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These notes are provisional

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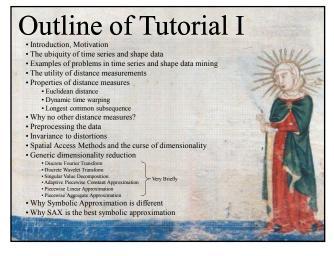
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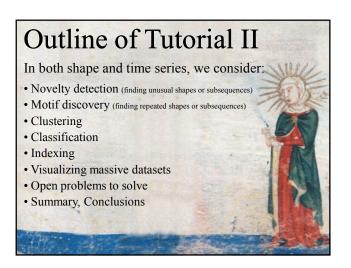
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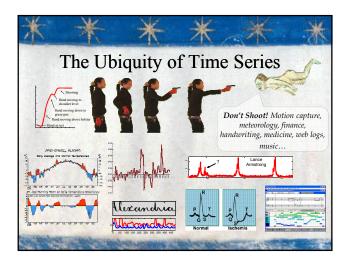
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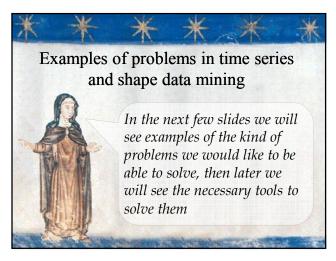


