## 8. Intermediate Code

- Intermediate code is closer to the target machine than the source language, and hence easier to generate code from.
- Unlike machine language, intermediate code is (more or less) machine independent. This makes it easier to retarget the compiler.
- It allows a variety of optimizations to be performed in a machine-independent way.
- Typically, intermediate code generation can be implemented via syntax-directed translation, and thus can be folded into parsing by augmenting the code for the parser.


## Intermediate Languages: Design Issues

- The set of operators in the intermediate language must be rich enough to allow the source language operations to be implemented.
- A small set of operations in the intermediate language makes it easy to retarget the compiler to a new machine.
- Intermediate code operations that are closely tied to a particular machine or architecture may make it harder to port the compiler to other architectures.
- A small set of intermediate code operations may lead to long instruction sequences for some source language constructs. This may require more work during optimization.


## High-Level Intermediate Representations

Examples : syntax trees, DAGs:

- (abstract) syntax trees : a compact form of a parse tree that represents the hierarchical structure of the program: nodes represent operators, the children of a node represent what it operates on.
- DAGs : similar to syntax trees, except that common subexpressions are represented by a single node.


## Example:

$$
\text { if }(x>0) \text { then } x:=3 *(y+1) \text { else } y:=y+1
$$


syntax tree


DAG

### 8.1.1. Low-Level Intermediate Representations

Examples: Three Address Code

- This is a sequence of instructions of the form

$$
\mathrm{x}:=\mathrm{y} \text { op } \mathrm{z}
$$

where $\mathrm{x}, \mathrm{y}$, and z are variable names, constants, or compiler generated variables ("temporaries").

- Only one operator is permitted on the RHS, so there are no "built-up" expressions. Instead, expressions are computed using temporaries. E.g. the source language construct

$$
\mathrm{x}:=\mathrm{y}+\mathrm{z} * \mathrm{w}
$$

might translate to

$$
\begin{aligned}
& \mathrm{t} 1:=\mathrm{z} * \mathrm{w} \\
& \mathrm{x}:=\mathrm{y}+\mathrm{t} 1
\end{aligned}
$$

## Different Kinds of Three-Address Statements

## Assignment :

$$
\begin{array}{ll}
\mathrm{x}:=\mathrm{y} \text { op } \mathrm{z}, & o p \text { binary } \\
\mathrm{x}:=o p \mathrm{y}, & o p \text { unary } \\
\mathrm{x}:=\mathrm{y} &
\end{array}
$$

Jumps :

$$
\begin{aligned}
& \text { goto } L, \\
& \text { jumpt t } L, \\
& \text { jumpf } \mathrm{t} L, \\
& \text { if } \times \text { relop } \mathrm{y} \text { goto } L, L \text { a label }
\end{aligned}
$$

## Procedure Call/Return :

```
param x,
call }p,n\mathrm{ ,
enter
exit
return
return x
retrieve }
```

$x$ an actual parameter
$n=$ no. of params to $p$
initialization (if any)
cleanup actions (if any)
save returned value in $x$

## Indexed Assignment :

$$
\begin{aligned}
& x:=y[i] \\
& x[i]:=y
\end{aligned}
$$

Address and Pointer Assignments :
$x:=\& y$
$x:=* y$
$x:=y$

## Miscellaneous :

label $L$

### 8.1.2. Implementing Three-Address Instructions

Each instruction is implemented as a structure called a quadruple:

- contains (upto) 4 fields: operation, (upto) two operands, and destination;
- for operands: use a bit to indicate whether it's a constant or a pointer into the symbol table.

$$
x:=y+z
$$

$$
\text { if } \mathrm{t} 1>=\mathrm{t} 2 \text { goto } \mathrm{L}
$$


$\square$

### 8.2. Intermediate Code Generation

- Source language constructs are decomposed to simpler constructs at the intermediate code level.
- When generating code to evaluate expressions, temporary names must be made up for internal nodes in the syntax tree for the expression.

