More on Random Walks, Electrical Networks, and the Harmonic k-Server Algorithm

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Abstract

Techniques from electrical network theory have been used to establish various properties of random walks. We explore this connection further, by showing how the classical formulas for the determinant and cofactors of the admittance matrix, due to Maxwell and Kirchoff, yield upper bounds on the edge stretch factor of the harmonic random walk. For any complete, n-vertex graph with distances assigned to its edges, we show the upper bound of $(n-1)^2$. If the distance function satisfies the triangle inequality, we give the upper bound of $\frac{1}{2}n(n-1)$. Both bounds are tight. As a consequence, we obtain that the harmonic algorithm for the k server problem is $\frac{1}{2}k(k+1)$-competitive against the lazy adversary.

1 Introduction

Random walks and electrical networks. Let G be a complete undirected graph with n vertices numbered $1, 2, \ldots, n$, in which each edge (u, v) is assigned its *distance* $d_{u,v} > 0$. We study the *harmonic random walk* in G, which, from a vertex u, moves to another vertex v with probability

$$p_{u,v} = \frac{1/d_{u,v}}{\sum_{x \neq u} 1/d_{u,x}}.$$

In the literature, the harmonic random walk was often studied using techniques from electrical network theory. Denote by $H_{u,v}$ the *hitting cost* of the harmonic walk from u to v, defined as the expected cost (total distance) to reach v for the first time when started from u. By elementary probability, the costs of the random walks ending at vertex n satisfy the following system of equations:

$$H_{u,n} = \sum_{v \neq u} p_{u,v}(d_{u,v} + H_{v,n}), \quad \text{for } u \neq n, \tag{1}$$

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and $H_{n,n} = 0$. As noted in [7], the hitting costs have an interpretation in terms of electrical networks. We can think of G as an electrical network in which each edge (u, v) has resistance $d_{u,v}$. If we inject current of value $n - 1$ into each node and draw current of value $n(n - 1)$ from node n, then the voltages relative to node n established at the nodes satisfy the same equation as (1). Therefore the voltage at u is equal to the hitting cost $H_{u,n}$.

Further connections between random walks and electrical networks were explored by Chandra *et al.* [3]. One result from [3] that is directly relevant to our work is that the *cycle stretch factor* of the harmonic random walk is at most $\frac{1}{2}n(n - 1)$, where the cycle stretch factor is defined as the maximum ratio between the cost of a random walk that visits the nodes of a cycle (in order) and the length of this cycle. Coppersmith *et al.* [6] use the connection to electrical networks for the design of random walks and randomized online algorithms.

The *edge stretch factor* of the harmonic random walk is the maximum ratio between the cost of a random walk between two nodes and the distance between these nodes, that is $\max_{u \neq v} H_{u,v}/d_{u,v}$. Applying the bound on the cycle stretch factor in [3] to a 2-cycle $u \to v \to u$, we get $H_{u,v} + H_{v,u} \leq \frac{1}{2}n(n - 1)(2d_{u,v})$, so the edge stretch factor is at most $n(n - 1)$ [9]. To our knowledge, this is the best upper bound known to date.

The k-server problem. In the *k-server problem* we have k servers that reside and move in a metric space M. At each time step a request $r \in M$ is specified, and we need to move one server to r to "satisfy" the request. The decision as to which server to move needs to be made *online*, without the knowledge about future requests. An online algorithm $\mathcal{A}$ for the k-server problem is called *R-competitive* if its cost on any request sequence ϱ is at most R times the optimal (offline) cost on ϱ, plus possibly an additive constant independent of ϱ. For randomized algorithms, by $\mathcal{A}$'s cost we mean its *expected* cost on ϱ. The *competitive ratio* of $\mathcal{A}$ is the smallest R for which $\mathcal{A}$ is R-competitive. We refer the reader to [2] for more background information on this problem.