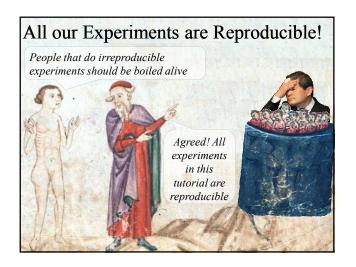


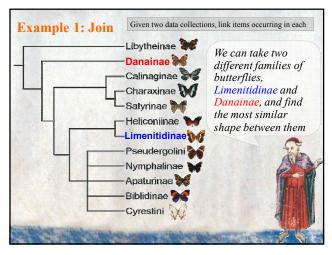


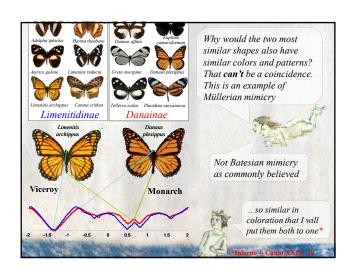




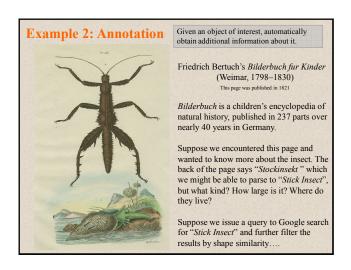


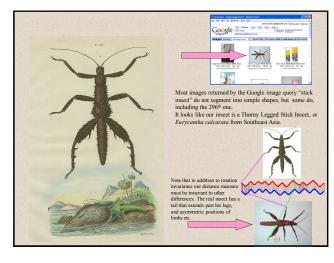


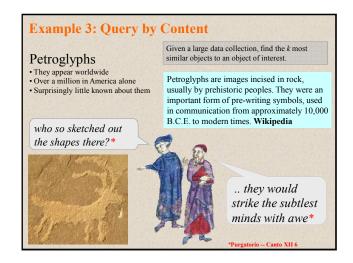


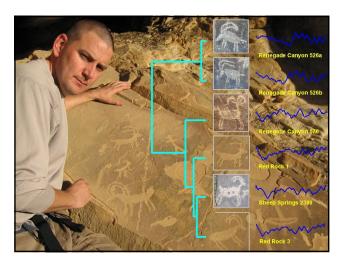


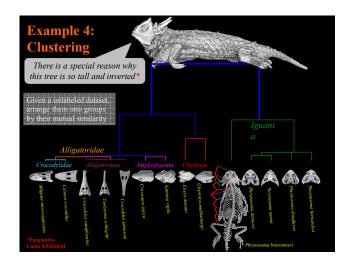


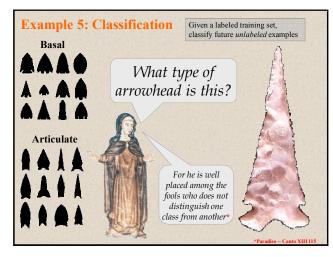


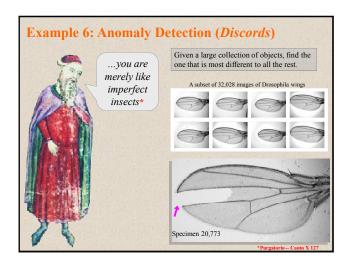


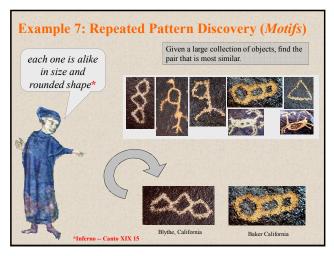


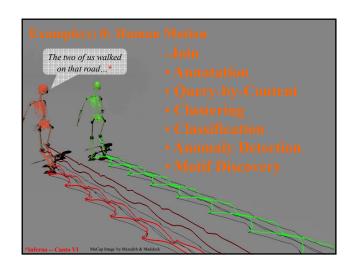


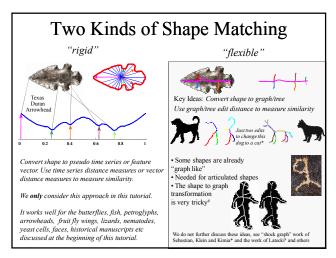


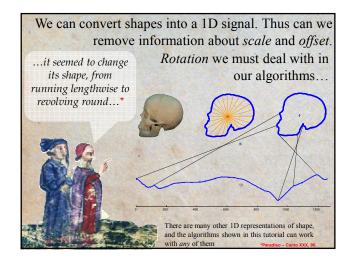


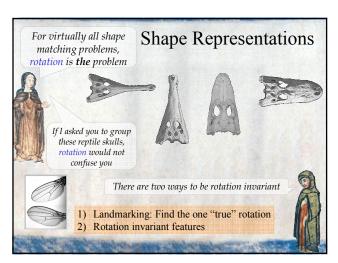


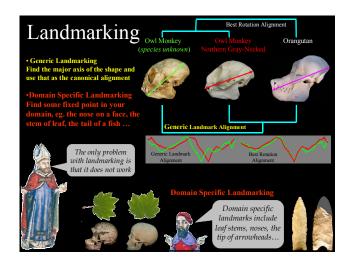


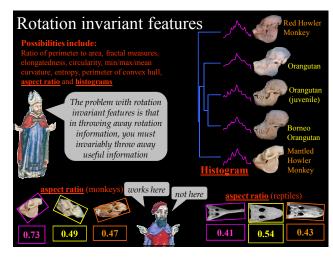


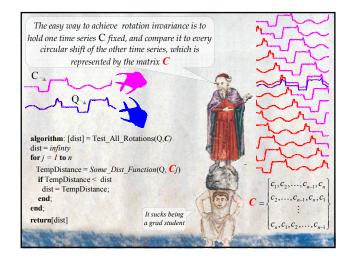


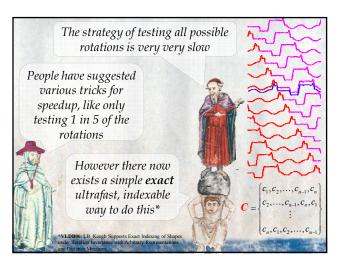


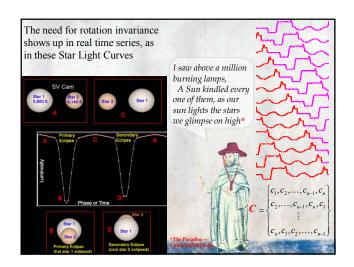


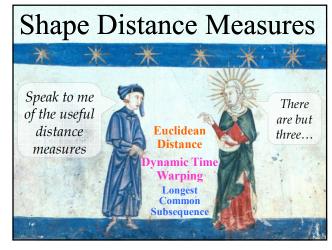


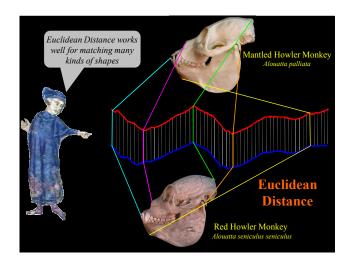


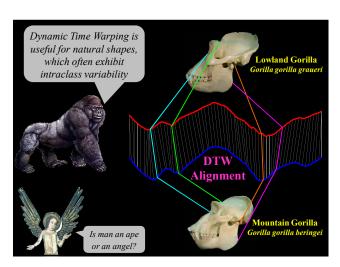


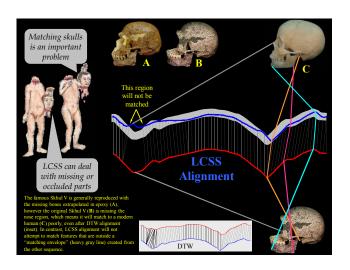


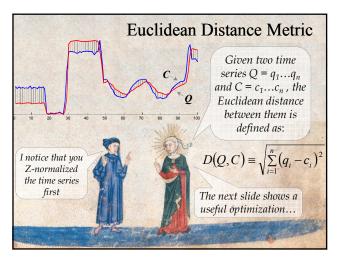


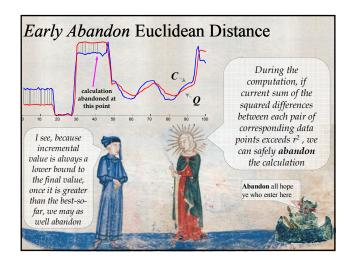


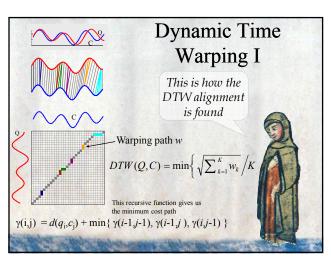


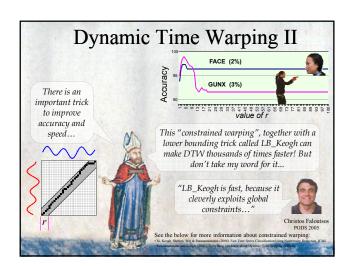


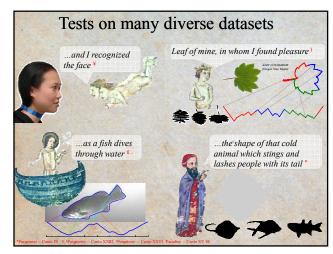




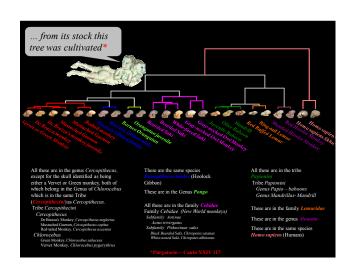


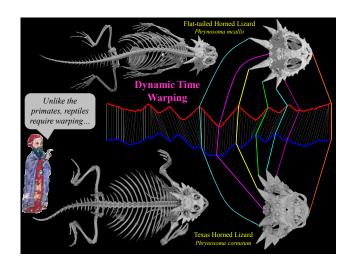


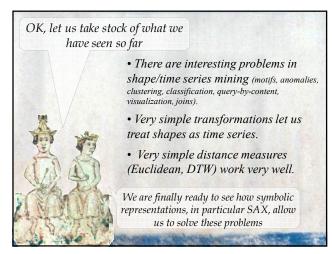


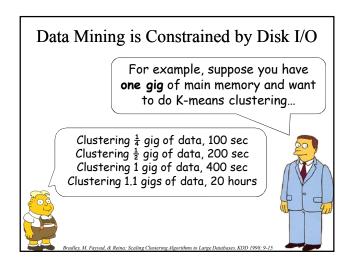


Name	Classes	Instances	Euclidean Error (%)	DTW Error (%) {r}	Other Techniques
Face	16	2240	3.839	3.170{3}	
