

$$f(x) = \frac{1}{2} x^T A x - b^T x + c$$

$$\nabla f(x) = \frac{1}{2}(A + A^T)x - b = Ax - b \quad (\text{if } A = A^T)$$

$$[-\nabla f(x) = b - Ax = r] = \text{residual (of } Ax = b)$$

1D line search along  $\vec{s}_k$

$$\phi(\alpha_k) = f(\vec{x}_k + \alpha_k \vec{s}_k)$$

find min by setting  $\frac{d\phi}{d\alpha} = 0$  and solving for  $\alpha_k$ . We can do this analytically for quadratic  $f$ :

$$\frac{d\phi}{d\alpha}(\alpha_k) = \underbrace{\nabla f(\vec{x}_k + \alpha_k \vec{s}_k)^T \vec{s}_k}_{\substack{\text{directional derivative} \\ \text{of } f \text{ along } \vec{s}_k}} = \nabla f(\vec{x}_{k+1})^T \vec{s}_k = 0$$

↑  
Chain rule

$$\Rightarrow \boxed{\vec{r}_{k+1}^T \vec{s}_k = 0}$$

Note: residual at  $\vec{x}_{k+1}$  is orthogonal to search direction  $\vec{s}_k$

$$\begin{aligned} \nabla f(\vec{x}_{k+1})^T \vec{s}_k &= (Ax_{k+1} - b)^T \vec{s}_k \\ &= (A(\vec{x}_k + \alpha_k \vec{s}_k) - b)^T \vec{s}_k \\ &= (Ax_k - b + \alpha_k A \vec{s}_k)^T \vec{s}_k \\ &= (-r_k + \alpha_k A \vec{s}_k)^T \vec{s}_k \end{aligned}$$

$$\Rightarrow \boxed{\alpha_k = \frac{\vec{s}_k^T r_k}{\vec{s}_k^T A \vec{s}_k}}$$

Proof: When  $s_k$  are A-orthogonal, only need  $n$  iterations.

$$e_0 = \sum_{i=0}^{n-1} \alpha_i s_i$$

S<sub>i</sub> linearly indep.  
Express e<sub>0</sub> in terms.

$$s_k^T A e_0 = \sum_{i=0}^{n-1} \cancel{\alpha_i} s_i^T A s_i = \star$$

if  $s_k^T A s_j = 0$  for  $j \neq k$ , then

$$\star = \alpha_k s_k^T A s_k$$

$$\Rightarrow \boxed{r_k = \frac{s_k^T A e_0}{s_k^T A s_k}} \quad \boxed{\alpha_k = \frac{s_k^T r_0}{s_k^T A s_k}}$$

$$s_k^T A e_0 = s_k^T A \left( e_0 + \sum_{i=0}^{k-1} \alpha_i s_i \right) = s_k^T A e_k$$

$$\Rightarrow \alpha_k = \frac{s_k^T A e_k}{s_k^T A s_k} = \boxed{\frac{s_k^T r_k}{s_k^T A s_k} = \alpha_k}$$

$$\Rightarrow \alpha_k = -\alpha_k$$

$$\begin{aligned} e_k &= e_0 + \sum_{j=0}^{k-1} \alpha_j s_j \\ &= \sum_{j=0}^{n-1} -\alpha_j s_j + \sum_{j=0}^{k-1} \alpha_j s_j \end{aligned}$$

$$= \sum_{j=k}^{n-1} \alpha_j s_j$$

$$e_n = 0$$

If we express the error  $e_0$  in terms of  $A$ -conjugate  $s_k$ , then we see the components are same as above

## Properties

$$x_{i+1} = x_i + \alpha_i s_i \quad e_0 = \sum_{k=0}^{n-1} \alpha_k s_k$$

$$e_i = \|x_i - x^*\|$$

~~$$r_i = b - Ax_i$$~~

already showed  $s_i^T r_{i-1} = 0$

~~$$-s_i^T r_j \quad \text{for } j > i$$~~

$$\textcircled{1} \quad = s_i^T A e_j$$

$$= s_i^T A \left( \sum_{k=j}^{n-1} \alpha_k s_k \right) = 0 \quad \checkmark$$

$$s_i^T r_j = 0 \quad \text{for } j > i$$

residuals are orthogonal

search directions are

A-orthogonal.

