

# CS130 - LAB - Bézier curves

Name: \_\_\_\_\_

SID: \_\_\_\_\_

In this lab, we will render an approximation of a parametric curve known as the Bézier.

Consider the parametric equation of a segment between two control points  $P_0$  and  $P_1$

$$B(t) = (1 - t)P_0 + tP_1 \quad (1)$$

For  $n$  control points, we can recursively apply Eq. (1) to consecutive control points until we are left with only  $P(t)$ . For three control points,  $B(t) = (1-t)[(1-t)P_0+tP_1]+t[(1-t)P_1+tP_2]$ .

1. Given  $n$  control points, what is the degree of the polynomial equation for the Bézier curve? In general,  $B(t)$  for  $n + 1$  points is given by:

$$B(t) = \sum_{i=0}^n \binom{n}{i} t^i (1-t)^{n-i} P_i$$

■

2. Since we may need the factorial  $n!$ , combination  $\binom{n}{k}$ , and polynomial of  $B(t)$  in this lab, complete the code to for these functions below.

```
float factorial(int n)
{
```

```
}
```

```
float combination(int n, int k)
{
```

```
}
```

```
float polynomial(int n, int k, float t)
{
```

}

■

The code is an  $O(n^2)$  algorithm for computing the  $n + 1$  coefficients

$$c_i = \binom{n}{i} t^i (1 - t)^{n-i}.$$

Next, lets improve upon this. Let

$$r_i = \binom{n}{i} t^i \qquad s_i = (1 - t)^{n-i} \qquad c_i = r_i s_i$$

**3.** The advantage of dividing  $c_i$  into two parts is that  $r_i$  can be easily computed left to right, since  $r_0 = \underline{\hspace{1cm}}$  and  $r_i = (\underline{\hspace{1cm}}) r_{i-1}$ . Similarly,  $s_i$  can be easily computed right to left, since  $s_n = \underline{\hspace{1cm}}$  and  $s_i = (\underline{\hspace{1cm}}) s_{i+1}$ . Note that each of these expressions should be  $O(1)$  and use only basic arithmetic  $(+, -, *, /)$ .

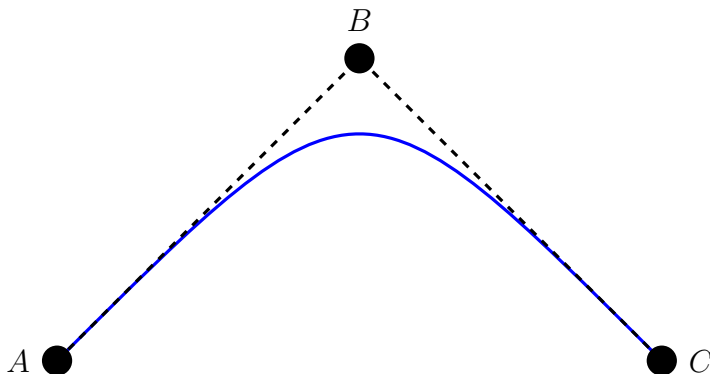
■

**4.** Next, write code for an  $O(n)$  algorithm that computes all of the coefficients  $c[0], \dots, c[n]$  at once. Use only basic arithmetic  $(+, -, *, /)$ .

```
void coefficients(float* c, int n, float t)
{
```

}

■



We can construct the quadratic Bézier curve by assuming that it takes the general form  $P(t) = (a_2 t^2 + a_1 t + a_0)A + (b_2 t^2 + b_1 t + b_0)B + (c_2 t^2 + c_1 t + c_0)C$ . We can use the properties below to solve for the coefficients.

5. Assumption:  $P(0) = A$ . Use this to solve for  $a_0 = \underline{\hspace{1cm}}$ ,  $b_0 = \underline{\hspace{1cm}}$ , and  $c_0 = \underline{\hspace{1cm}}$ .  
■
6. Assumption:  $P(1) = C$ . Use this to solve for  $a_1 = \underline{\hspace{1cm}}$ ,  $b_1 = \underline{\hspace{1cm}}$ , and  $c_1 = \underline{\hspace{1cm}}$ .  
■
7. Assumption: If  $A = B = C$ , then  $P(t) = A$  for all  $t$ . Use this to solve for  $b_2 = \underline{\hspace{1cm}}$ .  
■
8. Assumption:  $P'(0)$  depends on  $A$  and  $B$ , but it does not depend on  $C$ . Use this to solve for  $c_2 = \underline{\hspace{1cm}}$ .  
■
9. Assumption:  $P'(1)$  depends on  $B$  and  $C$ , but it does not depend on  $A$ . Use this to solve for  $a_2 = \underline{\hspace{1cm}}$ .  
■
10. Substituting in all of the coefficients and *factoring the resulting polynomials* produces  $P(t) = (\underline{\hspace{2cm}})A + (\underline{\hspace{2cm}})B + (\underline{\hspace{2cm}})C$ .  
■
11. One can show that  $P'(0) = \alpha(B - A)$  and  $P'(1) = \beta(B - C)$ . Find  $\alpha$  and  $\beta$ .  
■

## Part 2: Coding

Download the skeleton code and modify `main.cpp` as follows:

- Define a global vector to store the control points.
- Push back the mouse click coordinates into the vector in the function `GL_mouse`.
- Write the code for the `factorial`, `combination` and `binomial`.
- Draw line segments between points along the Bézier curve in `GL_render()`.
- You can use `GL_LINE_STRIP` to draw line segments between consecutive points.
- You can iterate  $t$  between 0 and 1 in steps of 0.01.

Optional: Rather than using the general equation for the Bézier curve to write your program, you can write a program where you recursively apply Eq. (1) to consecutive points to get  $B(t)$ . Alternatively, you can use the more efficient algorithm `coefficients`.