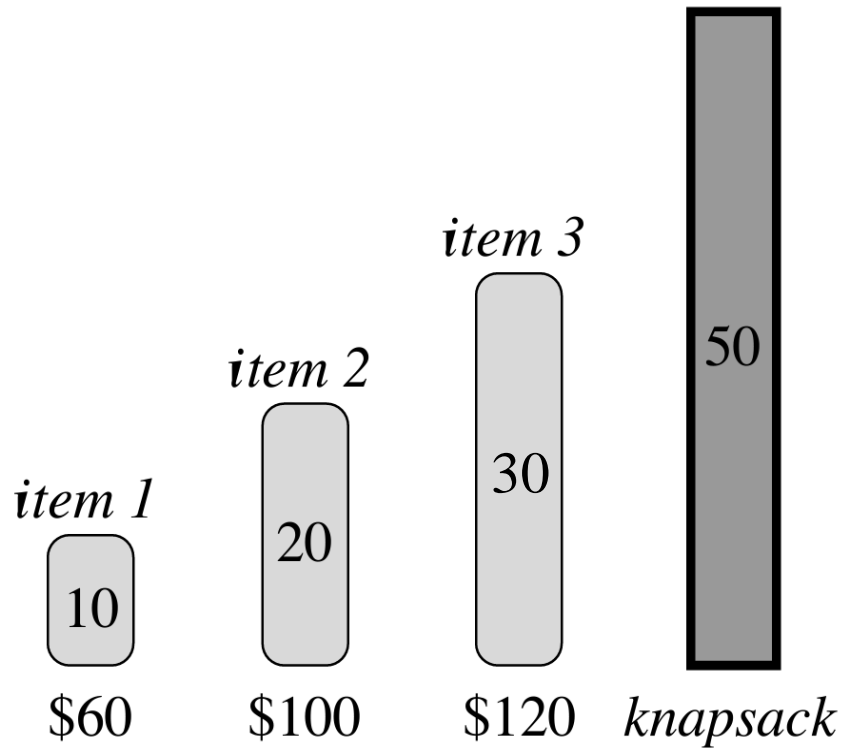
- 0-1 Knapsack: Each item either included or not
- Greedy choices:
 - Take the most valuable → Does not lead to optimal solution
 - Take the most valuable per unit → **Does not work**

Knapsack Problem



- Fractional Knapsack: Part of items can be included

Knapsack Problem



- ▶ Fractional Knapsack: Part of items can be included
- ▶ Greedy choices:
 - ▶ Take the most valuable → Does not lead to optimal solution
 - ▶ Take the most valuable per unit → Does work

Fractional Knapsack Problem



- › Greedy choice property: take the most valuable per weight unit

Fractional Knapsack Problem

- Greedy choice property: take the most valuable per weight unit
- Proof of optimality:
 - Given the set S ordered by the value-per-weight, taking as much as possible x_j from the item j with the highest value-per-weight will lead to an optimal solution X
 - Assume we have another optimal solution X' where we take less amount of item j , say $x'_j < x_j$.
 - Since $x'_j < x_j$, there must be another item k which was taken with a higher amount in X' , i.e., $x'_k > x_k$.
 - We create another solution X'' by doing the following changes in X'
 - Reduce the amount of item k by a value z and increase the amount of item j by a value z
 - The value of the new solution $V'' = V' + z v_j/w_j - z v_k/w_k = V' + z (v_j/w_j - v_k/w_k) \rightarrow v_j/w_j - v_k/w_k \geq 0 \rightarrow V'' \geq V'$

Fractional Knapsack Problem



- › Optimal substructure

Fractional Knapsack Problem

- › Optimal substructure
- › Given the problem S with an optimal solution X with value V , we want to prove that the solution $X' = X - x_j$ is optimal to the problem $S' = S - \{j\}$ and the knapsack capacity $W' = W - x_j$
- › Proof by contradiction
 - › Assume that X' is not optimal to S'
 - › There is another solution X'' to S' that has a higher total value $V'' > V'$
 - › Then $X'' \cup \{x_j\}$ is a solution to S with value $V'' + x_j > V' + x_j > V$
 - › Contradiction as V is the optimal value