Swedish Leaves	15	1125	13.33	10.84(2)	17.82 Söderkvist
Chicken	5	446	19.96	19.96(1)	20.5 Discrete strings
MixedBag T	9	160	4.375	4.375{1}	Chamfer 6.0, Hausdorff 7.0
OSU Leaves	6	442	33.71	15.61(2)	
Diatoms 🧨 🥞	37	781	27.53	27.53{1}	26.0 Morphological Curvature Scale Spaces
Plane -	7	210	0.95	0.0{3}	0.55 Markov Descriptor
Fish	7	350	11.43	9.71(1)	36.0 Fourier /Power Cepstrum





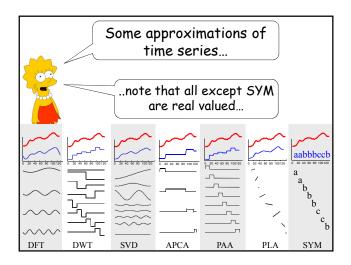


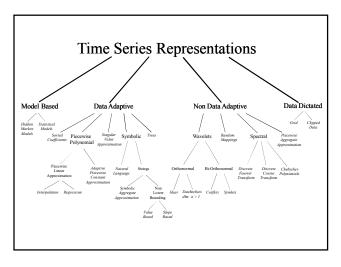


The Generic Data Mining Algorithm

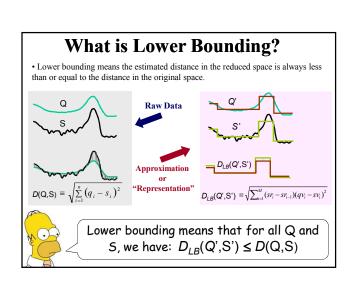
- Create an *approximation* of the data, which will fit in main memory, yet retains the essential features of interest
- · Approximately solve the problem at hand in main memory
- Make (hopefully very few) accesses to the original data on disk to confirm the solution obtained in Step 2, or to modify the solution so it agrees with the solution we would have obtained on the original data

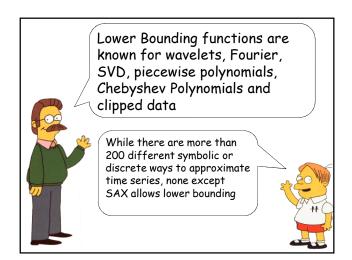
But which approximation should we use?

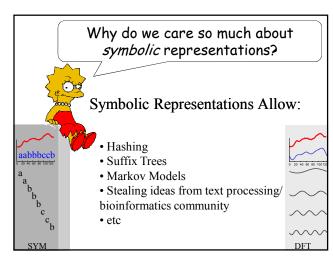




The Generic Data Mining Algorithm (revisited) Create an approximation of the data, which will fit in main memory, yet retains the essential features of interest Approximately solve the problem at hand in main memory Make (hopefully very few) accesses to the original data on disk to confirm the solution obtained in Step 2, or to modify the solution so it agrees with the solution we would have obtained on the original data This only works if the approximation allows lower bounding