HARMONIC is a randomized k-server algorithm proposed by Raghavan and Snir [9]. If the current configuration of HARMONIC is X, and the request point is $r \notin X$, it moves a server from $v \in X$ with probability inversely proportional to the distances to the request. Thus this probability is equal $p_{r,v}$, if we take $G = X \cup \{r\}$. The best upper bound on the competitive ratio of HARMONIC, by Bartal and Grove [1], is exponential in k (see also [2]), while the best lower bound is $\frac{1}{2}k(k + 1)$ [9]. For $k = 2$, it is known that HARMONIC is 3-competitive [4, 5], which is tight, by [9]. The $\frac{1}{2}k(k + 1)$ bound on the cycle stretch factor from [3] implies that HARMONIC is $\frac{1}{2}k(k + 1)$-competitive in all spaces with $k + 1$ points [9]. These upper bounds hold against the so-called *adaptive online adversary* that can choose requests using the knowledge of the current server locations of the algorithm. It has been conjectured that HARMONIC is $\frac{1}{2}k(k + 1)$-competitive in all metric spaces but, except the two cases mentioned above, this conjecture remains open.

The adversary is called *lazy* if, whenever one of his servers is not covered by our server, he requests this server's location. Otherwise, if the servers match, he moves one server to a new point. When the adversary is lazy, all $2k$ servers (ours and the adversary's) occupy at most $k + 1$ points at any given time. However, the argument that HARMONIC is $\frac{1}{2}k(k + 1)$-competitive in spaces with $k + 1$ points [9] does not apply to the lazy adversary case, since it is based on the assumption that this set of $k + 1$ points is fixed throughout the computation.

Our results. We show how the classical formulas for the determinant and cofactors of the admittance matrix, due to Maxwell and Kirchoff, yield upper bounds on the edge stretch factor of the harmonic random walk. For arbitrary positive distances, we obtain an upper bound of $(n-1)^2$. If the distances satisfy the triangle inequality, that is, if G is a metric space, then we show an upper bound of $\frac{1}{2}n(n-1)$. Both upper bounds are tight. It is not difficult to see that a bound of R_n on the edge stretch factor of a harmonic random walk in n-point metric spaces implies that HARMONIC is R_{k+1}-competitive for k servers against the lazy adversary [9, 2]. As a corollary, we obtain that HARMONIC is $\frac{1}{2}k(k+1)$-competitive against the lazy adversary.

The paper is organized as follows. In Section 2, we study the connection between harmonic random walks and electrical networks and we establish our upper bounds on the edge stretch factor. In Section 3, we use the upper bound on the stretch factor in metric spaces to determine the competitive ratio of HARMONIC. For interested readers, we also outline a different analysis of HARMONIC that does not use the theory of electrical networks.

2 Upper Bounds on the Stretch Factor

For convenience, we present the proof in terms of inverse distances $c_{u,v} = 1/d_{u,v}$. The triangle inequality translates then to: $c_{x,z}(c_{x,y} + c_{y,z}) \geq c_{x,y}c_{y,z}$, for all distinct nodes x, y, z. The move probability is $p_{u,v} = c_{u,v}/c_u$, where $c_u = \sum_{x \neq u} c_{u,x}$. Since $d_{u,v}$ represents the resistance of edge (u, v), we can think of $c_{u,v}$ as the *conductance* of (u, v). The system (1) can be written as

$$\begin{pmatrix} c_1 & -c_{1,2} & \dots & -c_{1,n-1} \\ -c_{2,1} & c_2 & \dots & -c_{2,n-1} \\ \vdots & \vdots & \ddots & \vdots \\ -c_{n-1,1} & -c_{n-1,2} & \dots & c_{n-1} \end{pmatrix} \begin{pmatrix} H_{1,n} \\ H_{2,n} \\ \vdots \\ H_{n-1,n} \end{pmatrix} = (n-1) \cdot \begin{pmatrix} 1 \\ 1 \\ \vdots \\ 1 \end{pmatrix},$$

or $\widetilde{C}H = (n-1)\mathbf{1}$. In the theory of electrical networks, $\widetilde{C}$ is called the *admittance matrix*. Let $\widetilde{C}_{i,j}$ be the sub-matrix of $\widetilde{C}$ obtained by removing row i and column j. Then

$$H_{i,n} = \frac{n-1}{\det(\widetilde{C})} \sum_{j=1}^{n-1} (-1)^{i+j} \det(\widetilde{C}_{j,i}). \tag{2}$$

We now fix G and consider various sets of edges of G. A 2-*tree* is a forest that consists of two disjoint trees. We identify trees and 2-trees with their sets of edges. A tree T in G is called *spanning* if it has $n-1$ edges. A 2-tree S is called *spanning* if it has $n-2$ edges.