Fractional Knapsack Problem

Fknapsack ($W, S, v's, w's$) {

- Sort S based on v_i/w_i value

- $rw = W$

- result = { }

- for each s_i in S

- if($w_i \leq rw$)

- result = result \cup s_i

- $rw = rw - w_i$

- else

- result = result \cup $rw/w_i * s_i$

- $rw = 0$

- return result

}

Huffman Codes



	a	b	c	d	e	f
Frequency (in thousands)	45	13	12	16	9	5
Fixed-length codeword	000	001	010	011	100	101
Variable-length codeword	0	101	100	111	1101	1100

Huffman Codes

	a	b	c	d	e	f
Frequency (in thousands)	45	13	12	16	9	5
Fixed-length codeword	000	001	010	011	100	101
Variable-length codeword	0	101	100	111	1101	1100

- ▶ Prefix Codes: No code is allowed to be a prefix of another code
 - ▶ Prefix codes give optimal data compression

Huffman Codes

	a	b	c	d	e	f
Frequency (in thousands)	45	13	12	16	9	5
Fixed-length codeword	000	001	010	011	100	101
Variable-length codeword	0	101	100	111	1101	1100

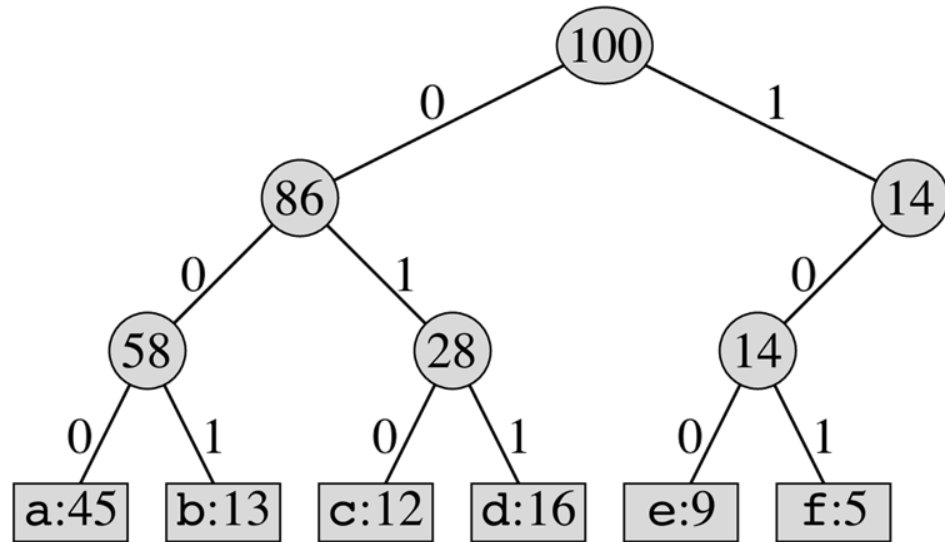
- ▶ Prefix Codes: No code is allowed to be a prefix of another code
 - ▶ Prefix codes give optimal data compression
- ▶ Example: Message 'JAVA' a = "0", j = "11", v = "10"
Encoded message "110100" Decoding "110100"

Huffman Codes

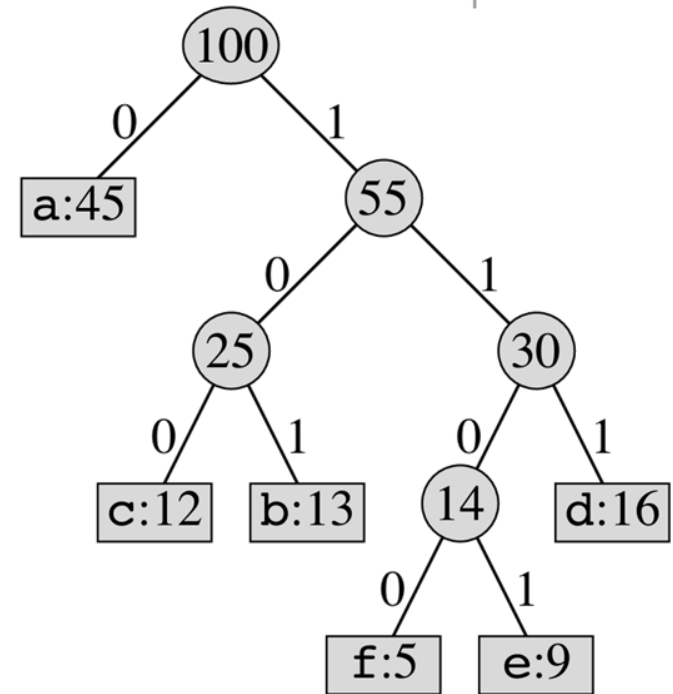
	a	b	c	d	e	f
Frequency (in thousands)	45	13	12	16	9	5
Fixed-length codeword	000	001	010	011	100	101
Variable-length codeword	0	101	100	111	1101	1100