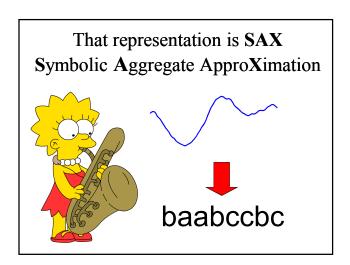


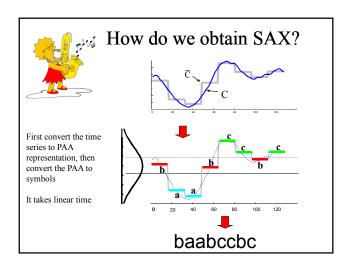


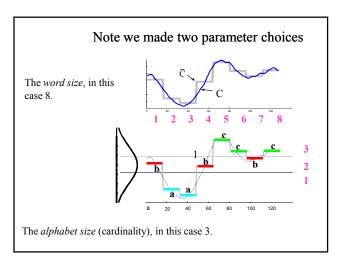


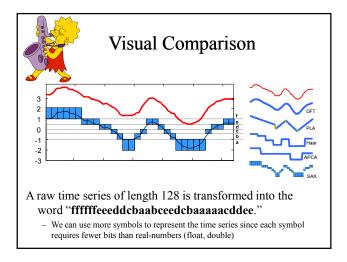
There is *one* symbolic representation of time series, that allows...

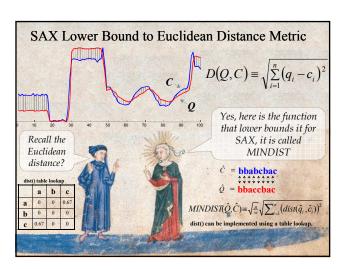
- Lower bounding of Euclidean distance
- Lower bounding of the DTW distance
- Dimensionality Reduction
- Numerosity Reduction













Let us consider the utility of SAX for visualizing time series. We start with an apparent digression, visualizing DNA....

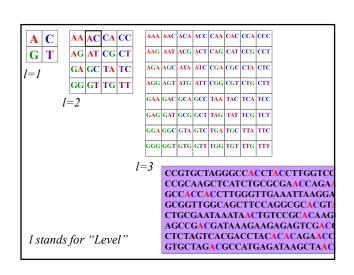
The DNA of two species...

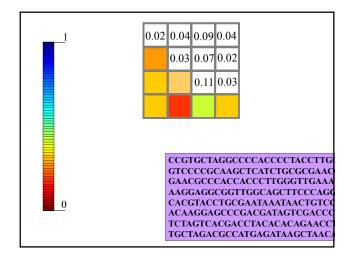
Are they similar?

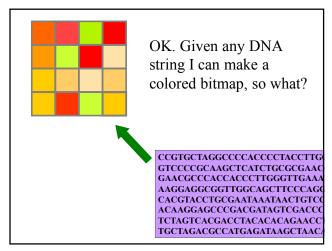
TGGCCGTGCTAGGCCCCACCCTACCTTG
GTCCCCGCAAGCTCATCTGCGCGAACCAC
ACGCCCACCACCTTGGGTGAAATTAAG
GGCGGTTGGCAGCTTCCCAGGCGCACATG
CTGCGAATAAATAACTGTCCGCACAAGGA
CCGACGATAAATAACTGTCCGCACAAGGA
CCGACGATAAATAACTGTCCTCTAGTCACG
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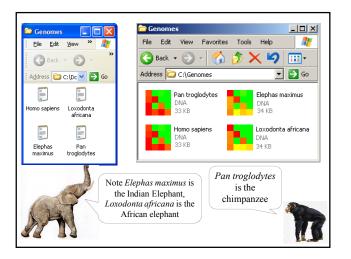
CCGTGCTAGGGCCACCTACCTTGGTCC CCGCAAGCTCATCTGCGCGAACCAGAA GCCACCACCTTGGGTTGAAATTAAGGA GCGGTTGGCAGCTTCCAGGCGCACCATA CTGCGAATAAATAACTGTCCGCACAAG AGCCGACGATAAAGAAGAGAGTCGACC CTCTAGTCACGACCTTACACACAGAACC GTGCTAGACGCCATGAGATAAGCTAAC

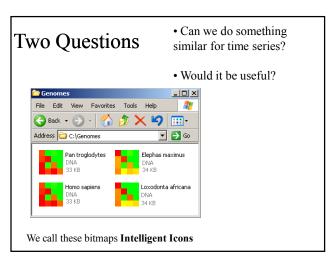
A C	
GT	
0.20 0.24	CCGTGCTAGGGCCACCTACCTTGGTCC CCGCAAGCTCATCTGCGCGAACCAGAA GCCACCACCTTGGGTTGAAATTAAGGA
0.26 0.30	GCGGTTGGCAGCTTCCAGGCGCACGTZ CTGCGAATAAATAACTGTCCGCACAAG AGCCGACGATAAAGAAGAGAGTCCAC CTCTAGTCACGACCTACACACAAACC GTGCTAGACGCCATGAGATAAGCTAAC