For any set of edges F, let $\xi_F = \prod_{(u,v) \in F} c_{u,v}$ be the product of all conductances in F. We use the following theorem from electrical network theory due to Maxwell and Kirchoff (see [8, 10]).

Theorem 1 (a) $\det(\widetilde{C}) = \sum_T \xi_T$, *where the sum is over all spanning trees* T.

(b) $(-1)^{i+j} \det(\widetilde{C}_{j,i}) = \sum_S \xi_S$, *where the sum is over all spanning* 2*-trees* S *in which nodes* i *and* j *are in one component and node* n *in the other.*

Now we are ready to prove our upper bounds on the edge stretch factor. All trees and 2-trees considered in this section are spanning subgraphs, so we will omit the adjective "spanning" from now on, for simplicity.

Theorem 2 (a) *The edge stretch factor of the harmonic random walk is at most* $(n-1)^2$.

(b) *If the distances satisfy the triangle inequality, then the edge stretch factor of the harmonic random walk is at most* $\frac{1}{2}n(n-1)$.

Proof: (a) We show that $H_{1,n} \leq (n-1)^2 d_{1,n}$. By (2), it is sufficient to prove that

$$c_{1,n} \sum_{j=1}^{n-1} (-1)^{j+1} \det(\widetilde{C}_{j,1}) \quad \leq \quad (n-1) \det(\widetilde{C}). \tag{3}$$

By Theorem 1, part (a), the right-hand side is $(n-1)\sum_T \xi_T$. By Theorem 1, part (b), the left-hand side of (3) is a sum of terms ξ_T, for trees T that contain edge $(1,n)$. Each tree appears on the left-hand side at most $n-1$ times, and (3) follows.

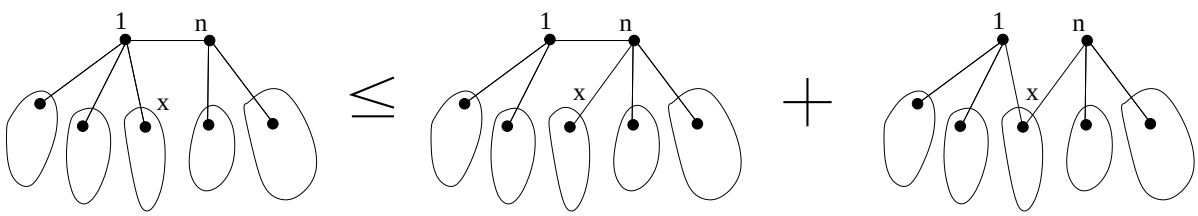
(b) Similar to (a), it is sufficient to prove that

$$2c_{1,n} \sum_{j=1}^{n-1} (-1)^{j+1} \det(\widetilde{C}_{j,1}) \quad \leq \quad n \det(\widetilde{C}). \tag{4}$$

As in (a), the right-hand side of (4) is $n\sum_T \xi_T$, and the left-hand side is a sum of terms ξ_T, for trees T that contain edge $(1,n)$. Each such tree T appears once in each term $c_{1,n}(-1)^{j+1}\det(\widetilde{C}_{j,1})$ where j is in the component of vertex 1 in the 2-tree $T-(1,n)$. We conclude that the left-hand side equals $2\sum_{T \ni (1,n)} r_T \xi_T$, where r_T is the size of the component of 1 in $T-(1,n)$. We call r_T the *rank of* T. Thus we reduced (4) to the following inequality:

$$2 \sum_{T \ni (1,n)} r_T \xi_T \quad \leq \quad n \sum_T \xi_T. \tag{5}$$

To prove (5), we will apply iteratively triangle inequalities to the tree products ξ_T that appear on the left-hand side of (5). For simplicity, in the rest of the proof we will identify ξ_T with the tree T itself and manipulate directly on trees rather than the corresponding products. We think of each tree T as being "rooted" at edge $(1,n)$. The triangle inequalities that we apply to T are $c_{1,x}c_{1,n} \leq c_{1,n}c_{x,n} + c_{1,x}c_{x,n}$, where x is a child of node 1. Applying this inequality to T is equivalent to replacing T by two trees $T-(1,x)+(n,x)$ and $T-(1,n)+(n,x)$, as illustrated in the following picture:



Using this operation, we will convert the trees in the left-hand side of (5) into another collection of trees, each with multiplicity at most n. This will prove (5) and the theorem.