- ▶ Prefix Codes: No code is allowed to be a prefix of another code
 - ▶ Prefix codes give optimal data compression
- ▶ Example: Message 'JAVA' a = "0", j = "11", v = "10"
Encoded message "110100" Decoding "110100"
- ▶ In the table:
Encoding with fixed-length needs 300K bits
Encoding with variable-length needs 224K bits

Huffman Codes

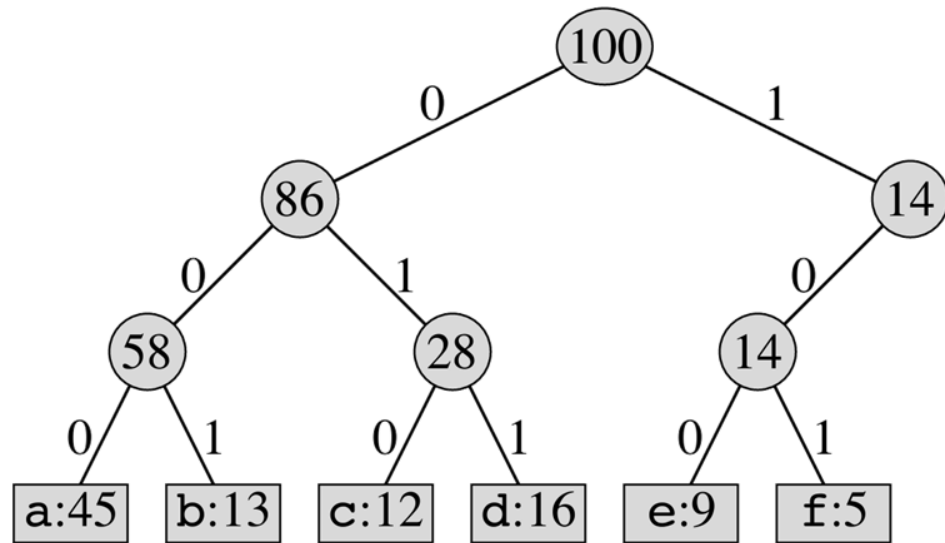


Fixed-length tree

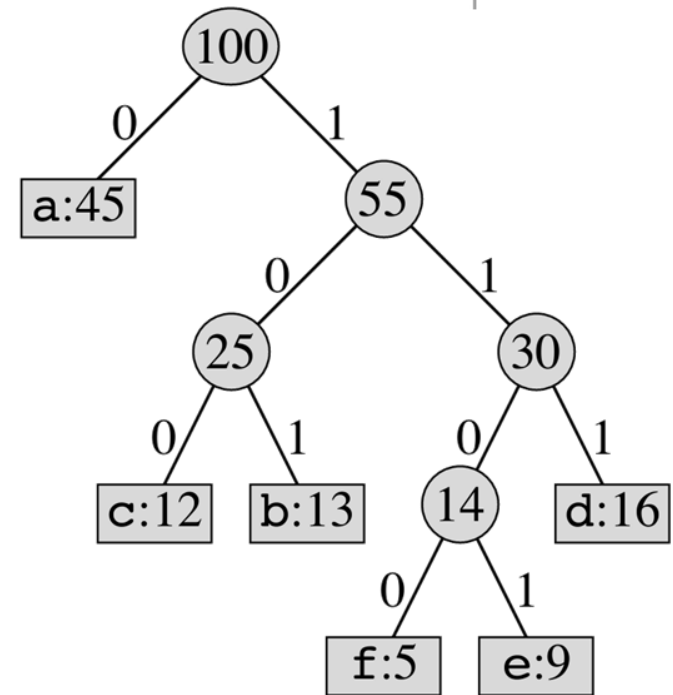


Variable-length tree

Huffman Codes



Fixed-length tree



Variable-length tree

We need an algorithm to build the optimal variable-length tree

Huffman Codes: Tree Construction

HUFFMAN(C)

```
1   $n = |C|$ 
2   $Q = C$ 
3  for  $i = 1$  to  $n - 1$ 
4      allocate a new node  $z$ 
5       $z.left = x = \text{EXTRACT-MIN}(Q)$ 
6       $z.right = y = \text{EXTRACT-MIN}(Q)$ 
7       $z.freq = x.freq + y.freq$ 
8      INSERT( $Q, z$ )
9  return EXTRACT-MIN( $Q$ )    // return the root of the tree
```