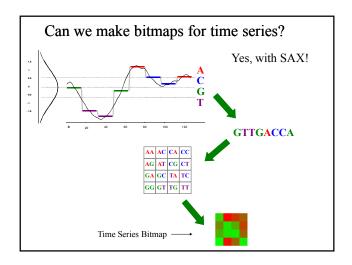


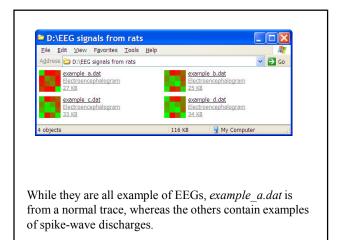


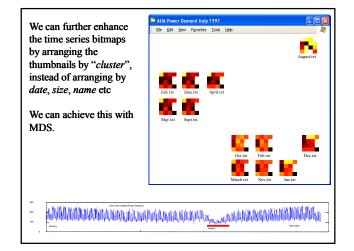


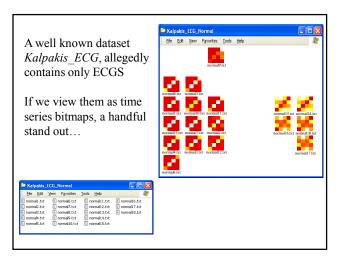


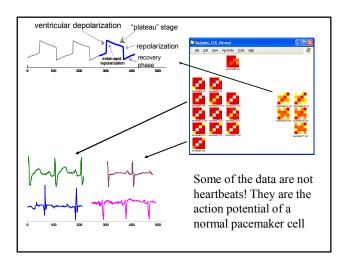


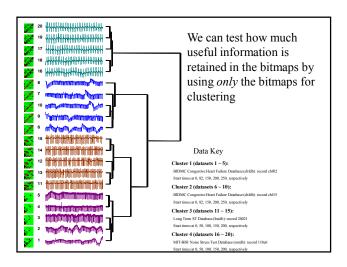


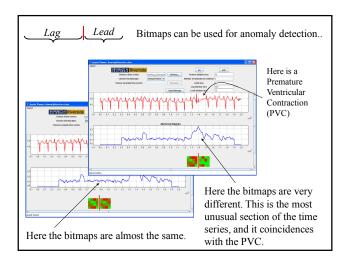


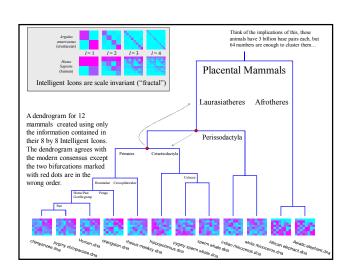


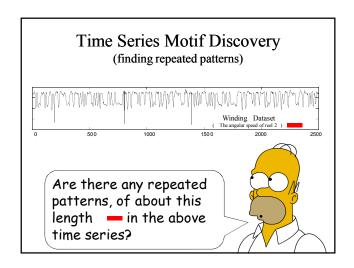


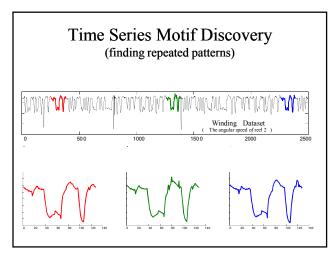


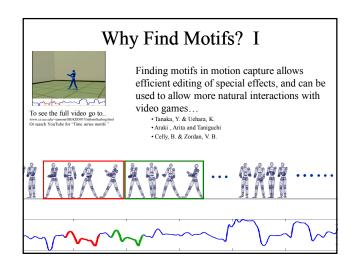






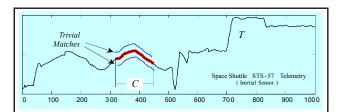






Why Find Motifs? II

- · Mining **association rules** in time series requires the discovery of motifs. These are referred to as *primitive shapes* and *frequent patterns*.
- · Several time series **classification algorithms** work by constructing typical prototypes of each class. These prototypes may be considered motifs.
- · Many time series **anomaly/interestingness detection** algorithms essentially consist of modeling normal behavior with a set of typical shapes (which we see as motifs), and detecting future patterns that are dissimilar to all typical shapes.
- · In **robotics**, Oates et al., have introduced a method to allow an autonomous agent to generalize from a set of qualitatively different *experiences* gleaned from sensors. We see these "*experiences*" as motifs. See also Murakami Yoshikazu, Doki & Okuma and Maja J Mataric
- · In **medical data mining**, Caraca-Valente and Lopez-Chavarrias have introduced a method for characterizing a physiotherapy patient's recovery based of the discovery of *similar patterns*. Once again, we see these "*similar patterns*" as motifs.



Definition 1. *Match:* Given a positive real number R (called *range*) and a time series T containing a subsequence C beginning at position p and a subsequence M beginning at q, if $D(C, M) \le R$, then M is called a *matching* subsequence of C.

Definition 2. Trivial Match: Given a time series T, containing a subsequence C beginning at position p and a matching subsequence M beginning at q, we say that M is a trivial match to C if either p=q or there does not exist a subsequence M beginning at q such that D(C, M') > R, and either q < q' < p or p < q' < q.

Definition 3. *K-Motif(n,R)*: Given a time series T, a subsequence length n and a range R, the most significant motif in T (hereafter called the I-Motif(n,R)) is the subsequence C_1 that has highest count of non-trivial matches (ties are broken by choosing the motif whose matches have the lower variance). The K^{th} most significant motif in T (hereafter called the K-Motif(n,R)) is the subsequence C_K that has the highest count of non-trivial matches, and satisfies $D(C_K, C_J) > 2R$, for all $1 \le i < K$.