Example:
Source : if $x+2>3 *(y-1)+4$ then $z:=0$;
Intermediate Code :

$$
\begin{aligned}
& \mathrm{t} 1:=\mathrm{x}+2 \\
& \mathrm{t} 2:=\mathrm{y}-1 \\
& \mathrm{t} 3:=3 * \mathrm{t} 2 \\
& \mathrm{t} 4:=\mathrm{t} 3+4 \\
& \text { if } 11<=\mathrm{t} 4 \text { goto } \mathrm{L} \\
& z:=0 \\
& \text { label } \mathrm{L}
\end{aligned}
$$

## Intermediate Code Generation

Syntax-Directed Translation :

- Intermediate code represented as a list of instructions. Instruction sequences are concatenated using the operator ||.
(In practice, we might choose to write the intermediate code instructions out into a file.)
- Attributes for Expressions E:
- E.place : denotes the location that holds the value of $E$.
- E.code: denotes the instruction sequence that evaluates $E$.
- Attributes for Statements $S$ :
- S.begin: denotes the first instruction in the code for $S$.
- S.after : denotes the first instruction after the code for $S$.
- S.code : denotes the instruction sequence that represents $S$.
- Auxiliary Functions :
- newtemp() : returns a new temporary each time it is called.
* returns a pointer to the ST entry of a temp.
* may take a parameter specifying the type of the temp (useful if reusing temps).
- newlabel() : returns a new label name each time it is called.
- Notation : we write

$$
\operatorname{gen}\left(x^{\prime}:==^{\prime} y^{\prime}+{ }^{\prime} z\right)
$$

to represent the instruction $x:=y+z$.

## PRODUCTION SEMANTIC RULE

$E \longrightarrow \mathrm{id} \quad$ E.place $:=$ id.place;
E.code $:={ }^{\prime \prime}$;
$E \longrightarrow\left(E_{1}\right) \quad$ E.place $:=E_{1}$.place $;$
E.code $:=E_{1}$.code;
$E \longrightarrow E_{1}+E_{2} \quad$ E.place $:=$ newtemp();
E.code $:=E_{1}$.code
$E_{2}$.code \||
gen(E.place ':='
$E_{1}$.place '+'
E2.place)
$E \longrightarrow-E_{1}$
E.place $:=$ newtemp();
E.code $:=E_{1}$.code \|
gen(E.place ':='
'-' E1.place)

### 8.3.2. Accessing Array Elements I

- Array elements can be accessed quickly if the elements are stored in a block of consecutive locations.
- Assume:
- we want the $i^{\text {th }}$ element of an array $A$ whose subscript ranges from lo to $h i$;
- the address of the first element of the array is base.
- We can avoid address computations in the intermediate code if we have indexed "addressing modes" at the intermediate code level.
In this case, $A[i]$ is the $(i-l o)^{t h}$ element of the array located at base (starting at element 0). So a reference $\mathrm{A}[\mathrm{i}$ ] translates to the code

$$
\begin{aligned}
\mathrm{t} 1 & :=\mathrm{i}-\boldsymbol{l o} \\
\mathrm{t} 2 & :=\mathrm{A}[\mathrm{t} 1]
\end{aligned}
$$

### 8.3.2. Accessing Array Elements II

- Address computations can't be avoided in general, because of pointer and record types.
- The simple approach using indexed expressions may recompute base addresses repeatedly, leading to inefficient code.
- Assume:
- we want the $i^{\text {th }}$ element of an array $A$ whose subscript ranges from lo to $h i$;
- the address of the first element of the array is base;
- each element of $A$ has width $w$.

Then, the address of $x[i]$ is

$$
\begin{aligned}
& \text { base }+(i-l o) * w \\
& =(\text { base }-l o * w)+i * w \\
& =C_{A}+i * w
\end{aligned}
$$

where $C_{A}$ depends on the array $A$ and is known at compile time.
Note : $C_{A}$ is a memory address if $A$ is a global, and is a stack displacement if $A$ is a local.

- The idea extends to multidimensional arrays in the obvious way: need to know whether the elements are stored in row-major or column-major order.


### 8.4. Logical Expressions

$B E x p \longrightarrow E_{1}$ relop $E_{2}$

### 8.4.3. Naive but Simple Approach :

Intermediate Code (TRUE $==1$, FALSE $==0$ ) :

$$
\begin{aligned}
& {\left[\text { t1 } \leftarrow \text { value of } E_{1}\right.} \\
& {\left[\text { t2 } \leftarrow \text { value of } E_{2}\right.} \\
& t 3:=\text { TRUE } \\
& \text { if } t 1 \text { relop } t 2 \text { goto } L \\
& t 3:=\text { FALSE } \\
& \text { label } L
\end{aligned}
$$

$\frac{\text { Disadvantage }}{\text { traffic. }}$ Lots of (usually unnecessary) memory

