TABLE 1 Commonly Used Terminology for the Complexity of Algorithms.

Complexity	*Terminology*
$\Theta(1)$	Constant complexity
$\Theta(\log n)$	Logarithmic complexity
$\Theta(n)$	Linear complexity
$\Theta(n \log n)$	Linearithmic complexity
$\Theta(n^b)$	Polynomial complexity
$\Theta(b^n)$, where $b > 1$	Exponential complexity
$\Theta(n!)$	Factorial complexity

An algorithm has **polynomial complexity** if it has complexity $\Theta(n^b)$, where b is an integer with $b \geq 1$. For example, the bubble sort algorithm is a polynomial-time algorithm because it uses $\Theta(n^2)$ comparisons in the worst case. An algorithm has **exponential complexity** if it has time complexity $\Theta(b^n)$, where $b > 1$. The algorithm that determines whether a compound proposition in n variables is satisfiable by checking all possible assignments of truth variables is an algorithm with exponential complexity, because it uses $\Theta(2^n)$ operations. Finally, an algorithm has **factorial complexity** if it has $\Theta(n!)$ time complexity. The algorithm that finds all orders that a traveling salesperson could use to visit n cities has factorial complexity; we will discuss this algorithm in Chapter 9.

TRACTABILITY A problem that is solvable using an algorithm with polynomial worst-case complexity is called **tractable**, because the expectation is that the algorithm will produce the solution to the problem for reasonably sized input in a relatively short time. However, if the polynomial in the big-Θ estimate has high degree (such as degree 100) or if the coefficients are extremely large, the algorithm may take an extremely long time to solve the problem. Consequently, that a problem can be solved using an algorithm with polynomial worst-case time complexity is no guarantee that the problem can be solved in a reasonable amount of time for even relatively small input values. Fortunately, in practice, the degree and coefficients of polynomials in such estimates are often small.

The situation is much worse for problems that cannot be solved using an algorithm with worst-case polynomial time complexity. Such problems are called **intractable**. Usually, but not always, an extremely large amount of time is required to solve the problem for the worst cases of even small input values. In practice, however, there are situations where an algorithm with a certain worst-case time complexity may be able to solve a problem much more quickly for most cases than for its worst case. When we are willing to allow that some, perhaps small, number of cases may not be solved in a reasonable amount of time, the average-case time complexity is a better measure of how long an algorithm takes to solve a problem. Many problems important in industry are thought to be intractable but can be practically solved for essentially all sets of input that arise in daily life. Another way that intractable problems are handled when they arise in practical applications is that instead of looking for exact solutions of a problem, approximate solutions are sought. It may be the case that fast algorithms exist for finding such approximate solutions, perhaps even with a guarantee that they do not differ by very much from an exact solution.

Some problems even exist for which it can be shown that no algorithm exists for solving them. Such problems are called **unsolvable** (as opposed to **solvable** problems that can be solved using an algorithm). The first proof that there are unsolvable problems was provided by the great English mathematician and computer scientist Alan Turing when he showed that the halting problem is unsolvable. Recall that we proved that the halting problem is unsolvable in Section 3.1. (A biography of Alan Turing and a description of some of his other work can be found in Chapter 13.)