The procedure works as follows. We process all trees containing edge $(1, n)$ in order of decreasing rank. Suppose that T is a tree that we are currently processing. For any child x of node 1, if the subtree rooted at x has cardinality a, then replace a copies of T by a copies of $T - (1, x) + (n, x)$ and a copies of $T - (1, n) + (n, x)$.

We claim that, after we are done, the coefficient of any tree T that contains edge $(1, n)$ is n. Let $a_1, \ldots, a_l$ be the cardinalities of the subtrees of T rooted at the children of 1, and $b_1, \ldots, b_m$ the cardinalities of the subtrees rooted at the children of n. When processing T, we start with $2r_T$ copies of T. By the previous paragraph, we will convert $\sum_{s=1}^{l} a_s = r_T - 1$ copies of T into trees of smaller rank. However, T can itself be obtained from converting trees of higher rank in previous steps in $\sum_{s=1}^{m} b_s = n - r_T - 1$ ways. So the number of copies of T that remain is $2r_T - (r_T - 1) + (n - r_T - 1) = n$.

In addition to trees that contain edge $(1, n)$, this process will also produce trees in which nodes 1 and n are at distance 2 apart. When we process T, as described above, we create $a \leq n - 2$ copies of $T - (1, n) + (n, x)$. This tree cannot be produced in any other way during this process, so its coefficient is at most $n - 2$. This completes the proof of (b). □

Both upper bounds in Theorem 2 are tight. To show that part (a) is tight, consider the graph G with distances $d_{i,j} = 1$ for $i < j < n$, $d_{1,n} = 1$, and $d_{i,n} = D$ for $i \neq 1, n$. By elementary calculations, we get $H_{1,n} \to (n-1)^2$ for $D \to \infty$. The proof that the upper bound from (b) is tight appeared in [9, 2]. (For readers who may wish to verify this result, the space used in this lower bound is defined by $d_{i,j} = D$ for $\{i, j\} \neq \{1, n\}$ and $d_{1,n} = 1$, where D is arbitrarily large.)

3 The HARMONIC Algorithm

The relation between the edge stretch factor and the competitiveness of HARMONIC against the lazy adversary is known [9]. Divide the computation into phases, each phase starting and ending at matched configurations, when HARMONIC and the adversary occupy the same set of k points. From a matched configuration X, the adversary moves a server, say from a point v to a new point u, at cost $d_{u,v}$. Then HARMONIC executes its random moves until it converges to configuration $X - v + u$. The changes of the *hole*, that is, the unique point in $X + u$ not occupied by HARMONIC constitute the harmonic random walk from u to v in the $k+1$-point space $X + u$. Thus HARMONIC's cost in this phase is $H_{u,v}$, which, by Theorem 2, is at most $\frac{1}{2}k(k+1)$ times the adversary cost. Summing it over all phases, we get the following theorem.

Theorem 3 *Algorithm* HARMONIC *is* $\frac{1}{2}k(k+1)$*-competitive against the lazy adversary.*

Unplugged proof. For interested readers, we also outline a direct competitiveness proof that does not use electrical network theory. The proof is by amortized analysis. At any time step, all k HARMONIC's servers and k adversary's servers cover at most $k + 1$ points. We define a potential function Φ that assigns to each such configuration a non-negative real value, and we prove that Φ satisfies certain inequalities that imply competitiveness.

If only k points are covered, that is, when the locations of HARMONIC's and the adversary's servers are the same, we take $\Phi = 0$. Otherwise, number the covered points $1, 2, \ldots, k+1$, with the

adversary hole on $k+1$ and HARMONIC's hole on 1.