Huffman Codes: Tree Construction



f:5

e:9

c:12

b:13

d:16

a:45

Huffman Codes: Tree Construction

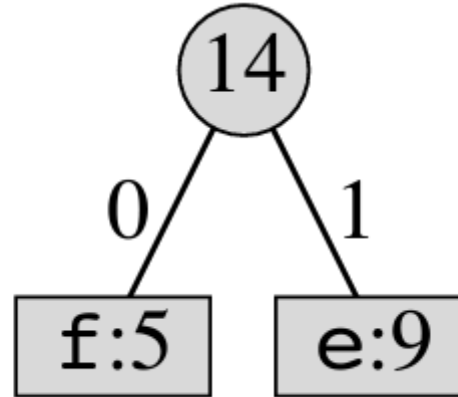


c:12

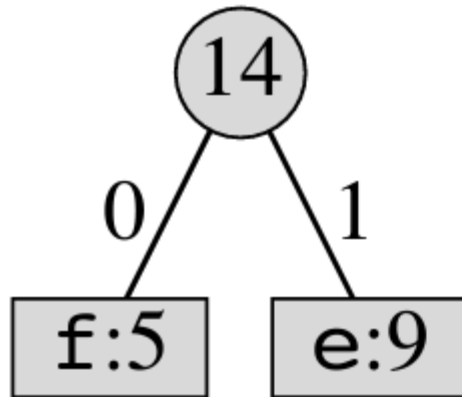
b:13

d:16

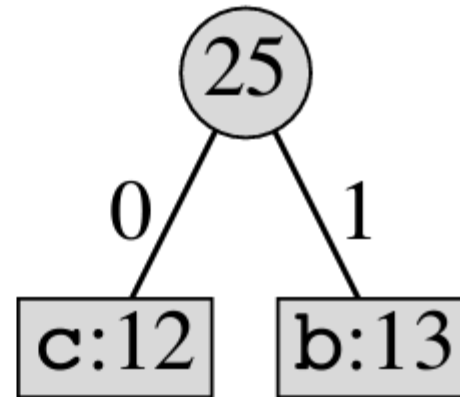
a:45



Huffman Codes: Tree Construction

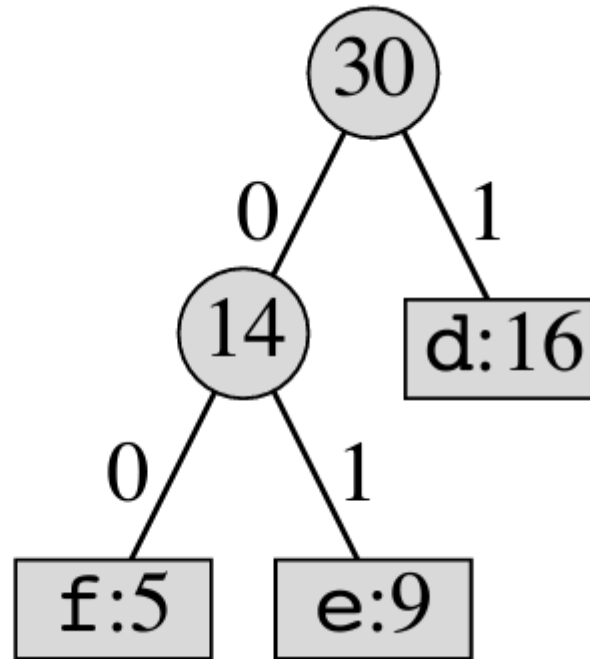
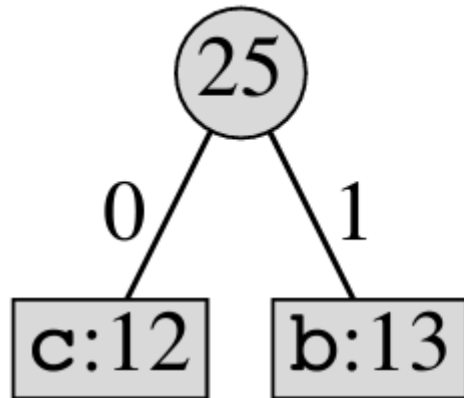


