

CS133 Computational Geometry

Review of Linear Algebra

In this class ...

- > Vectors
- > Dot product
- Cross product
- > Determinants



Vectors



- > Euclidean vector or geometric vector
- A geometric object that has magnitude and direction
- > Notation: $a = \overrightarrow{AB}$
- Cartesian representation
 - > $a = (a_1, a_2)$
- Magnitude

>
$$\|a\| = \sqrt{a_1^2 + a_2^2}$$

>
$$\tan(\theta) = \frac{a_2}{a_1}$$



Addition/Subtraction





 $a + b = (a_1 + b_1, a_2 + b_2)$

 $a - b = (a_1 - b_1, a_2 - b_2)$



Scalar Multiplication



 $r\mathbf{a} = \mathbf{a} + \mathbf{a} + \dots + \mathbf{a} = (ra_1, ra_2)$



Dot Product

 $a \cdot b = ||a|| ||b|| \cos(\theta)$

 $a \cdot b = a_1 b_1 + a_2 b_2$

The result of a dot product is a scalar value

$$a \cdot b = b \cdot a$$

$$a \cdot a = \|a\|^2$$







Cross Product



 $a \times b = ||a|| ||b|| \sin(\theta) \mathbf{n}$

 $a \times b = a_1 b_2 - a_2 b_1$

The result of a cross product is a vector

$$a \times b = -b \times a$$

a

Determinants



$$|D| = \begin{vmatrix} a & b \\ c & d \end{vmatrix} = a \cdot d - b \cdot c$$

$$|D| = \begin{vmatrix} a & b & c \\ d & e & f \\ g & h & i \end{vmatrix} = a \begin{vmatrix} e & f \\ h & i \end{vmatrix} - b \begin{vmatrix} d & f \\ g & i \end{vmatrix} + c \begin{vmatrix} d & e \\ g & h \end{vmatrix}$$

$$= aei + bfg + cdh - ceg - bdi - afh$$