~~$$-s_i^T A e_j \\ -s_i^T A \left( \sum_{k=j}^{n-1} \alpha_k s_k \right) \\ = 0 \\ \text{if } j > i$$~~

$$s_i = r_i + \sum_{k=0}^{i-1} \beta_{ik} s_k$$

$$\Rightarrow (r_i + \sum_{k=0}^{i-1} \beta_{ik} s_k)^T r_j = 0.$$

$$r_i^T r_j + \sum_{k=0}^{i-1} \beta_{ik} s_k^T r_j = 0 \quad \text{all } \Rightarrow \boxed{r_i^T r_j = 0 \quad j > i}$$

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$$r_{i+1} = -Ae_{i+1} \\ = -A(e_i + \alpha_i s_i)$$

$$r_{i+1} = r_i - \alpha_i As_i$$

$$\boxed{As_i = \frac{1}{\alpha_i} (r_i - r_{i+1})}$$

What happens when we use residuals as the  $\gamma_{k+1}$ ?

$$\begin{aligned} r_{i+1} &= -Ae_{i+1} \\ &= -A(e_i + \alpha_i s_i) \\ r_{i+1} &= r_i + \alpha_i A s_i \end{aligned}$$

Recall:  $\beta_{ik} = \frac{-s_k^T A r_i}{s_k^T A s_k}, k=0, \dots, i-1$

$$\begin{aligned} s_k^T A r_i &= r_i^T A s_k = \langle 3 \rangle && \text{" by } (2) \\ &= -r_i^T [r_{k+1} - r_k] = -\frac{1}{\alpha_k} [r_i^T r_{k+1} - r_i^T r_k] \\ &= \begin{cases} -\frac{1}{\alpha_k} r_i^T r_{k+1} & k = i-1 \\ 0 & k < i-1 \end{cases} \text{ by } (2) \end{aligned}$$

only non-zero

$$\beta \text{ if } \Rightarrow \beta_{i,i-1} = \frac{-s_{i-1}^T A r_i}{s_{i-1}^T A s_{i-1}} = \frac{1}{\alpha_{i-1}} \frac{r_i^T r_i}{s_{i-1}^T A s_{i-1}} \stackrel{\Delta}{=} \beta_i$$

Recall  $\alpha_{i-1} = \frac{s_{i-1}^T r_{i-1}}{s_{i-1}^T A s_{i-1}} = \frac{r_{i-1}^T r_{i-1}}{s_{i-1}^T A s_{i-1}}$  by (1), and  $s_{i-1} = r_{i-1} + \sum_{k=0}^{i-2} \beta_{i,k} s_k$

$$\Rightarrow \beta_i = \frac{r_i^T r_i}{s_{i-1}^T r_{i-1}} = \frac{r_i^T r_i}{r_{i-1}^T r_{i-1}}$$

$(s_{i-1} \text{ and } r_{i-1})$   
differ by  
search direction  
prior to  $i-1$ )

## Method of Conjugate Gradients

$$s_0 = r_0 = b - Ax_0 \quad (\text{steepest descent direction})$$

for  $i = 0, 1, 2, \dots$

$$\alpha_i = \frac{r_i^T r_i}{s_i^T A s_i}$$

$$x_{i+1} = x_i + \alpha_i s_i$$

$$r_{i+1} = r_i - \alpha_i A s_i$$

$$\beta_{i+1} = \frac{r_{i+1}^T r_{i+1}}{r_i^T r_i}$$

$$s_{i+1} = r_{i+1} + \beta_{i+1} s_i$$

end.

Space & time requirements have been reduced  
from  $O(n^2) \rightarrow O(m)$ .