d:16



a:45

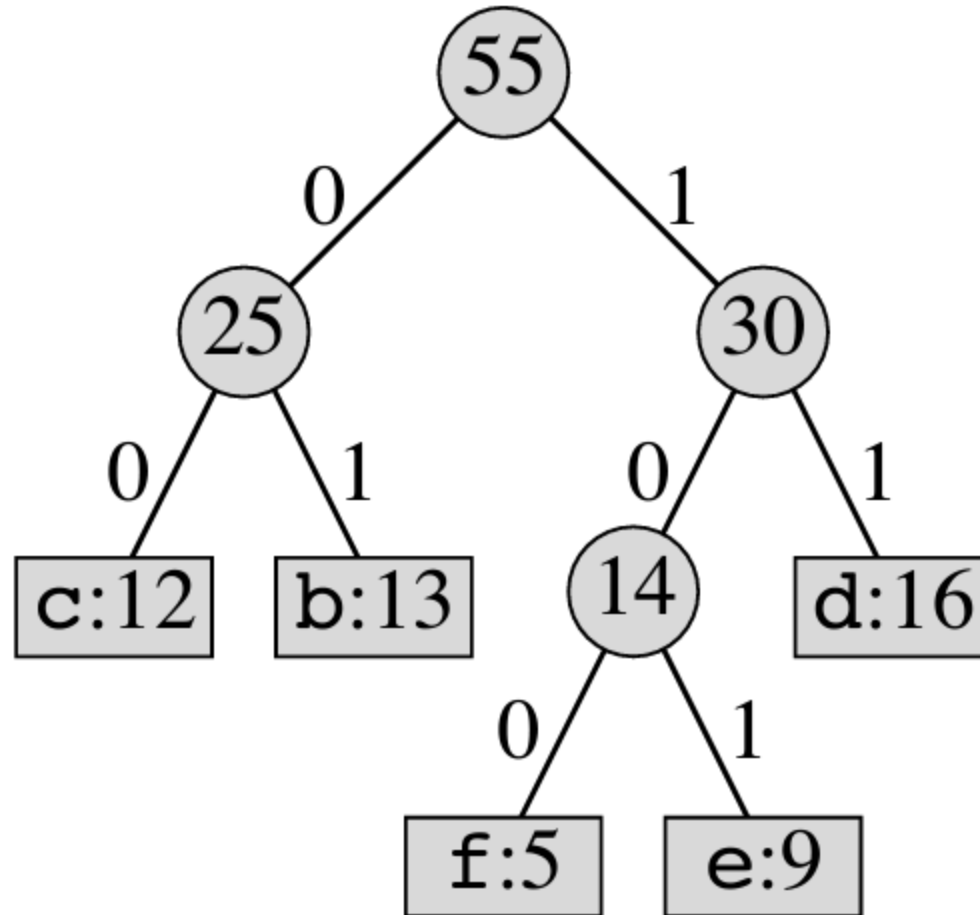
Huffman Codes: Tree Construction



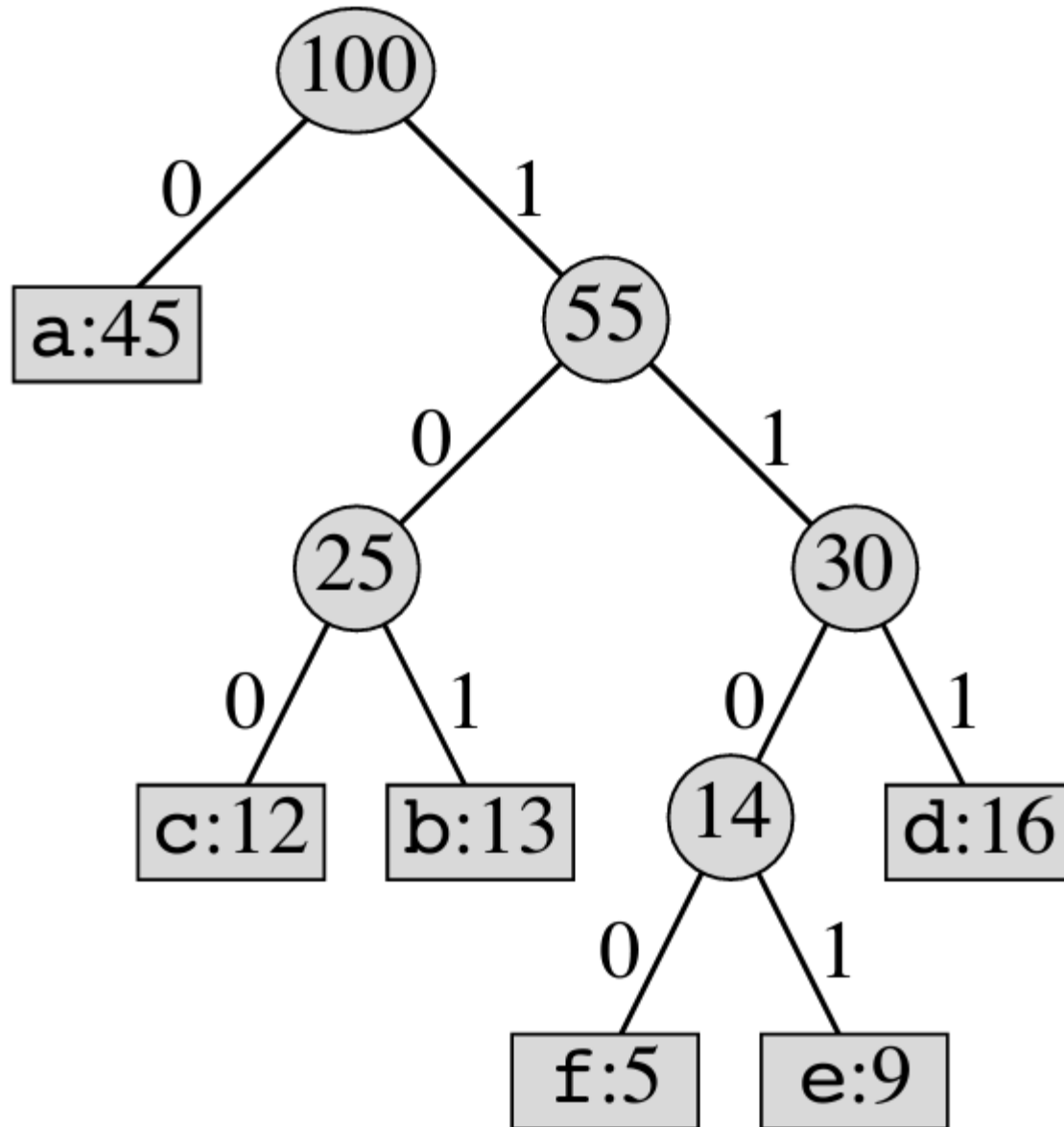
a:45

Huffman Codes: Tree Construction

a:45



Huffman Codes: Tree Construction



Huffman Codes



- › Details of optimal substructure and greedy choice property in the text book

Book Readings and Credits

- › Book Readings:
 - › 16.1 – 16.3
- › Credits to:
 - › Prof. Ahmed Eldawy notes