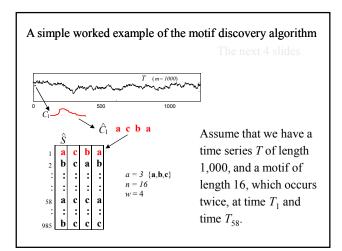
OK, we can define motifs, but how do we find them?

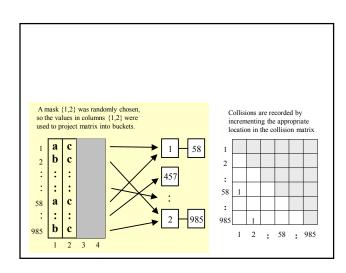
The obvious brute force search algorithm is just too slow...

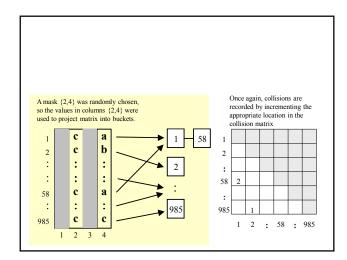
The most reference algorithm is based on a *hot* idea from bioinformatics, *random projection** and the fact that SAX allows use to **lower bound** discrete representations of time series

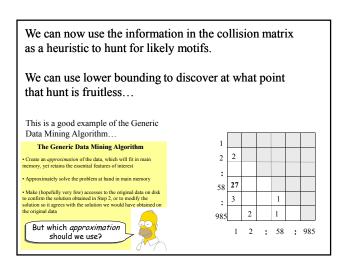
* J Buhler and M Tompa. Finding motifs using random projections. In RECOMB'01. 2001.

