LECTURE 6

Distributed Snapshotting/Checkpointing

Replicated State Machine



RSMs with Logical Clocks

- Any replica can execute an update only after confirming clock is higher on all other replicas
- Implication: If any one replica is down, all other replicas cannot progress

Types of failures

□ Crash failures

Can resume with saved state

□ Fail stop

All state is lost upon failure

Recovering from failures

- Checkpoint process state periodically
 Where to store checkpoint?
 Persistent storage vs. volatile memory
 - Local machine vs. remote machine
- Where you store checkpoint depends on
 Types of failures you want to tolerate
 Performance overhead you are willing to bear

Resume from last checkpoint after restart





















Checkpoint-based Recovery

Problem: Domino effect

Cause: Uncoordinated checkpointing

Coordinated checkpointing

- Example: Chandy-Lamport snapshot
 - Distributed Snapshots: Determining Global States of Distributed Systems: ACM Transactions on Computer Systems 1985
- Global snapshot of a distributed system

Example

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Chandy-Lamport algorithm

□ How to take a snapshot of a distributed system?

Example use cases:

- Deadlock detection
- Garbage collection
- Evaluation of any stable property

Example: Token ring



Example snapshot 1



Example snapshot 2



Global snapshot

Captured state must satisfy "happens before"

□ If event b in snapshot and a → b, then event a must be in snapshot

Example desired snapshot



Global snapshot

□ Goals of capturing global snapshot

- Capture instantaneous state of every process
- Capture relevant messages in transit
- What comprises a distributed system's state?
 - State of individual processes
 - State of every communication channel

□ N processes in the system

- Processes don't fail while taking snapshot
- Any process may initiate collection of snapshot
- One unidirectional channel in either direction between each pair of processes
 All channels ensure FIFO delivery
 Lossless and no duplication



Chandy-Lamport: Intuition

- Enable snapshot by broadcasting marker message
 Distinct from the application's messages
- Marker messages serve two purposes:
- 1. Enable processes to discover need for snapshot
- 2. Serve as a barrier on every channel
 - Record all messages received before marker



Initiator process does the following:

- Records its local state
- Sends out marker messages on every outgoing channel
- Starts recording messages on every incoming channel
- Two cases for how P_i should handle receipt of marker message from P_i

- If the state has not been recorded by P_i upon the receipt of a marker along a channel c
 - Record local state
 - Record state of channel from P_i to P_i as empty
 - Send marker messages on all outgoing channels
- □ If state was previously recorded
 - Stop recording channel from P_i to P_i
 - Record state of channel as all messages received since marker
- Snapshot complete when every process has received marker on every incoming channel

Chandy-Lamport in action



Coordinated checkpointing

- When to initiate global snapshot?
- External environment does not checkpoint
 - Cannot roll back output
 - Cannot re-issue inputs
- Implication: Need coordinated checkpoint upon input or output
 - Too slow!







Message logging

Between checkpoints, log all events that lead to non-determinism

- □ For example, log every message received
- Log everything necessary to ensure same messages are sent as in original execution