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(a) A is invertible as it has all singular values > 0 .

$$\begin{aligned} A^{-1} &= (U \Sigma V^T)^{-1} = (V^T)^{-1} \Sigma^{-1} U^{-1} \\ &= V \Sigma^{-1} U^T, \text{ where } \Sigma^{-1} = \begin{pmatrix} \frac{1}{\sigma_1} & & & \\ & \frac{1}{\sigma_2} & & \\ & & \dots & \\ & & & \frac{1}{\sigma_n} \end{pmatrix} \end{aligned}$$

(b)

$$\begin{aligned} AX &= U \Sigma V^T (V \Sigma^{-1} U^T + \varepsilon v_n u_i^T) = I + \varepsilon U \Sigma V^T v_n u_i^T \\ &= I + \varepsilon U \Sigma \hat{e}_n u_i^T = I + \varepsilon U \sigma_n \hat{e}_n u_i^T, \text{ since } \Sigma \hat{e}_n = \sigma_n \hat{e}_n \\ &= \boxed{I + \varepsilon \sigma_n \vec{u}_n \vec{u}_i^T}, \text{ since } U \hat{e}_n = \vec{u}_n \end{aligned}$$

$$\begin{aligned} XA &= (A^{-1} + \varepsilon v_n u_i^T) A = I + \varepsilon v_n (u_i^T A) \\ &= I + \varepsilon \vec{v}_n u_i^T U \Sigma V^T \\ &= I + \varepsilon \vec{v}_n \hat{e}_i^T \Sigma V^T, \text{ since } u_i^T U = \hat{e}_i^T \\ &= I + \varepsilon \vec{v}_n \sigma_i \hat{e}_i^T V^T, \text{ since } \hat{e}_i^T \Sigma = \sigma_i \hat{e}_i^T \\ &= \boxed{I + \varepsilon \sigma_i \vec{v}_n \vec{v}_i^T}, \text{ since } \hat{e}_i^T V^T = \vec{v}_i^T \end{aligned}$$

$$(c) \quad \|uv^T\|_2 = \left\| \frac{u}{\|u\|_2} \frac{v^T}{\|v\|_2} \right\|_2$$

$$= \|u\|_2 \|v\|_2 \left\| \frac{u}{\|u\|_2} \frac{v^T}{\|v\|_2} \right\|_2$$

$$= \|u\|_2 \|v\|_2 \|A\|_2, = \textcircled{*}$$

where $A = \frac{u}{\|u\|_2} \frac{v^T}{\|v\|_2}$

The SVD of A is

$$A = \begin{pmatrix} | & | & | \\ \frac{u}{\|u\|_2} & \vec{u}_2 & \dots & \vec{u}_n \\ | & | & | \end{pmatrix} \begin{pmatrix} 1 & & \\ & 0 & \\ & & \dots & \\ & & & 0 \end{pmatrix} \begin{pmatrix} -\frac{v^T}{\|v\|_2} \\ -v_2^T \\ \vdots \\ -v_n^T \end{pmatrix}$$

for $\vec{u}_2, \dots, \vec{u}_n$ complete orthonormal basis with $\frac{u}{\|u\|_2}$

and $\vec{v}_1, \dots, \vec{v}_n$ complete orthonormal basis with $\frac{v}{\|v\|_2}$

Therefore

$$\sigma_{\max}(A) = \sigma_{\max}\left(\frac{u}{\|u\|_2} \frac{v^T}{\|v\|_2}\right) = 1$$

So $\textcircled{*} = \|u\|_2 \|v\|_2 \quad \checkmark$

(d)

$$\|AX - I\|_2 = \|\cancel{I} + \varepsilon \sigma_n \vec{u}_n \vec{u}_1^T - \cancel{I}\|_2$$

$$= |\varepsilon| \sigma_n \|u_n u_1^T\|_2$$

$$= |\varepsilon| \sigma_n$$

$$\|XA - I\|_2 = \|\cancel{I} + \varepsilon \sigma_1 v_n v_1^T - \cancel{I}\|_2$$

$$= |\varepsilon| \sigma_1 \|v_n v_1^T\|_2$$

$$= |\varepsilon| \sigma_1$$

X is more ^{or equally} accurate as a right inverse than as a left inverse, because

$$\|AX - I\|_2 = |\varepsilon| \sigma_n \leq |\varepsilon| \sigma_1 = \|XA - I\|_2$$