For $u, v \leq k$ we define the numbers $H'_{u,v}$ to be the solution of

$$\sum_{u \neq z,k+1} c_{z,u} H'_{u,v} + k \quad = \quad (c_z + c_{z,v} - c_{z,k+1}) H'_{z,v} \quad \text{for all } z \neq v, \tag{6}$$

and $H'_{v,v} = 0$. Note that $H'_{u,v}$ can be interpreted as a cost of a certain random walk. This random walk takes place in an auxiliary $k+1$-vertex graph induced by the vertices $1, \ldots, k$, plus one extra copy of vertex v. Then $H'_{u,v}$ is the expected cost of the harmonic random walk in this graph that starts at u and ends at v or its copy. This implies that $H'_{u,v}$ is uniquely defined.

Let $\Phi = \min_v \left\{ \frac{1}{2} k(k+1) d_{v,k+1} + H'_{1,v} \right\}$. Denote by $\Delta\Phi$ the change of the potential in one move. We need to show that

(i) when the adversary moves then $\Delta\Phi$ is at most $\frac{1}{2}k(k+1)$ times his cost, and

(ii) when HARMONIC moves then its expected cost is at most $-\Delta\Phi$.

The competitiveness follows from (i) and (ii) by amortization.

To show (i), suppose that the adversary has just moved his server from $k+1$ to 1, paying $d_{1,k+1}$. By choosing $v = 1$ in the definition of Φ, we get $\Delta\Phi \leq \frac{1}{2}k(k+1)d_{1,k+1}$, and (i) follows.

We now prove (ii). The next request is on vertex 1 and HARMONIC's expected cost in this move is k/c_1. Thus it is sufficient to prove that $\Delta\Phi \leq -k/c_1$.

Fix v that minimizes Φ. We distinguish two cases, $v \neq 1$ and $v = 1$. Assume first that $v \neq 1$. As explained in the introduction, the results from [3] imply an upper bound of $n(n-1)$ on the edge stretch factor. In the definition of the numbers $H'_{u,v}$, instead of creating a copy of v, we could have instead reduced the distances to v by half. Thus we get $H'_{1,v} \leq \frac{1}{2}k(k+1)d_{1,v}$. Using this bound, equation (6), and the triangle inequality $c_{1,v} - c_{1,s} \leq d_{v,s} c_{1,v} c_{1,s}$, we have

$$\begin{aligned}
c_1 \Delta\Phi &= \sum_{u \neq 1,k+1} c_{1,u} \min_t \left\{ \tfrac{1}{2}k(k+1)d_{t,k+1} + H'_{u,t} \right\} - c_1[\tfrac{1}{2}k(k+1)d_{v,k+1} + H'_{1,v}] \\
&\leq \sum_{u \neq 1,k+1} c_{1,u}[\tfrac{1}{2}k(k+1)d_{v,k+1} + H'_{u,v}] - c_1[\tfrac{1}{2}k(k+1)d_{v,k+1} + H'_{1,v}] \\
&= -\tfrac{1}{2}k(k+1)c_{1,k+1}d_{v,k+1} + (c_{1,v} - c_{1,k+1})H'_{1,v} - k \\
&\leq -\tfrac{1}{2}k(k+1)c_{1,k+1}d_{v,k+1} + d_{v,k+1}c_{1,v}c_{1,k+1}H'_{1,v} - k \\
&= d_{v,k+1}c_{1,k+1}[-\tfrac{1}{2}k(k+1) + c_{1,v}H'_{1,v}] - k \\
&\leq -k.
\end{aligned}$$

The second case is when $v = 1$. Summing (6) for all $z \neq v, k+1$, we get $\sum_{u \neq v,k+1} c_{u,v} H'_{u,v} = \frac{1}{2}k(k-1)$. Using this equality, we have

$$\begin{aligned}
c_1 \Delta\Phi &\leq \sum_{u \neq 1,k+1} c_{1,u}[\tfrac{1}{2}k(k+1)d_{1,k+1} + H'_{u,1}] - c_1[\tfrac{1}{2}k(k+1)d_{1,k+1}] \\
&= \sum_{u \neq 1,k+1} c_{1,u}H'_{u,1} - c_{1,k+1}[\tfrac{1}{2}k(k+1)d_{1,k+1}] \\
&= -k.
\end{aligned}$$

This completes the proof of (ii) and of Theorem 3.

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