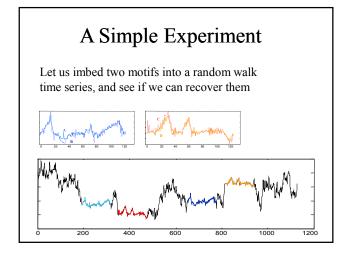


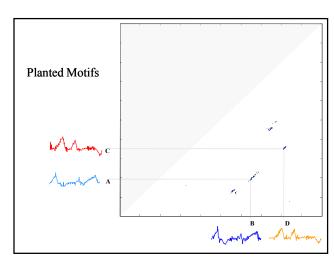


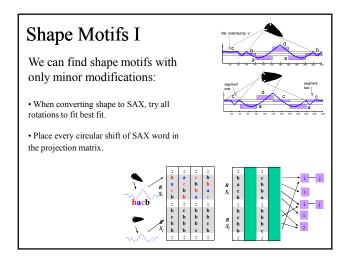


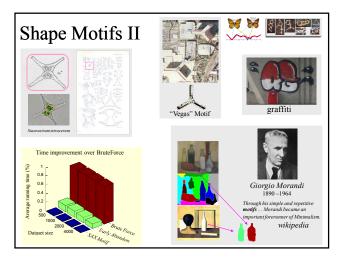


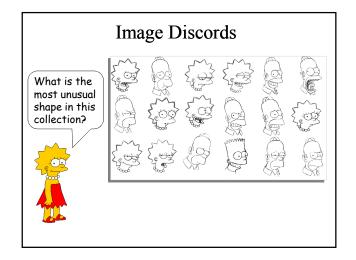


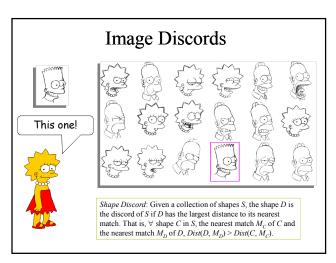


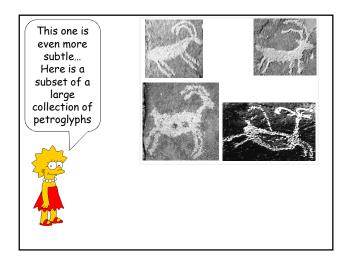


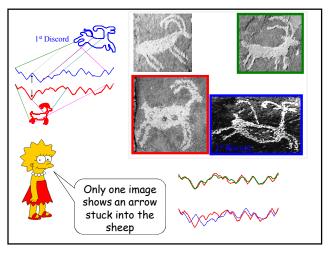


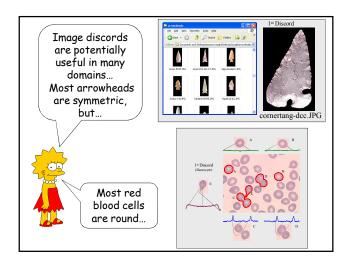


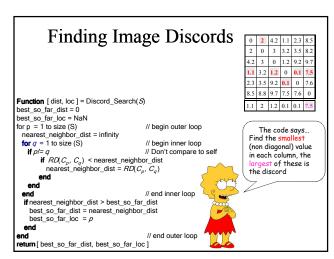


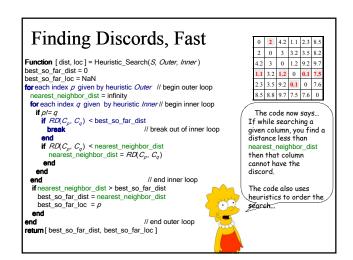


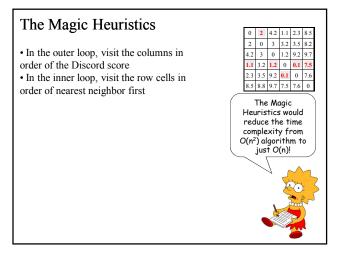


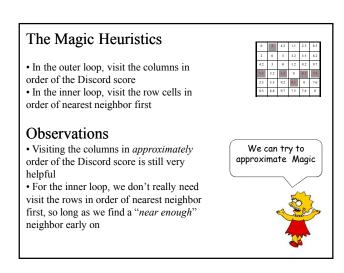


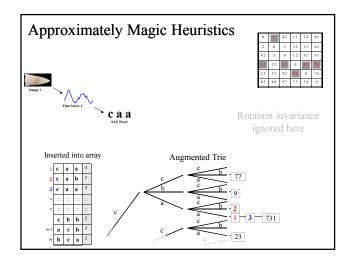


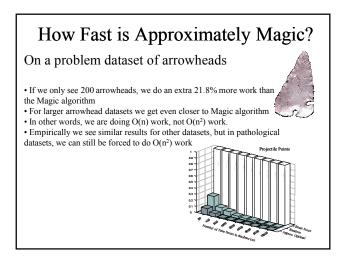


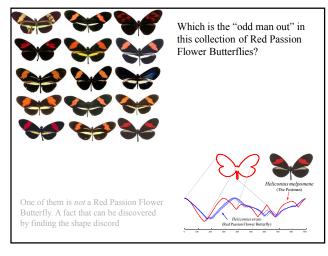


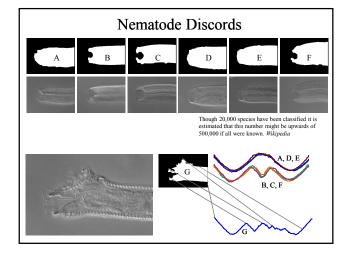


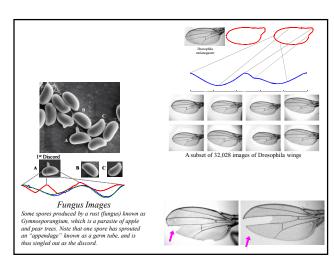


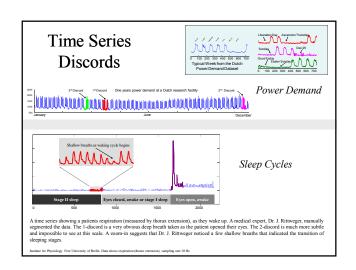


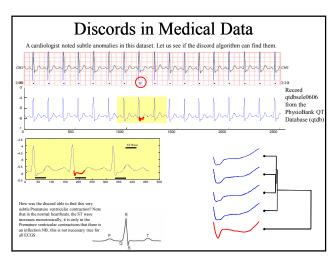


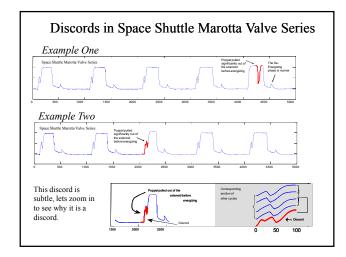






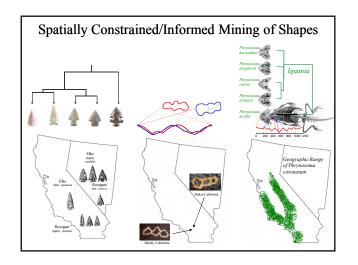






Open Problems

• Let us finish with a brief discussion of some open problems worthy of study



Assessing the Significance of Motifs/Discords

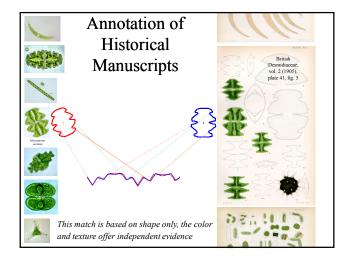
The motif and discord algorithms always return *some* answer, but is the result interesting, or something we should have expected by chance?

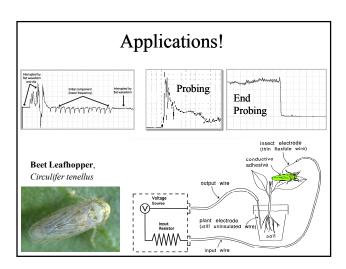
In a large string database, like this ABBANBCJSMBAVSMABG.. would it be more interesting to find...

