

Math 142-1, Group work 7

Problem 1

Suggest a traffic following model of the form $\dot{v}_k(t) = f(x_k, x_{k-1}, v_k, v_{k-1})$ that would lead to the relationship $\hat{u}(\rho) = u_{\max} \left(1 - \frac{\rho}{\rho_{\max}}\right)$.

Problem 2

Consider the model $\dot{v}_k(t) = -\lambda(x_k(t) - x_{k-1}(t) + d)$.

- (a) What do λ and d represent?
- (b) Why is $-\lambda$ more reasonable than λ ?
- (c) Show that no density-velocity relationship $\hat{u}(\rho)$ is implied by this model. (Hint: Show that $\hat{u}(\rho)$ implies $\dot{v}_k(t) = (v_k(t) - v_{k-1}(t))f(x_k(t) - x_{k-1}(t))$ for some function $f(x)$.)
- (d) Do you think this model reasonably describes the behavior of drivers?
- (e) Construct a traffic following model with a density-velocity relationship $\hat{u}(\rho)$ such that drivers try to maintain a fixed following time. (For example, drivers always try to stay two seconds behind the car in front.) Is this always possible?
- (f) Is the model $\dot{v}_k(t) = \frac{v_k(t) - v_{k-1}(t)}{x_k(t) - x_{k-1}(t) + d}$ plausible?

Problem 3

Find the general solution to each of the differential equations below.

- (a) $x''' = x$
- (b) $tx' + ax = 0$
- (c) $tx' + ax = b + ct$
- (d) $t^2x'' + 4tx + 2x = 0$
- (e) $\frac{\partial f}{\partial x} \frac{\partial f}{\partial y} = 0$
- (f) $\frac{\partial^2 f}{\partial x \partial y} = 0$
- (g) $\left(\frac{\partial f}{\partial x}\right)^2 = \left(\frac{\partial f}{\partial y}\right)^2$
- (h) $\frac{\partial^2 f}{\partial x^2} = \frac{\partial^2 f}{\partial y^2}$