Scheduling Overview

- Scheduler runs when we context switching among processes/threads to pick who runs next
  - Under what situation does this occur?
  - What should it do? Does it matter?

- Making this decision is called scheduling

- Now, we’ll look at:
  - The goals of scheduling
  - Starvation
  - Various well-known scheduling algorithms
  - Standard Unix scheduling algorithm
Multiprogramming

- In a multiprogramming system, we try to increase CPU utilization and job throughput by overlapping I/O and CPU activities
  - Doing this requires a combination of mechanisms and policy
- We have covered the mechanisms
  - Context switching, how and when it happens
  - Process queues and process states
- Now we’ll look at the policies
  - Which process (thread) to run, for how long, etc.
- We’ll refer to schedulable entities as jobs (standard usage) – could be processes, threads, people, etc.
Scheduling Goals

- Scheduling works at two levels in an operating system
  1. To determine the **multiprogramming level** – the number of jobs loaded into primary memory
     » Moving jobs to/from memory is often called swapping
     » **Long term scheduler**: infrequent
  2. To decide what job to run next to guarantee “good service”
     » Good service could be one of many different criteria
     » **Short term scheduler**: frequent
     » **We are concerned with this level of scheduling**
Scheduling

- The **scheduler** (aka dispatcher) is the module that manipulates the queues, moving jobs to and fro.

- The **scheduling algorithm** determines which jobs are chosen to run next and what queues they wait on.

- In general, the scheduler runs:
  - When a job switches from running to waiting
  - When an interrupt occurs
  - When a job is created or terminated
Preemptive vs. Non-preemptive scheduling

- We’ll discuss scheduling algorithms in two contexts
  - In **preemptive** systems the scheduler can interrupt a running job (involuntary context switch)
  - In **non-preemptive** systems, the scheduler waits for a running job to explicitly block (voluntary context switch)
Scheduling Goals

- What are some reasonable goals for a scheduler?
- Scheduling algorithms can have many different goals:
  - CPU utilization
  - Job throughput (# jobs/unit time)
  - Turnaround time ($T_{\text{finish}} - T_{\text{start}}$)
  - Waiting time ($\text{Avg}(T_{\text{wait}})$: avg time spent on wait queues)
  - Response time ($\text{Avg}(T_{\text{ready}})$: avg time spent on ready queue)

- Batch systems
  - Strive for job throughput, turnaround time (supercomputers)

- Interactive systems
  - Strive to minimize response time for interactive jobs (PC)
Starvation

Starvation is a scheduling “non-goal”:

- **Starvation** is a situation where a process is prevented from making progress because some other process has the resource it requires
  - Resource could be the CPU, or a lock (recall readers/writers)
- **Starvation usually a side effect of the sched. algorithm**
  - A high priority process always prevents a low priority process from running on the CPU
  - One thread always beats another when acquiring a lock
- **Starvation can be a side effect of synchronization**
  - Constant supply of readers always blocks out writers
First In First Out (FIFO)

- Schedule tasks in the order they arrive
  - Continue running them until they complete or give up the processor
- Example: memcached
  - Facebook cache of friend lists, …

- On what workloads is FIFO particularly bad?
  - Imagine being at supermarket to buy a drink of water, but get stuck behind someone with a huge cart (or two!)
    » …and who pays in pennies!
  - Can we do better?
Shortest Job First (SJF)

- Always do the task that has the shortest remaining amount of work to do
  - Often called Shortest Remaining Time First (SRTF)

- Suppose we have five tasks arrive one right after each other, but the first one is much longer than the others
  - Which completes first in FIFO? Next?
  - Which completes first in SJF? Next?
# FIFO vs. SJF

<table>
<thead>
<tr>
<th>Tasks</th>
<th>FIFO</th>
<th>SJF</th>
</tr>
</thead>
<tbody>
<tr>
<td>(1)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>(2)</td>
<td></td>
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<tr>
<td>(3)</td>
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<tr>
<td>(4)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>(5)</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

What's the big deal? Don't they finish at the same time?
**SJF Example**

\[
\begin{align*}
AWT &= \frac{(8 + (8+4)+(8+4+2))}{3} = 11.33 \\
AWT &= \frac{(4 + (4+8)+(4+8+2))}{3} = 10 \\
AWT &= \frac{(4+ (4+2)+(4+2+8))}{3} = 8 \\
AWT &= \frac{(2 + (2+4)+(2+4+8))}{3} = 7.33
\end{align*}
\]
Claim: SJF is optimal for average response time
   Why?

For what workloads is FIFO optimal?
   For what is it pessimal (i.e., worst)?