### 8.4.1. Code Generation for Conditionals

## Production $: S \longrightarrow$ if $E$ then $S_{1}$ else $S_{2}$

## Semantic Rule

```
\(\{\) S.begin \(:=\) newlabel();
    S.after \(:=\) newlabel();
    S.code \(:=\operatorname{gen}(\) 'Iabel' S.begin) \|
        E.code \|
        gen('if'E.place' \(=\) " O "goto' \(S_{2}\).begin) ||
        \(S_{1}\).code \||
        gen('goto' S.after) ||
        \(S_{2}\).code ||
        gen('Iabel' S.after)
\}
```


### 8.4.1. Code Generation for Loops

Production $: S \longrightarrow$ while $E$ do $S_{1}$

## Structure of Generated Code :

$L_{1}$ :
[ evaluate $E$
if ( $E==$ FALSE) goto $L_{2}$
Code for $S_{1}$
goto $L_{1}$
$L_{2}$ : ...

## Semantic Rule :

```
{ S.begin := newlabel();
    S.after := newlabel();
    S.code := gen('label' S.begin) |
        E.code ||
        gen('if'E.place' = "O"goto'S.after) |
        S1.code ||
        gen('goto' S.begin)|
        gen('label' S.after)
}
```


## Intermediate Code Generation: Assignment

- Grammar productions:

$$
S \longrightarrow L h s:=R h s
$$

- Semantic Rule:

$$
\begin{aligned}
\{\text { S.code }:= & \text { Lhs.code } \| \\
& \text { Rhs.code } \| \\
& \text { gen(Lhs.place ':=' Rhs.place })\}
\end{aligned}
$$

## Relational Expressions: Better Approach

- Often, relational expressions occur in the context of boolean conditions of control statements.
- Instead of creating temporaries which are set to true or false, based upon the outcome of evaluating a boolean condition, generate direct branches to true and false targets.
- Short circuit evaluation of boolean expressions can also be handled effectively by this approach.


## Relational Expressions: Example

$$
\begin{aligned}
& E=a<b \text { or } c<d \text { and } e<f \\
& 100: \text { if } a<b \text { goto _- } \\
& 101: \text { goto } 102 \\
& 102: \text { if } c<d \text { goto } 104 \\
& 103: \text { goto }-- \\
& 104: \text { if } e<f \text { goto _- } \\
& 105: \text { goto _- } \\
& \\
& \text { E.truelist }=\{100,104\} \\
& \text { E.falselist }=\{103,105\}
\end{aligned}
$$

## $E \longrightarrow E_{1}$ or $M E_{2}$

\{
backpatch( $E_{1}$.falselist, M.quad);
E.truelist $=$ merge $\left(E_{1}\right.$. truelist,$E_{2}$. truelist $)$;
E.falselist $=E_{2} \cdot f$ alselist;
$M^{\}} \longrightarrow \epsilon$
$\{$ M.quad $=$ nextquad $\}$
$E \longrightarrow E_{1}$ and $M E_{2}$
\{
backpatch( $E_{1}$. truelist, M.quad);
E.truelist $=E_{2}$.truelist;
E.falselist $=\operatorname{merge}\left(E_{1}\right.$. falselist,$E_{2} . f$ falselist $)$; \}

## Relational Expressions: cont'd.

```
E\longrightarrownot E1
    {
    E.truelist = E . .falselist;
    E.falselist = E1.truelist;
    }
E\longrightarrow(E1)
    {
    E.truelist = E1.truelist;
    E.falselist = E1.falselist;
}
E\longrightarrowid}\mp@subsup{|}{1}{}\mathrm{ relop id 
    {
    E.truelist = makelist(nextquad);
    E.falselist = makelist(nextquad + 1);
    generate(if id .addr relop id 2.addr goto_)
    generate(goto_)
_}
```

```
E}->\mathrm{ true
    {
    E.truelist = makelist ( nextquad );
    generate (goto__ )
    }
E}->\mathrm{ false
    {
    E.falselist = makelist ( nextquad );
    generate (goto
    }
```


## Code Generation for Loops and Conditionals

- Straightforward approach can introduce branch instructions whose targets are unconditional jumps.
while $\mathrm{a}<\mathrm{b}$ do
if $\mathrm{x}<\mathrm{y}$ then S endif
endwhile
100: if $a<b$ go to 102
101: go to 106
102: if $x<y$ go to 104
103: go to 105100
104: S.code
105: go to 100
106:
- We can avoid this by maintaining an additional attribute for statements called the nextlist. This attribute tracks branches in the statements whose target should be set to code that follows them in the execution sequence.