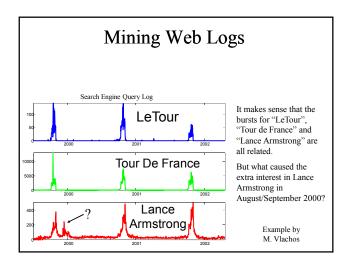
A motif pair {ABBA, ABBA}

A motif pair {ABBAACCC, ABBBCCCCC}

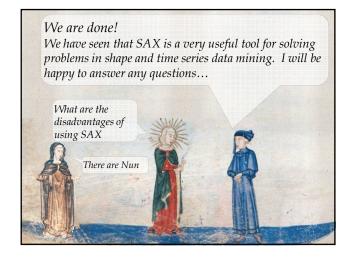
(i.e. shorter but perfect or longer with some misspellings)

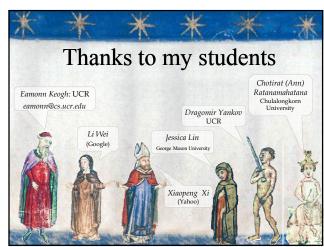






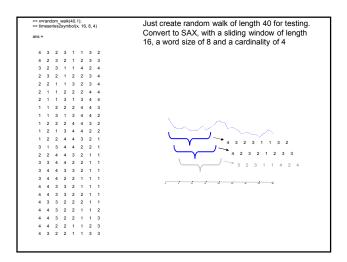


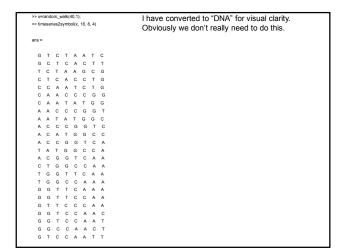


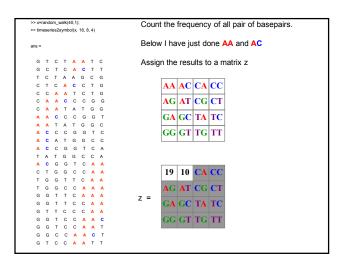


Appendix A

• Converting a long time series to a time series bitmap (Intelligent Icon)







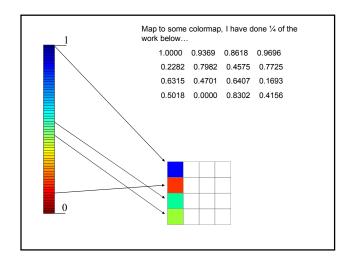
We need to normalize the matrix z, below is one way to do it such that the min value is 0 and the max values is 1. (matlab code)

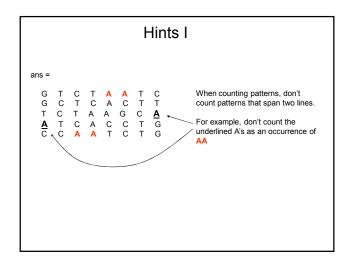
There may be better ways to normalize...

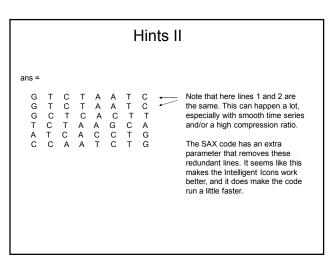
>> z=(z-min(min(z)));
>> z=(z/max(max(z)))

z =

1.0000 0.9369 0.8618 0.9696
 0.2282 0.7982 0.4575 0.7725
 0.6315 0.4701 0.6407 0.1693
 0.5018 0.0000 0.8302 0.4156







Hints III

But what is the best sliding window length?

What is the best a word size?

At the moment there is no answer to this other than playing with the data (or CV if you have labeled data)

The good news is that once you find good settings for your domain (say ECGs) then the settings should work for all ECGS.

The sliding window length should be about twice the length of the natural scale at which the data is interesting. For example, about two heartbeats for cardiology, or for power demand, about two days.

The smoother the data, the smaller you can make the word size.



Appendix: DTW

- There are some critical facts about the size of the warping window r.

 can vary from 0% (the special case of Euclidian distance) to 100% (the special case of full DTW).
- \bullet Without lower bounding, the time taken is approximately linear in r, so r =5% is about twice as
- fast as r = 10%. With lower bounding, the time taken is highly non-linear in r, so r = 5% is perhaps 10 to 100
- times as fast as t = 10%.

 In general (empirically measured over 35 datasets) the following is true.
- If you start with r = 0 and you make it larger, the accuracy improves, then gets worse (see the two examples for FACE and GUN in this tutorial, but it is true for other datasets)

 The best accuracy tends to be at a relatively small value for r (usually just 2 to 5%)

- For any dataset, the best value for r depends on the size of the training set. For example for CBF with just 20 instances, you might need r = 8%, but with 200 instances you only need 1 or 2%, and with 2,000 instances, you need r = 0% (the Euclidean distance).
- How do you find the best choice for r? Use cross valuation to test for the best value.

See [a] and [b]
[a] Xiaopeng Xi, Eamonn Keogh, Christian Shelton, Li Wei & Chotirat Ann Ratanamahatana (2006). Fast Time Series
Classification Using Nimerosity Reduction. ICML
[b] Ratanamahatana, C. A. and Keogh. E. (2004). Everything you know about Dynamic Time Warping is Wrong. Third
Workshop on Mining Temporal and Sequential Data, in conjunction with the Tenth ACM SIGKDD International
Conference on Knowledge Discovery and Data Mining (KDD-2004), August 22-25, 2004 - Seattle, WA