Does SJF have any downsides?
Shortest Job First (SJF)

- Problems?
  - Impossible to know size of CPU burst
    » Like choosing person in line without looking inside basket/cart
  - How can you make a reasonable guess?
  - Can potentially starve

- Flavors
  - Can be either preemptive or non-preemptive
  - Preemptive SJF is called shortest remaining time first (SRTF)
Round Robin

- Each task gets resource for a fixed period of time (time quantum)
  - If task doesn’t complete, it goes back in line
- Need to pick a time quantum
  - What if time quantum is too long?
    » Infinite?
  - What if time quantum is too short?
    » One instruction?
Round Robin

Tasks

Round Robin (1 ms time slice)

(1)  
(2)  
(3)  
(4)  
(5)  

rest of task 1

Round Robin (100 ms time slice)

(1)  
(2)  
(3)  
(4)  
(5)  

rest of task 1

Time
Round Robin vs. FIFO

- Many context switches can be costly
- Other than that, is Round Robin always better than FIFO?
Round Robin vs. FIFO

Tasks

Round Robin (1 ms time slice)

(1)
(2)
(3)
(4)
(5)

FIFO and SJF

(1)
(2)
(3)
(4)
(5)

Is Round Robin always fair?
Mixed Workload

Tasks

I/O bound

I/O completes

issues I/O request

CPU bound

CPU bound

Time

I/O completes

gets CPU
Max-Min Fairness

• How do we balance a mixture of repeating tasks:
  ◆ Some I/O bound, need only a little CPU
  ◆ Some compute bound, can use as much CPU as they are assigned

• One approach: maximize the minimum allocation given to a task
  ◆ Schedule the smallest task first, then split the remaining time using max-min
Priority Scheduling

- Priority Scheduling
  - Choose next job based on priority
    - Airline checkin for first class passengers
  - Can implement SJF, priority = 1/(expected CPU burst)
  - Also can be either preemptive or non-preemptive

- Problem?
  - Starvation – low priority jobs can wait indefinitely

- Solution
  - “Age” processes
    - Increase priority as a function of waiting time
    - Decrease priority as a function of CPU consumption
More on Priority Scheduling

- For real-time (predictable) systems, priority is often used to isolate a process from those with lower priority. *Priority inversion* is a risk unless all resources are jointly scheduled.
Combining Algorithms

- Scheduling algorithms can be combined
  - Have multiple queues
  - Use a different algorithm for each queue
  - Move processes among queues

- Example: Multiple-level feedback queues (MLFQ)
  - Multiple queues representing different job types
    - Interactive, CPU-bound, batch, system, etc.
  - Queues have priorities, jobs on same queue scheduled RR
  - Jobs can move among queues based upon execution history
    - Feedback: Switch from interactive to CPU-bound behavior
Multi-level Feedback Queue (MFQ)

- **Goals:**
  - Responsiveness
  - Low overhead
  - Starvation freedom
  - Some tasks are high/low priority
  - Fairness (among equal priority tasks)

- Not perfect at any of them!
  - Used in Linux (and probably Windows, MacOS)
**MFQ**

- Set of Round Robin queues
  - Each queue has a separate priority
- High priority queues have short time slices
  - Low priority queues have long time slices
- Scheduler picks first thread in highest priority queue
- Tasks start in highest priority queue
  - If time slice expires, task drops one level
### MFQ

<table>
<thead>
<tr>
<th>Priority</th>
<th>Time Slice (ms)</th>
<th>Round Robin Queues</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>10</td>
<td></td>
</tr>
<tr>
<td>2</td>
<td>20</td>
<td></td>
</tr>
<tr>
<td>3</td>
<td>40</td>
<td></td>
</tr>
<tr>
<td>4</td>
<td>80</td>
<td></td>
</tr>
</tbody>
</table>

- **new or I/O bound task**
- **time slice expiration**
The canonical Unix scheduler uses a MLFQ
- 3-4 classes spanning ~170 priority levels
  - Timesharing: first 60 priorities
  - System: next 40 priorities
  - Real-time: next 60 priorities
  - Interrupt: next 10 (Solaris)

Priority scheduling across queues, RR within a queue
- The process with the highest priority always runs
- Processes with the same priority are scheduled RR

Processes dynamically change priority
- Increases over time if process blocks before end of quantum
- Decreases over time if process uses entire quantum
Motivation of Unix Scheduler

- The idea behind the Unix scheduler is to reward interactive processes over CPU hogs.
- Interactive processes (shell, editor, etc.) typically run using short CPU bursts:
  - They do not finish quantum before waiting for more input.
- Want to minimize response time:
  - Time from keystroke (putting process on ready queue) to executing keystroke handler (process running).
  - Don’t want editor to wait until CPU hog finishes quantum.
- This policy delays execution of CPU-bound jobs:
  - But that’s ok.
Multiprocessor Scheduling

- This is its own topic, we won't go into it in detail
  - Could come back to it towards the end of the quarter

- What would happen if we used MFQ on a multiprocessor?
  - Contention for scheduler spinlock
  - Multiple MFQ used – this optimization technique is called distributed locking and is common in concurrent programming

- A couple of other considerations
  - Co-scheduling for parallel programs
  - Core affinity
Scheduling Summary

- Scheduler (dispatcher) is the module that gets invoked when a context switch needs to happen.
- Scheduling algorithm determines which process runs, where processes are placed on queues.
- Many potential goals of scheduling algorithms:
  - Utilization, throughput, wait time, response time, etc.
- Various algorithms to meet these goals:
  - FCFS/FIFO, SJF, Priority, RR
- Can combine algorithms:
  - Multiple-level feedback queues
  - Unix example
Practice

- Look at xv6 code
- Lets do an example
Next class

- Deadlock