Loops and Conditionals: cont'd.

Loops and Conditionals: cont'd.
$S \longrightarrow$ while $M_{1} E$ do $M_{2} S_{1}$
$\frac{\{ }{\text { backpatch }\left(S_{1} . \text { nextlist }, M_{1} . \text { quad }\right) ;} \quad<\quad$ Optimization $\quad$ takes place here
S.nextlist $=$ E.falselist;
generate(gotoM $\left.M_{1} . q u a d\right)$;
\}
$S \longrightarrow$ begin $L$ end
$\{$ S.nextlist $=$ L.nextlist $\}$
$S \longrightarrow A$
$\{$ S.nextlist $=$ nil $\}$
$L \longrightarrow L_{1} ; M S$
\{
backpatch( $L_{1}$. nextlist, M.quad);
L.nextlist $=$ S.nextlist;
\}
$L \longrightarrow S$
$\{$ L.nextlist $=$ S.nextlist $\}$

```
    while a<b do
        while x<y do
                        S
                        endwhile
endwhile
100: if a < b go to }10
101: go to 107
102: if }x<y\mathrm{ go to }10
103: go to 106 100
104: S.code
105: go to }10
106: go to }10
107: ....
```


## Intermediate Code Generation: case Statements

Implementation issue : Need to generate code so that we can (efficiently) choose one of a set of different alternatives, depending on the value of an expression.

## Implementation choices :

1. linear search
2. binary search
3. jump table

## Implementation considerations

1. Execution Cost: linear or binary search may be cheaper if the no. of cases is small.
For a large no. of cases, a jump table may be cheaper.
2. Space cost : a jump table may take too much space if the case values are not clustered closely together, e.g.:
```
switch (x) {
            case 1 : ...
            case 1000 : ...
            case 1000000 : ...
}
```


### 8.5. Code Generation for Function Calls

## Calling Sequence: Caller :

- Evaluate actual parameters; place actuals where the callee wants them.
Instruction : param $t$
- Save machine state (current stack and/or frame pointers, return address) and transfer control to callee.
Instruction : call $p, n \quad(n=$ no. of actuals)
Calling Sequence: Callee :
- Save registers (if necessary); update stack and frame pointers to accommodate $m$ bytes of local storage.
Instruction : enter $m$.


## Return Sequence: Callee

- Place return value $x$ (if any) where the caller wants it; adjust stack/frame pointers (maybe); jump to return address.
Instruction : return $x$ or return.
Return Sequence: Caller :
- Save the value returned by the callee (if any) into $x$.
Instruction : retrieve $x$.


## Intermediate Code for Function Calls: An Example

## Source Code :

$$
x=f(0, y+1)-1 ;
$$

## Intermediate Code Generated

$$
\begin{array}{ll}
\mathrm{t} 1:=\mathrm{y}+1 & \\
\text { param } \mathrm{t} 1 & / * \arg 2 * / \\
\text { param } 0 & / * \arg 1 * / \\
\text { call } \mathrm{f}, 2 & \\
\text { retrieve t2 } & / * \mathrm{t} 2:=\mathrm{f}(0, \mathrm{t} 1) * / \\
\mathrm{t} 3:=\mathrm{t} 2-1 & \\
\mathrm{x}:=\mathrm{t} 3
\end{array}
$$

Suppose function $f$ needs 24 bytes of space for its locals and temporaries. Its code has the form

```
enter 24
return t17
    /* suppose return value is in t17 */
```


## Code Generation for Functions: Storage Allocation

Problem : The first instruction in a function is enter $n \quad / * n=$ space for locals, temps */ but $n$ is not known until the whole function has been processed.

Solution 1 : generate final code into a list, "backpatch" the appropriate instructions after processing the function body.
Advantage: Can also do machine-dependent optimizations (e.g., instruction scheduling).
Disadvantage : slower, requires more memory.

Solution 2 : Generate code of the form

|  | goto L1 |
| :---: | :---: |
| code | L2: |
| for | code for |
| function | body of foo |
| foo | L1: $L$ codefor enter $n$ goto L2 |

## Reusing Temporaries

Storage requirements can be reduced considerably if we reuse temporaries:

- Maintain a free list of temporaries:
- When a temporary is no longer necessary, it is returned to the free list.
- The function newtemp() is modified to first search the free list, and to allocate a new temporary only if there is nothing in the free list.
- To handle objects of different sizes, we can maintain a free list for each type (or size).

